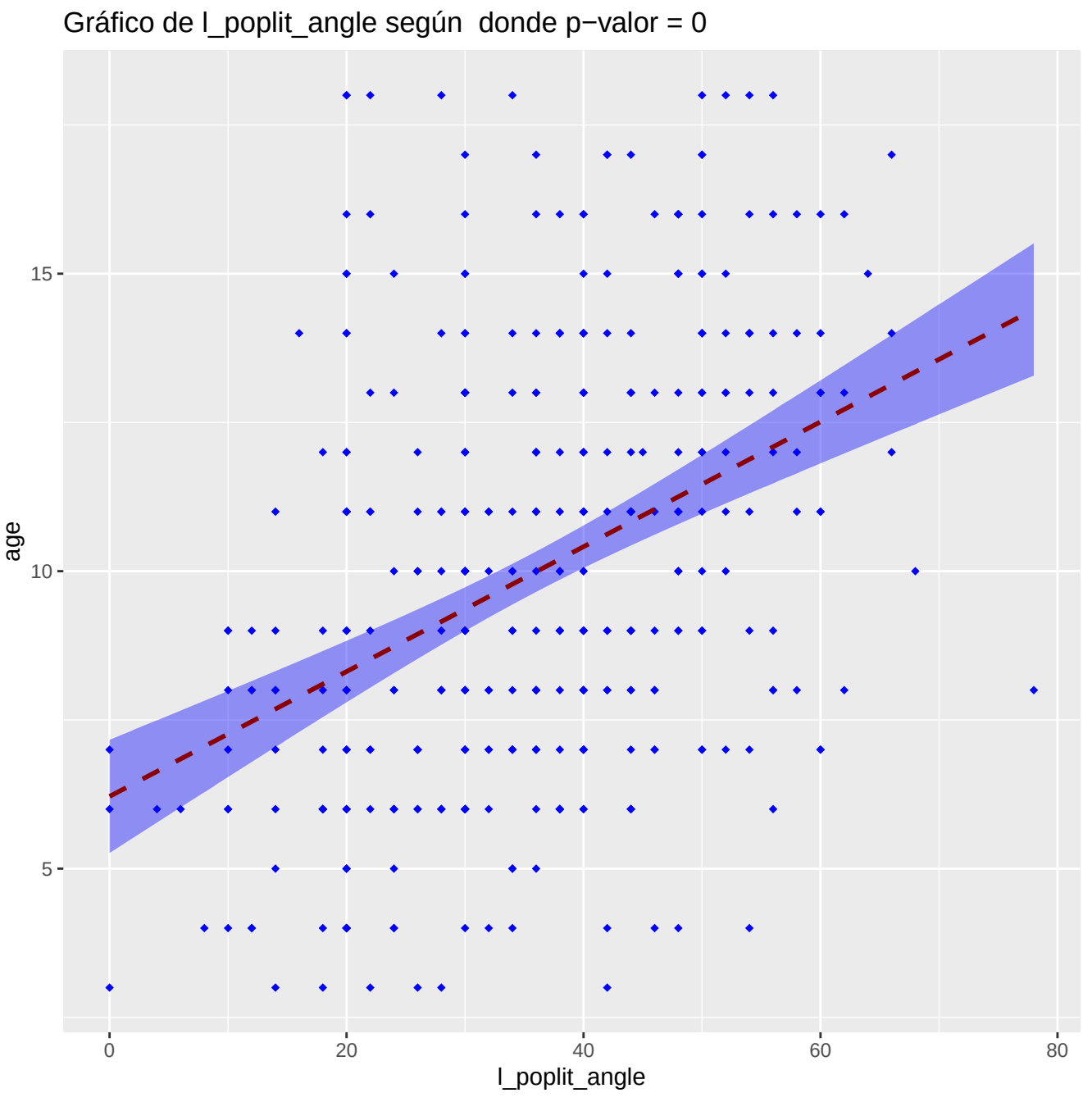
Gráfico de l_poplit_angle según donde p−valor = 0
age
15
10
5
0
20
40
60
80
l_poplit_angle

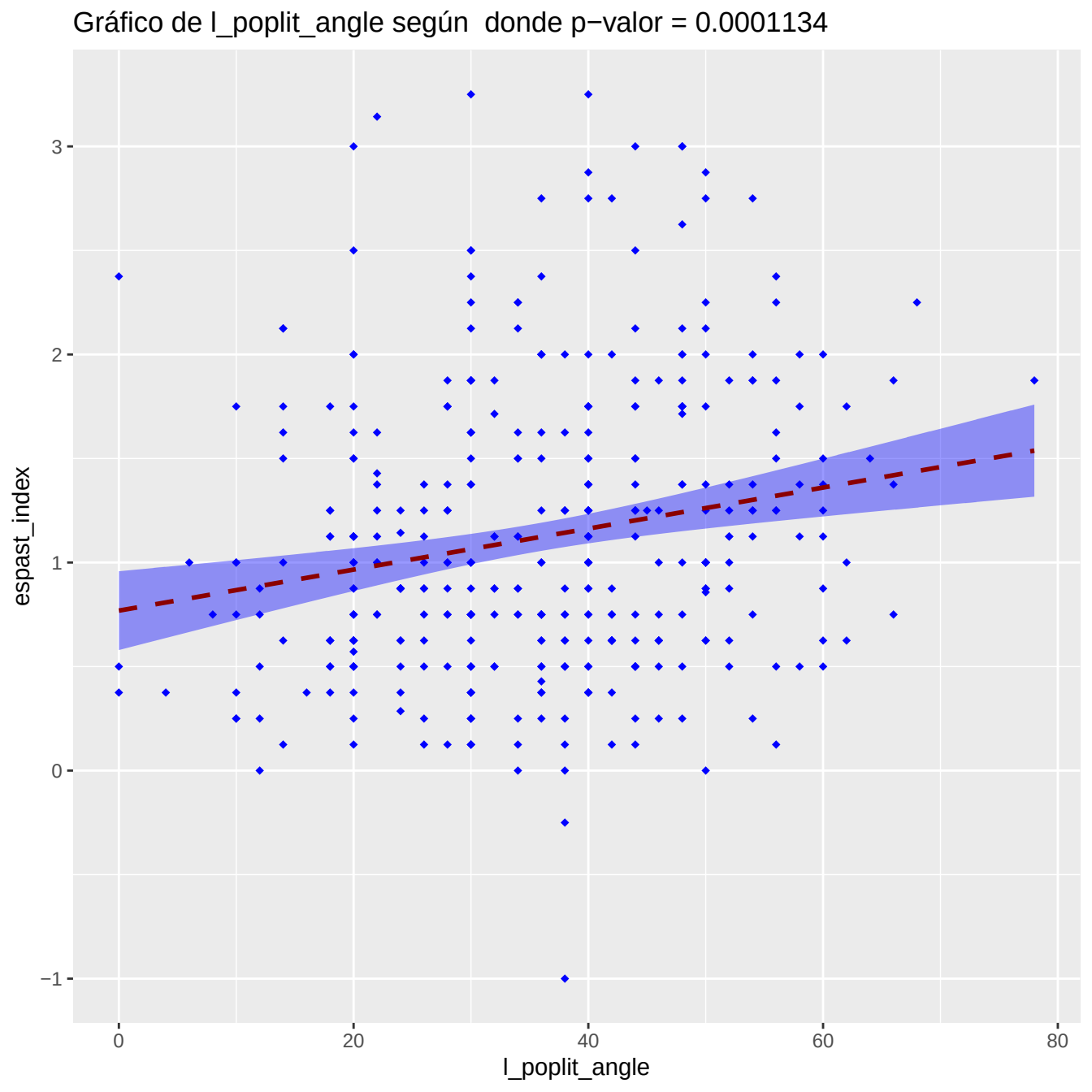
Gráfico de l_poplit_angle según donde p−valor = 0.0001134
espast_index
l_poplit_angle
3
2
1
0
−1
0
20
40
60
80

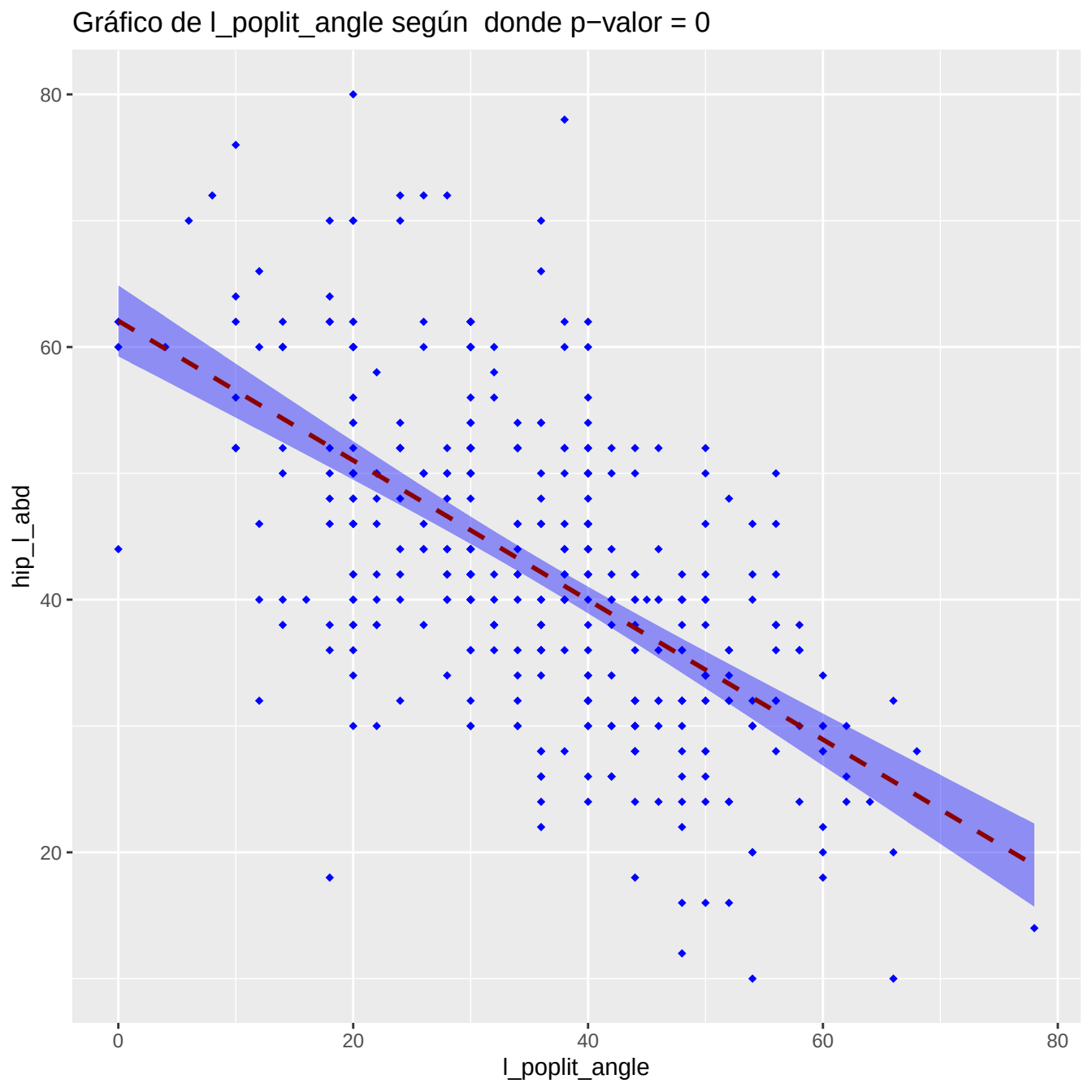
Gráfico de l_poplit_angle según donde p−valor = 0
hip_l_abd
80
60
40
20
0
20
40
60
80
l_poplit_angle

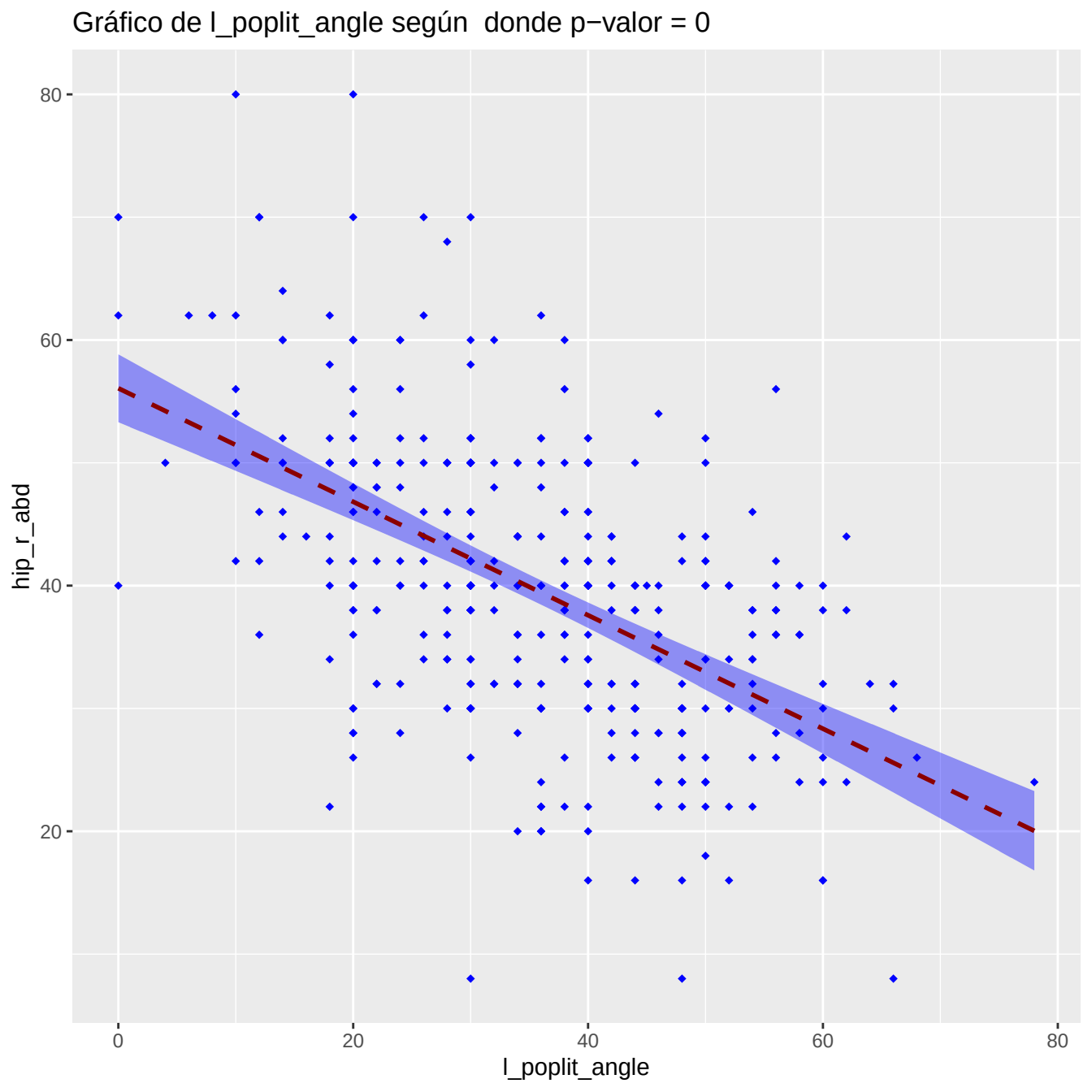
Gráfico de l_poplit_angle según donde p−valor = 0
hip_r_abd
80
60
40
20
0
20
40
60
80
l_poplit_angle

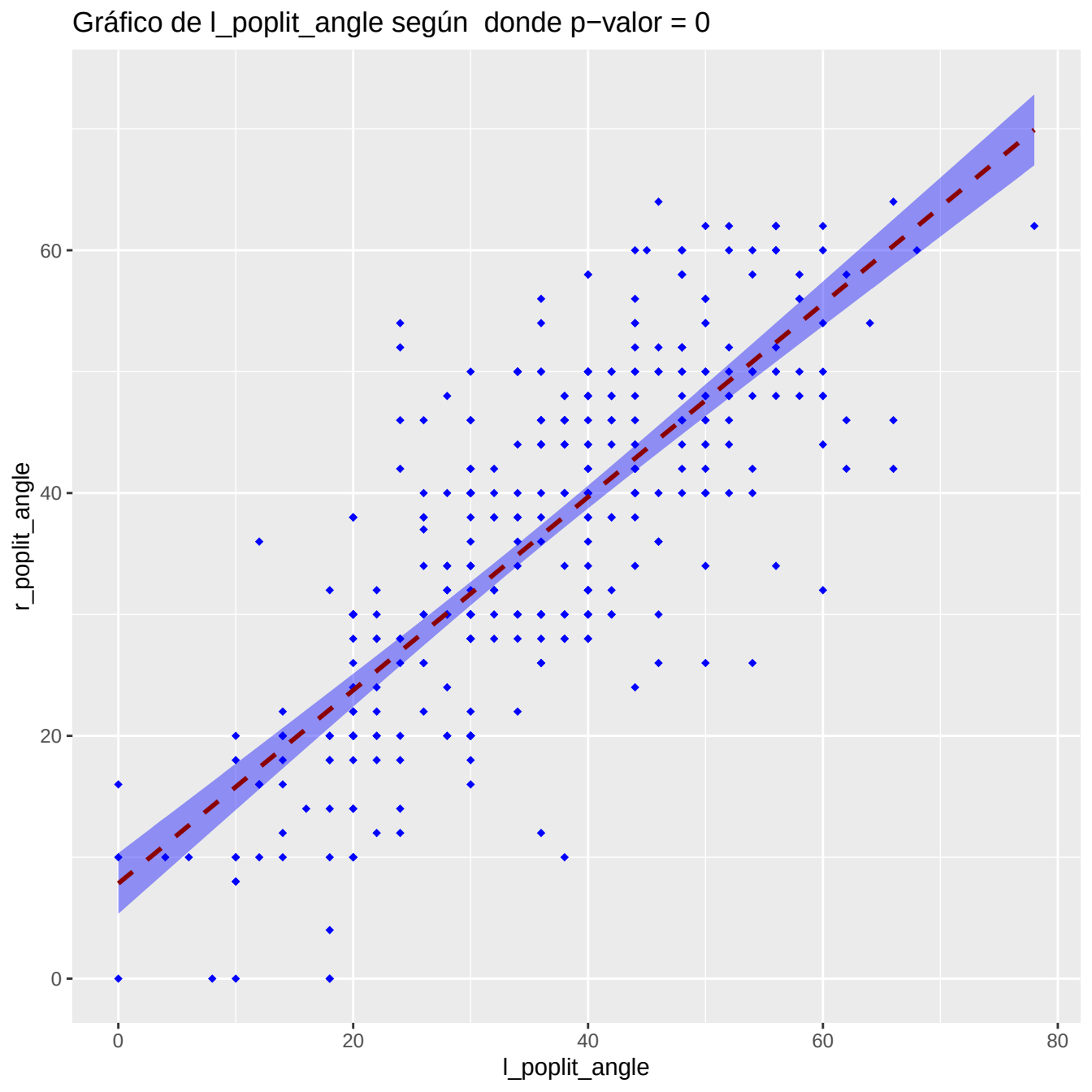
Gráfico de l_poplit_angle según donde p−valor = 0
r_poplit_angle
0
20
40
60
l_poplit_angle
0
20
40
60
80

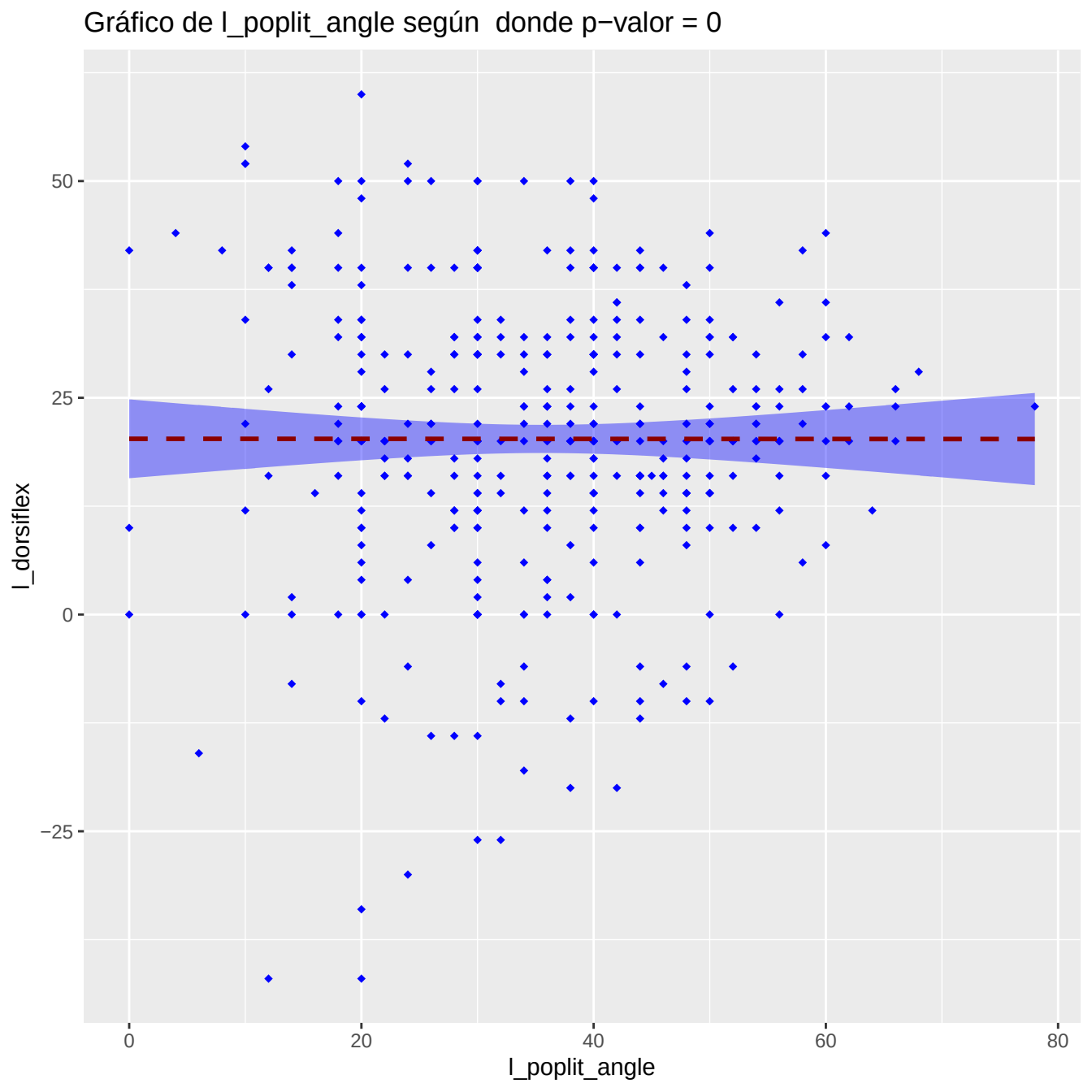
Gráfico de l_poplit_angle según donde p−valor = 0
l_dorsiflex
50
25
0
−25
0
20
40
60
80
l_poplit_angle

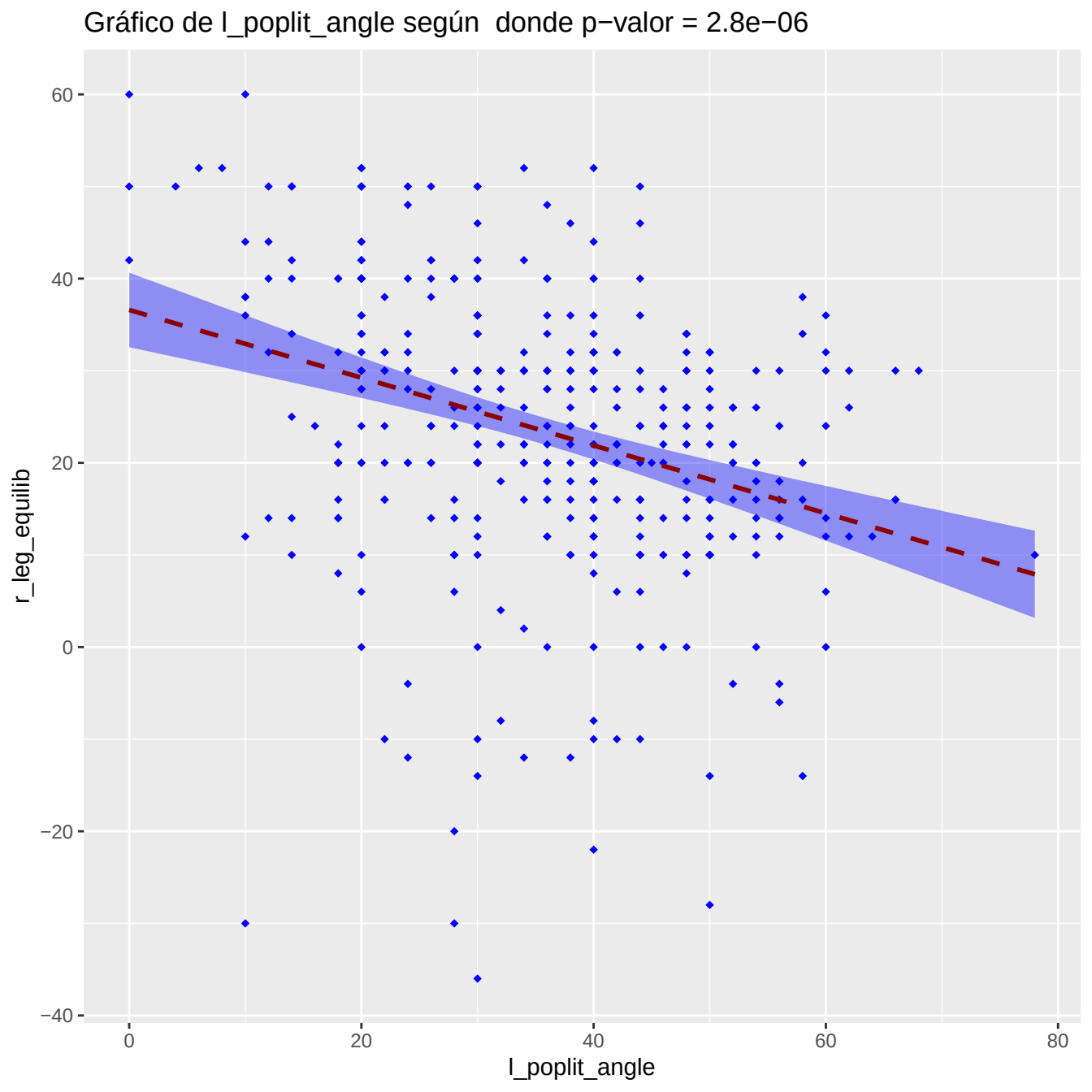
Gráfico de l_poplit_angle según donde p−valor = 2.8e−06
r_leg_equilib
l_poplit_angle
60
40
20
0
−20
−40
0
20
40
60
80

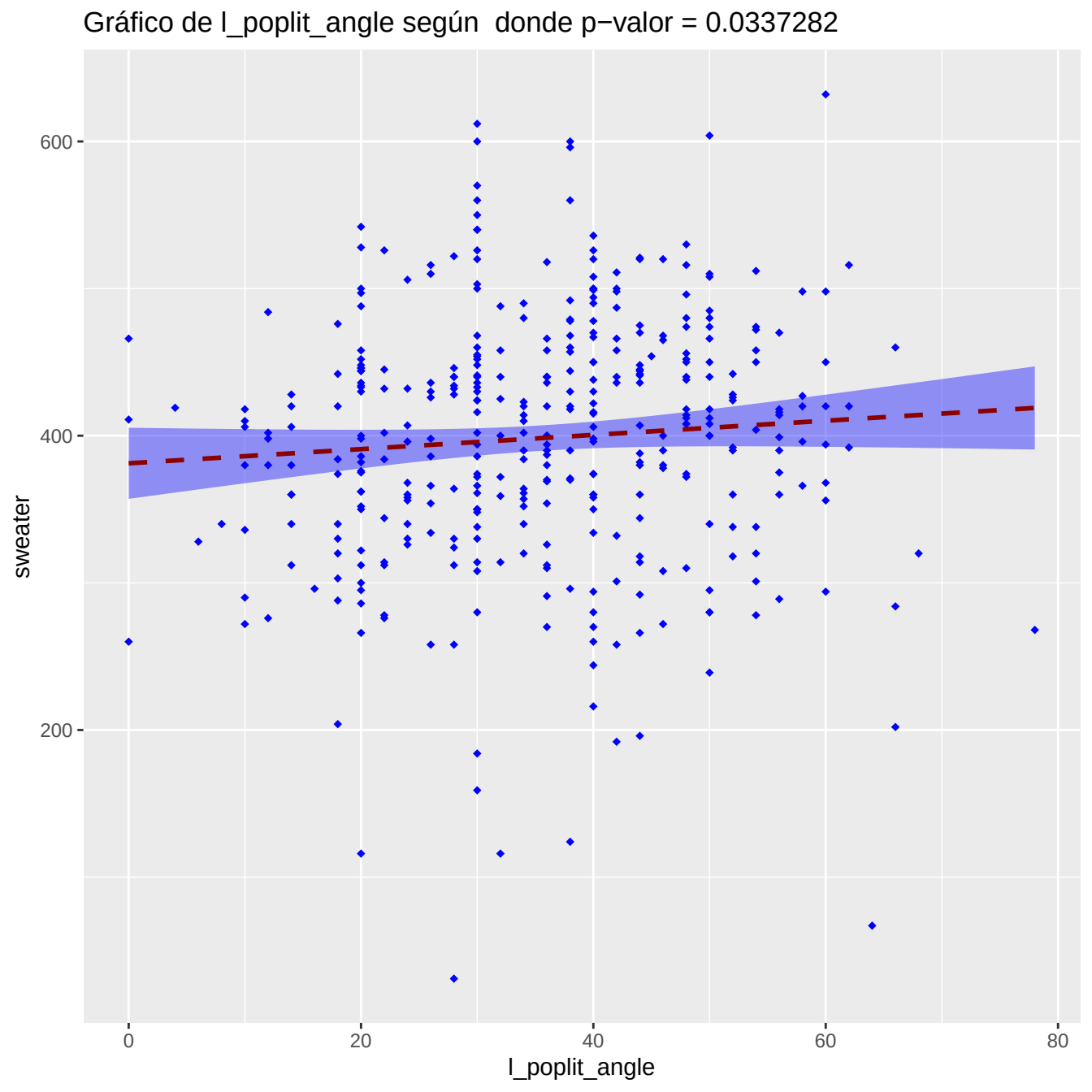
Gráfico de l_poplit_angle según donde p−valor = 0.0337282
600
400
200
sweater
0
20
40
60
80
l_poplit_angle

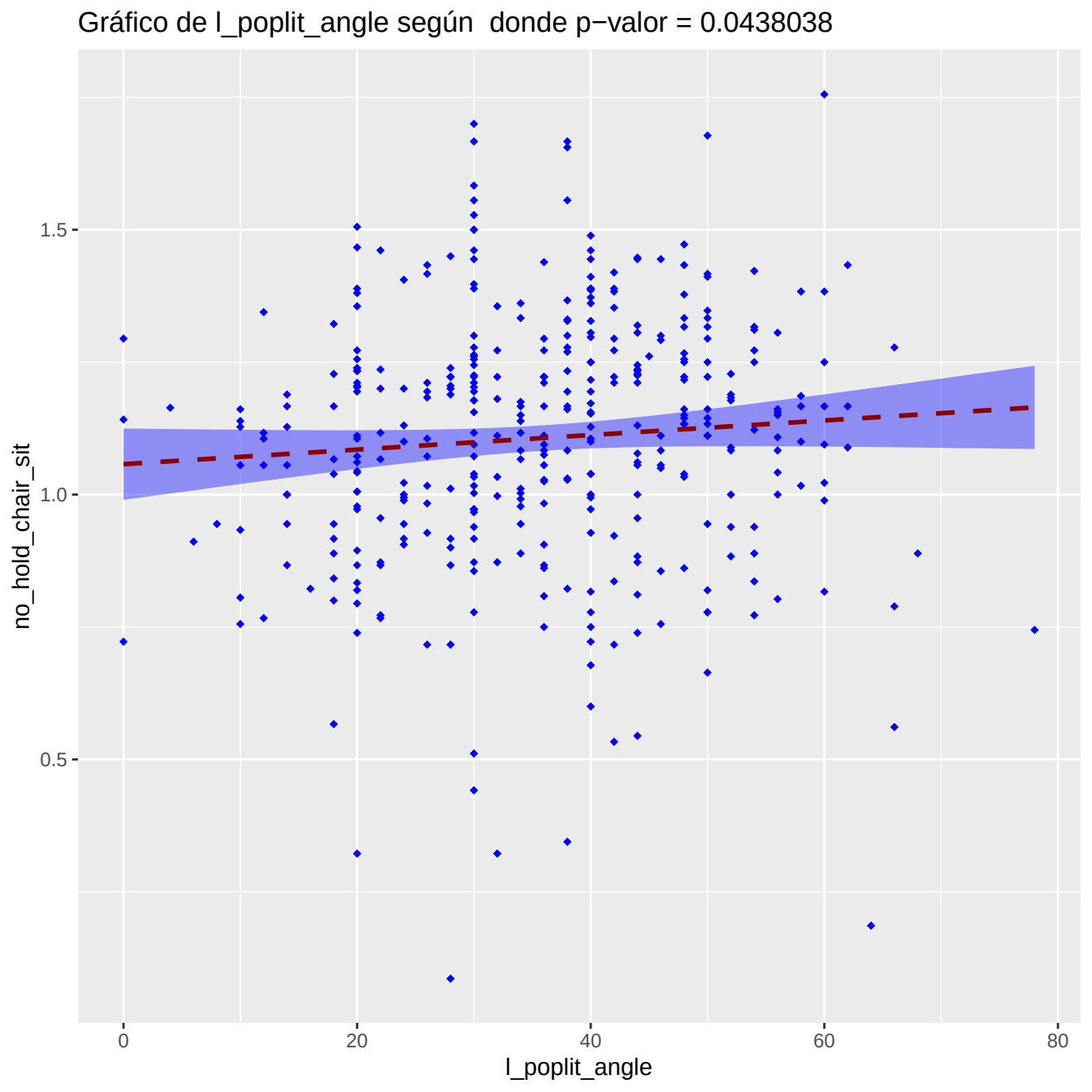
Gráfico de l_poplit_angle según donde p−valor = 0.0438038
no_hold_chair_sit
1.5
1.0
0.5
0
20
40
60
80
l_poplit_angle

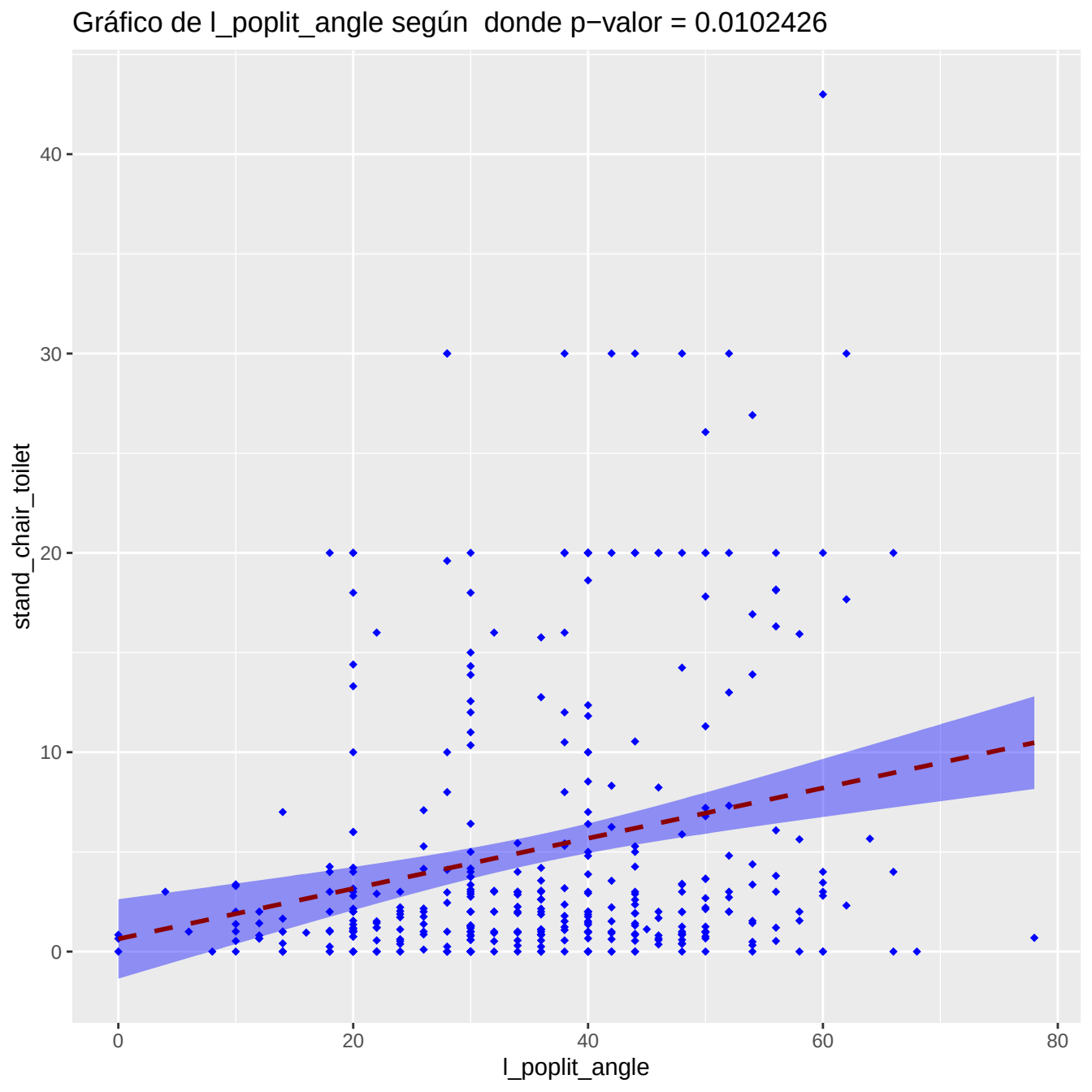
Gráfico de l_poplit_angle según donde p−valor = 0.0102426
stand_chair_toilet
0
10
20
30
40
l_poplit_angle
0
20
40
60
80

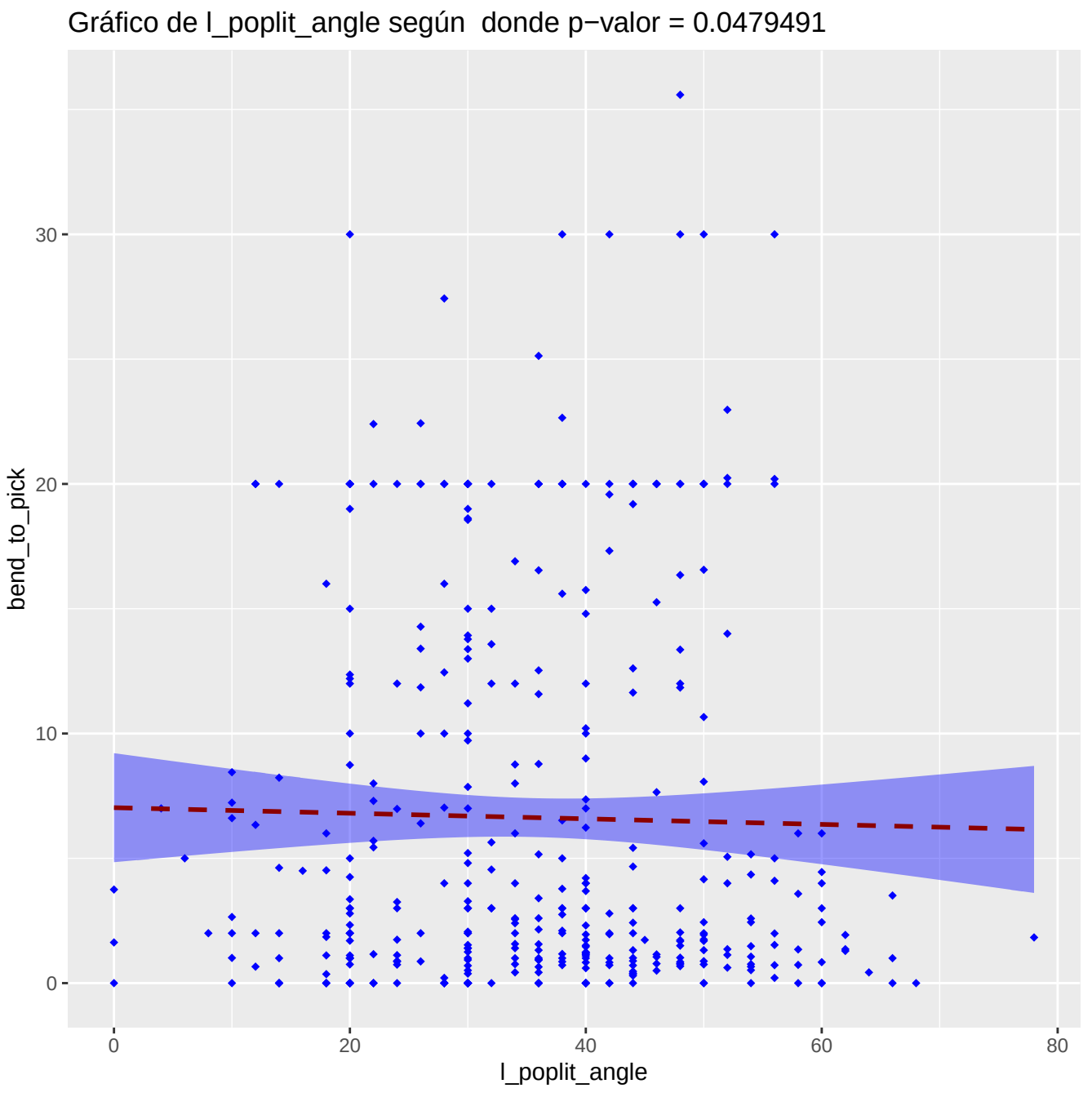
Gráfico de l_poplit_angle según donde p−valor = 0.0479491
bend_to_pick
30
20
10
0
0
20
40
60
80
l_poplit_angle

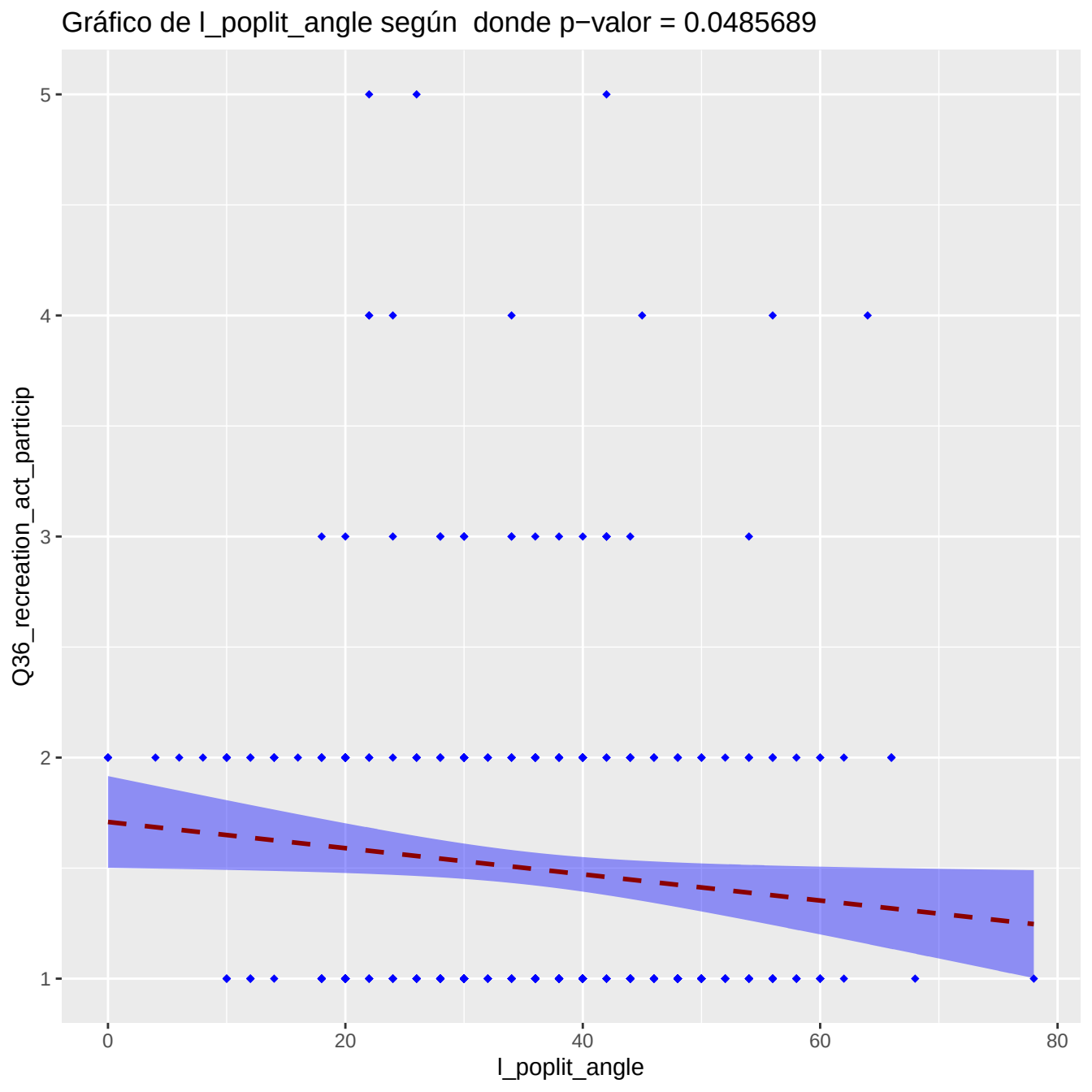
Gráfico de l_poplit_angle según donde p−valor = 0.0485689
Q36_recreation_act_particip
5
4
3
2
1
0
20
40
60
80
l_poplit_angle

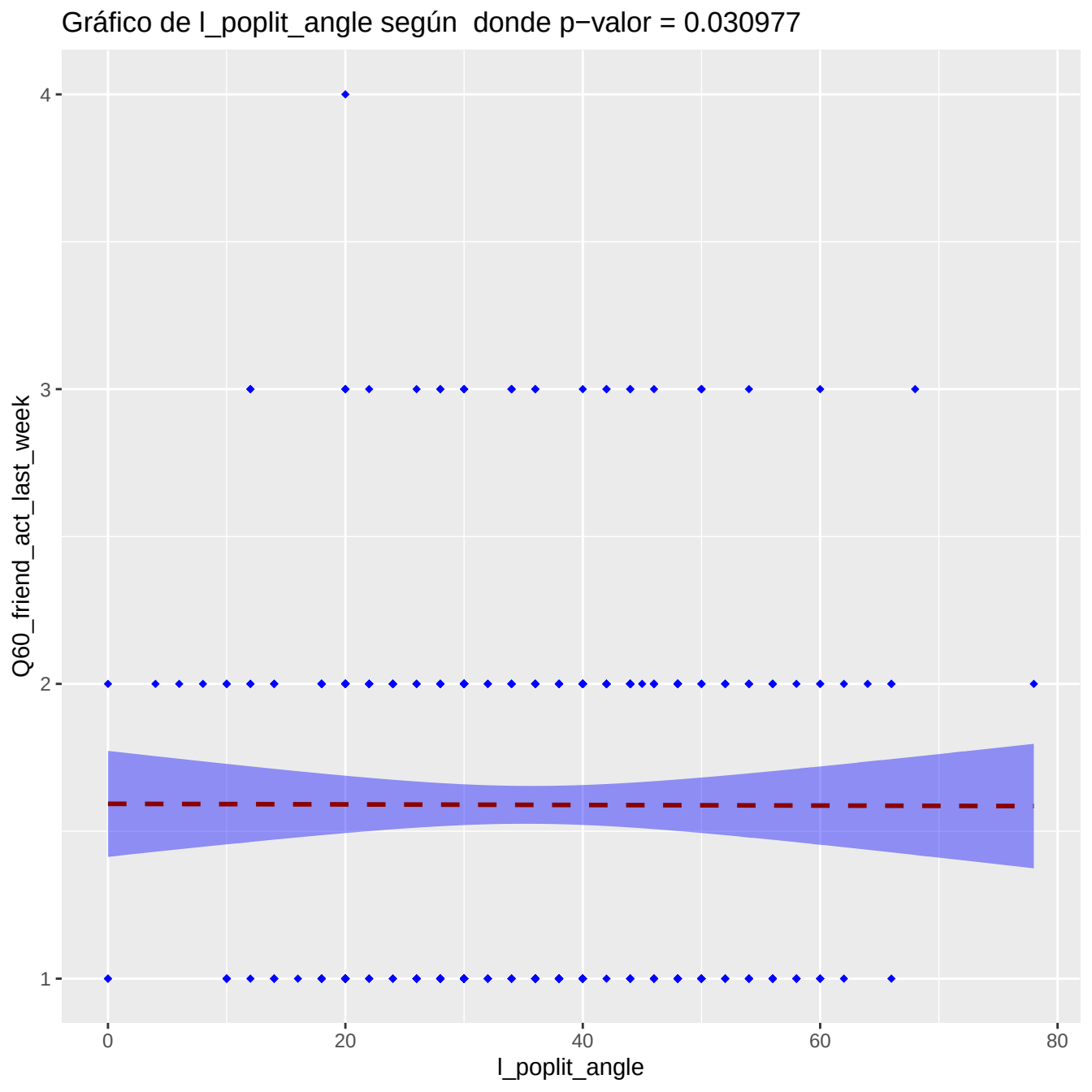
Gráfico de l_poplit_angle según donde p−valor = 0.030977
Q60_friend_act_last_week
4
3
2
1
0
20
40
60
80
l_poplit_angle

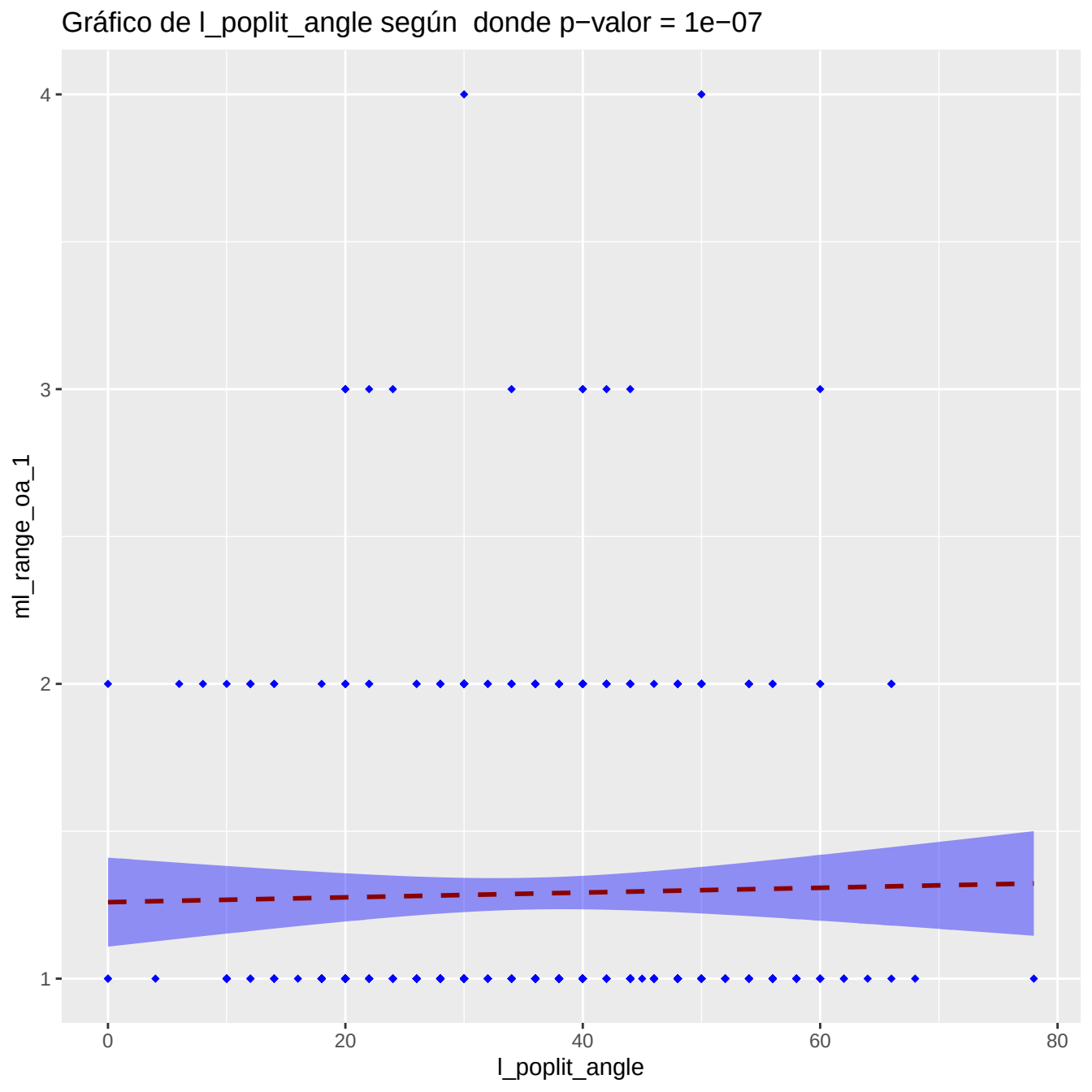
Gráfico de l_poplit_angle según donde p−valor = 1e−07
ml_range_oa_1
4
3
2
1
0
20
40
60
80
l_poplit_angle

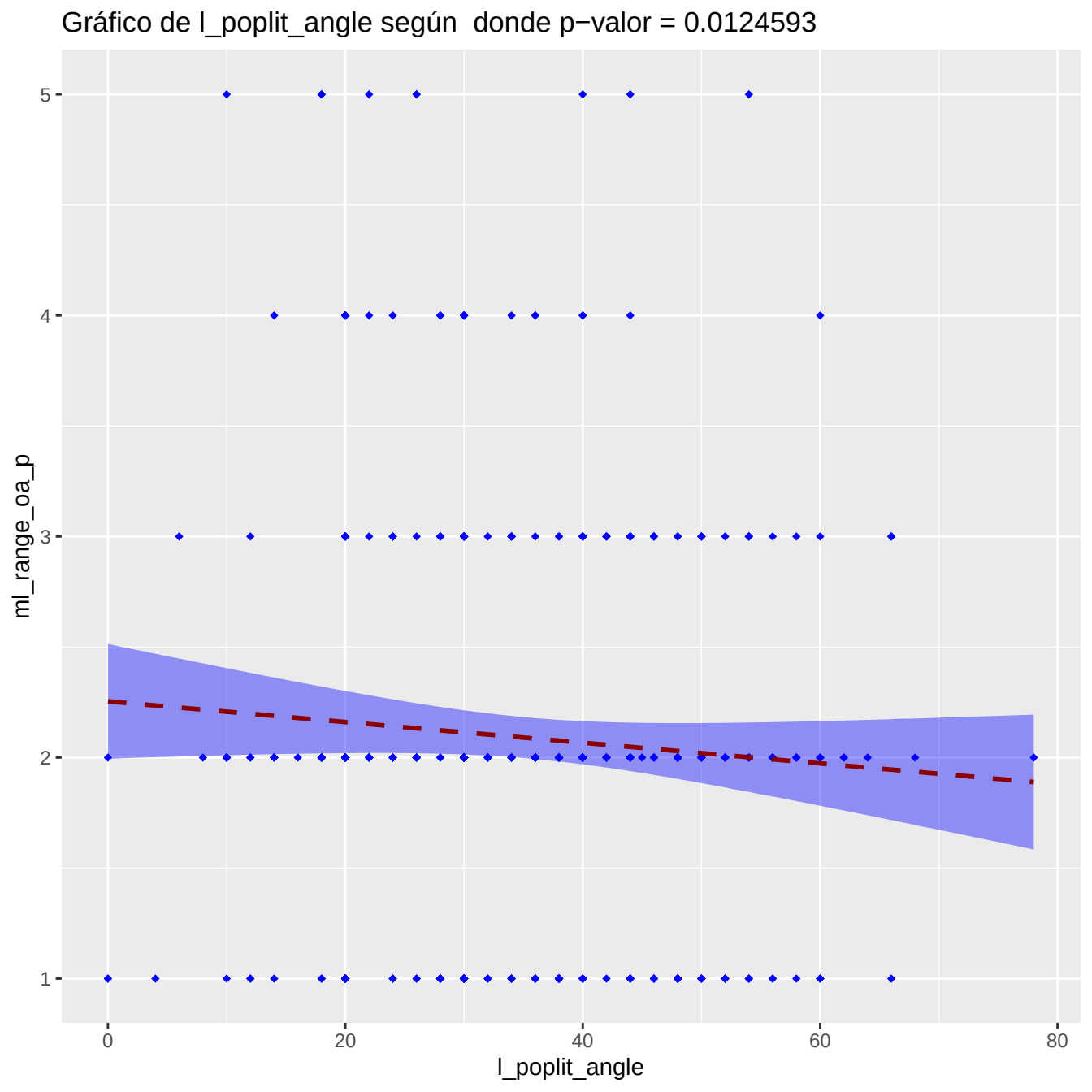
Gráfico de l_poplit_angle según donde p−valor = 0.0124593
ml_range_oa_p
5
4
3
2
1
0
20
40
60
80
l_poplit_angle

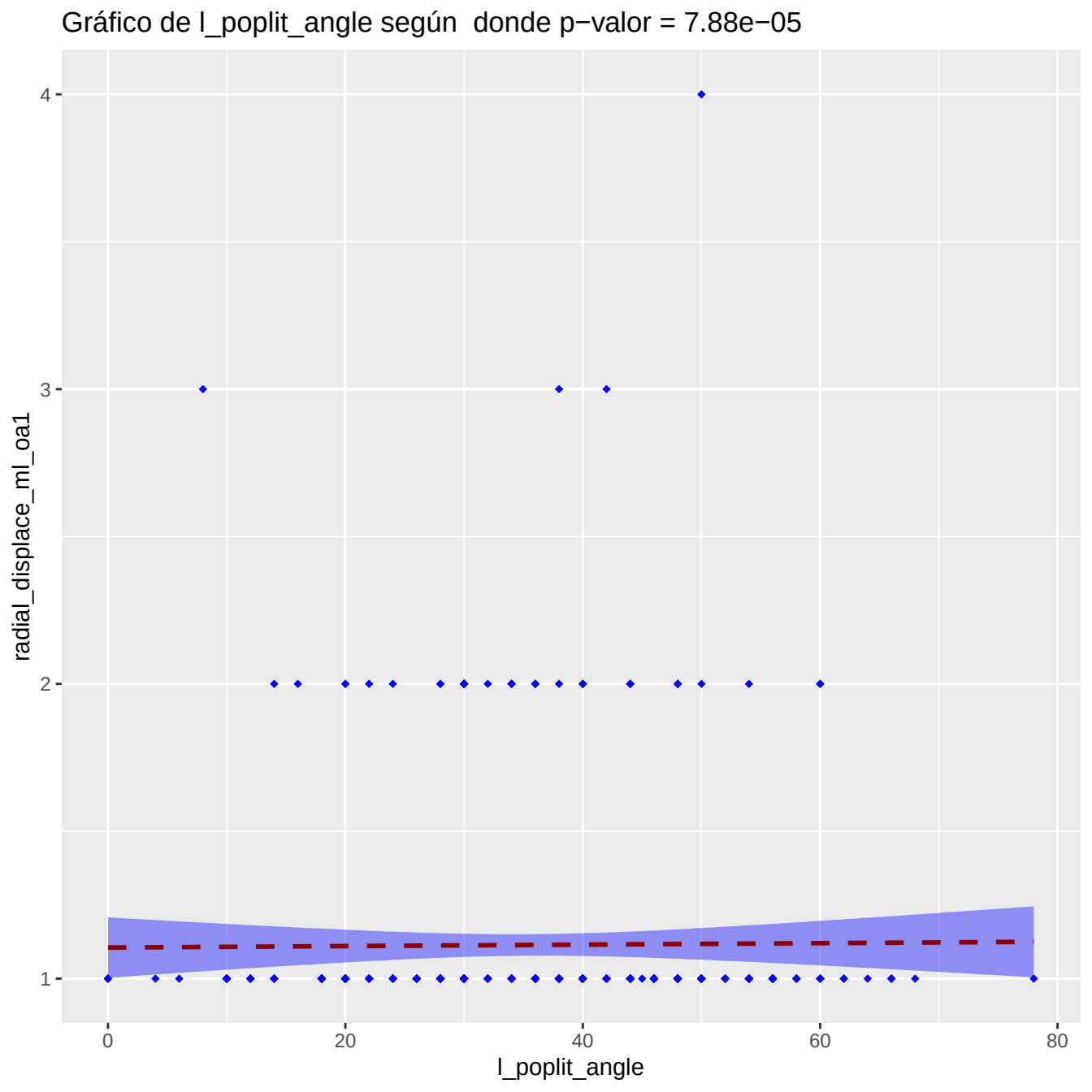
Gráfico de l_poplit_angle según donde p−valor = 7.88e−05
radial_displace_ml_oa1
4
3
2
1
0
20
40
60
80
l_poplit_angle

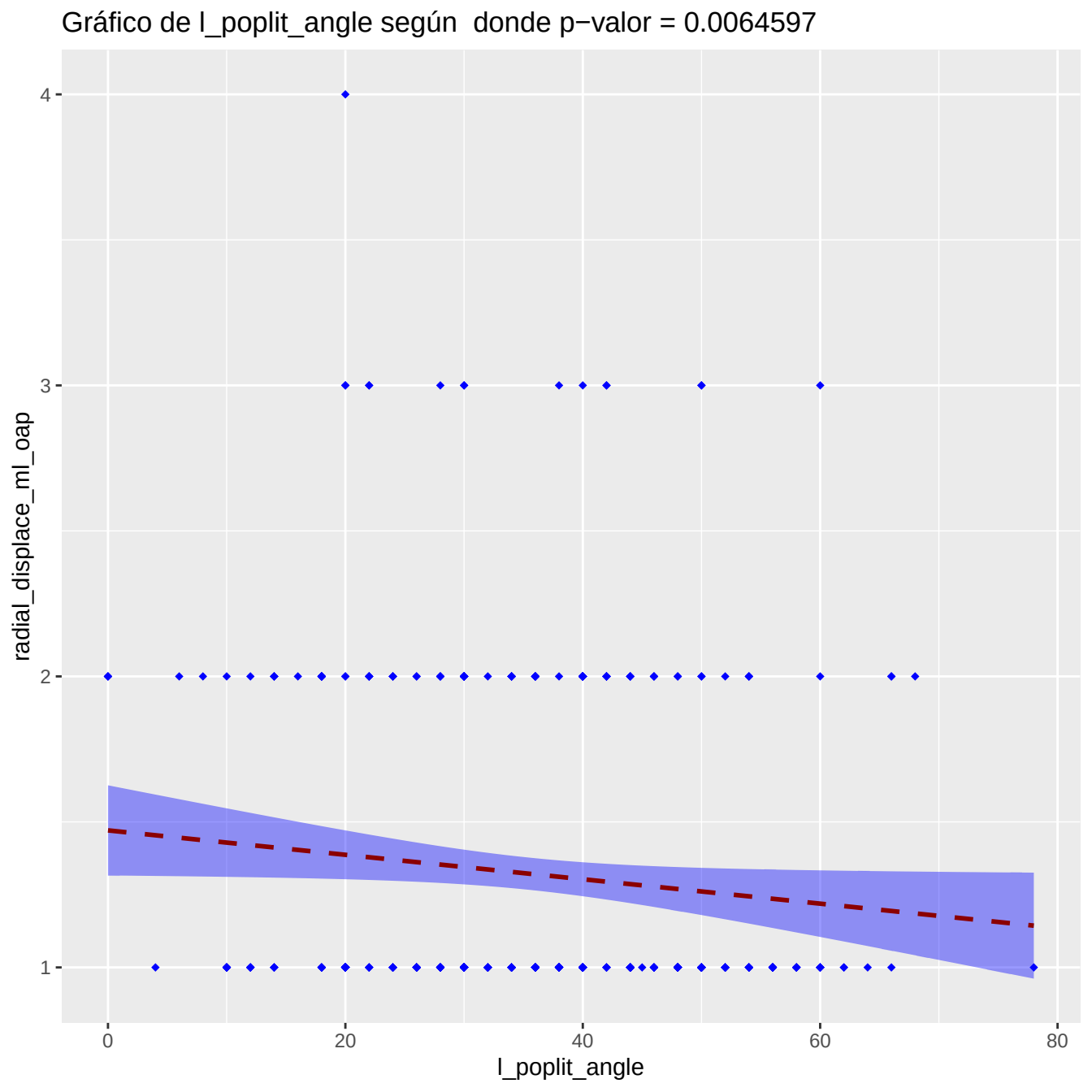
Gráfico de l_poplit_angle según donde p−valor = 0.0064597
radial_displace_ml_oap
4
3
2
1
0
20
40
60
80
l_poplit_angle

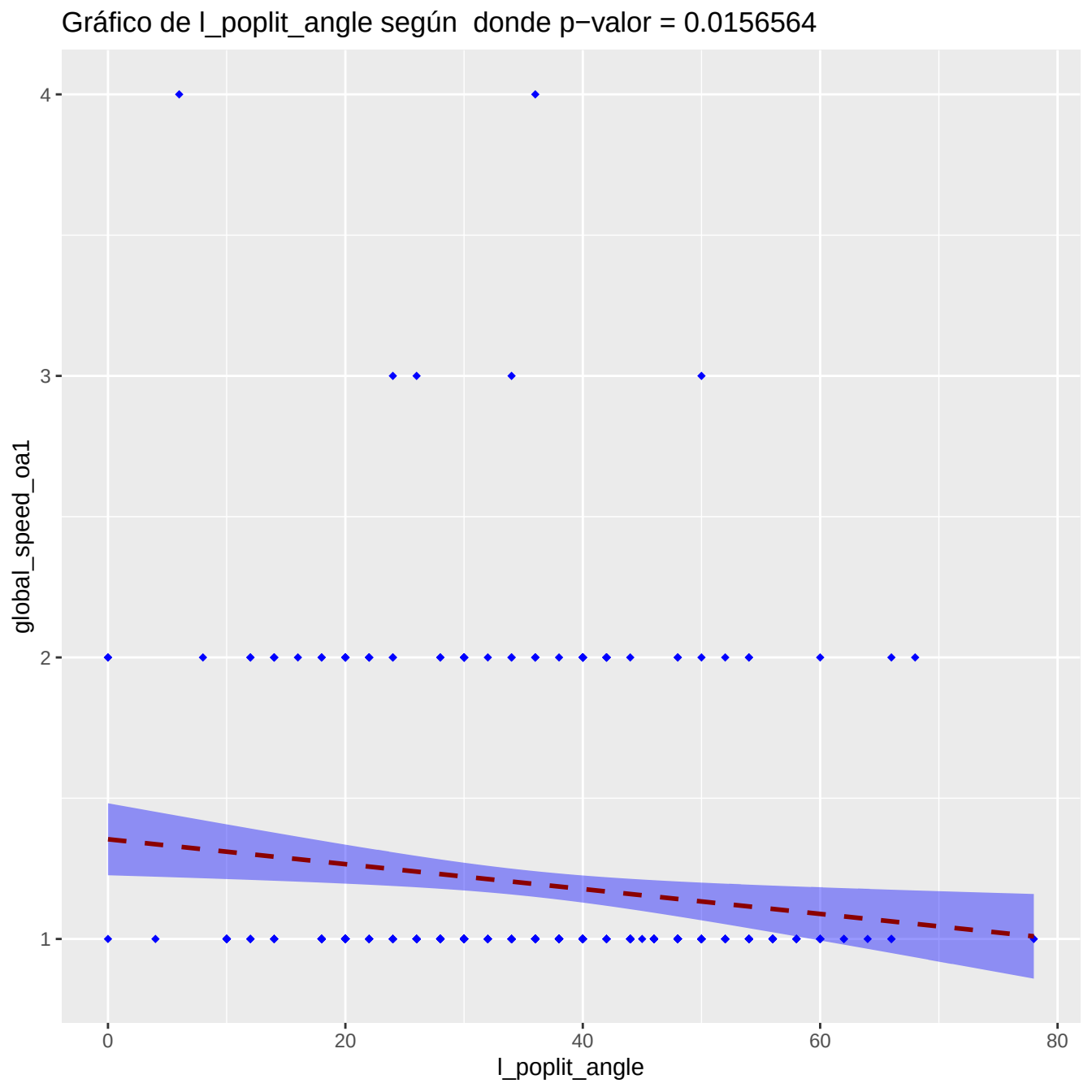
Gráfico de l_poplit_angle según donde p−valor = 0.0156564
global_speed_oa1
4
3
2
1
0
20
40
60
80
l_poplit_angle

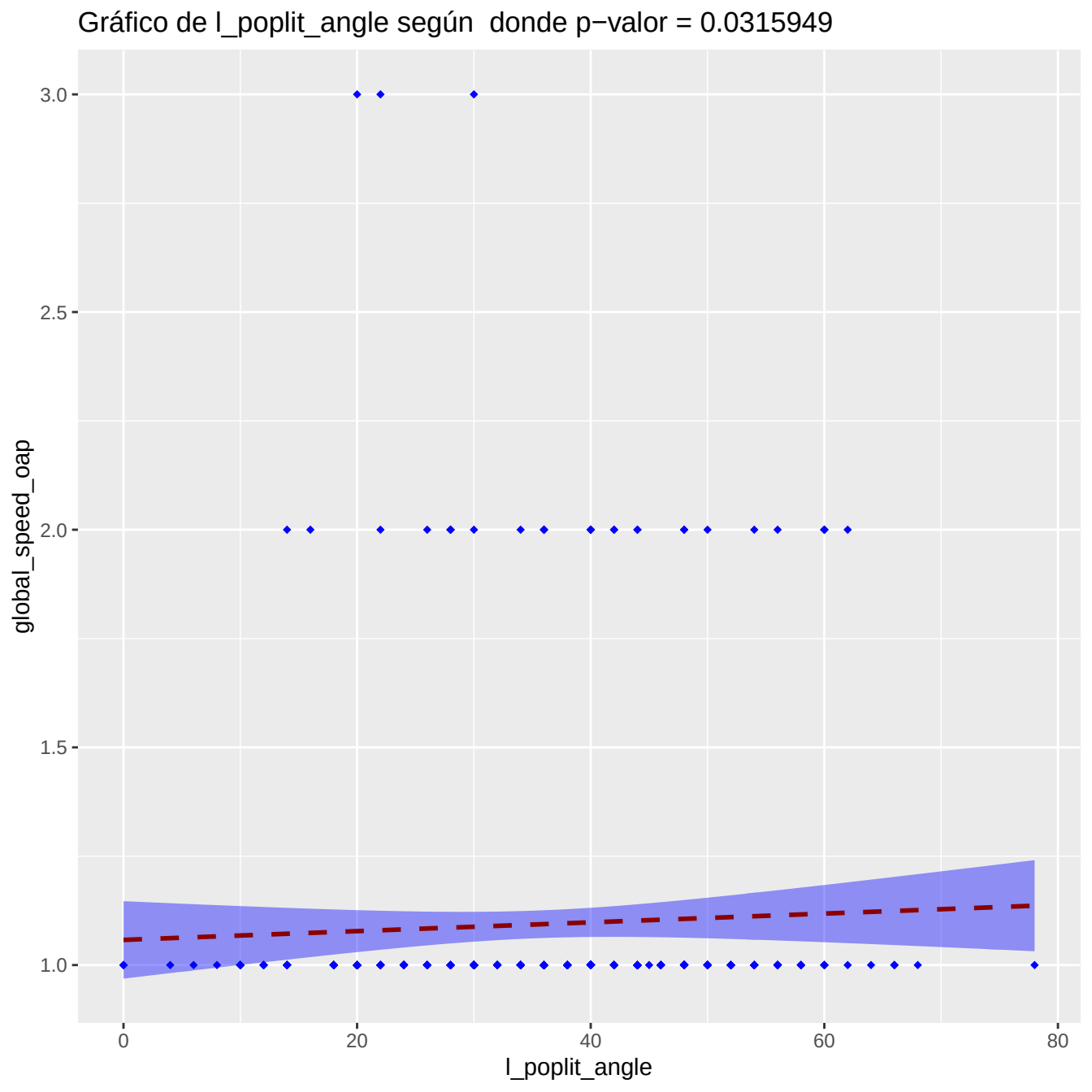
Gráfico de l_poplit_angle según donde p−valor = 0.0315949
global_speed_oap
3.0
2.5
2.0
1.5
1.0
0
20
40
60
80
l_poplit_angle

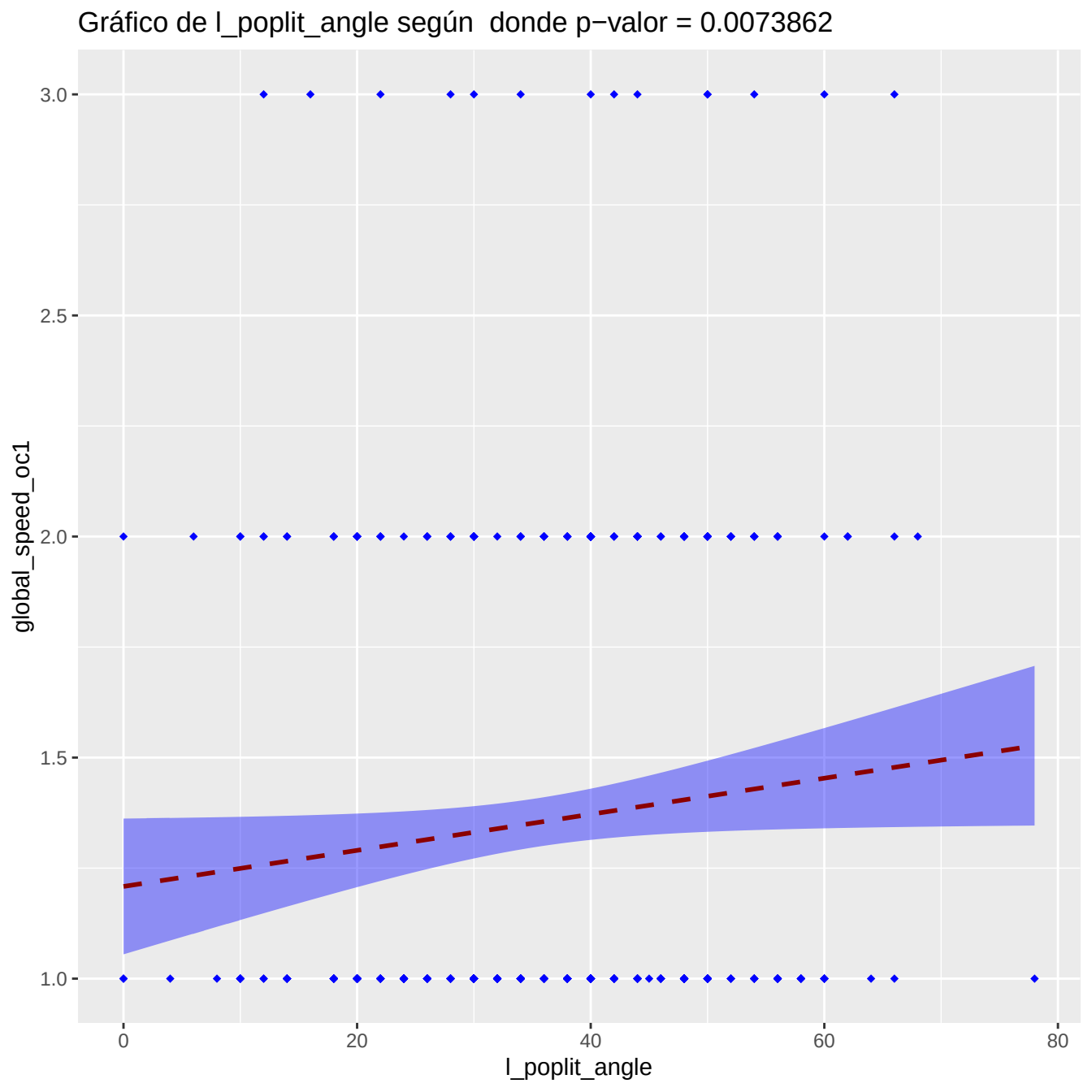
Gráfico de l_poplit_angle según donde p−valor = 0.0073862
global_speed_oc1
3.0
2.5
2.0
1.5
1.0
0
20
40
60
80
l_poplit_angle

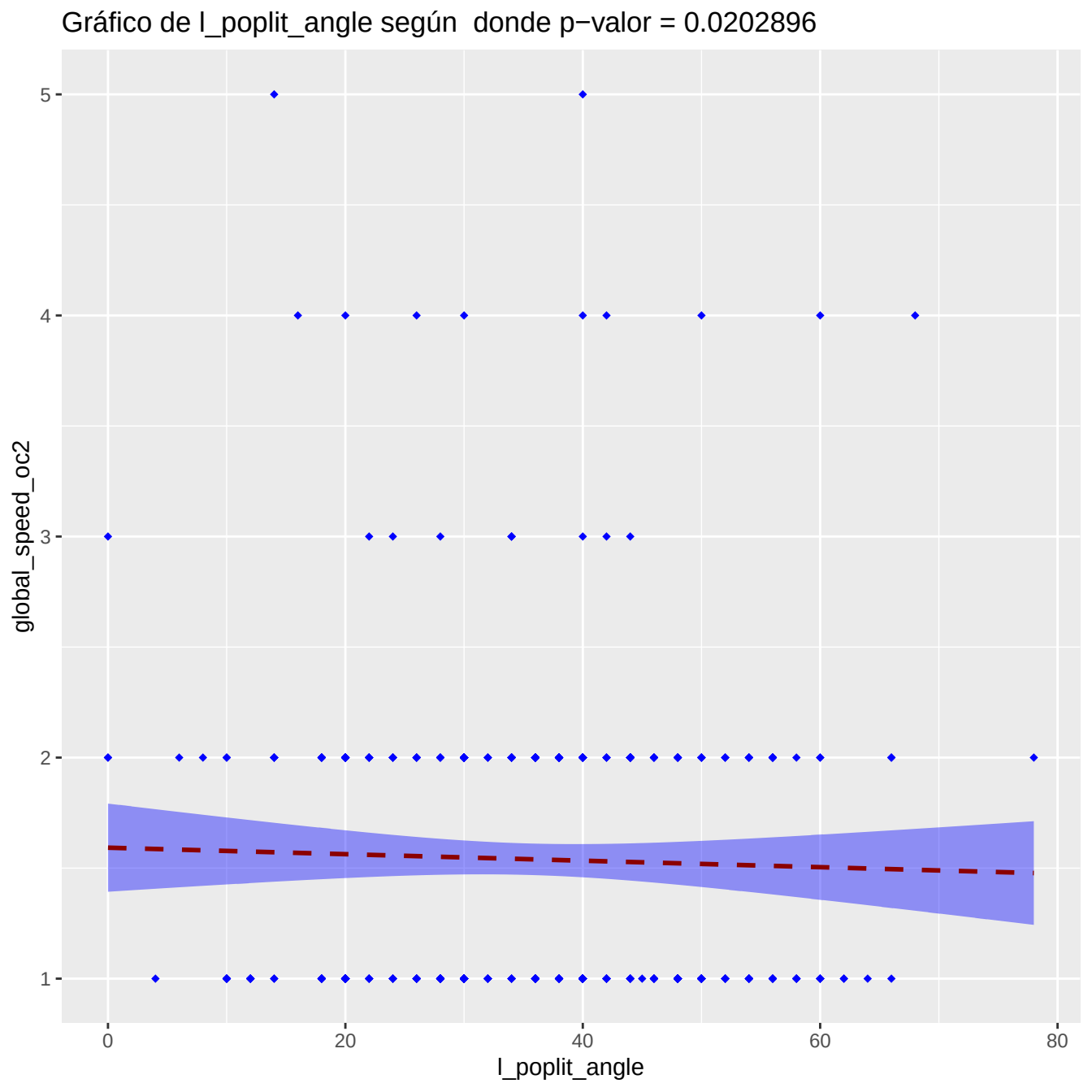
Gráfico de l_poplit_angle según donde p−valor = 0.0202896
global_speed_oc2
5
4
3
2
1
0
20
40
60
80
l_poplit_angle

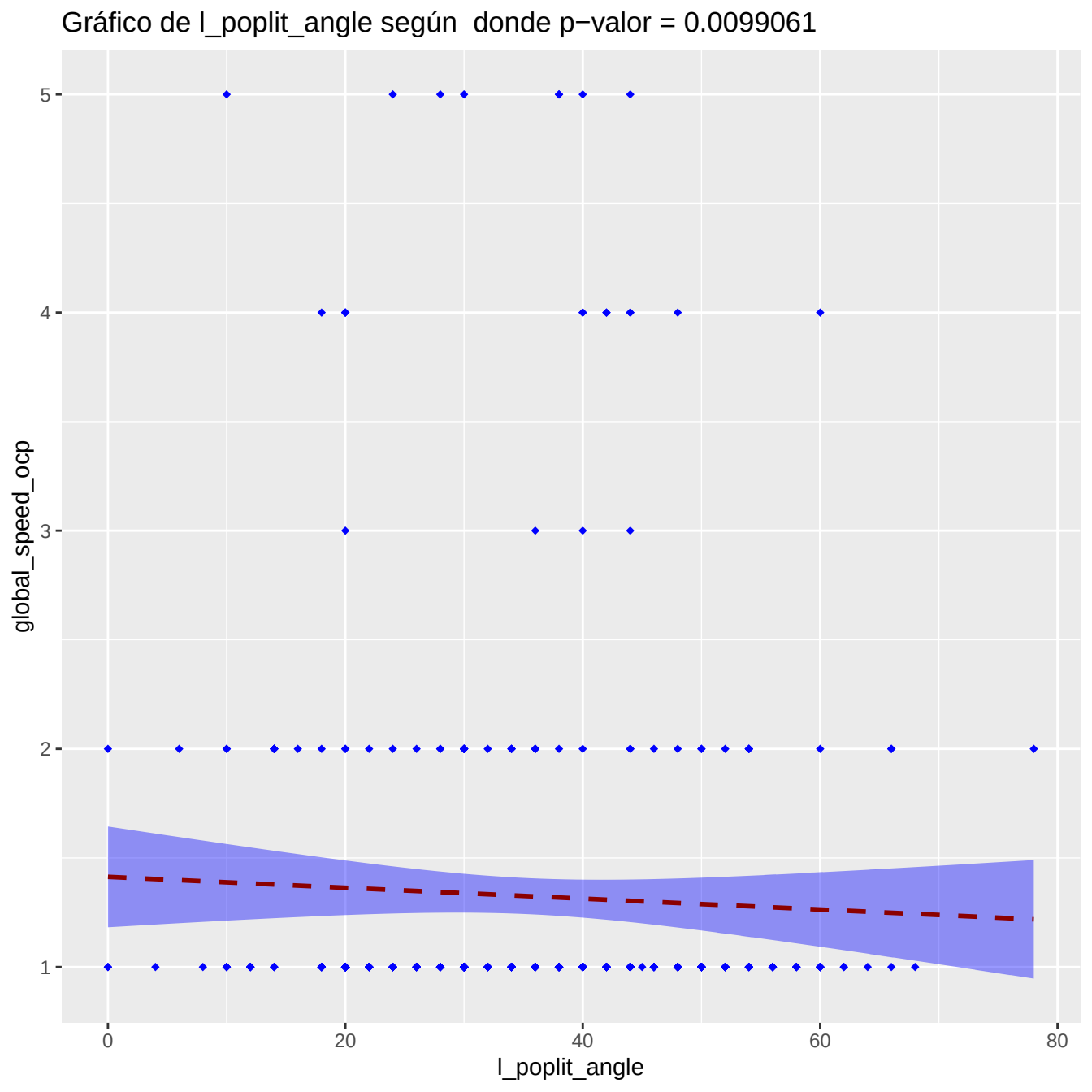
Gráfico de l_poplit_angle según donde p−valor = 0.0099061
global_speed_ocp
5
4
3
2
1
0
20
40
60
80
l_poplit_angle

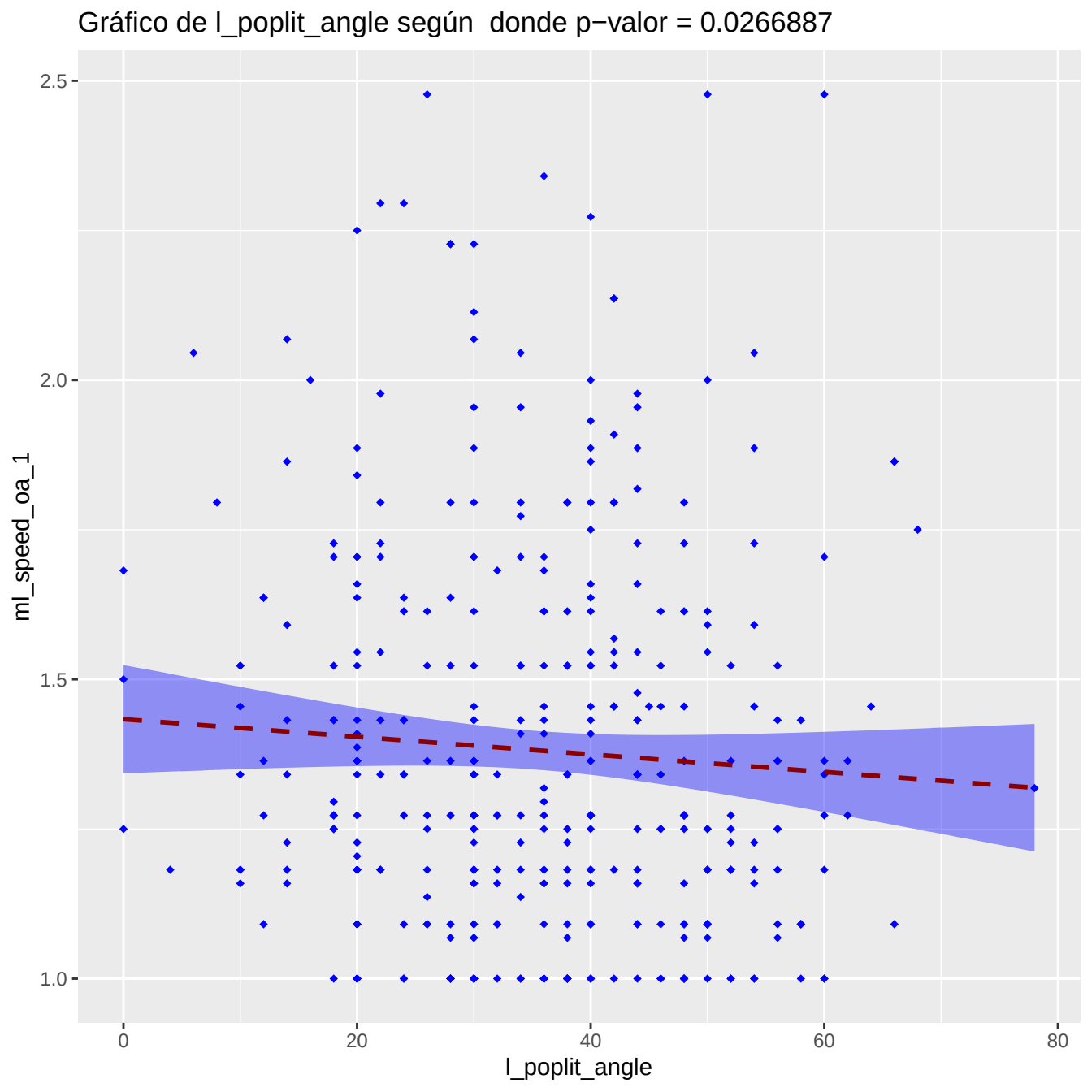
Gráfico de l_poplit_angle según donde p−valor = 0.0266887
ml_speed_oa_1
2.5
2.0
1.5
1.0
0
20
40
60
80
l_poplit_angle

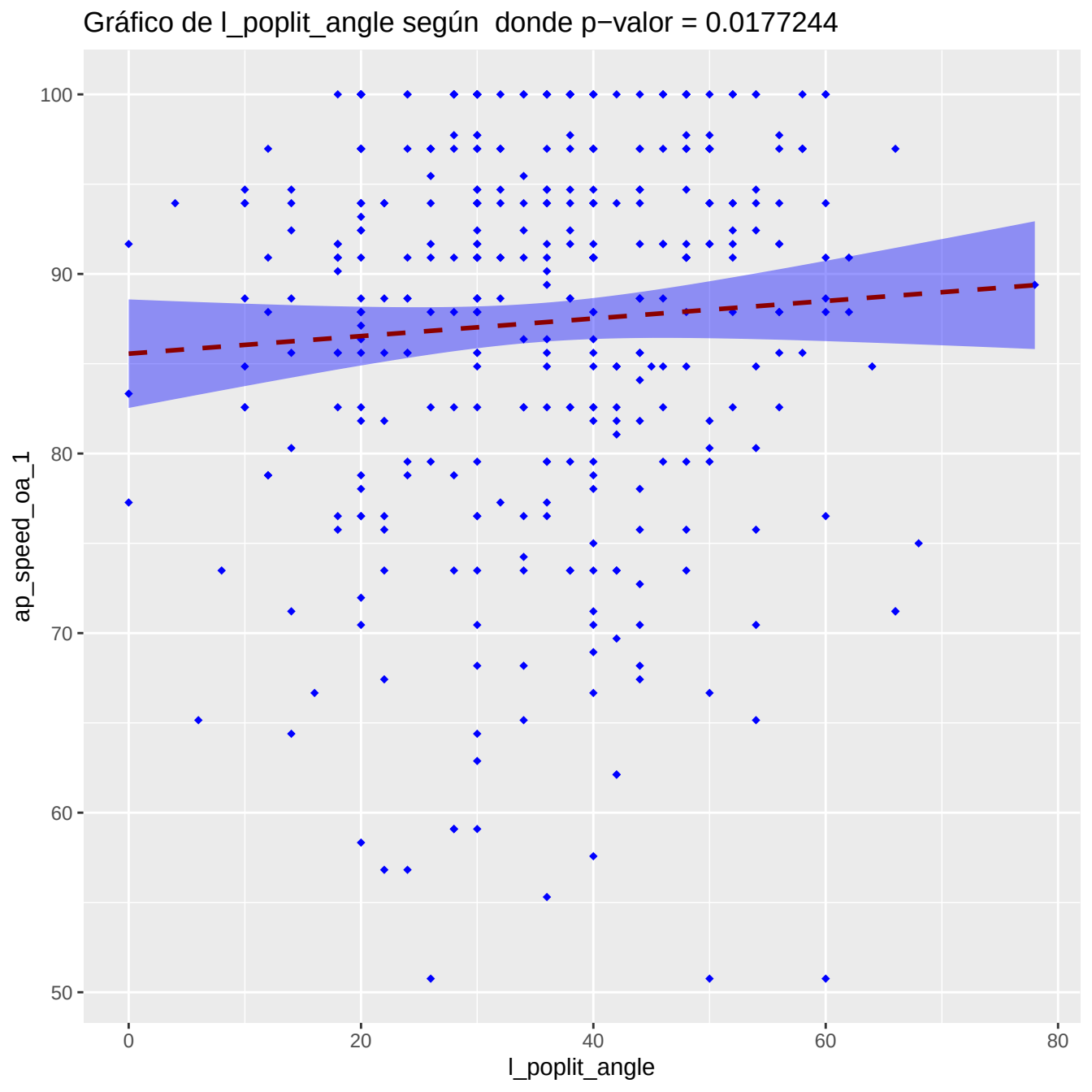
Gráfico de l_poplit_angle según donde p−valor = 0.0177244
ap_speed_oa_1
l_poplit_angle
100
90
80
70
60
50
0
20
40
60
80

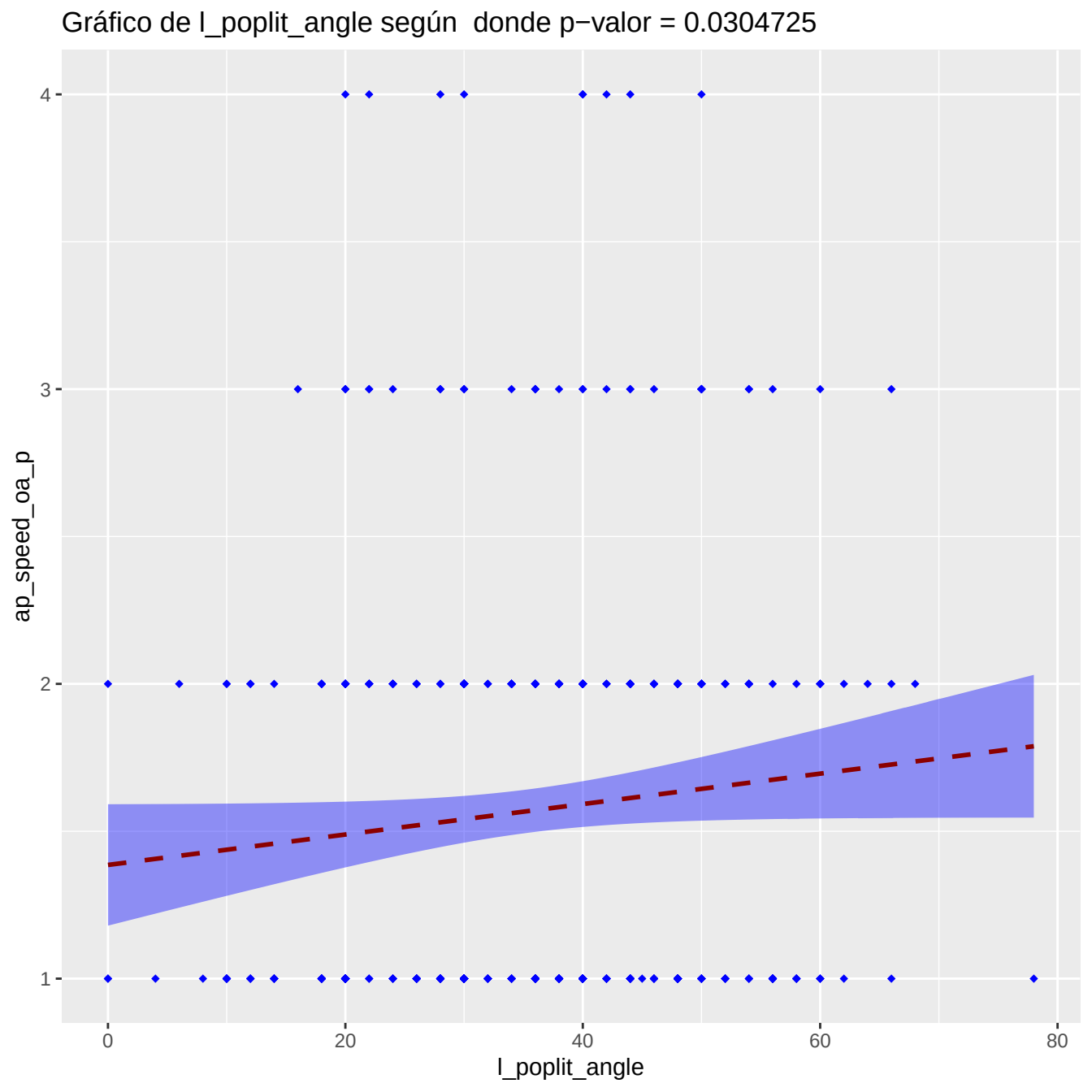
Gráfico de l_poplit_angle según donde p−valor = 0.0304725
ap_speed_oa_p
4
3
2
1
0
20
40
60
80
l_poplit_angle

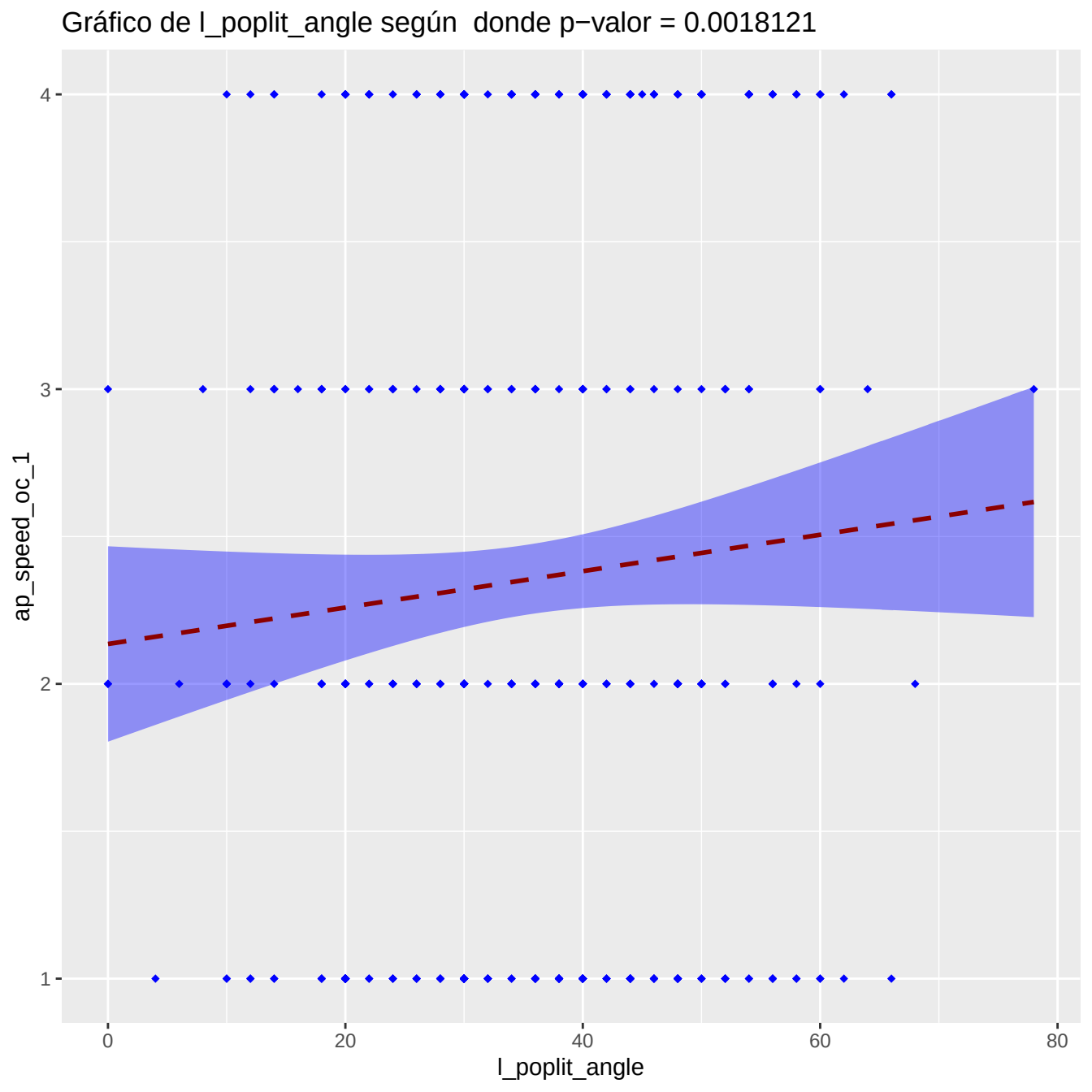
Gráfico de l_poplit_angle según donde p−valor = 0.0018121
ap_speed_oc_1
4
3
2
1
0
20
40
60
80
l_poplit_angle

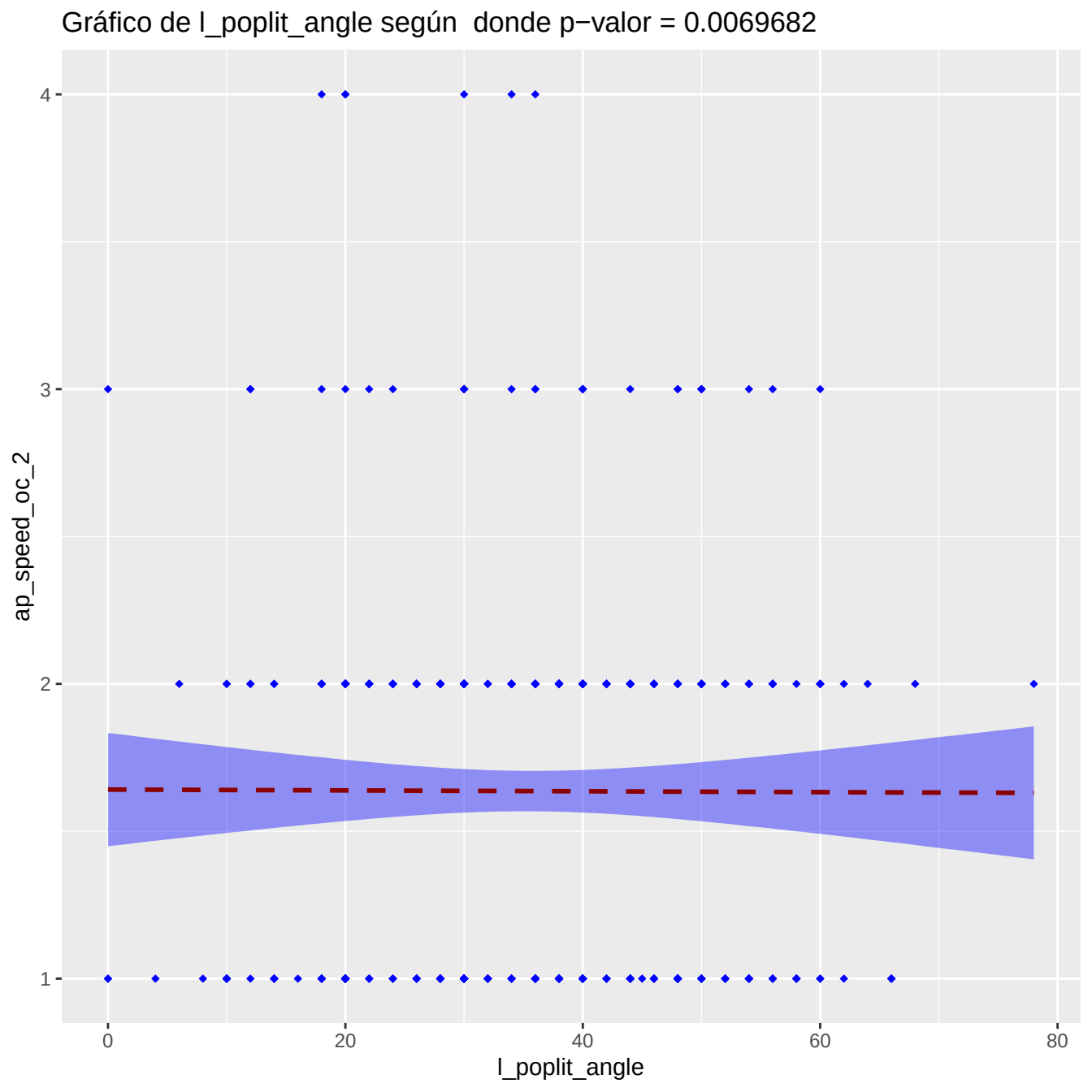
Gráfico de l_poplit_angle según donde p−valor = 0.0069682
ap_speed_oc_2
4
3
2
1
0
20
40
60
80
l_poplit_angle

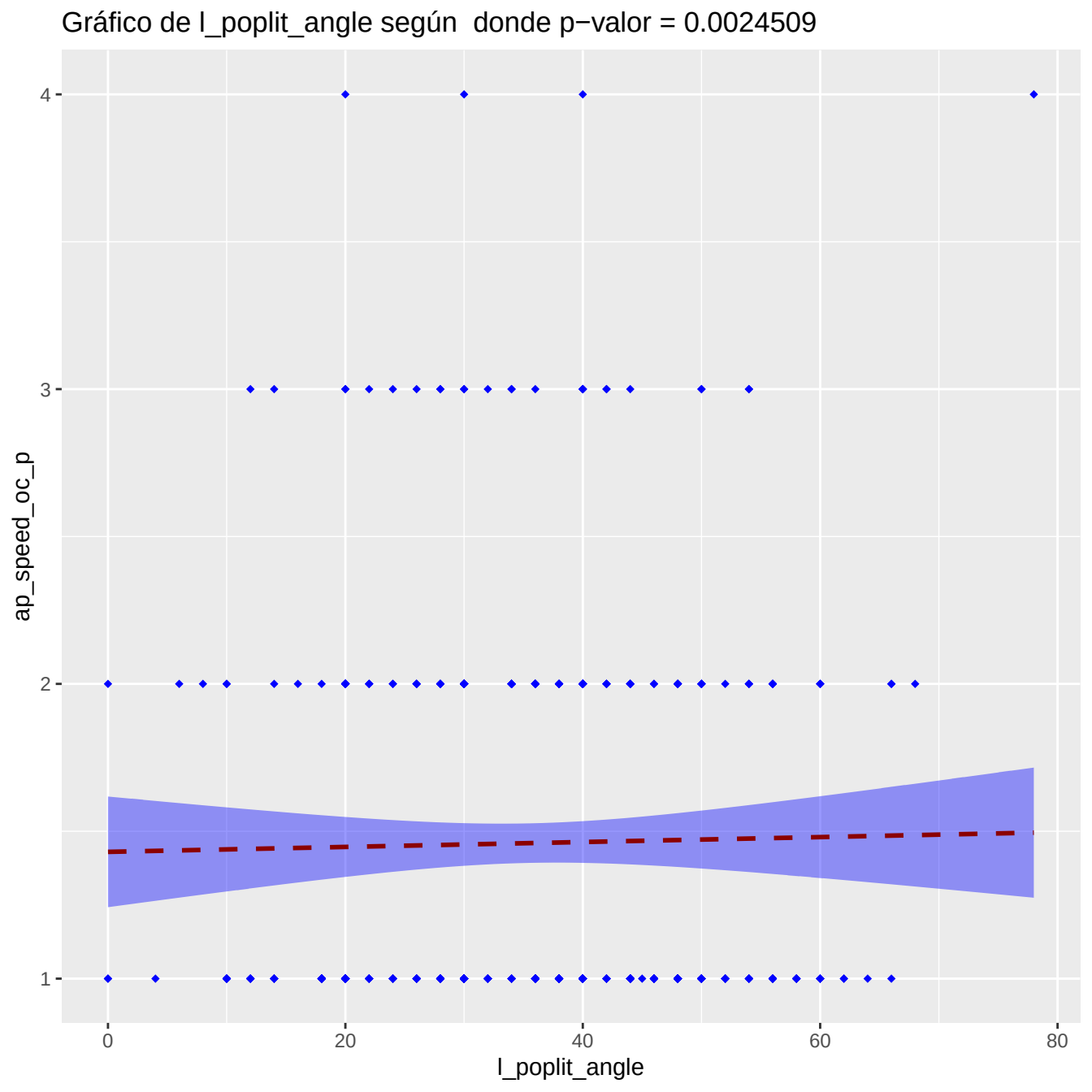
Gráfico de l_poplit_angle según donde p−valor = 0.0024509
ap_speed_oc_p
4
3
2
1
0
20
40
60
80
l_poplit_angle

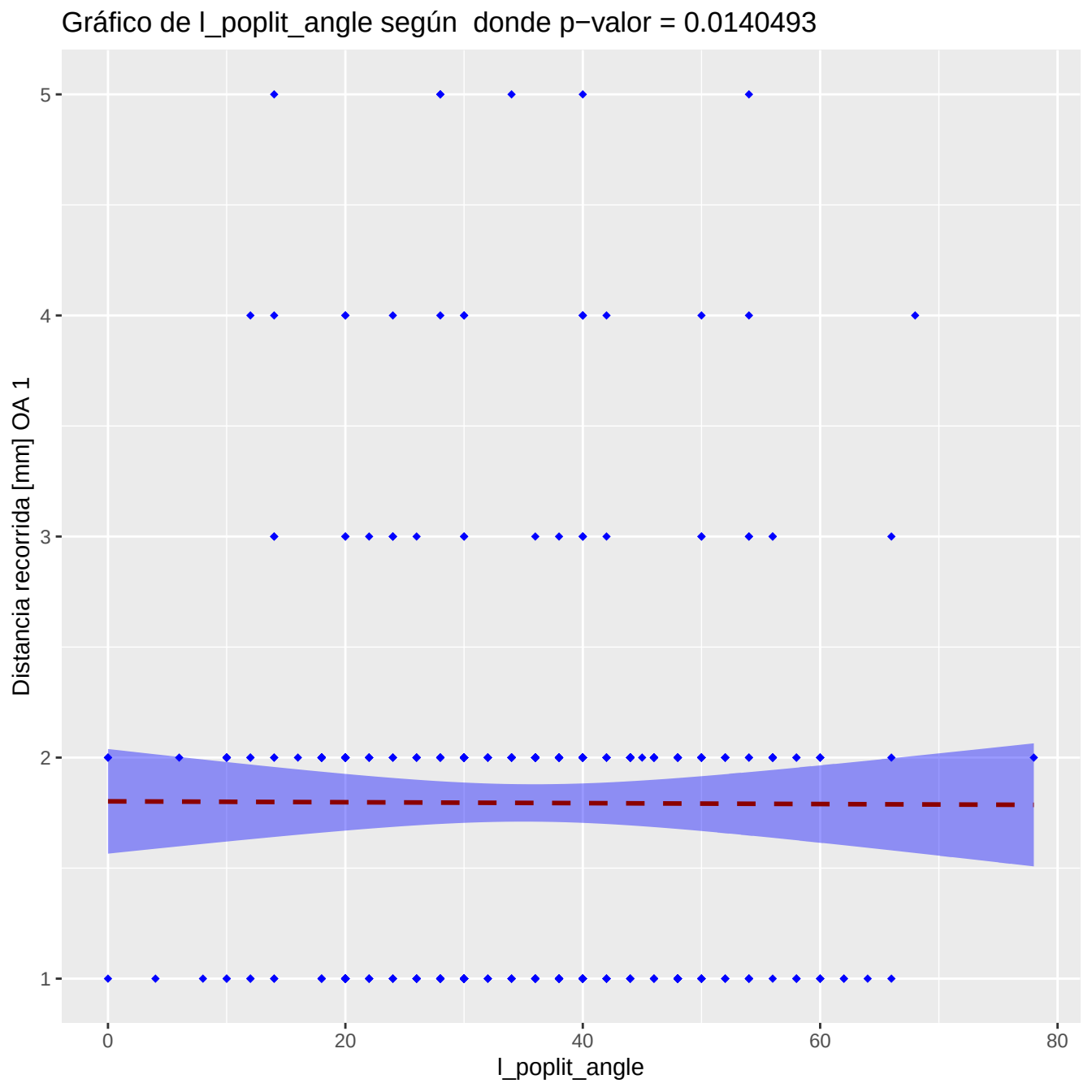
Gráfico de l_poplit_angle según donde p−valor = 0.0140493
Distancia recorrida [mm] OA 1
l_poplit_angle
5
4
3
2
1
0
20
40
60
80

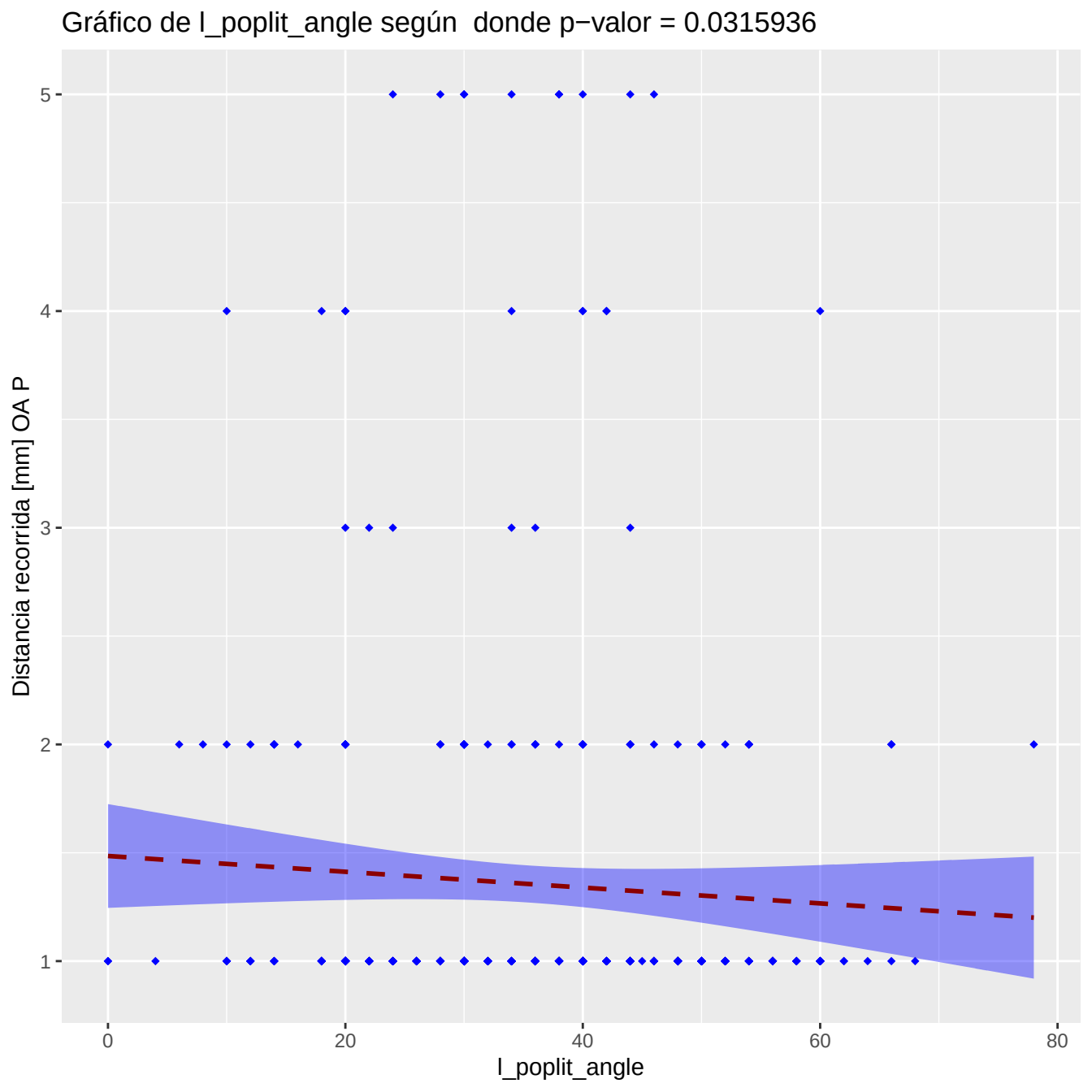
Gráfico de l_poplit_angle según donde p−valor = 0.0315936
Distancia recorrida [mm] OA P
l_poplit_angle
5
4
3
2
1
0
20
40
60
80

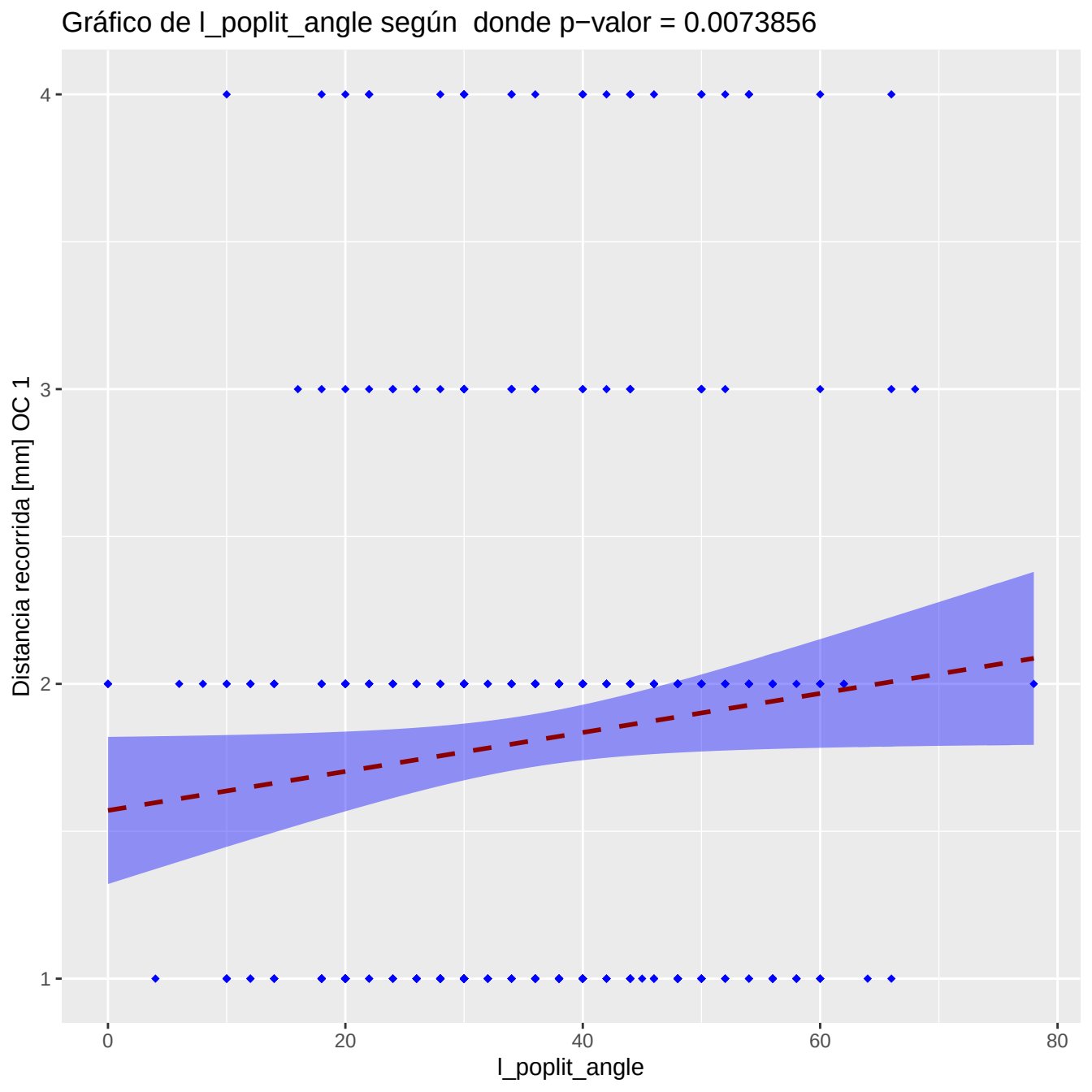
Gráfico de l_poplit_angle según donde p−valor = 0.0073856
Distancia recorrida [mm] OC 1
4
3
2
1
0
20
40
60
80
l_poplit_angle

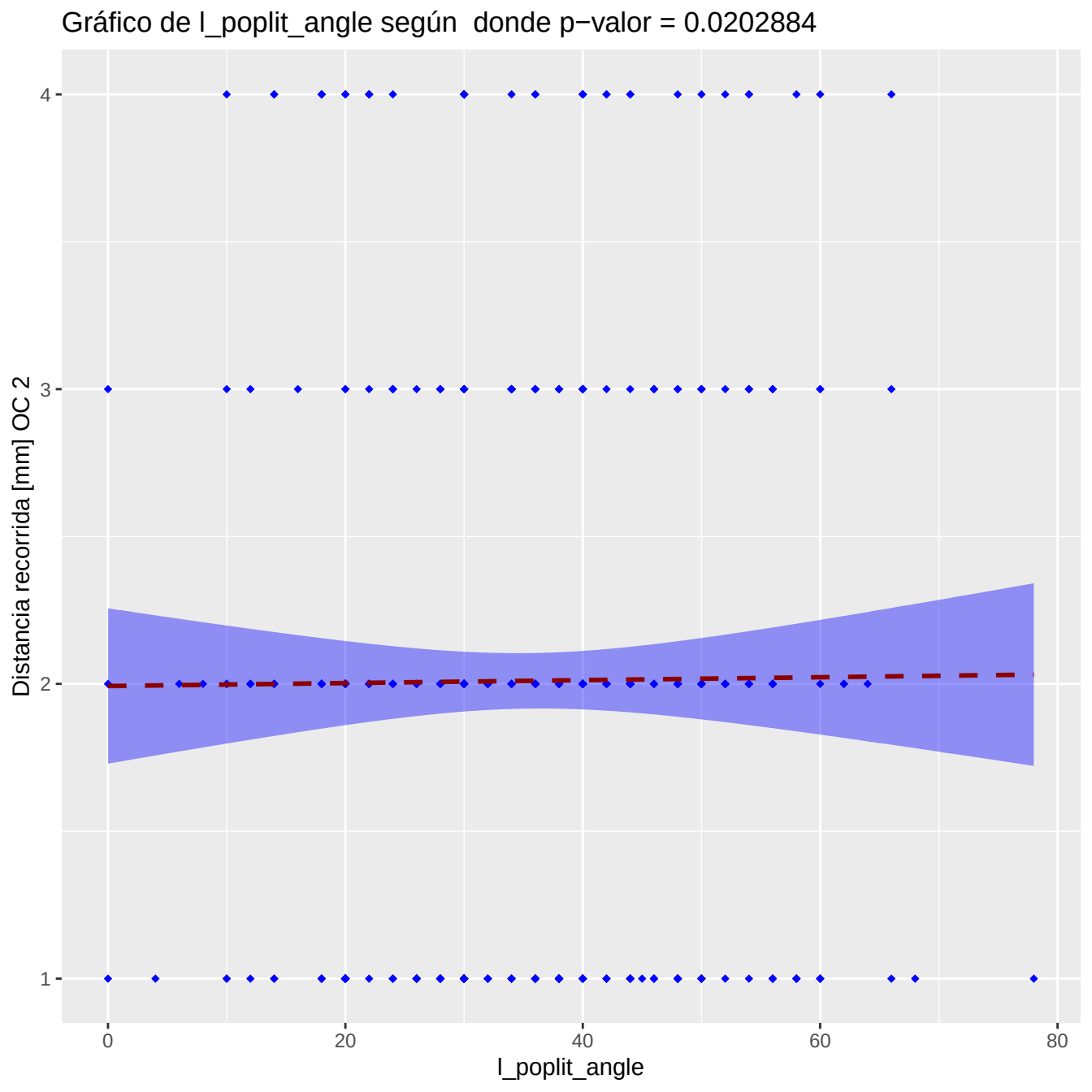
Gráfico de l_poplit_angle según donde p−valor = 0.0202884
Distancia recorrida [mm] OC 2
4
3
2
1
0
20
40
60
80
l_poplit_angle

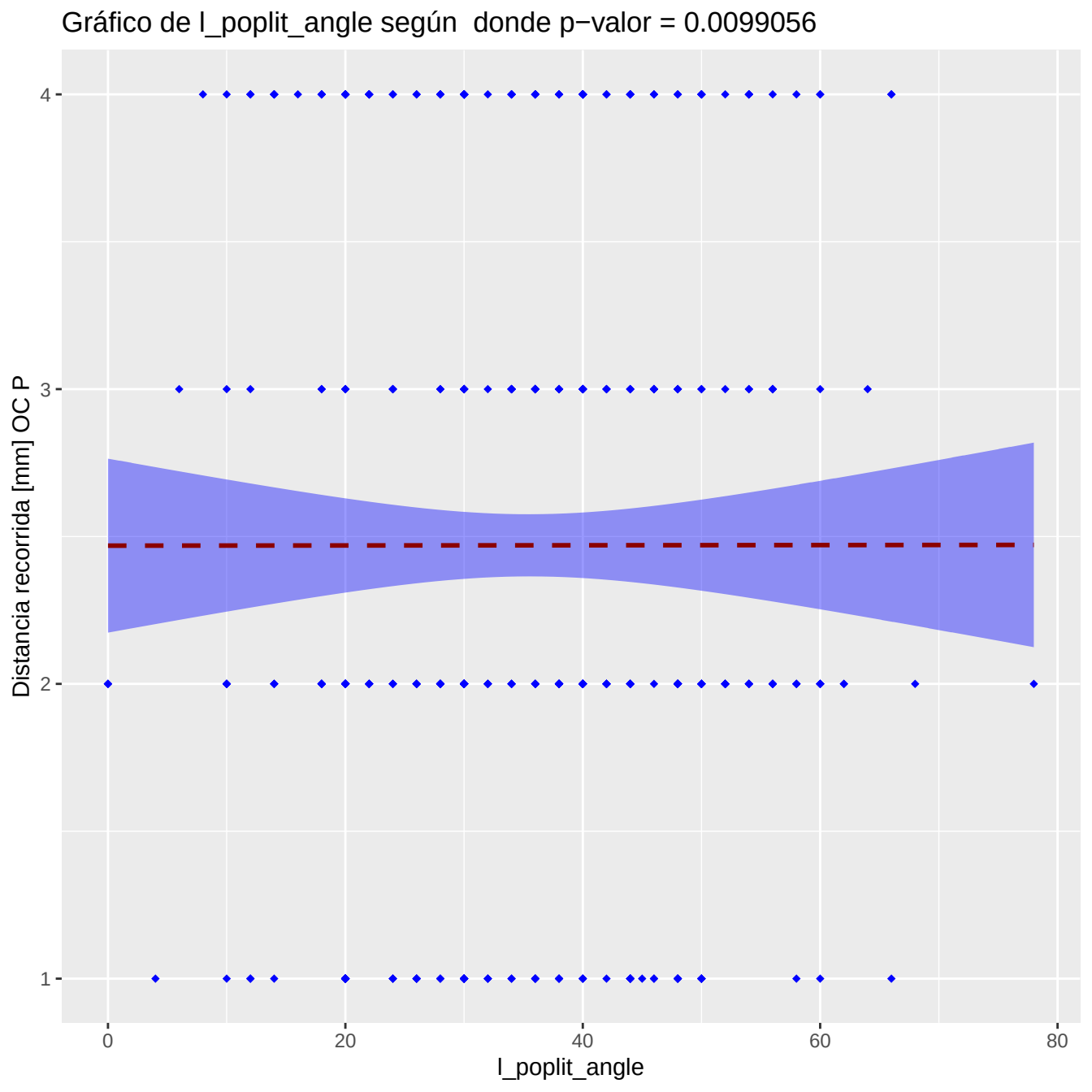
Gráfico de l_poplit_angle según donde p−valor = 0.0099056
Distancia recorrida [mm] OC P
4
3
2
1
0
20
40
60
80
l_poplit_angle

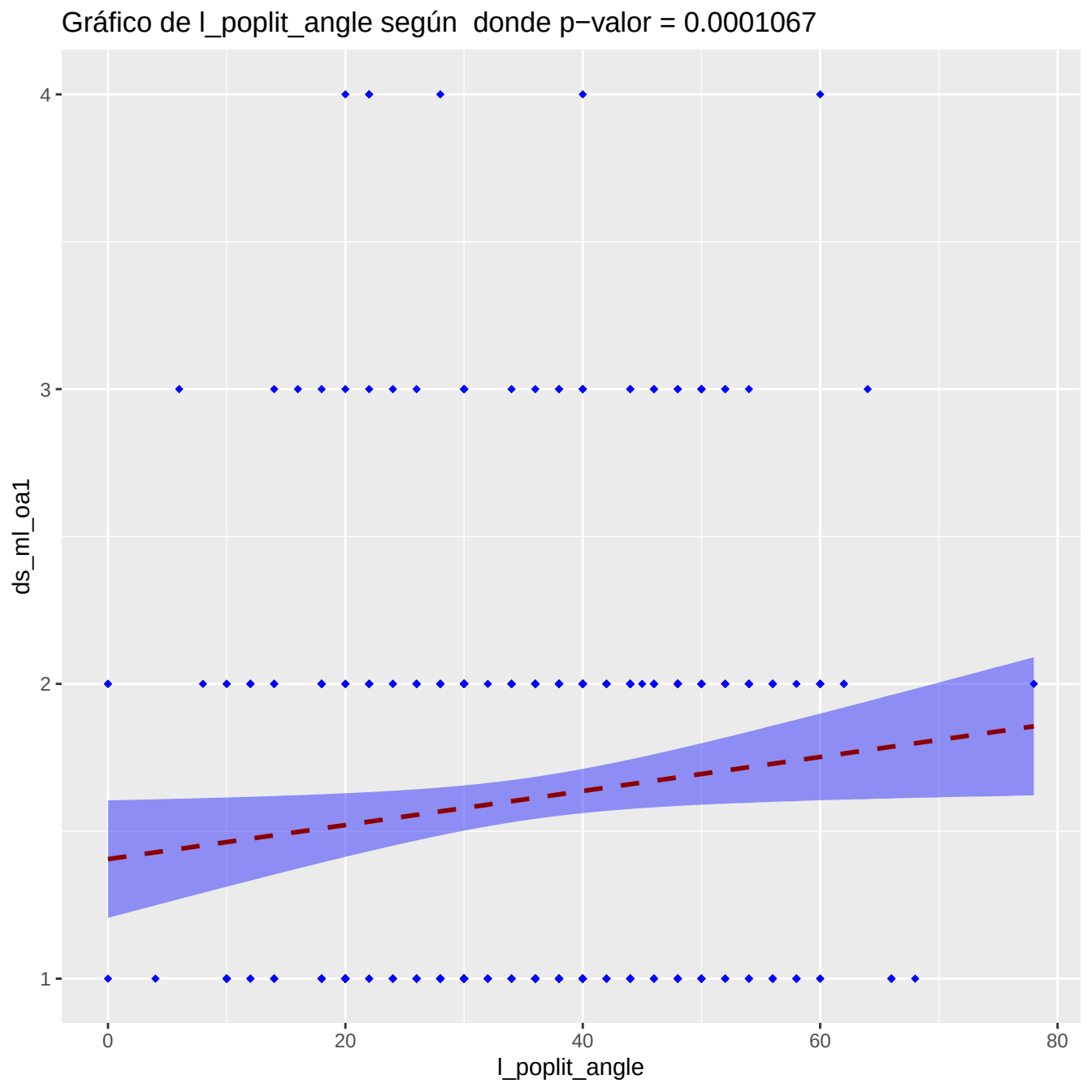
Gráfico de l_poplit_angle según donde p−valor = 0.0001067
ds_ml_oa1
l_poplit_angle
4
3
2
1
0
20
40
60
80

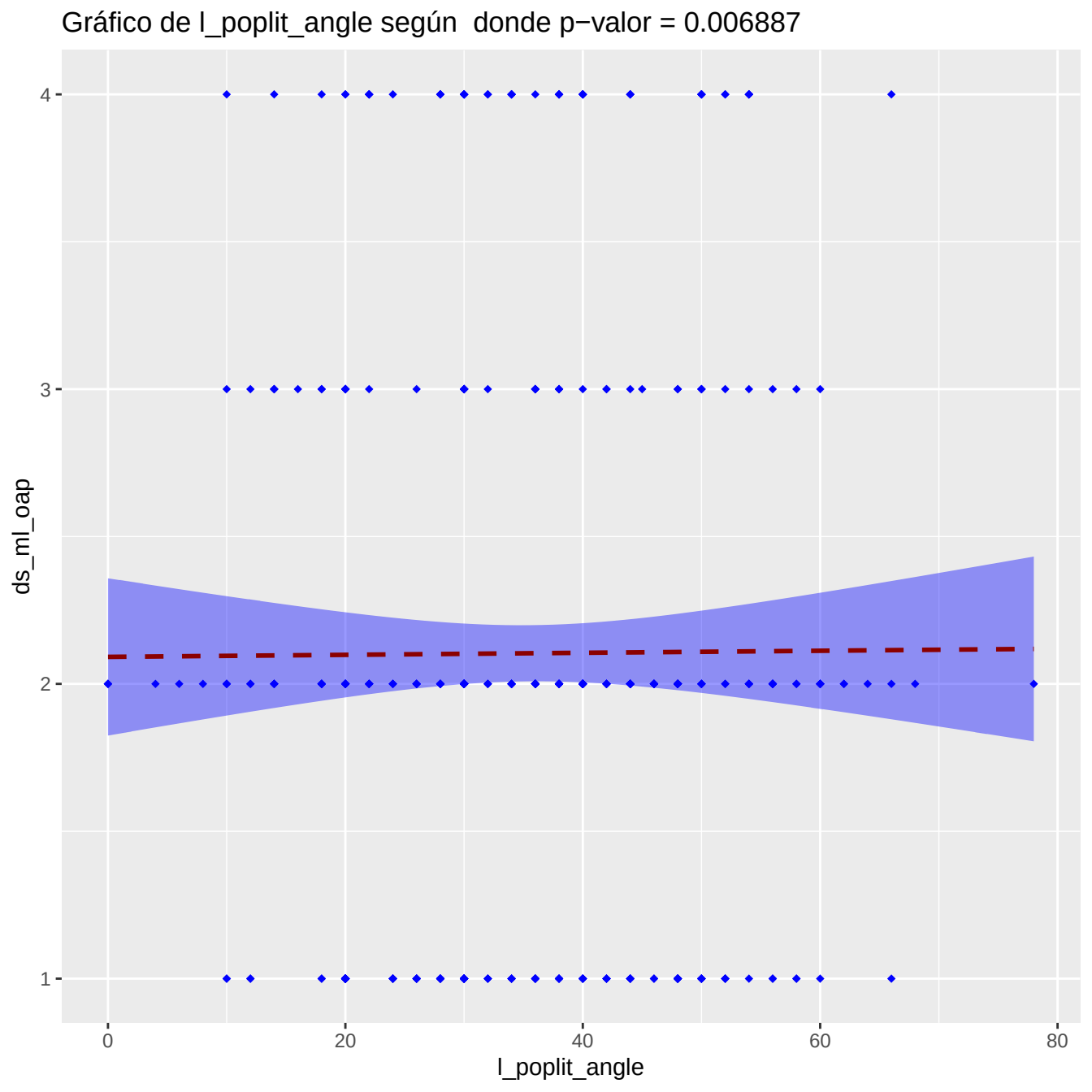
Gráfico de l_poplit_angle según donde p−valor = 0.006887
ds_ml_oap
l_poplit_angle
4
3
2
1
0
20
40
60
80

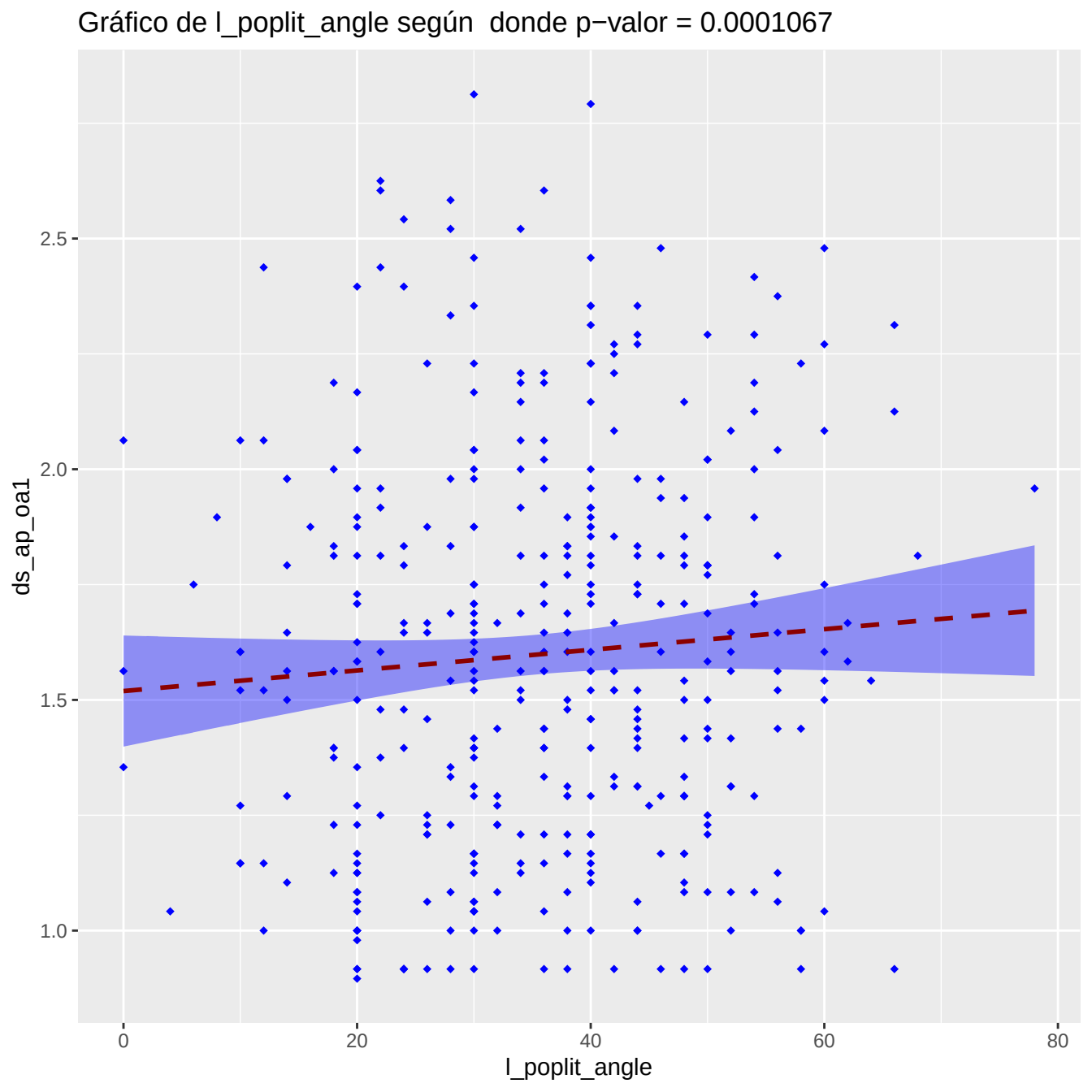
Gráfico de l_poplit_angle según donde p−valor = 0.0001067
ds_ap_oa1
2.5
2.0
1.5
1.0
0
20
40
60
80
l_poplit_angle

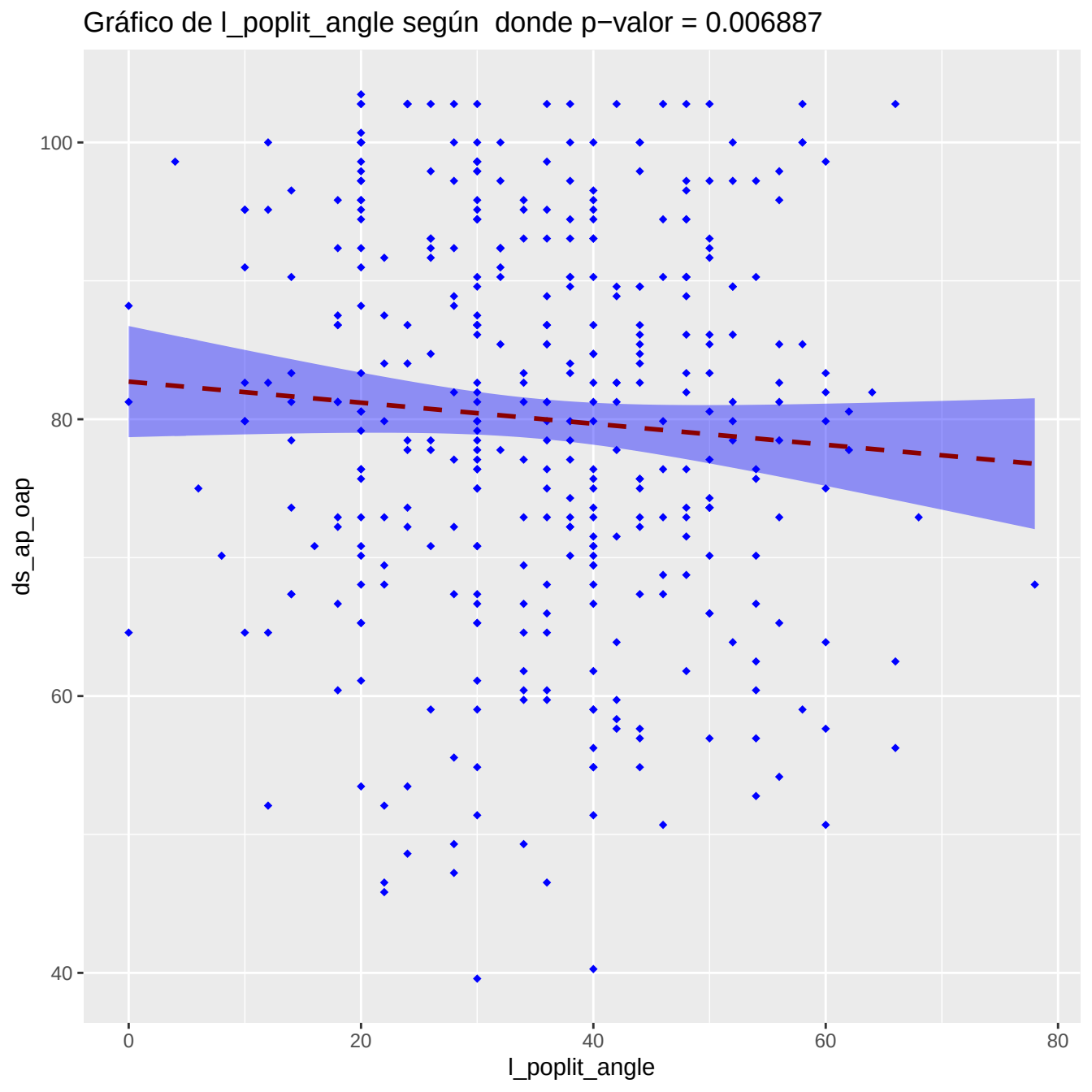
Gráfico de l_poplit_angle según donde p−valor = 0.006887
ds_ap_oap
100
80
60
40
0
20
40
60
80
l_poplit_angle

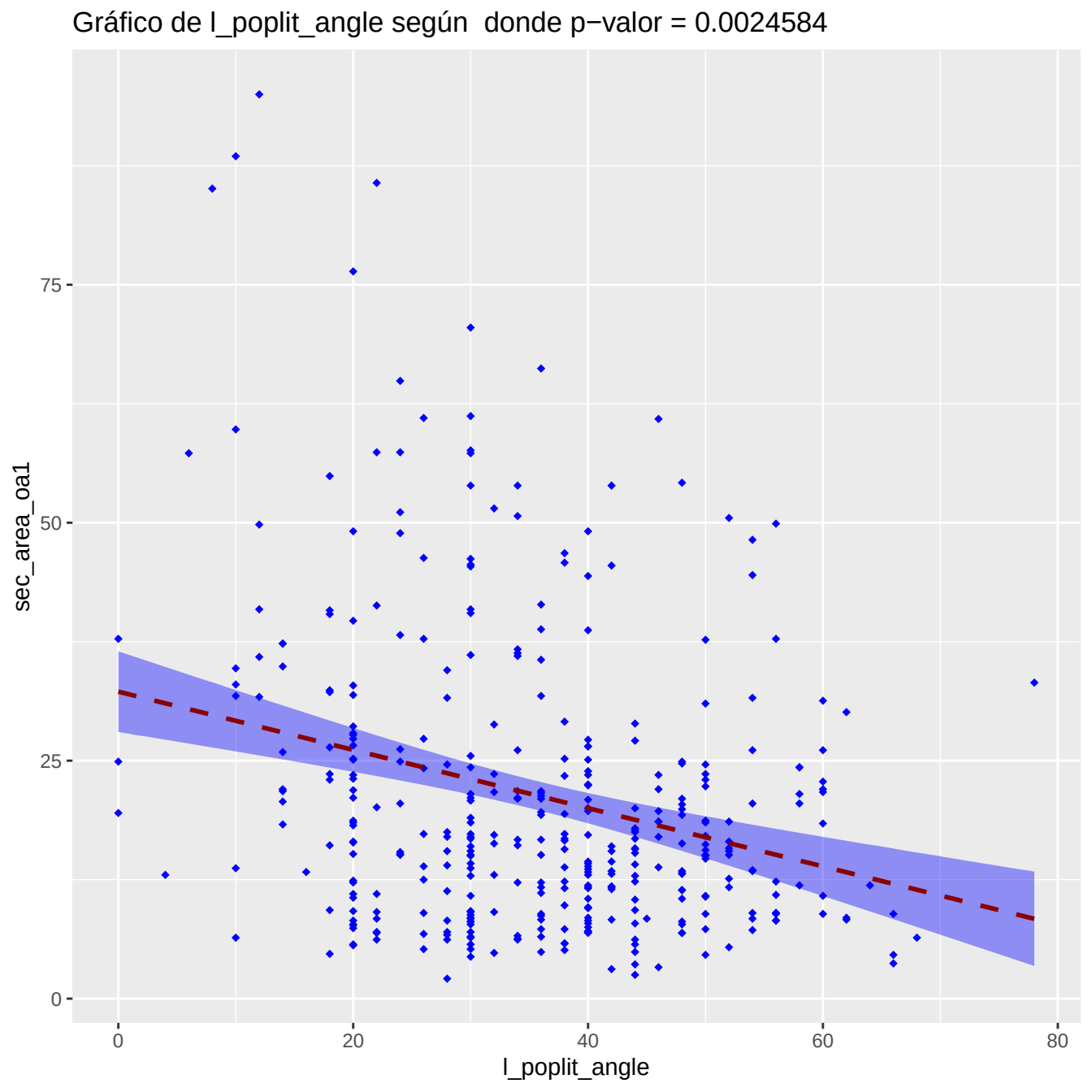
Gráfico de l_poplit_angle según donde p−valor = 0.0024584
sec_area_oa1
75
50
25
0
0
20
40
60
80
l_poplit_angle

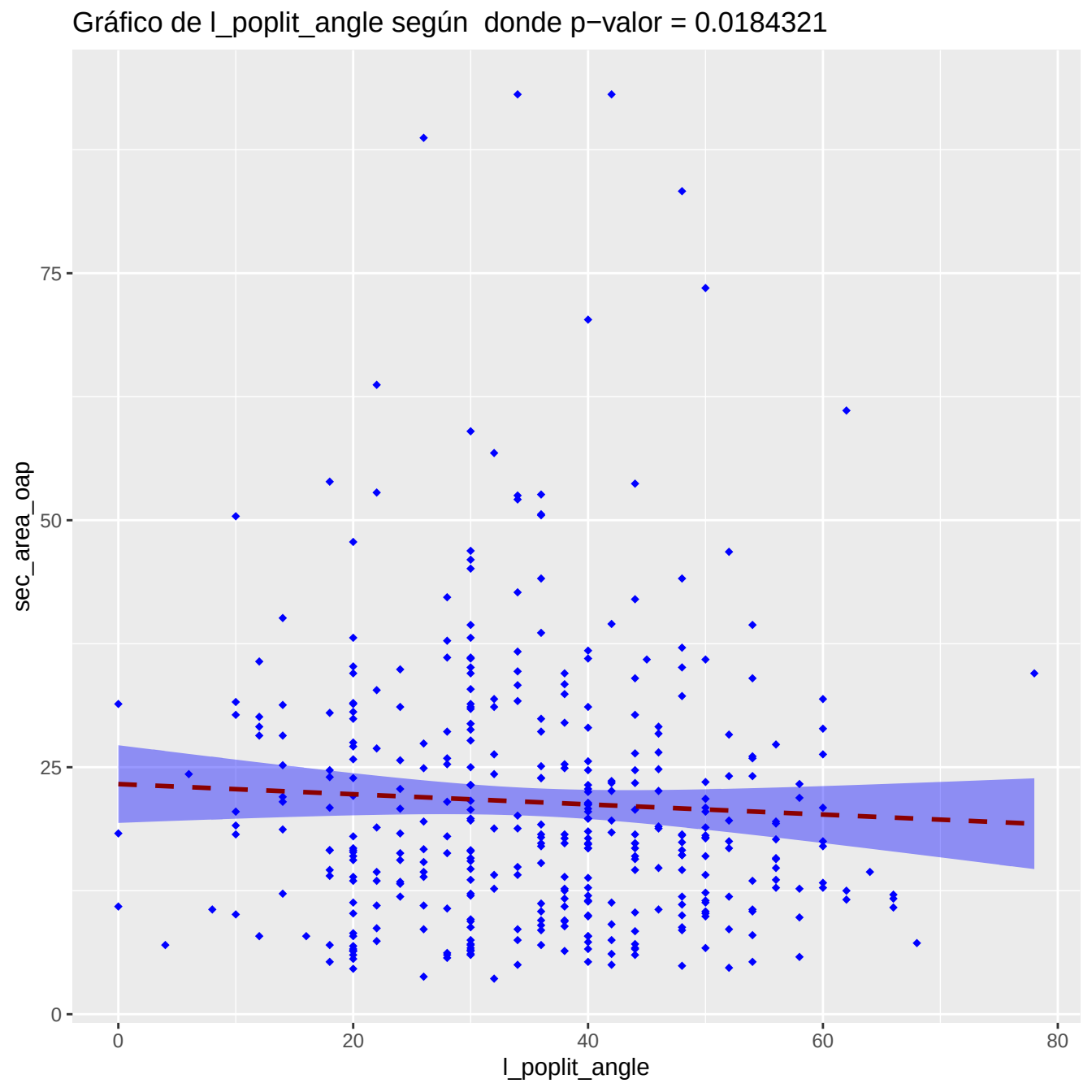
Gráfico de l_poplit_angle según donde p−valor = 0.0184321
sec_area_oap
0
25
50
75
0
20
40
60
80
l_poplit_angle

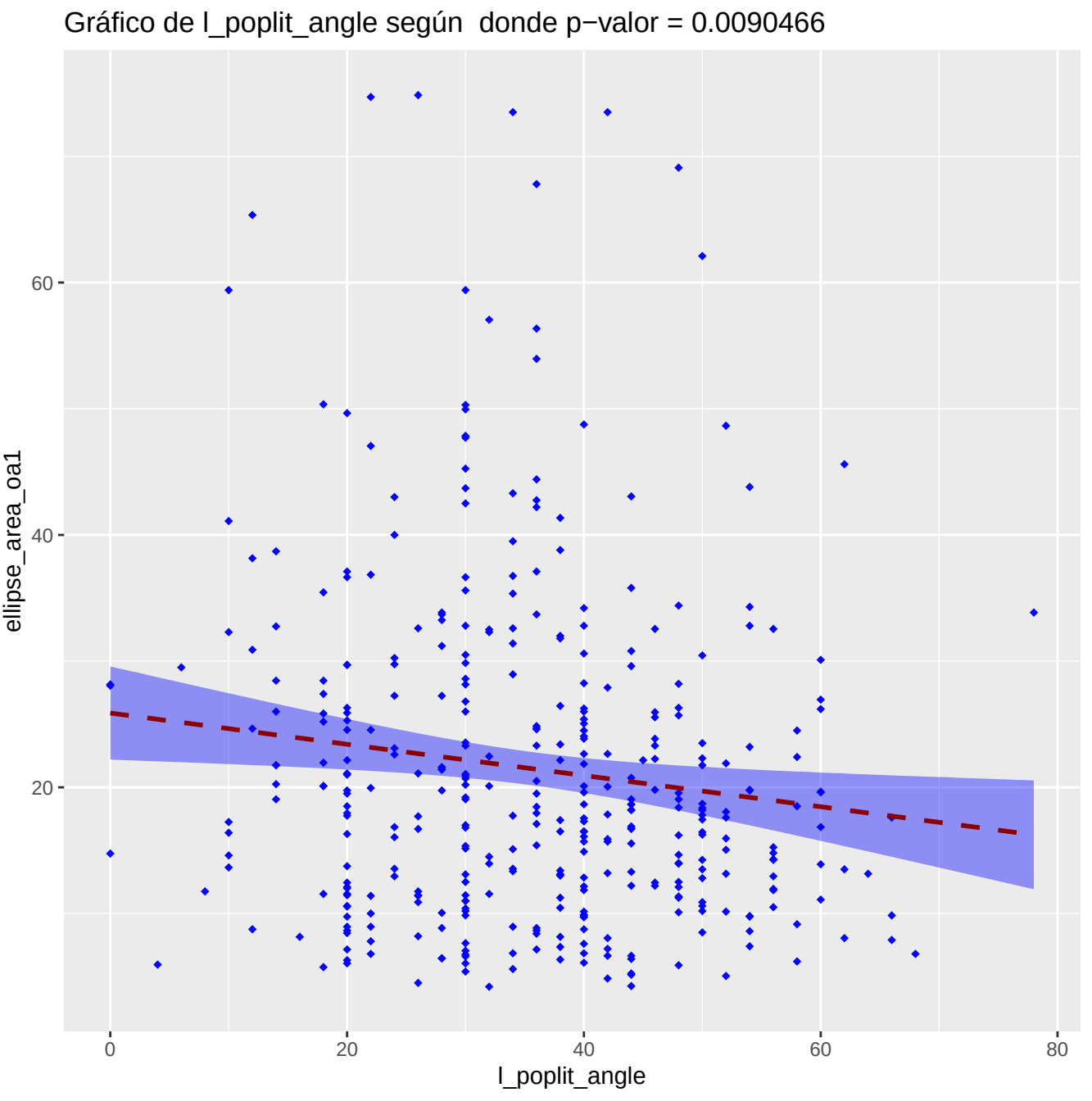
Gráfico de l_poplit_angle según donde p−valor = 0.0090466
ellipse_area_oa1
60
40
20
0
20
40
60
80
l_poplit_angle

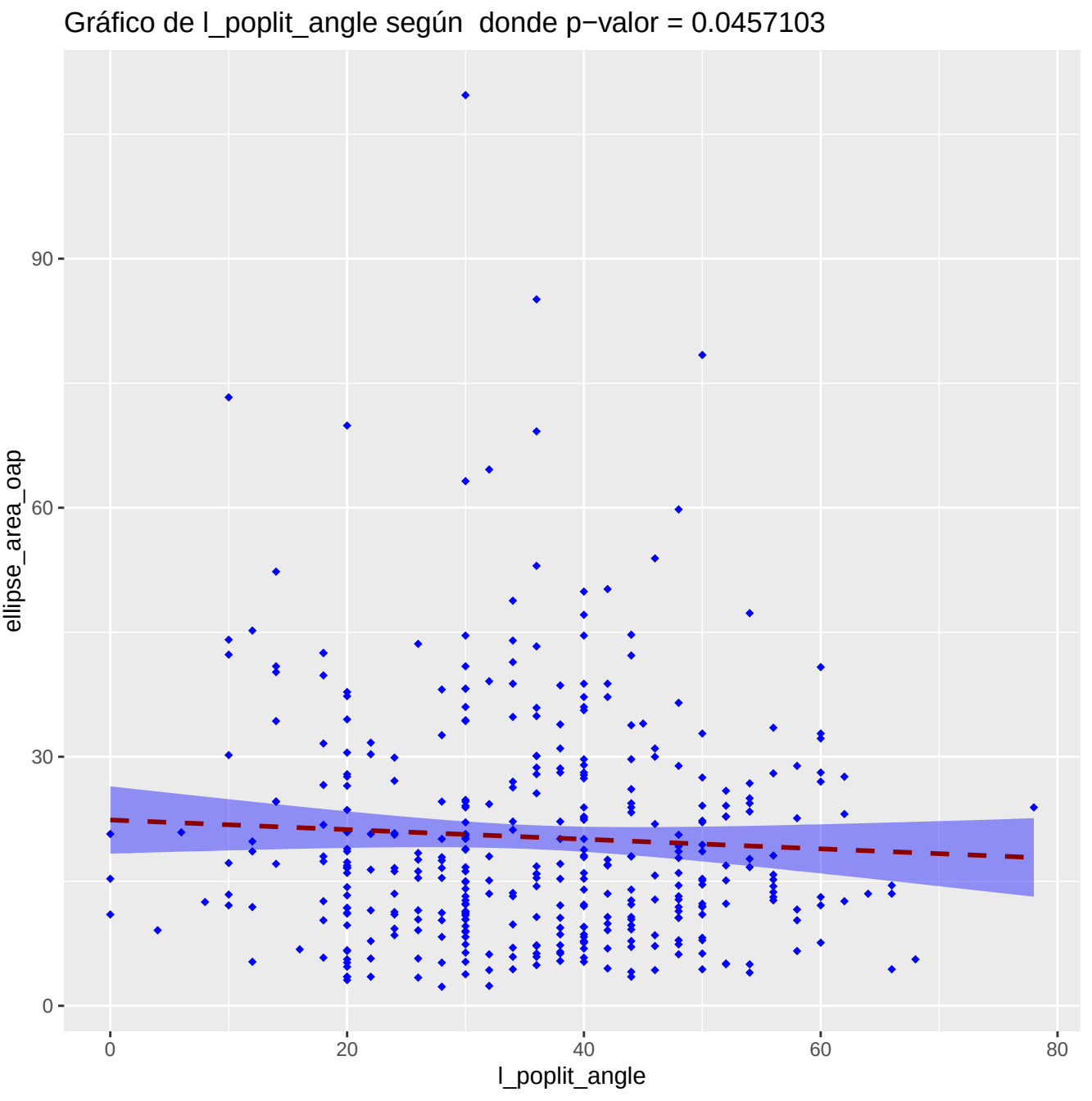
Gráfico de l_poplit_angle según donde p−valor = 0.0457103
ellipse_area_oap
90
60
30
0
0
20
40
60
80
l_poplit_angle

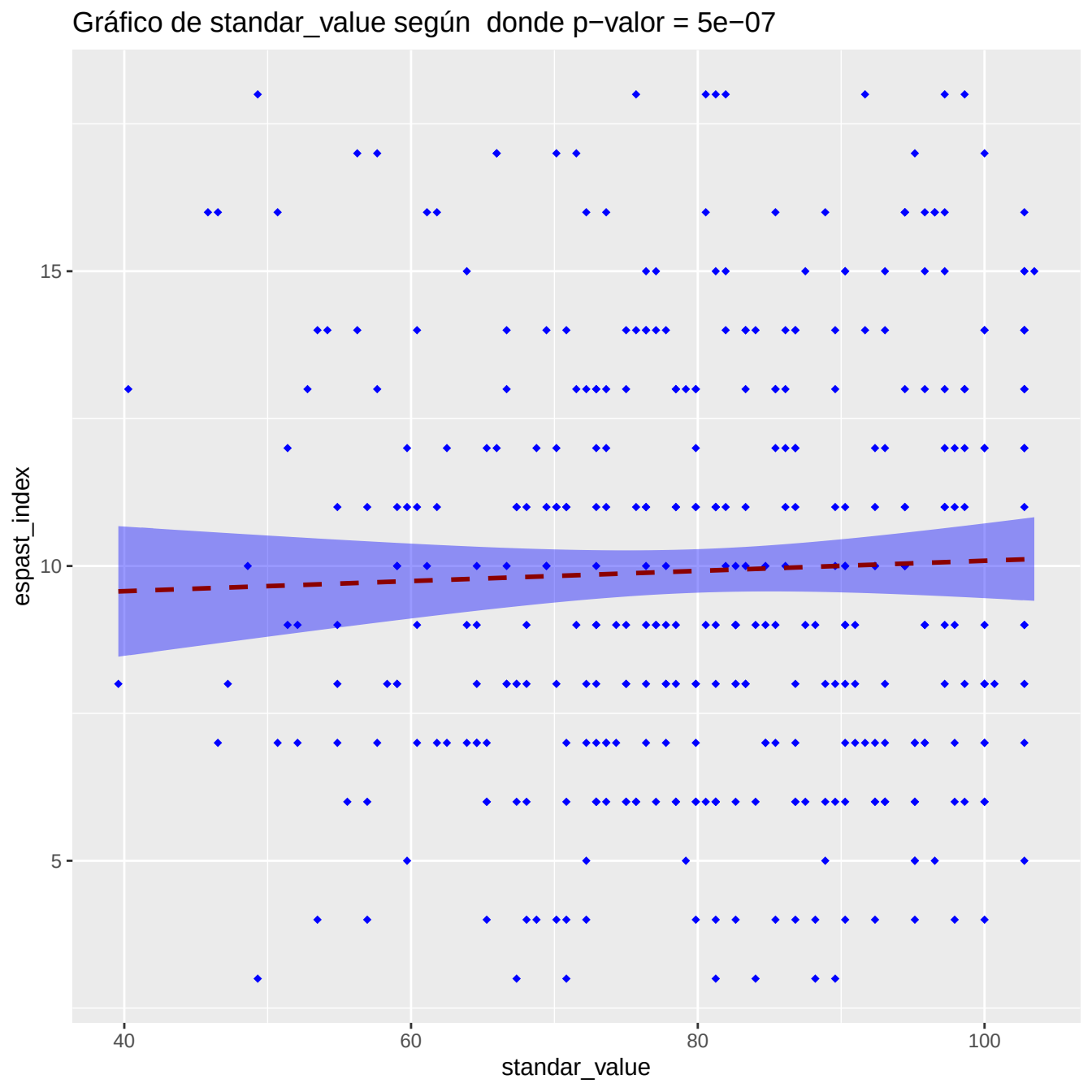
Gráfico de standar_value según donde p−valor = 5e−07
espast_index
15
10
5
40
60
80
100
standar_value

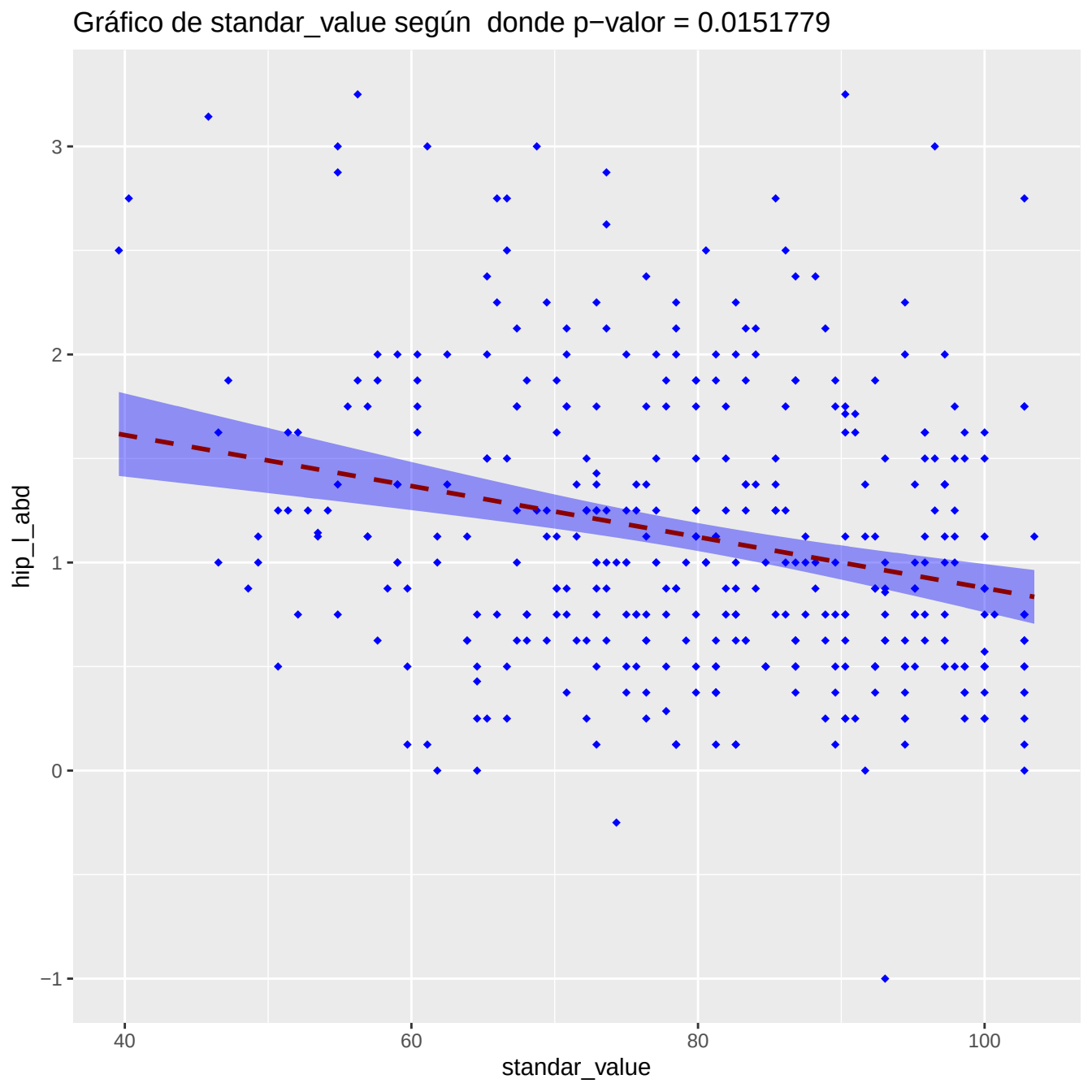
Gráfico de standar_value según donde p−valor = 0.0151779
hip_l_abd
standar_value
3
2
1
0
−1
40
60
80
100

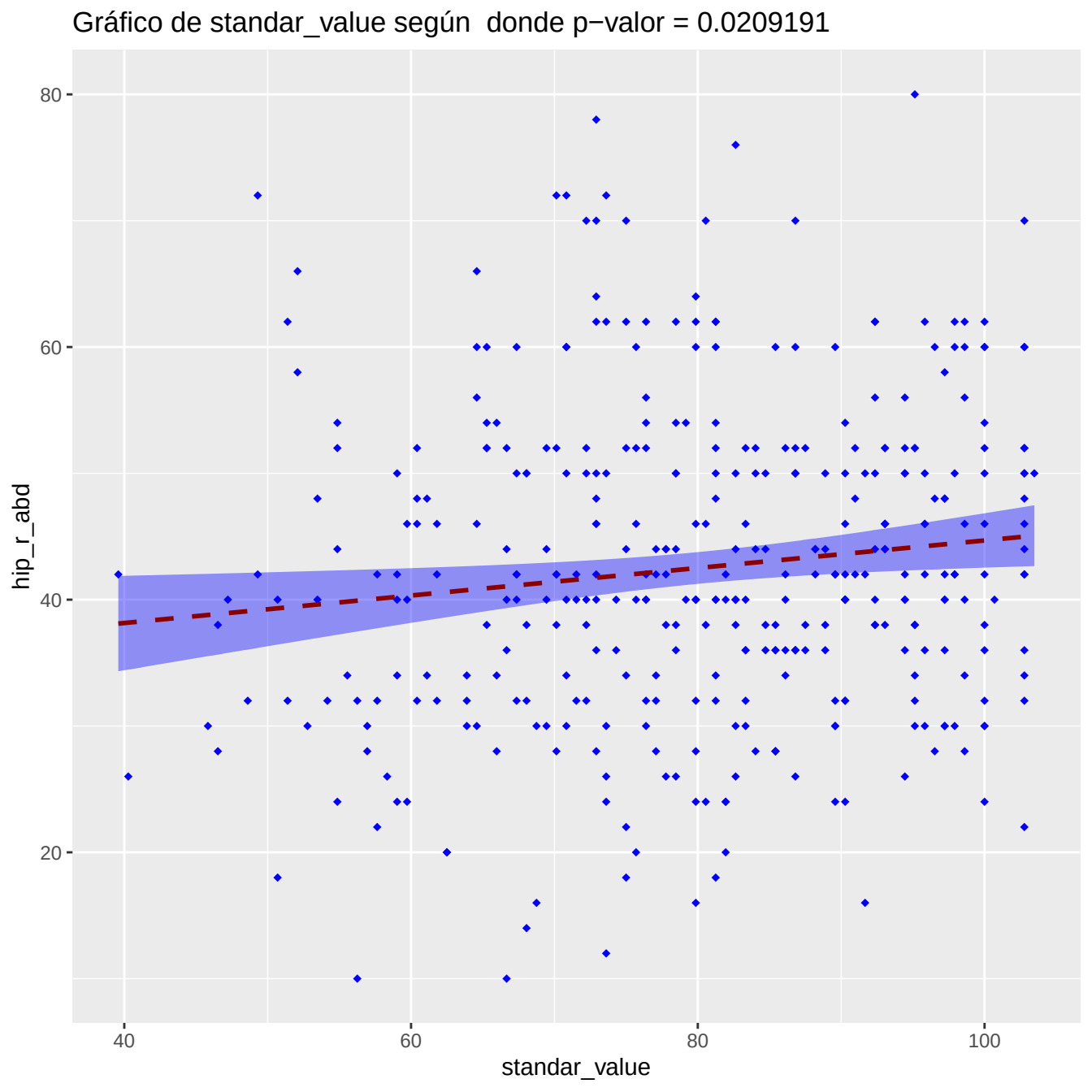
Gráfico de standar_value según donde p−valor = 0.0209191
hip_r_abd
standar_value
80
60
40
20
40
60
80
100

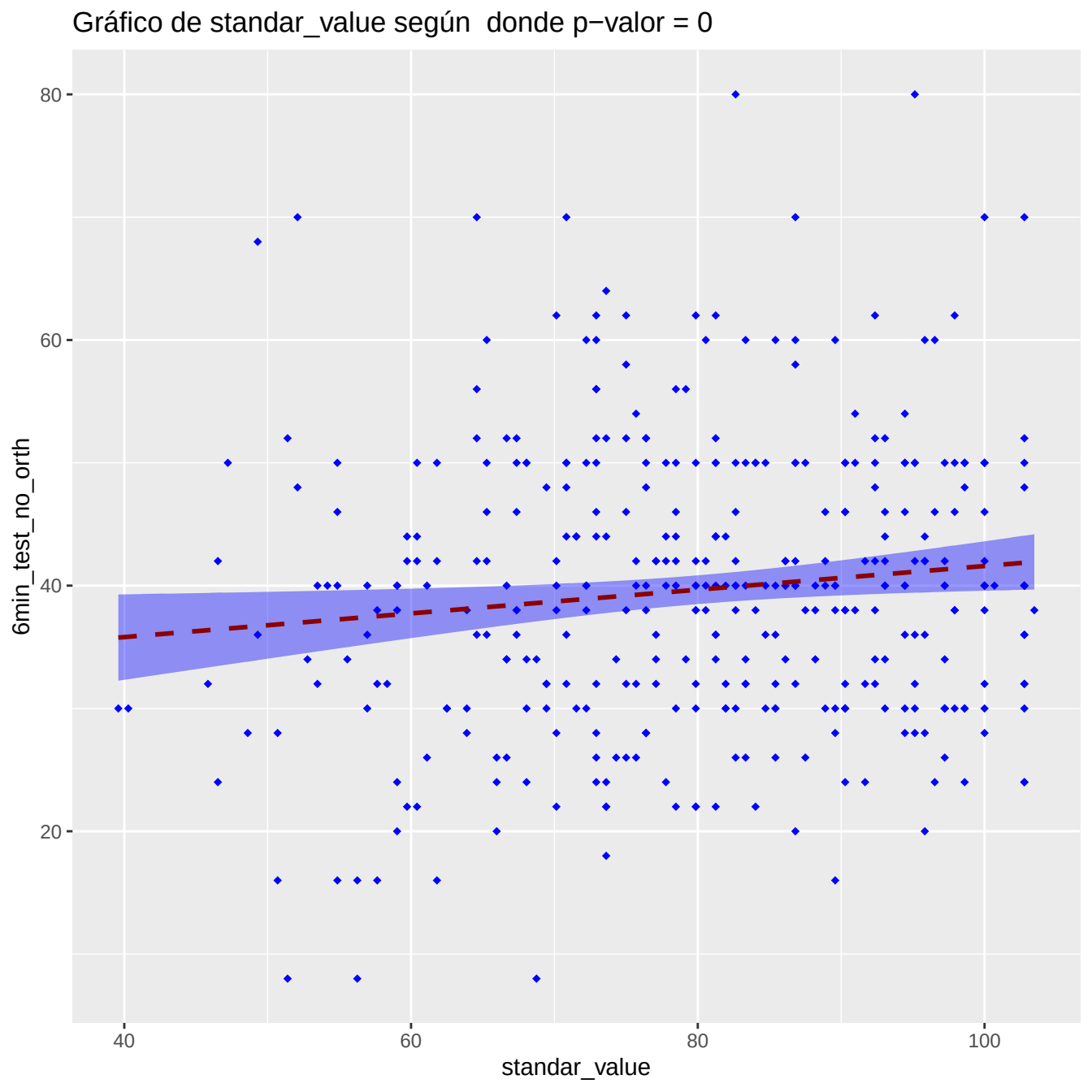
Gráfico de standar_value según donde p−valor = 0
6min_test_no_orth
80
60
40
20
40
60
80
100
standar_value

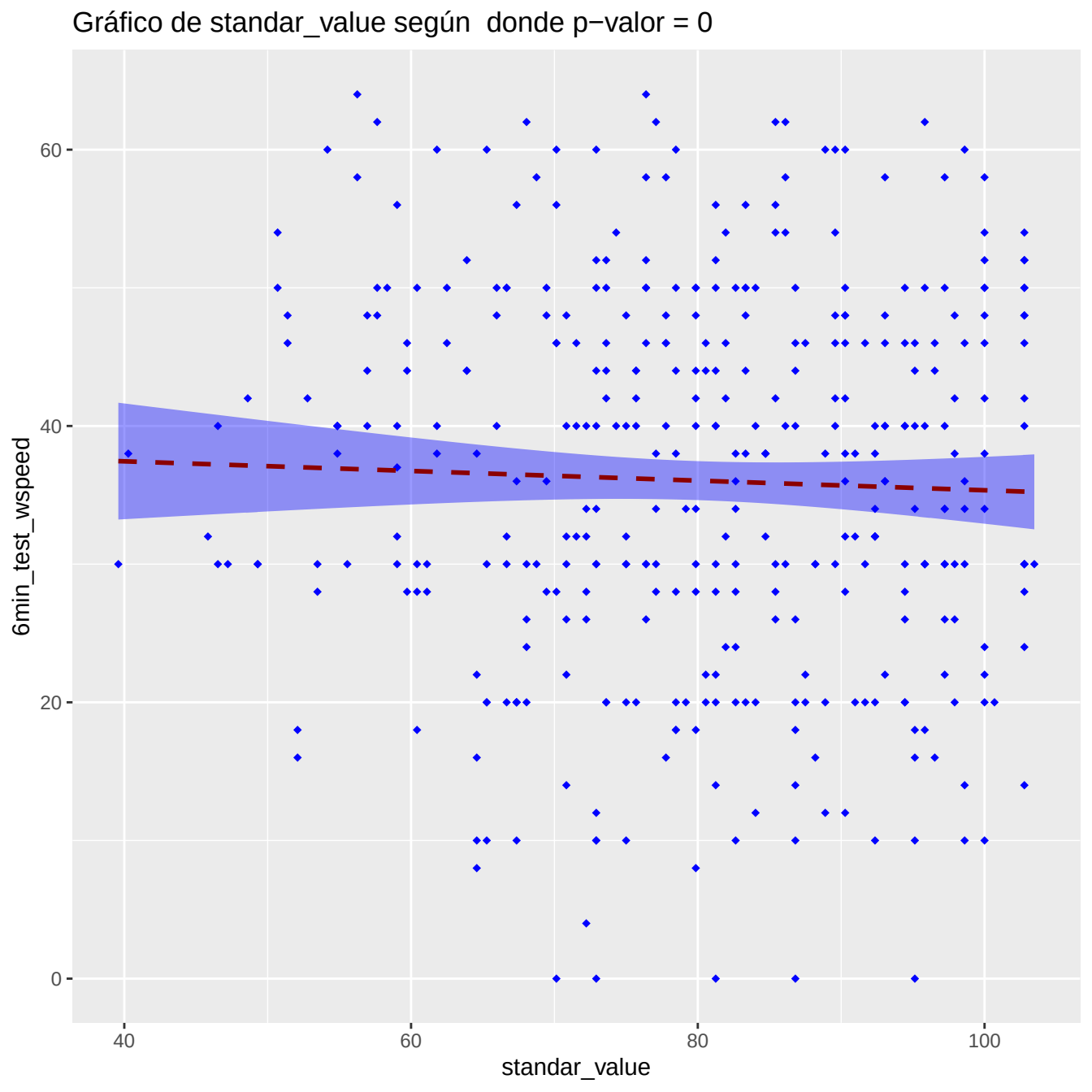
Gráfico de standar_value según donde p−valor = 0
6min_test_wspeed
60
40
20
0
40
60
80
100
standar_value

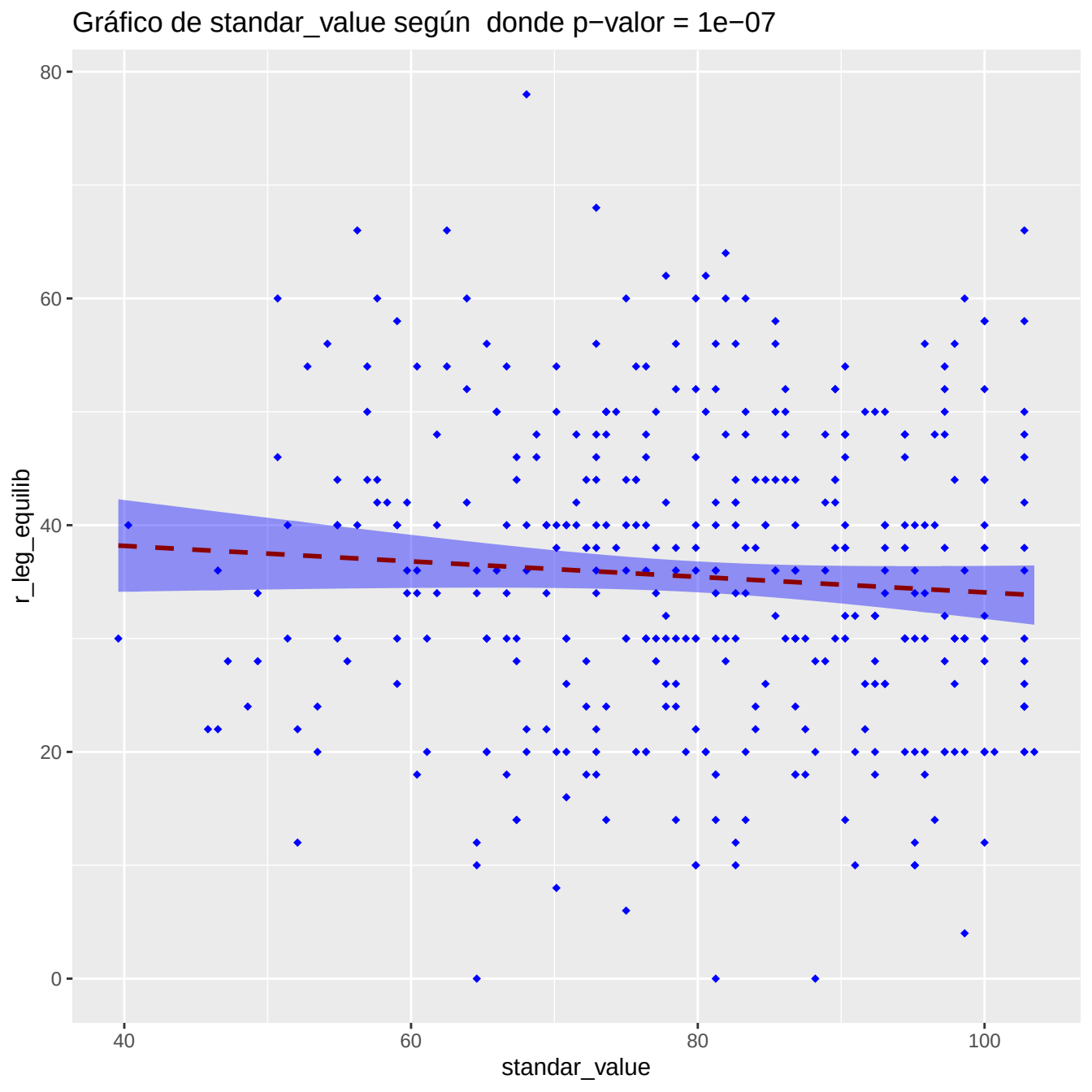
Gráfico de standar_value según donde p−valor = 1e−07
r_leg_equilib
standar_value
80
60
40
20
0
40
60
80
100

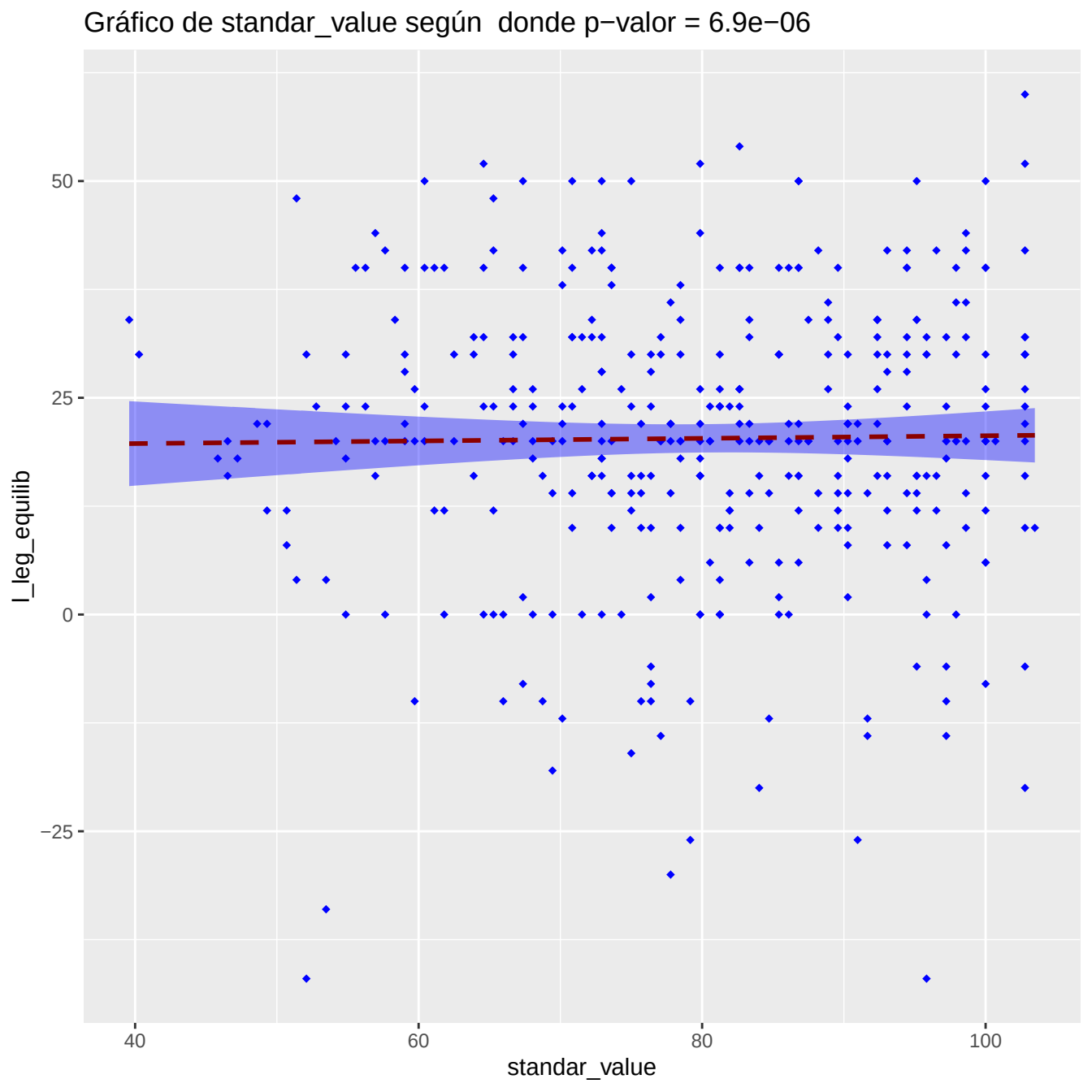
Gráfico de standar_value según donde p−valor = 6.9e−06
50
25
0
−25
l_leg_equilib
40
60
80
100
standar_value

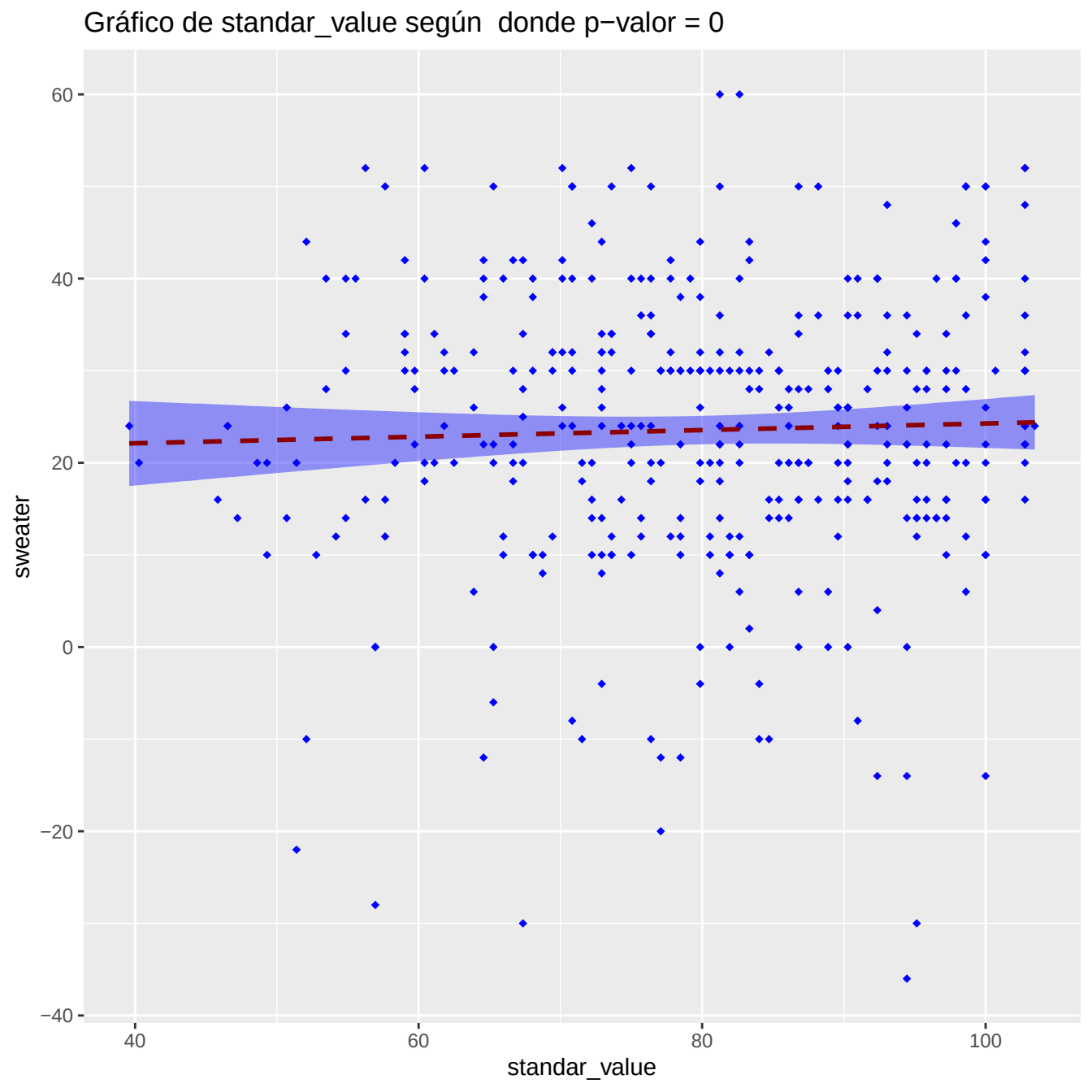
Gráfico de standar_value según donde p−valor = 0
60
40
20
0
−20
−40
sweater
40
60
80
100
standar_value

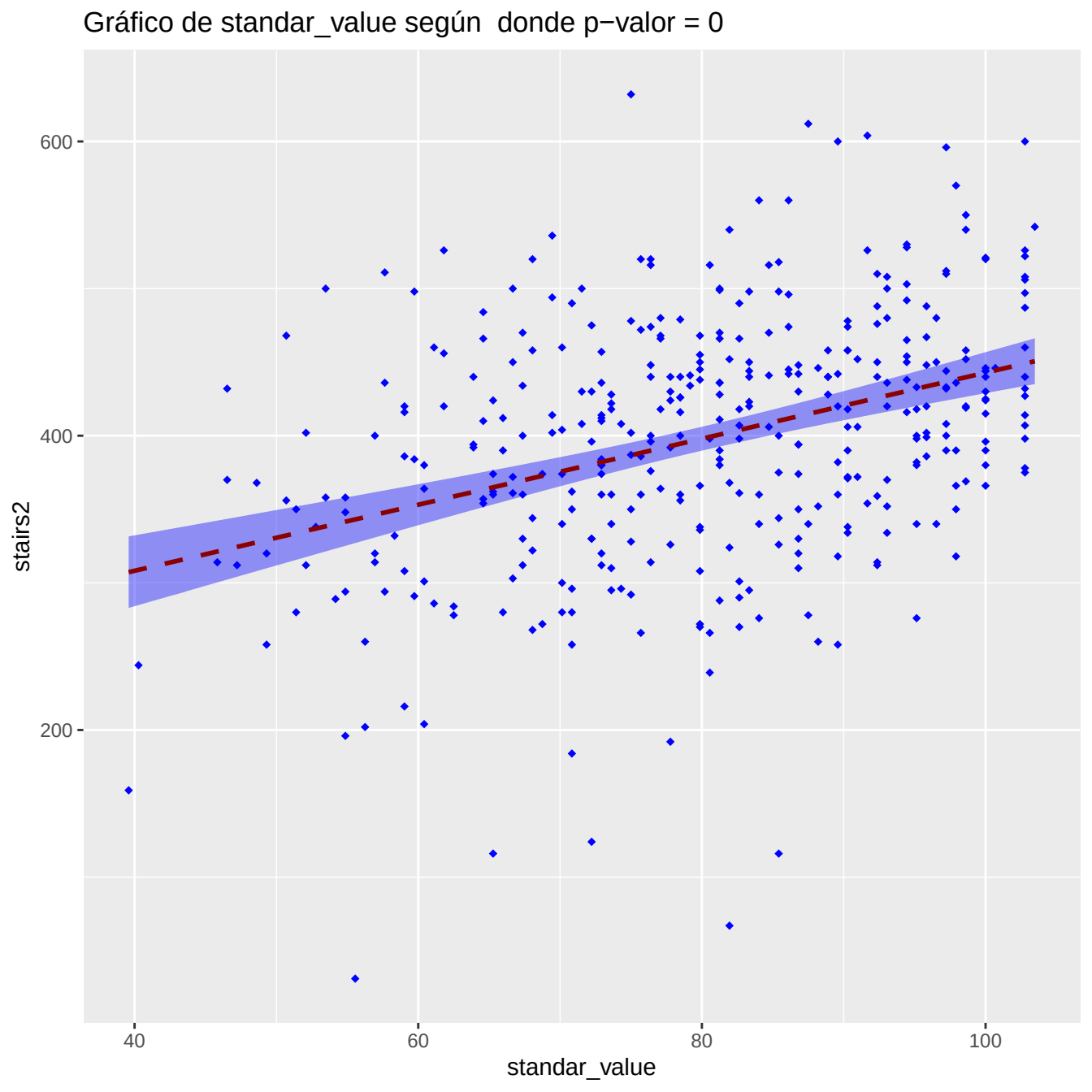
Gráfico de standar_value según donde p−valor = 0
600
400
200
stairs2
40
60
80
100
standar_value

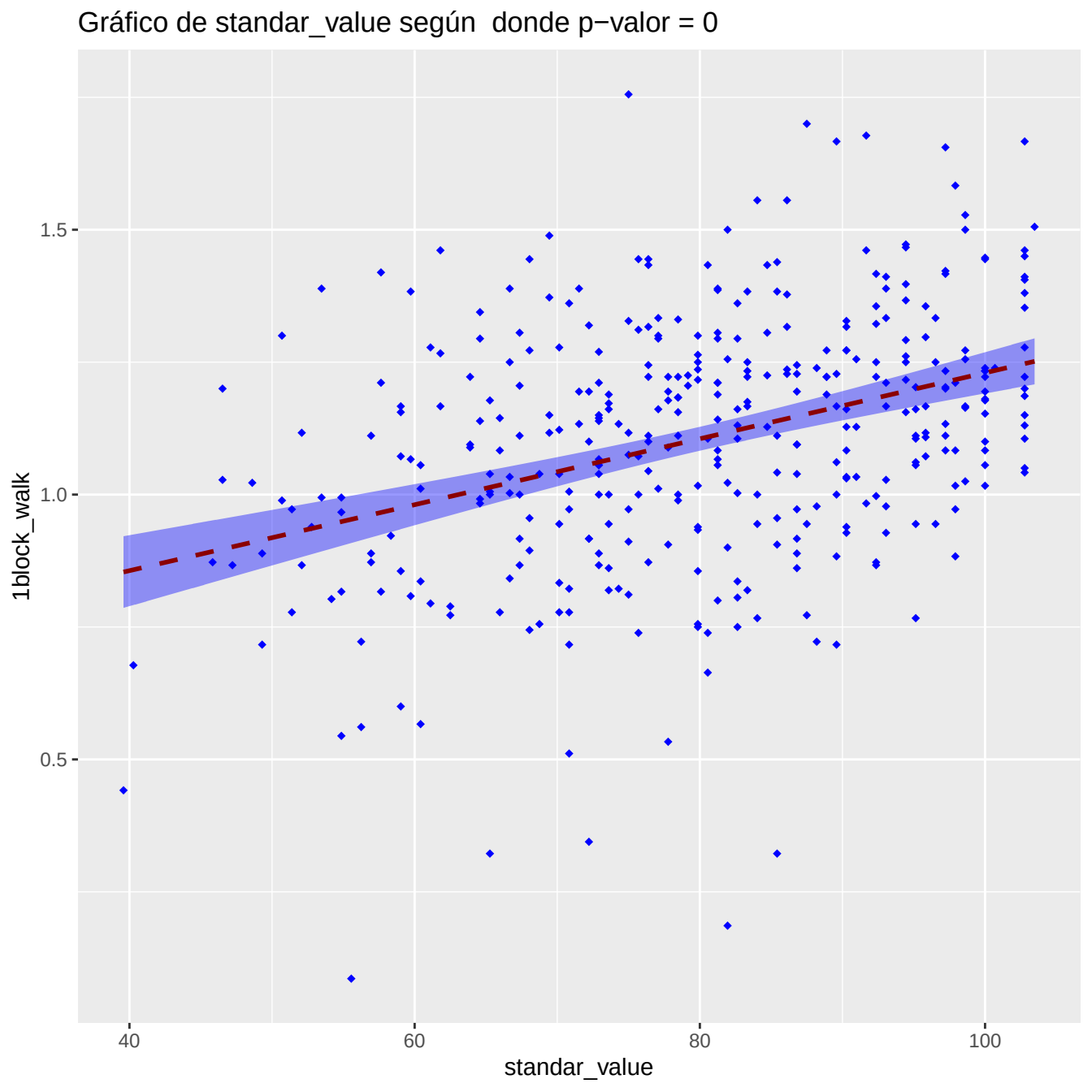
Gráfico de standar_value según donde p−valor = 0
1block_walk
1.5
1.0
0.5
40
60
80
100
standar_value

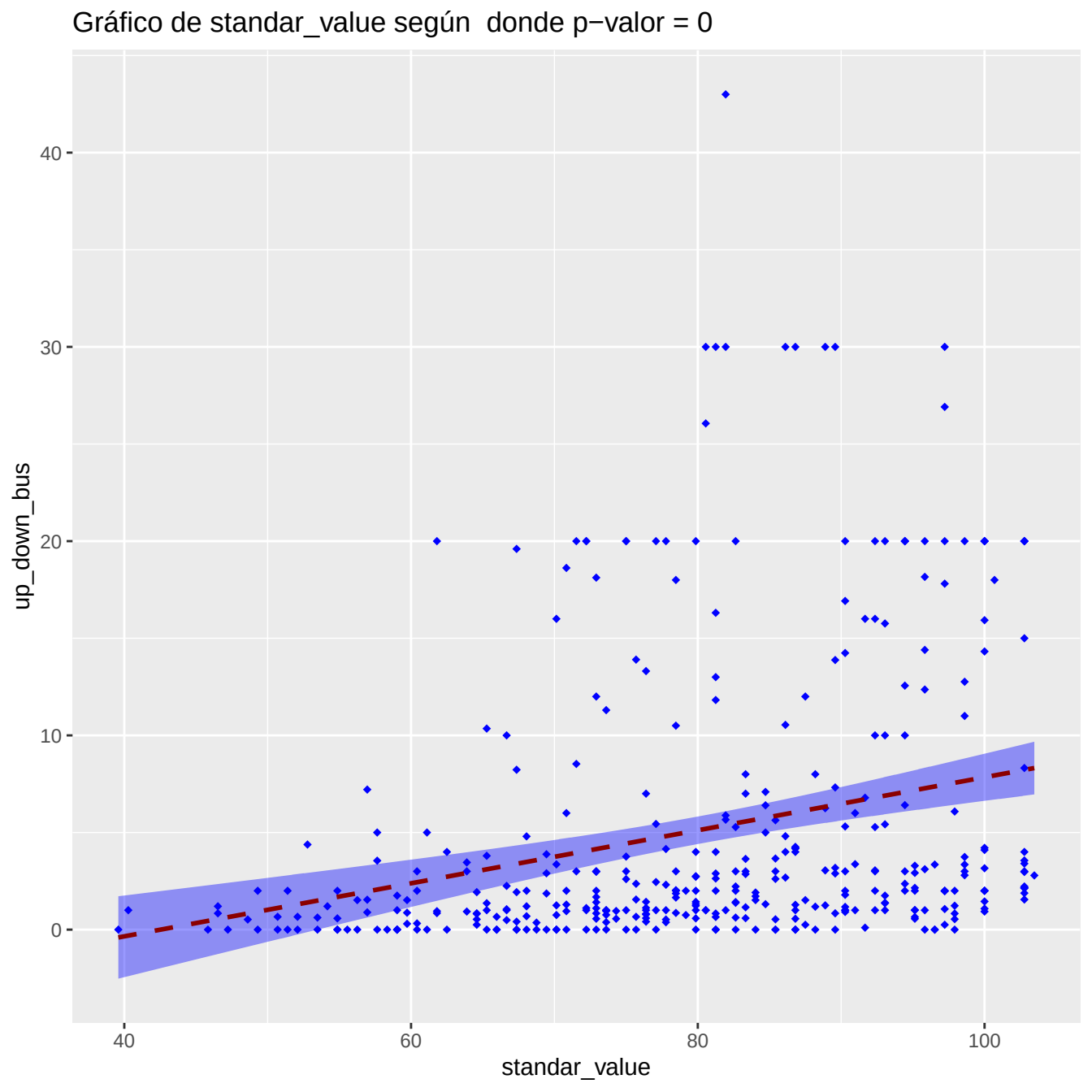
Gráfico de standar_value según donde p−valor = 0
up_down_bus
40
30
20
10
0
40
60
80
100
standar_value

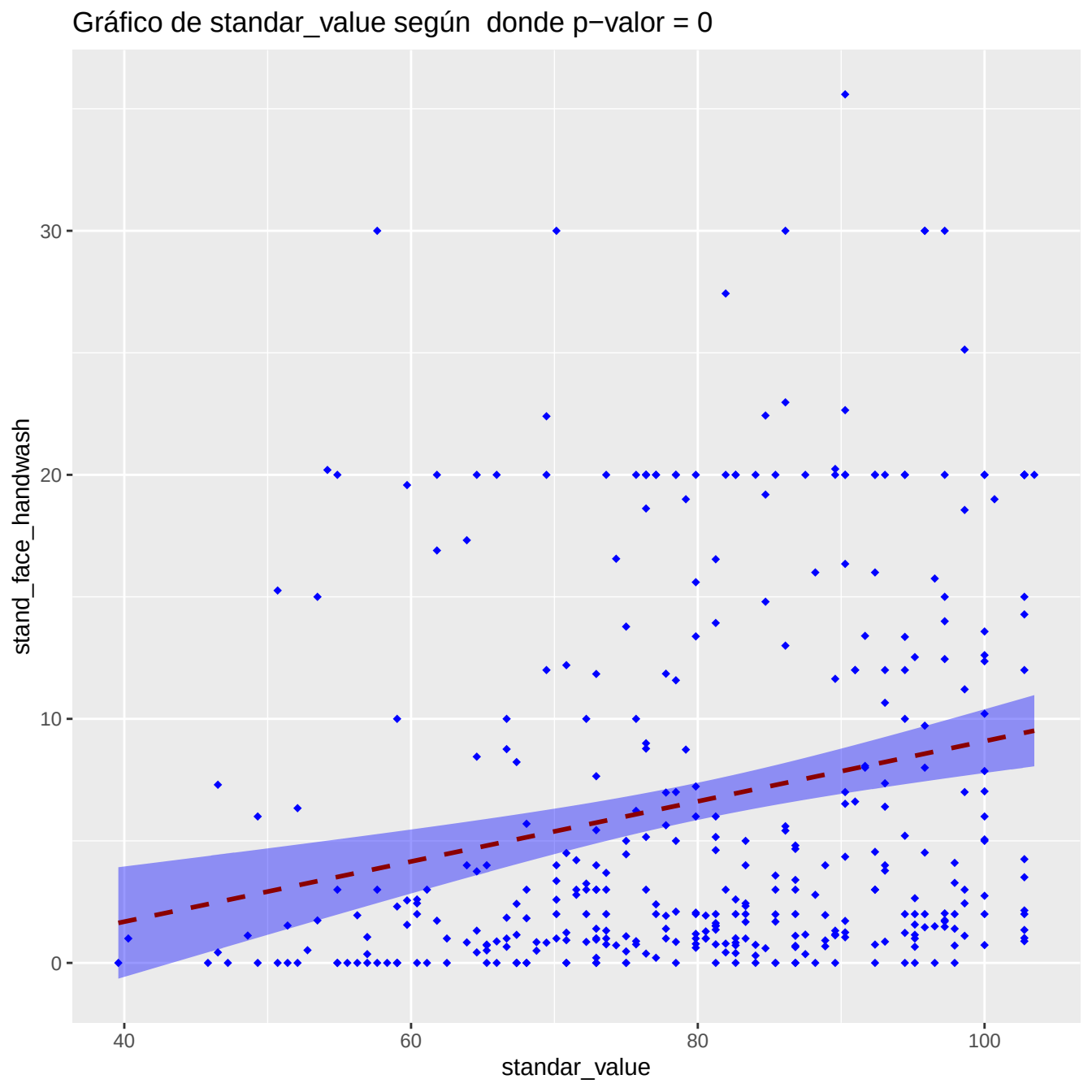
Gráfico de standar_value según donde p−valor = 0
stand_face_handwash
30
20
10
0
40
60
80
100
standar_value

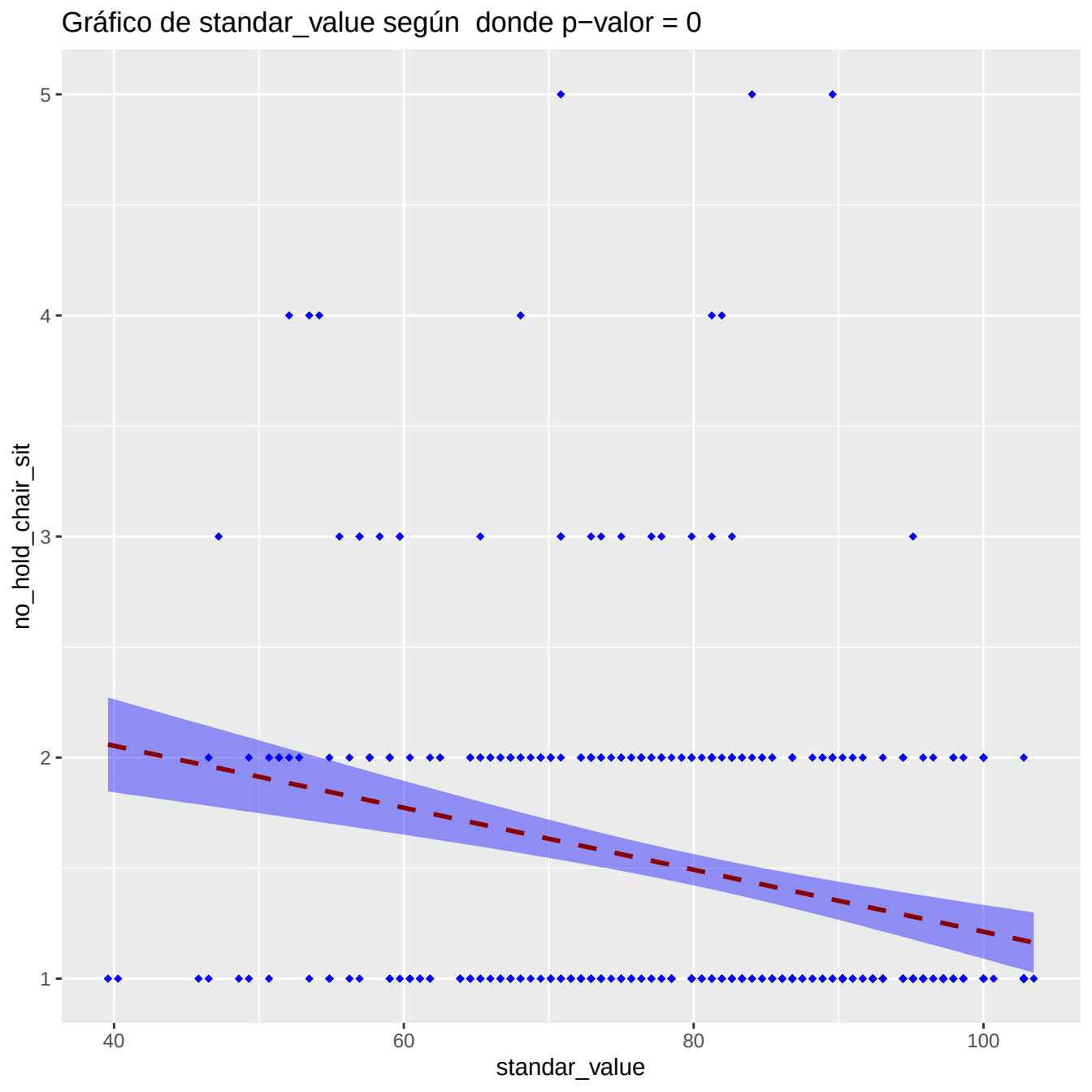
Gráfico de standar_value según donde p−valor = 0
no_hold_chair_sit
5
4
3
2
1
40
60
80
100
standar_value

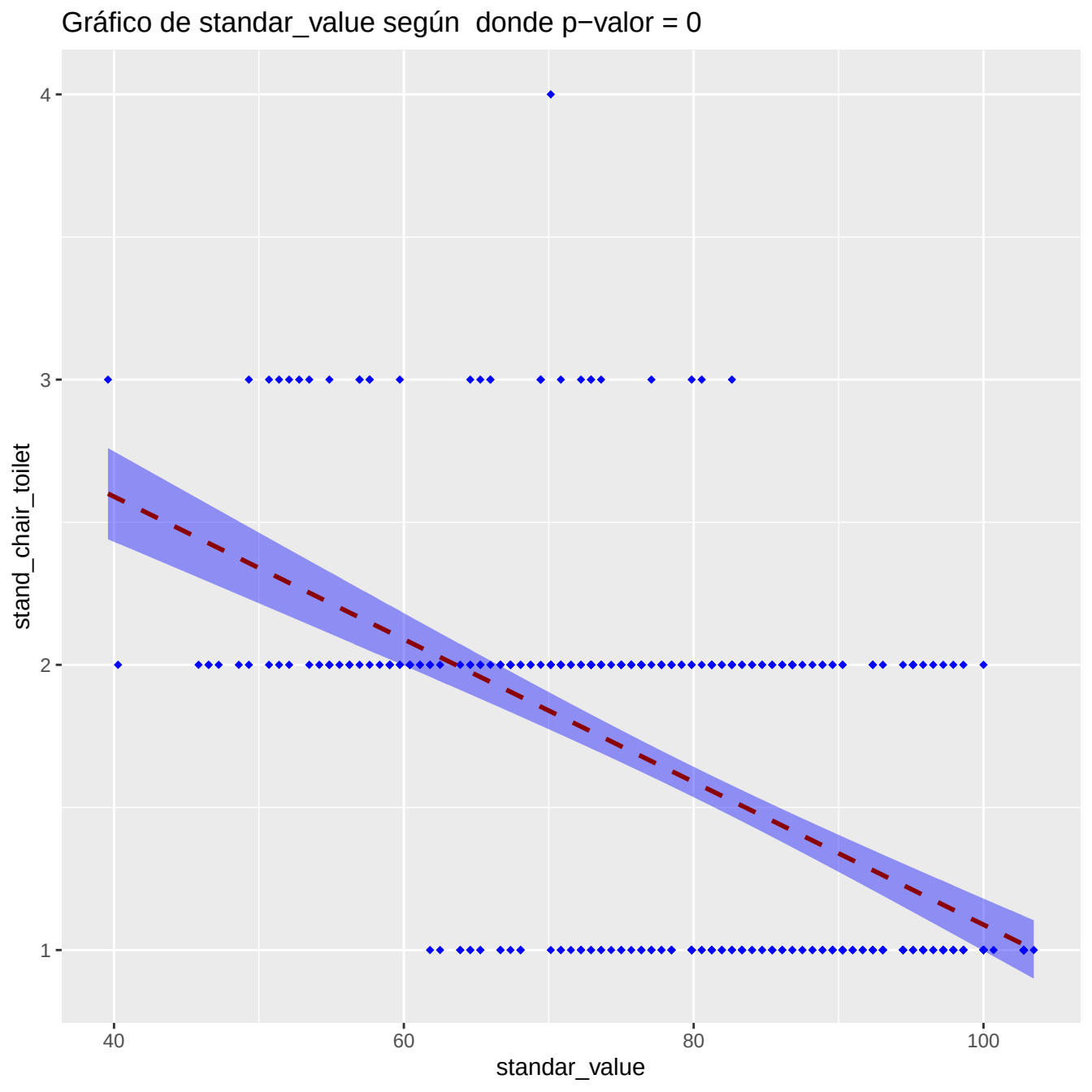
Gráfico de standar_value según donde p−valor = 0
4
3
2
1
stand_chair_toilet
40
60
80
100
standar_value

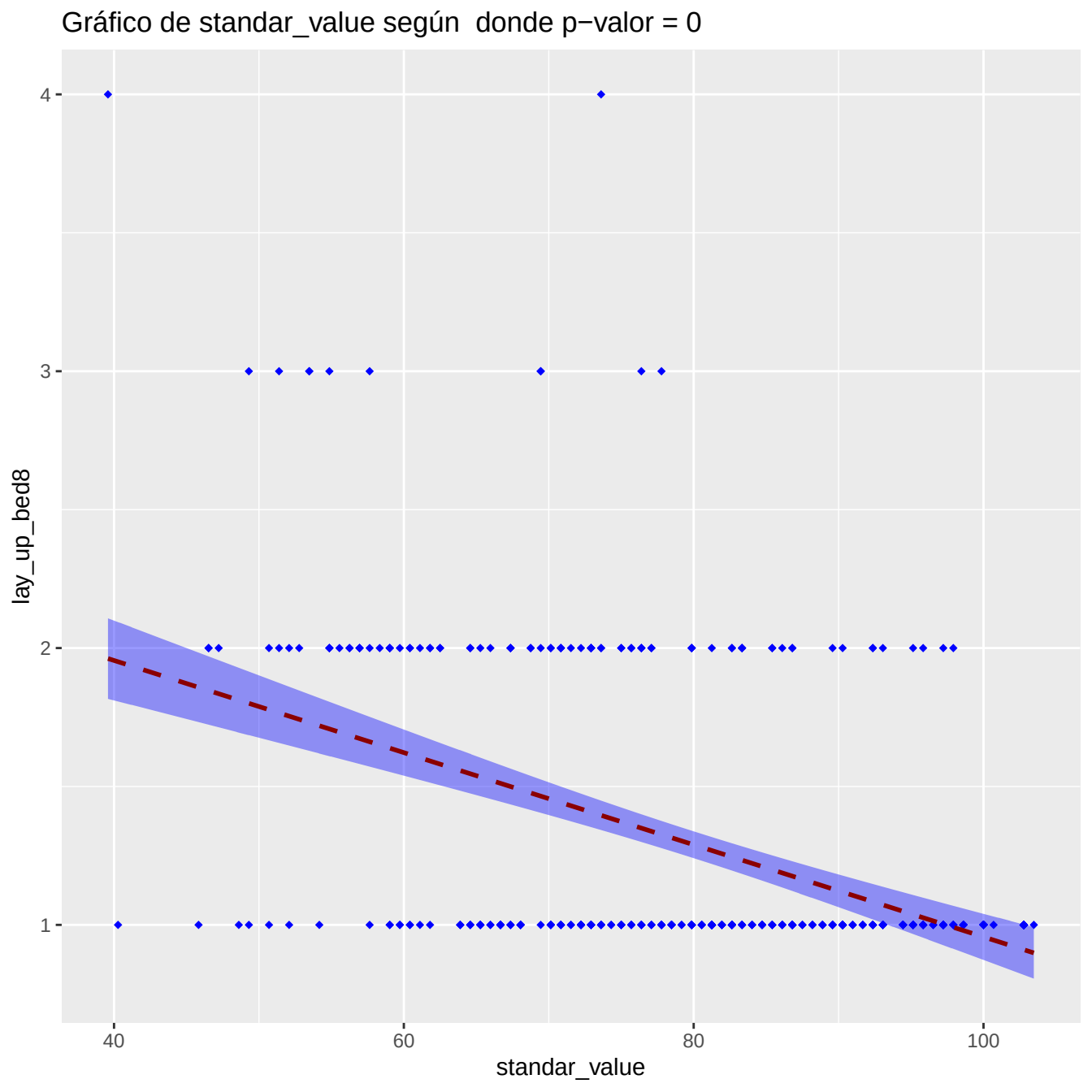
Gráfico de standar_value según donde p−valor = 0
lay_up_bed8
4
3
2
1
40
60
80
100
standar_value

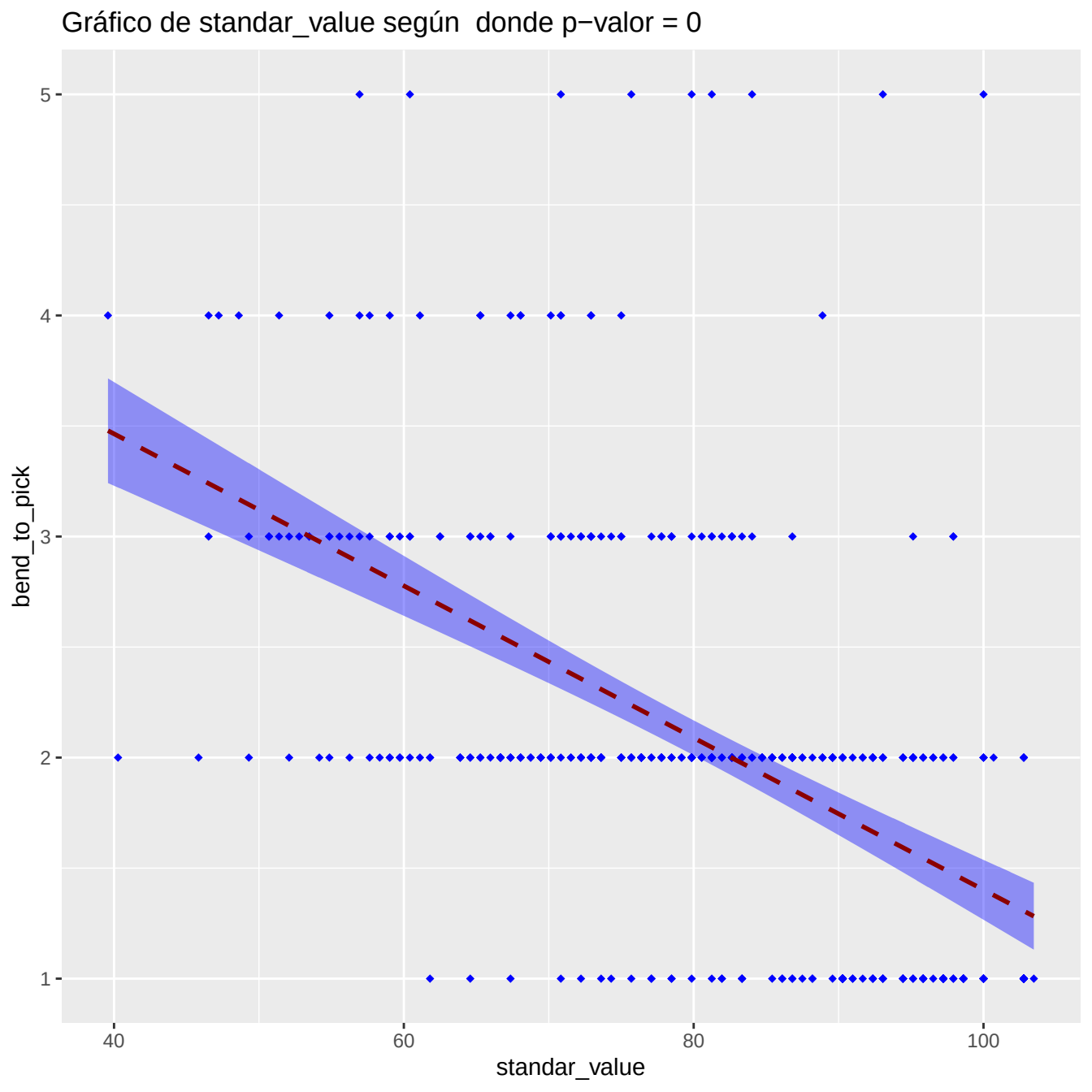
Gráfico de standar_value según donde p−valor = 0
bend_to_pick
5
4
3
2
1
40
60
80
100
standar_value

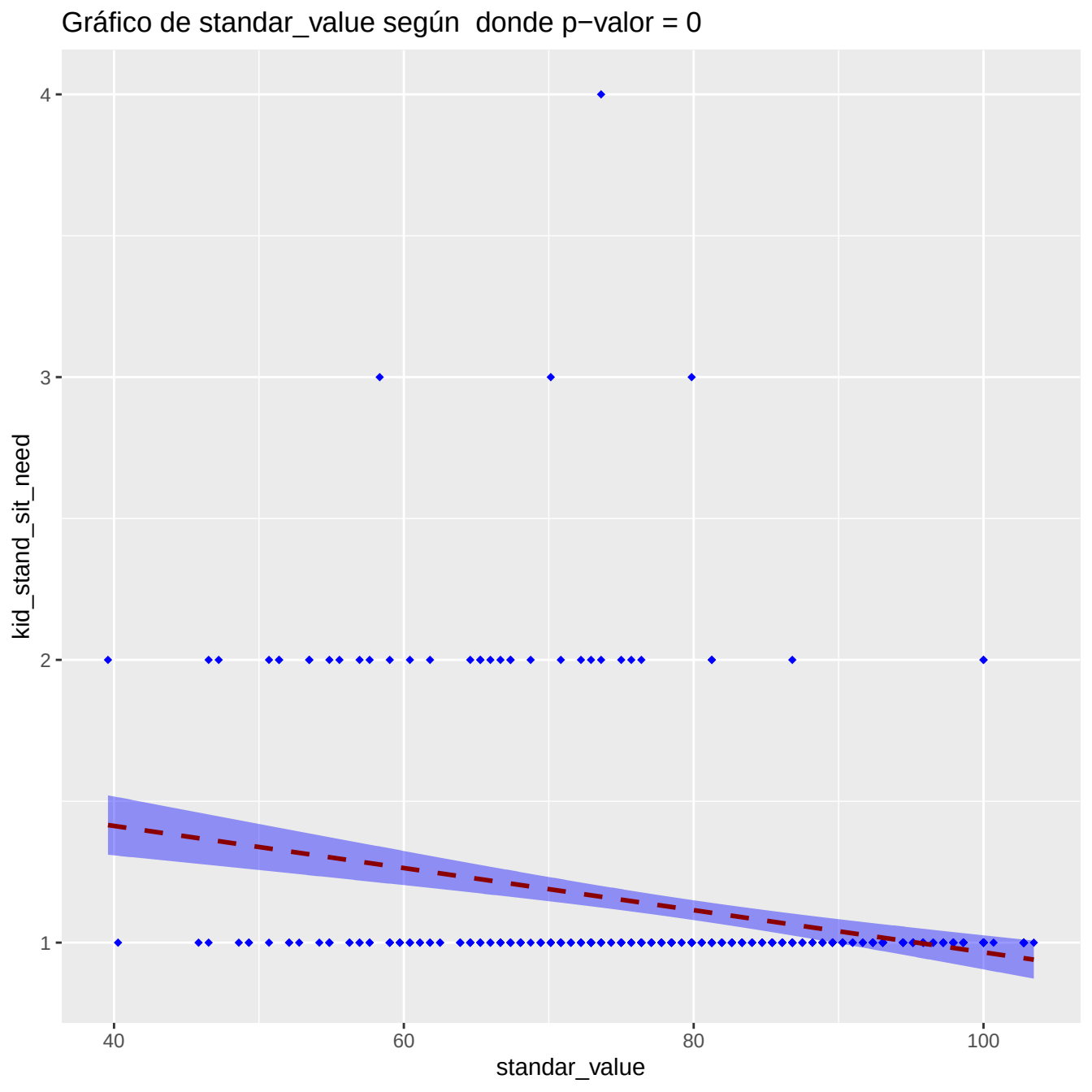
Gráfico de standar_value según donde p−valor = 0
kid_stand_sit_need
4
3
2
1
40
60
80
100
standar_value

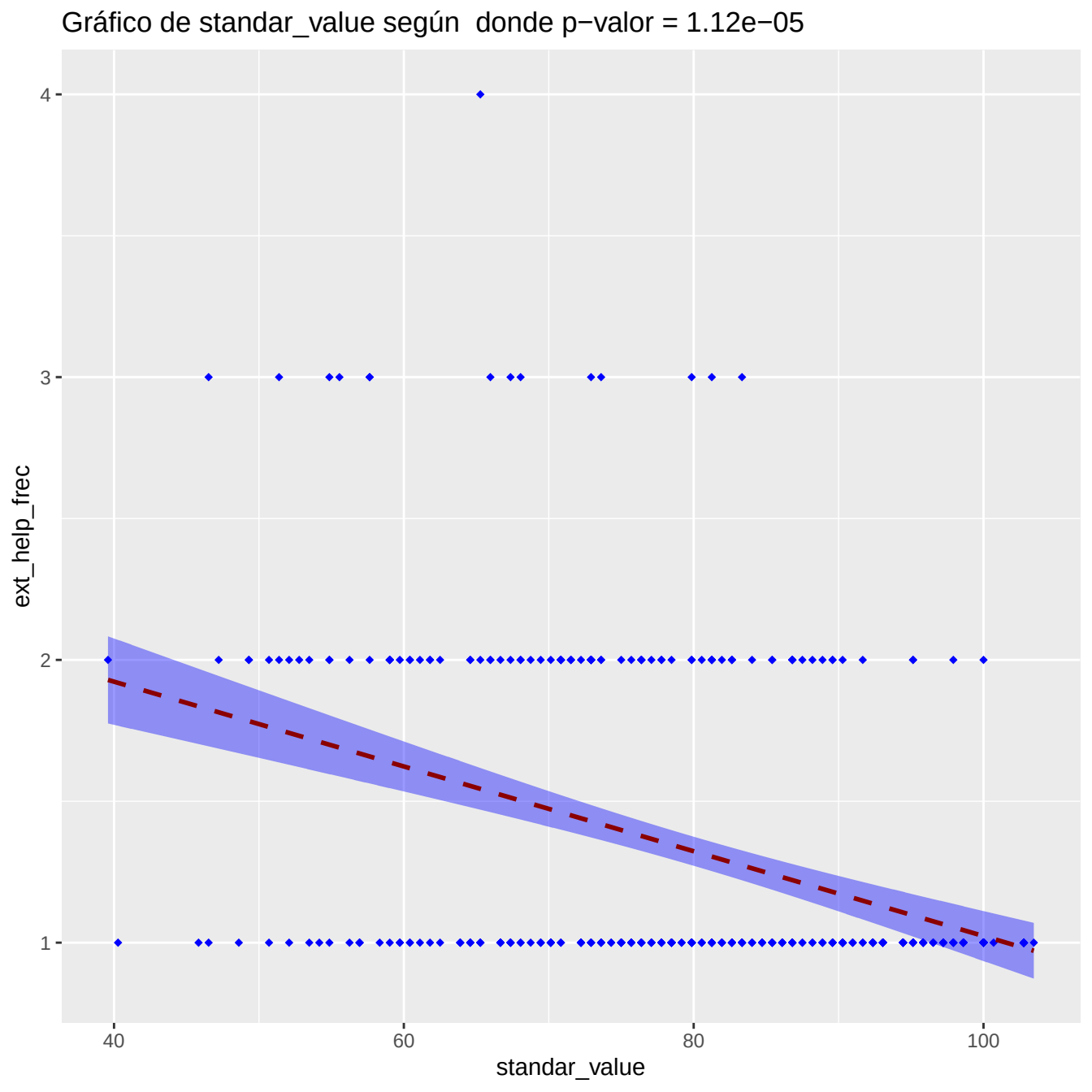
Gráfico de standar_value según donde p−valor = 1.12e−05
ext_help_frec
4
3
2
1
40
60
80
100
standar_value

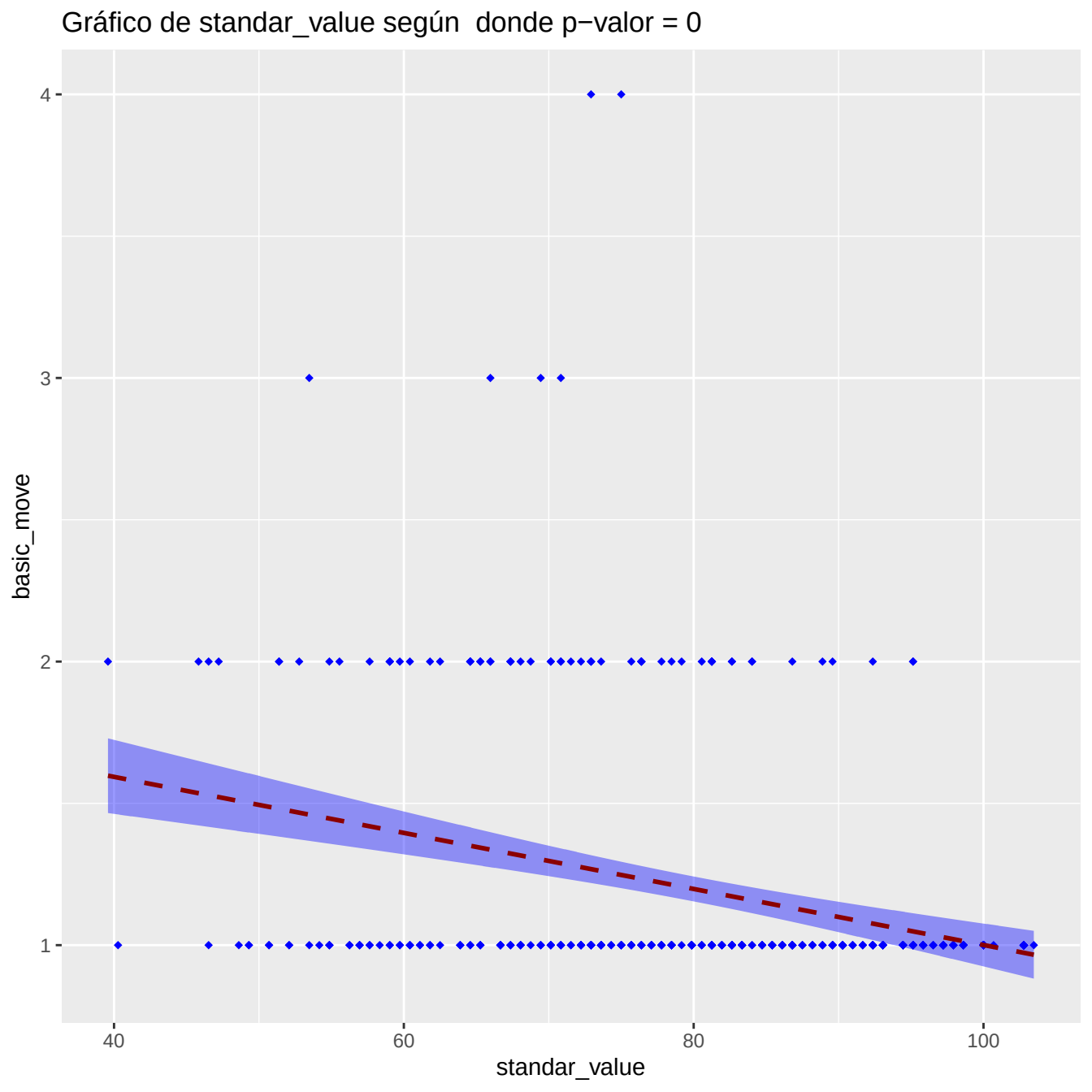
Gráfico de standar_value según donde p−valor = 0
basic_move
4
3
2
1
40
60
80
100
standar_value

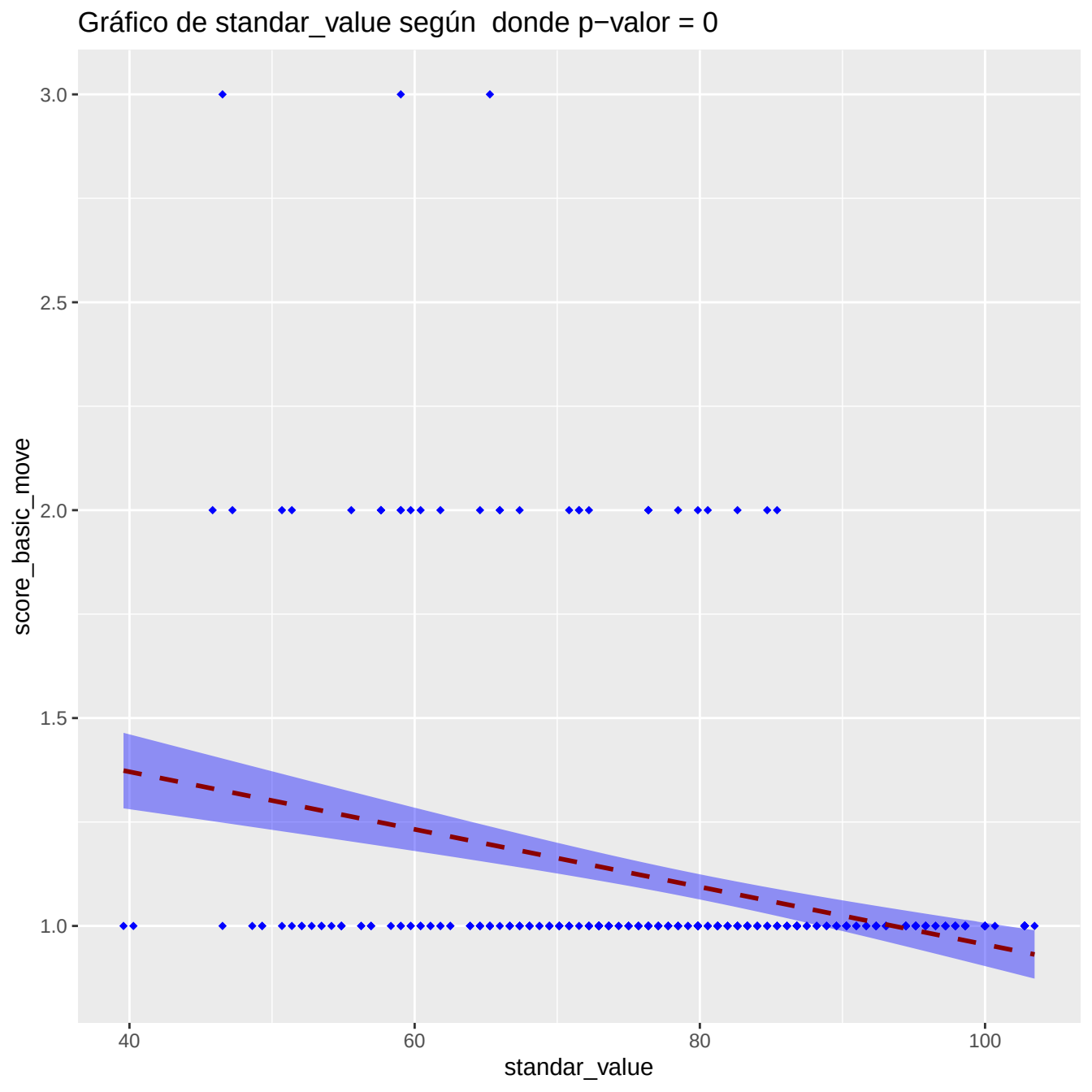
Gráfico de standar_value según donde p−valor = 0
score_basic_move
3.0
2.5
2.0
1.5
1.0
40
60
80
100
standar_value

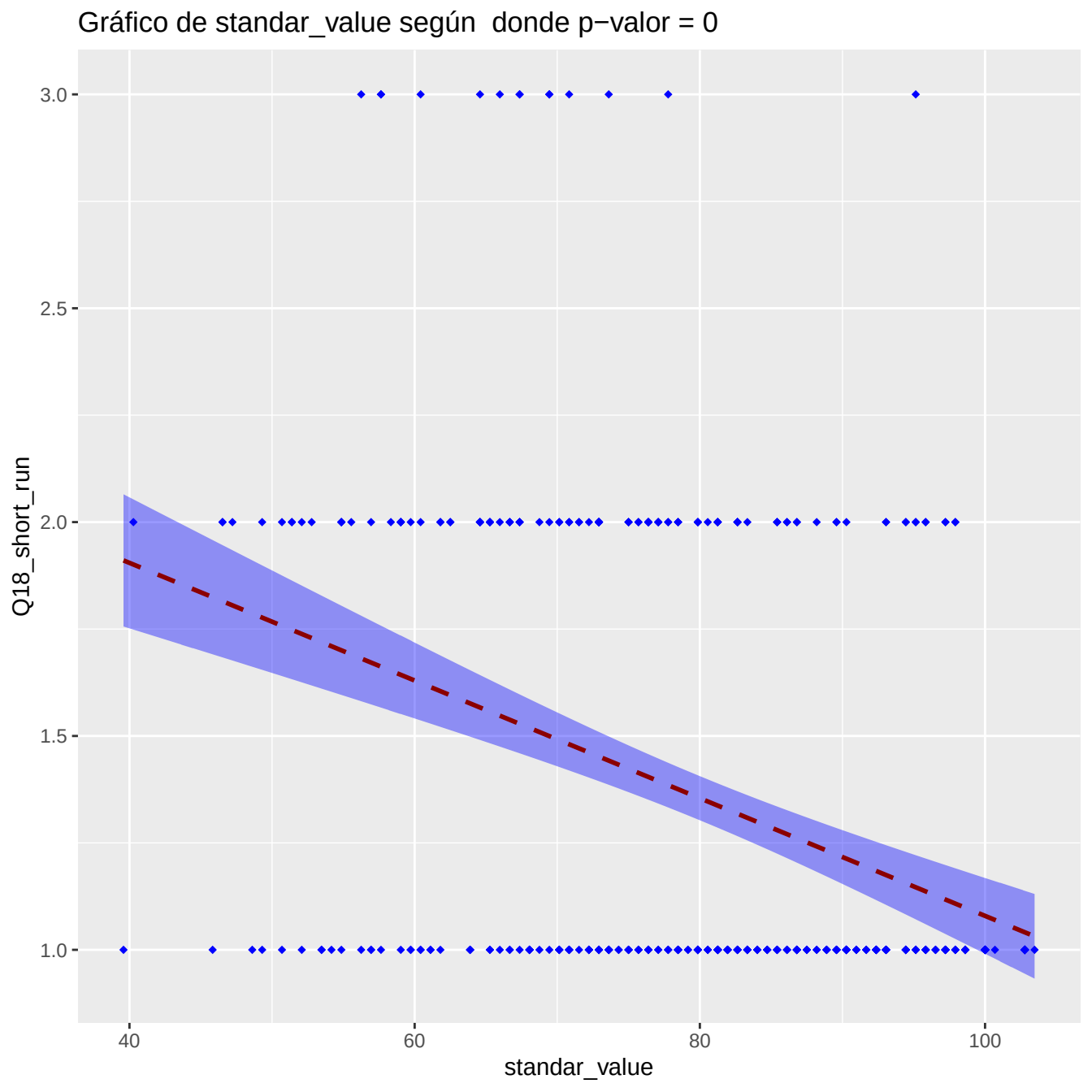
Gráfico de standar_value según donde p−valor = 0
Q18_short_run
3.0
2.5
2.0
1.5
1.0
40
60
80
100
standar_value

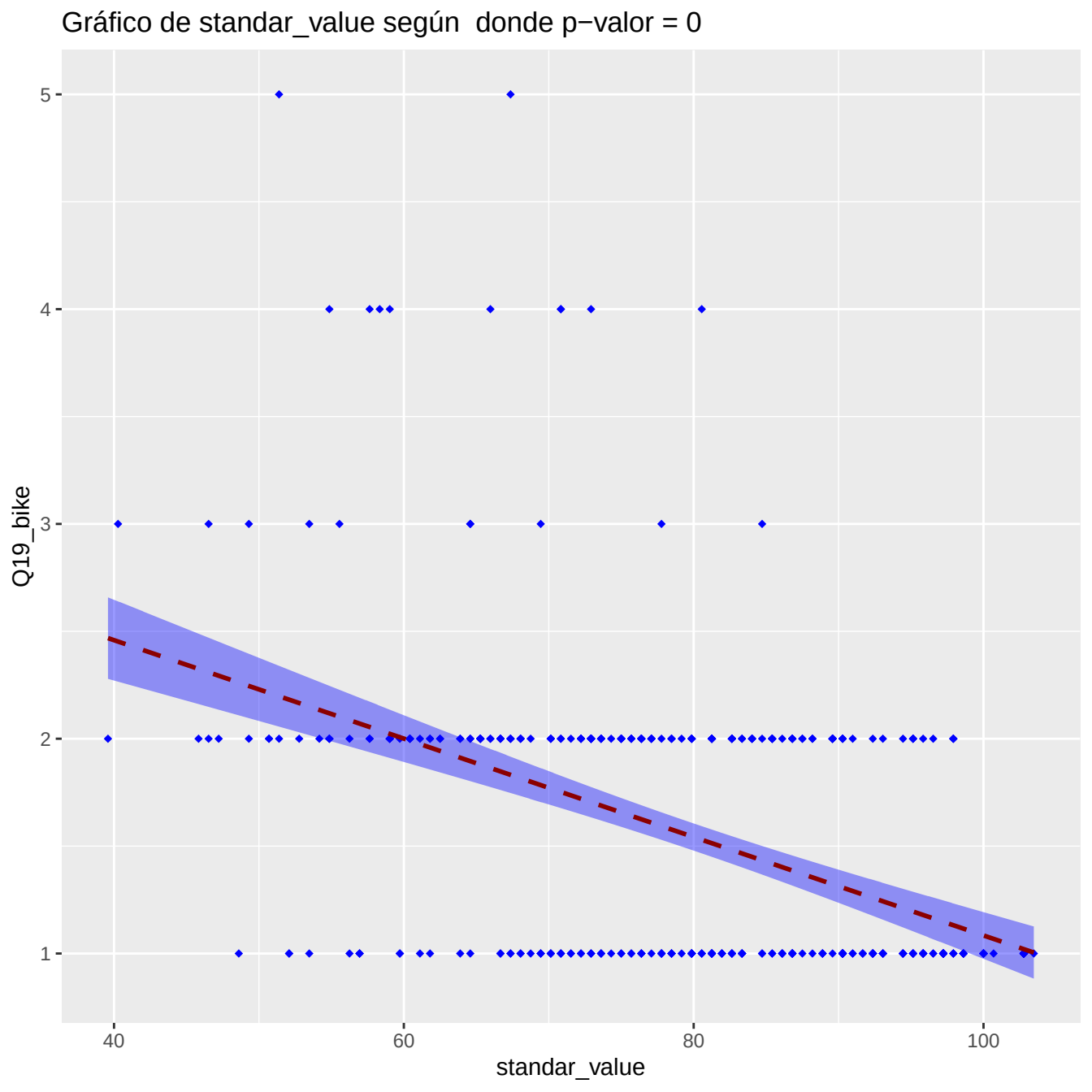
Gráfico de standar_value según donde p−valor = 0
Q19_bike
5
4
3
2
1
40
60
80
100
standar_value

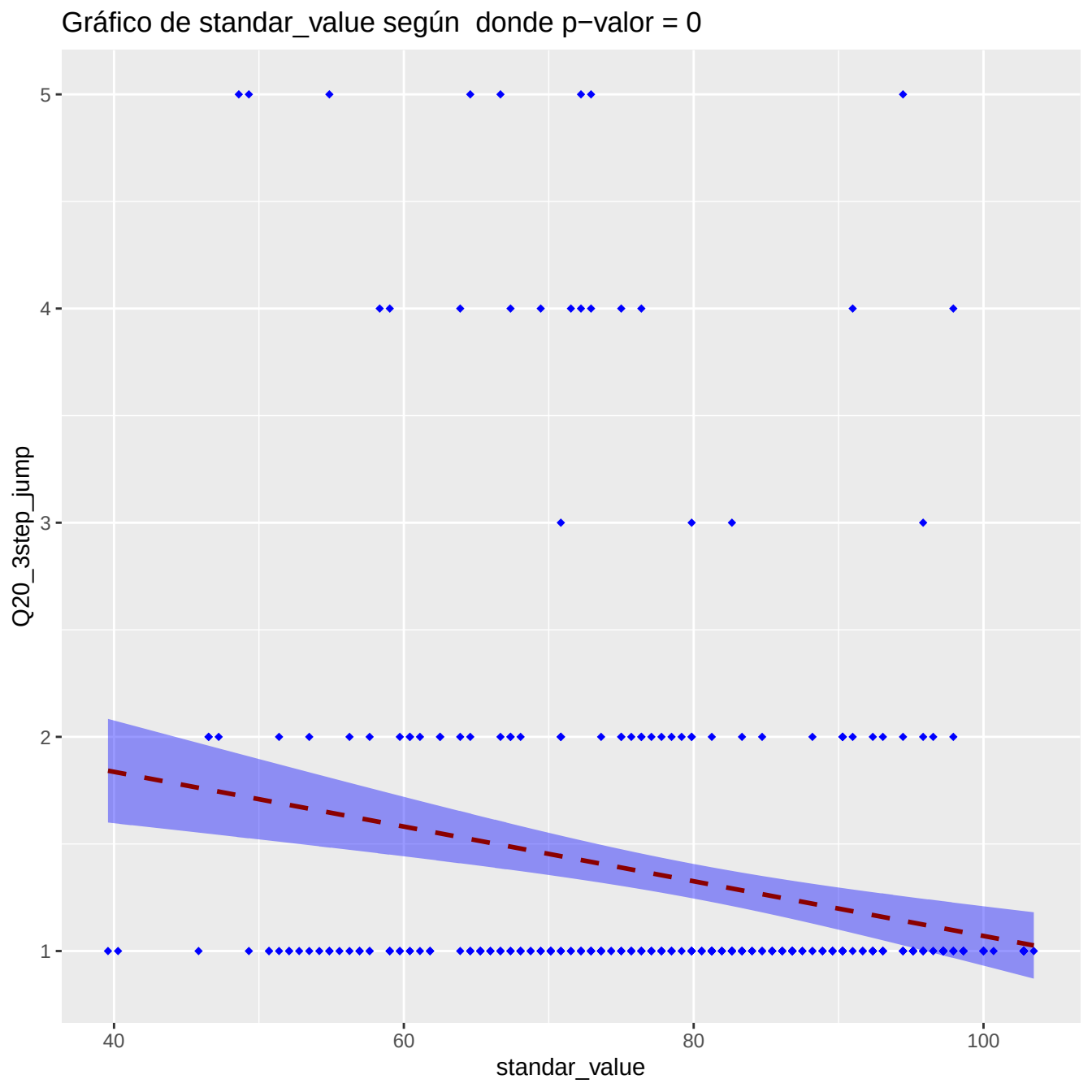
Gráfico de standar_value según donde p−valor = 0
Q20_3step_jump
standar_value
5
4
3
2
1
40
60
80
100

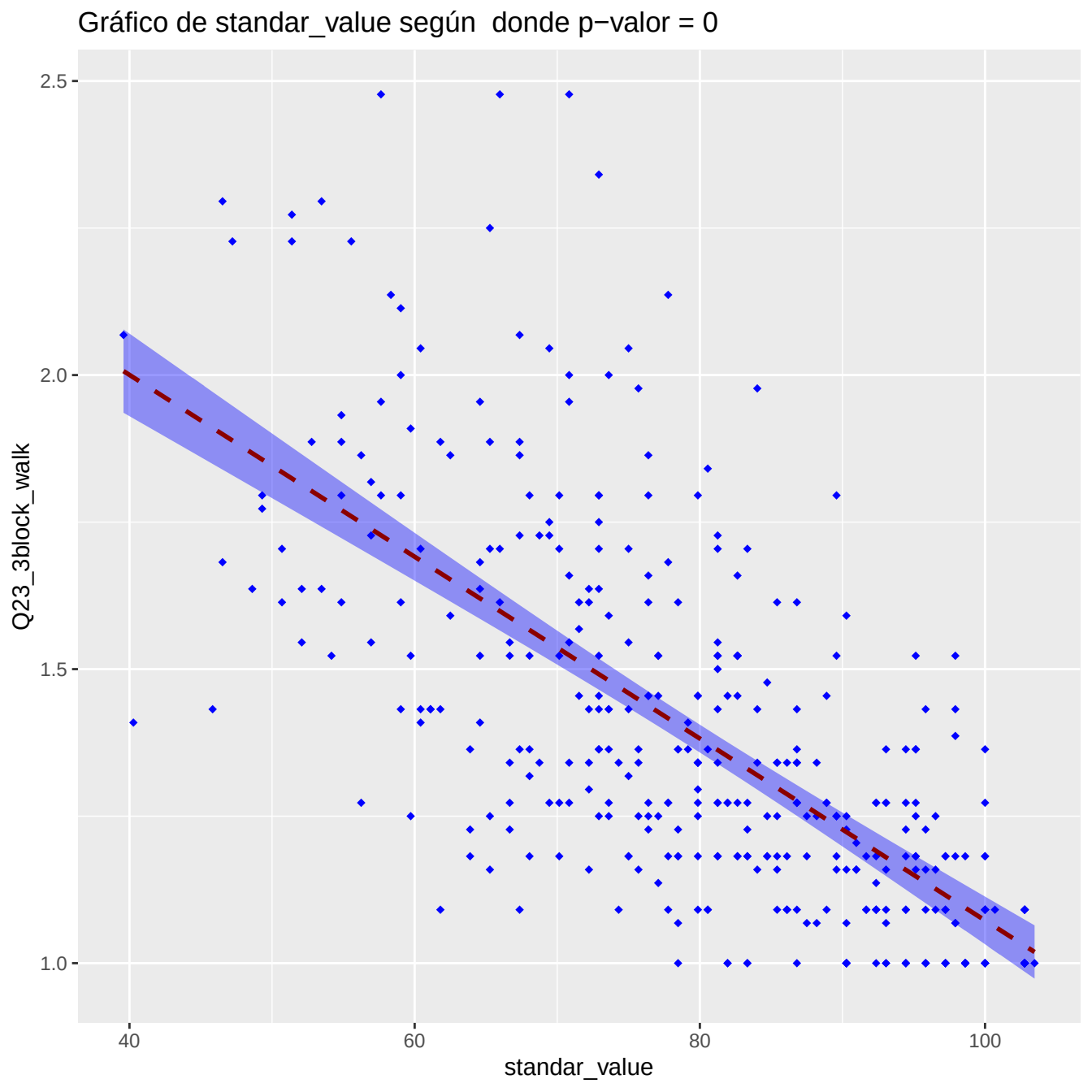
Gráfico de standar_value según donde p−valor = 0
Q23_3block_walk
2.5
2.0
1.5
1.0
40
60
80
100
standar_value

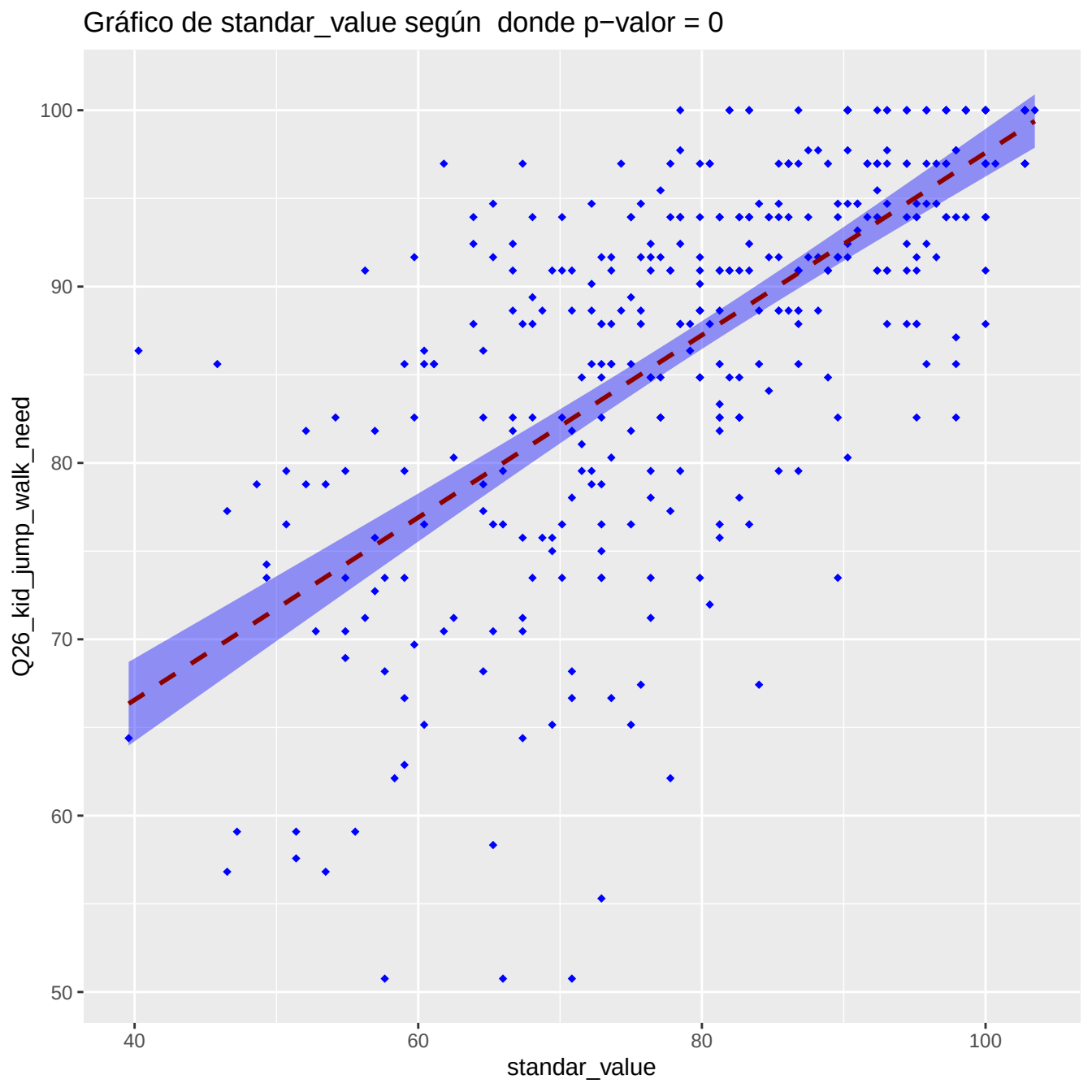
Gráfico de standar_value según donde p−valor = 0
Q26_kid_jump_walk_need
standar_value
100
90
80
70
60
50
40
60
80
100

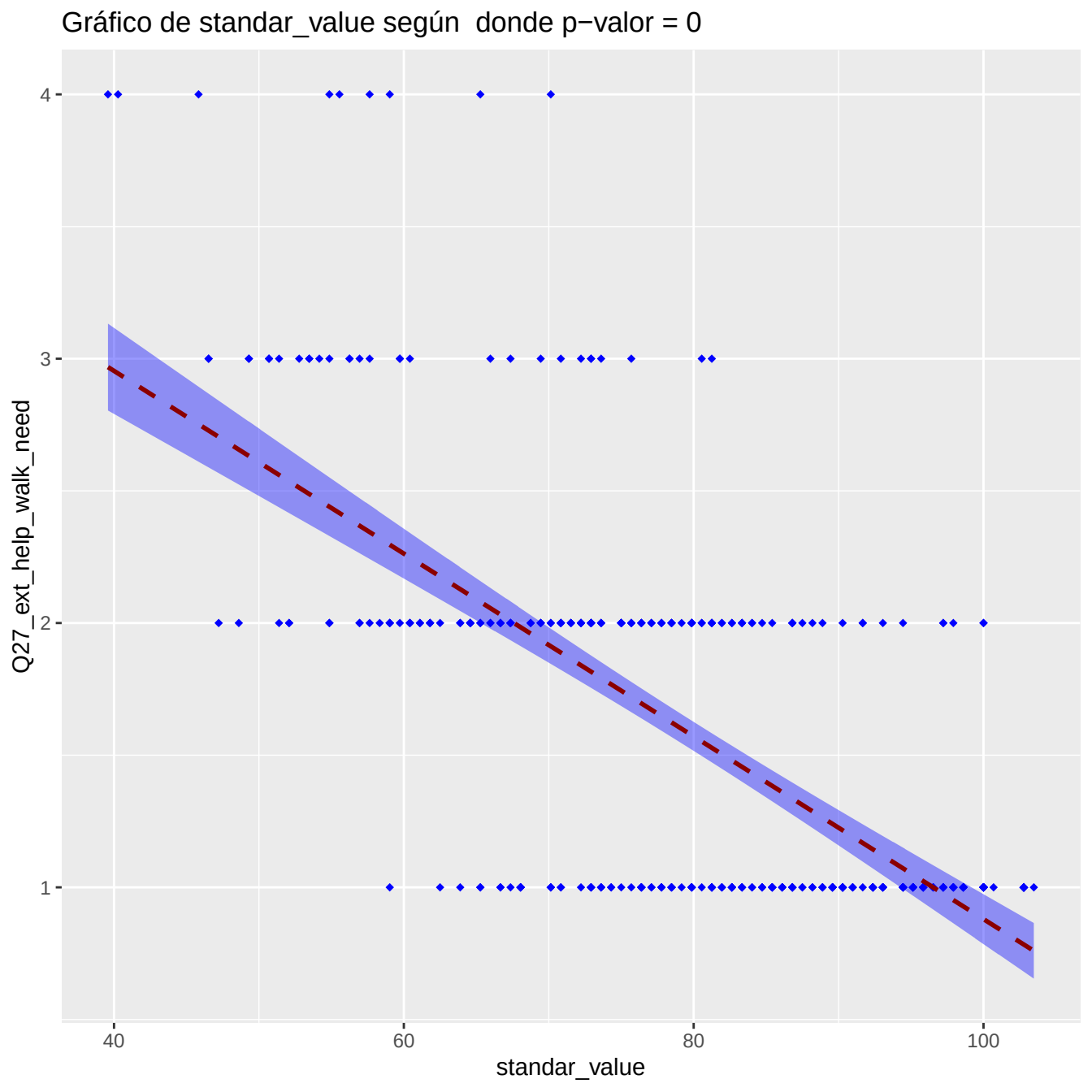
Gráfico de standar_value según donde p−valor = 0
Q27_ext_help_walk_need
4
3
2
1
40
60
80
100
standar_value

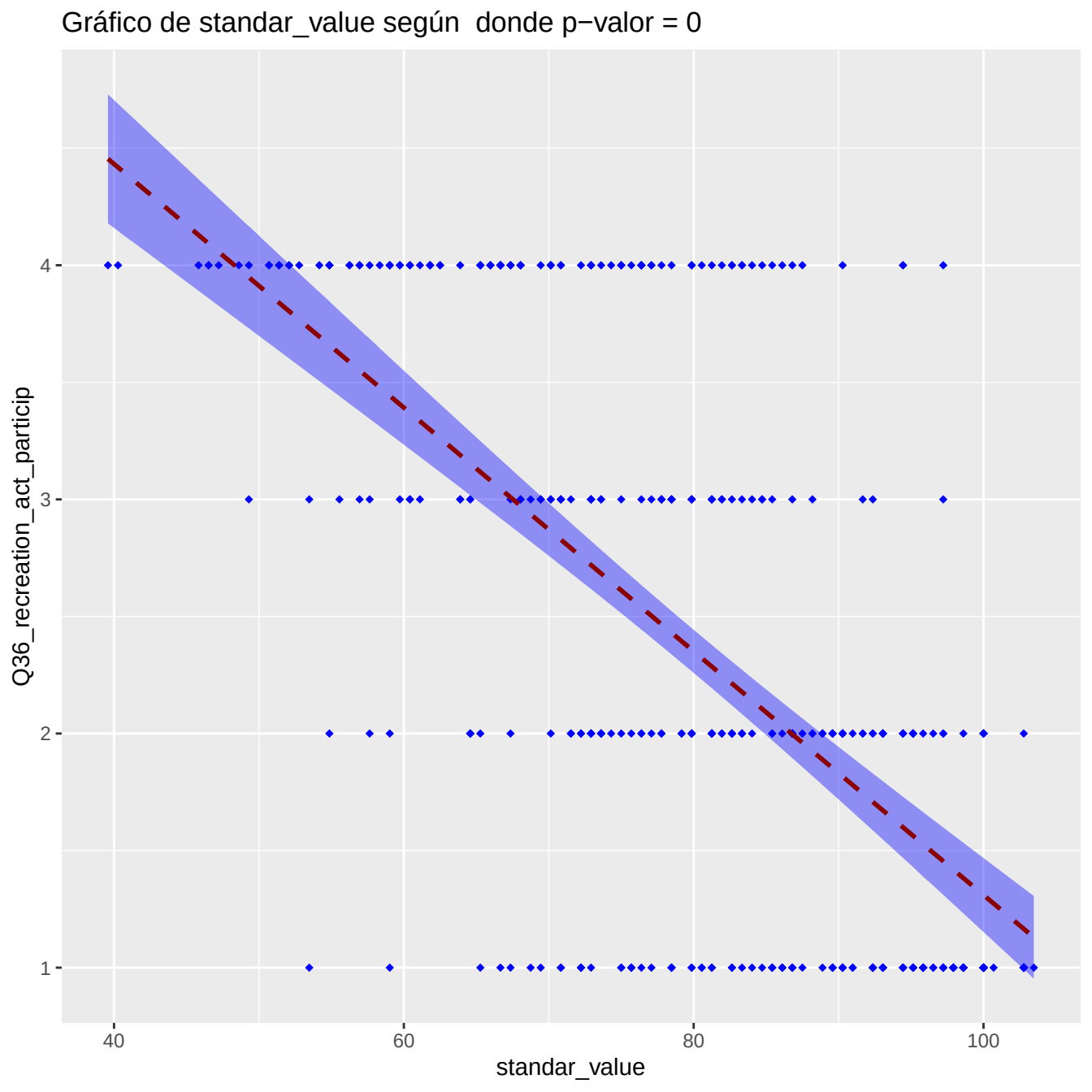
Gráfico de standar_value según donde p−valor = 0
Q36_recreation_act_particip
4
3
2
1
40
60
80
100
standar_value

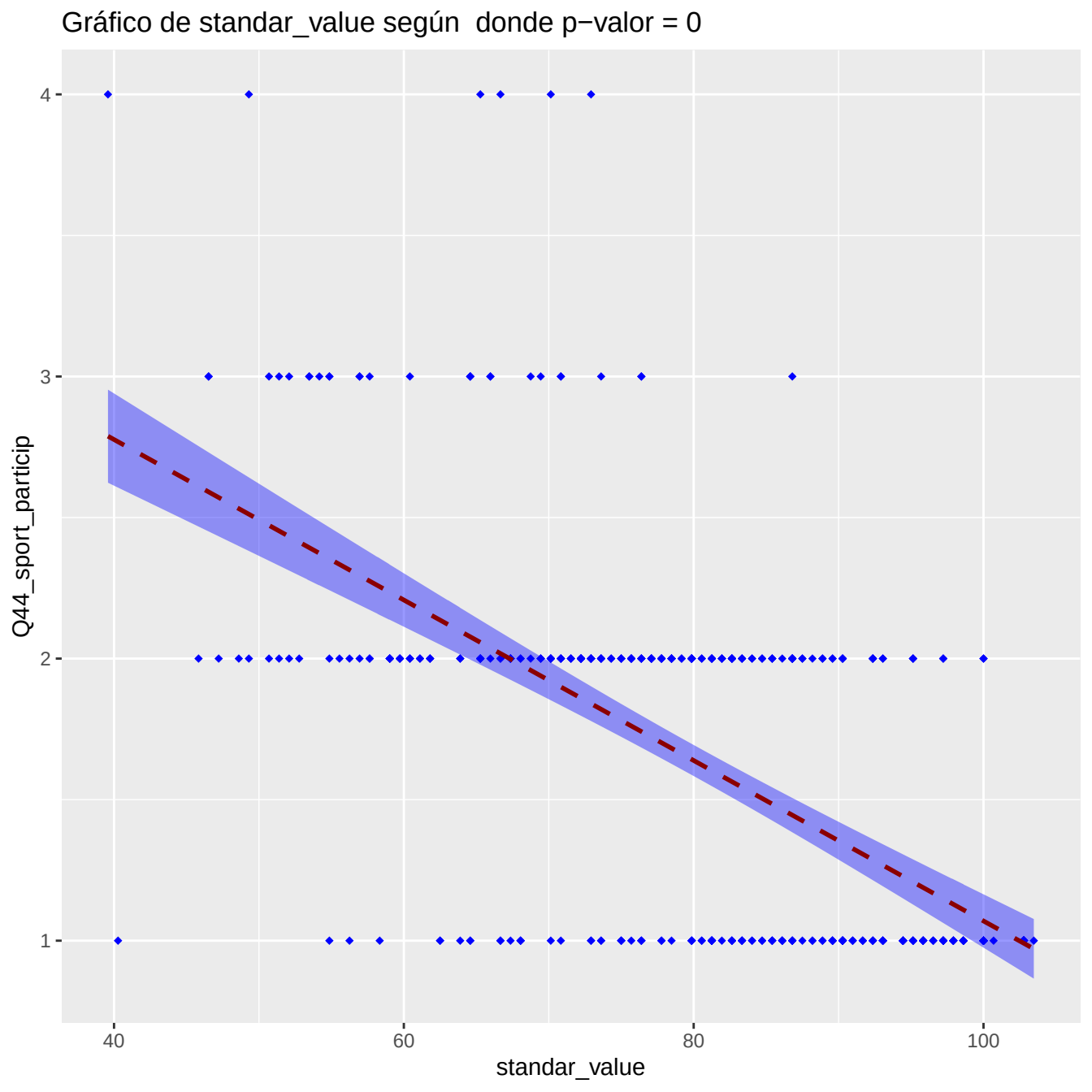
Gráfico de standar_value según donde p−valor = 0
Q44_sport_particip
standar_value
4
3
2
1
40
60
80
100

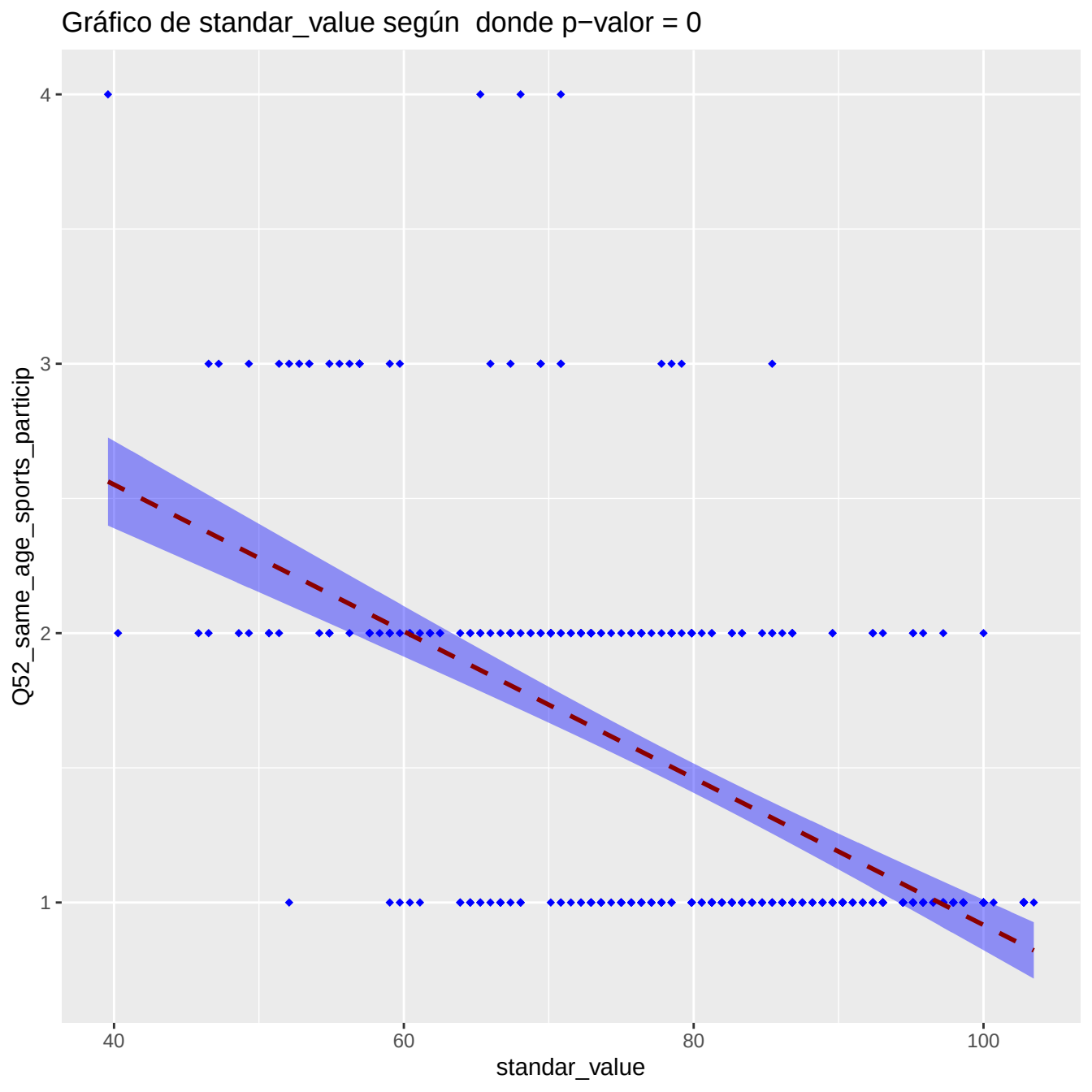
Gráfico de standar_value según donde p−valor = 0
Q52_same_age_sports_particip
4
3
2
1
40
60
80
100
standar_value

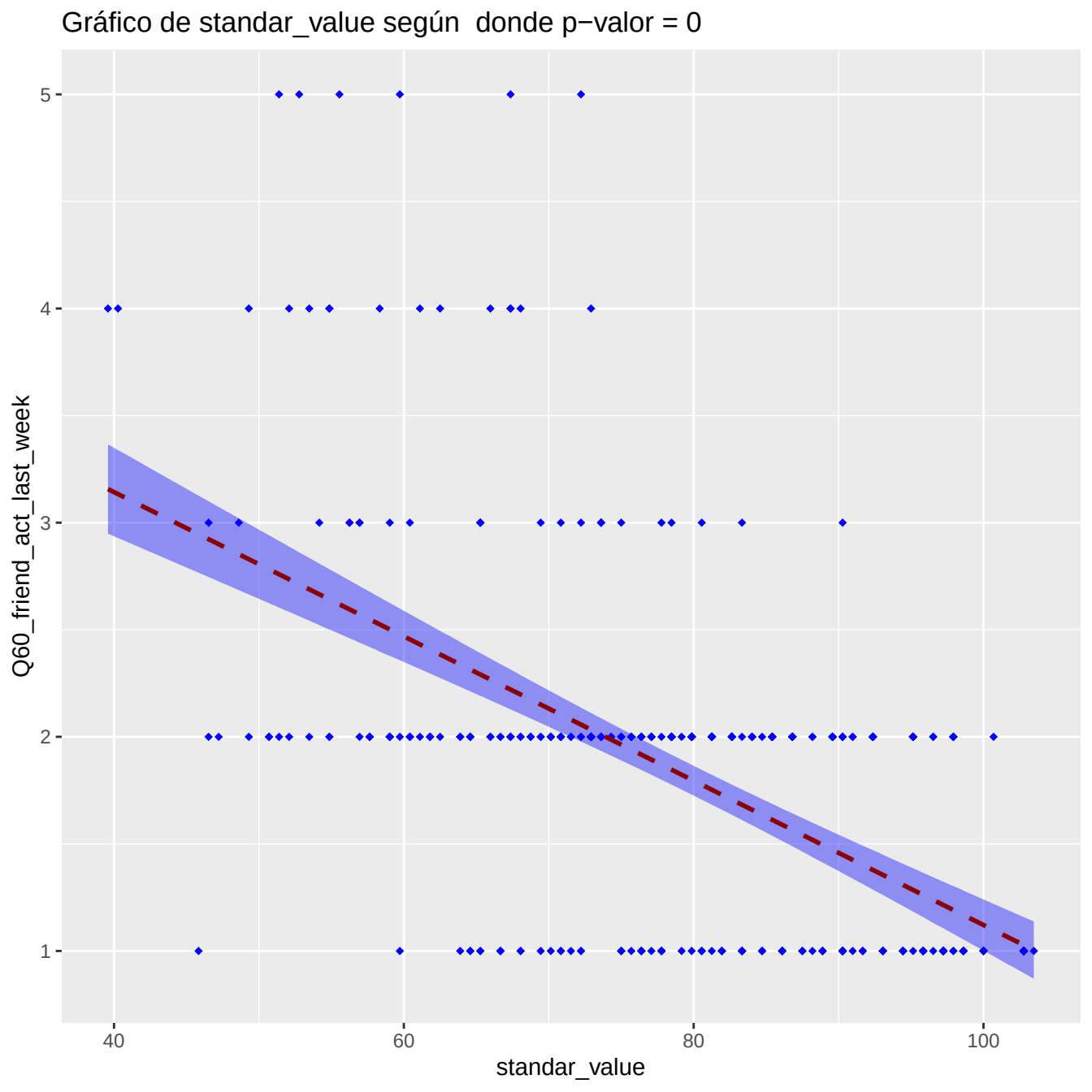
Gráfico de standar_value según donde p−valor = 0
Q60_friend_act_last_week
standar_value
5
4
3
2
1
40
60
80
100

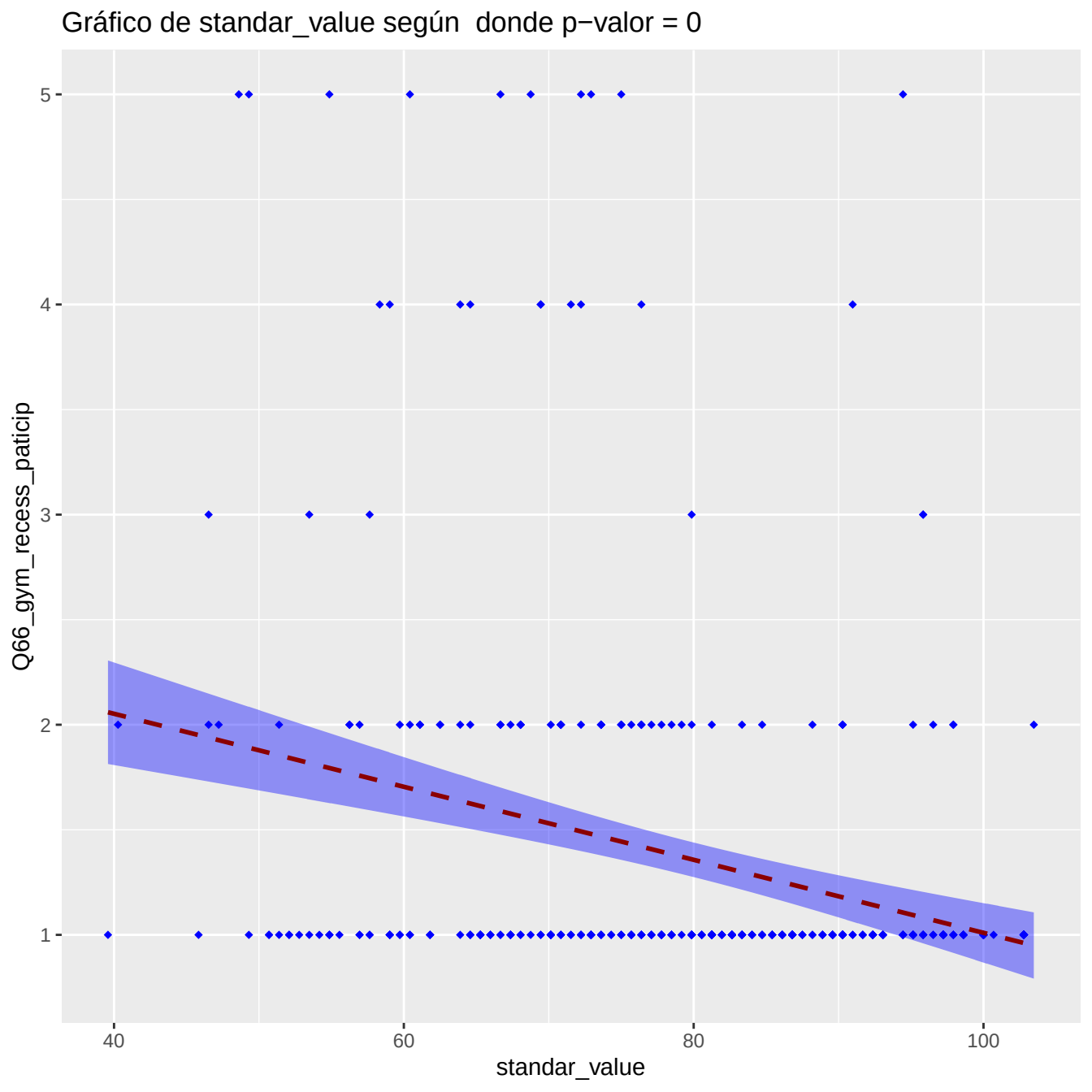
Gráfico de standar_value según donde p−valor = 0
Q66_gym_recess_paticip
5
4
3
2
1
40
60
80
100
standar_value

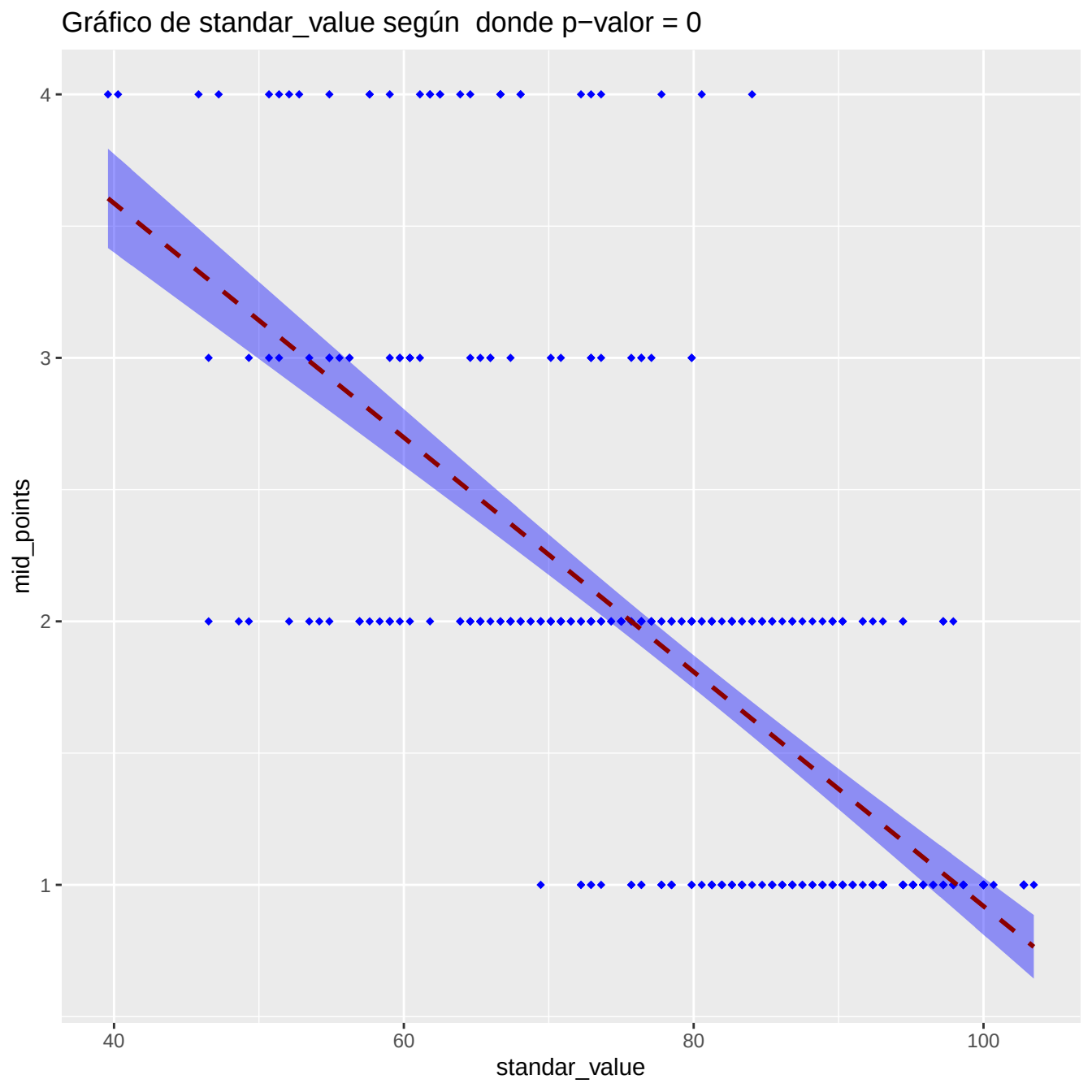
Gráfico de standar_value según donde p−valor = 0
mid_points
4
3
2
1
40
60
80
100
standar_value

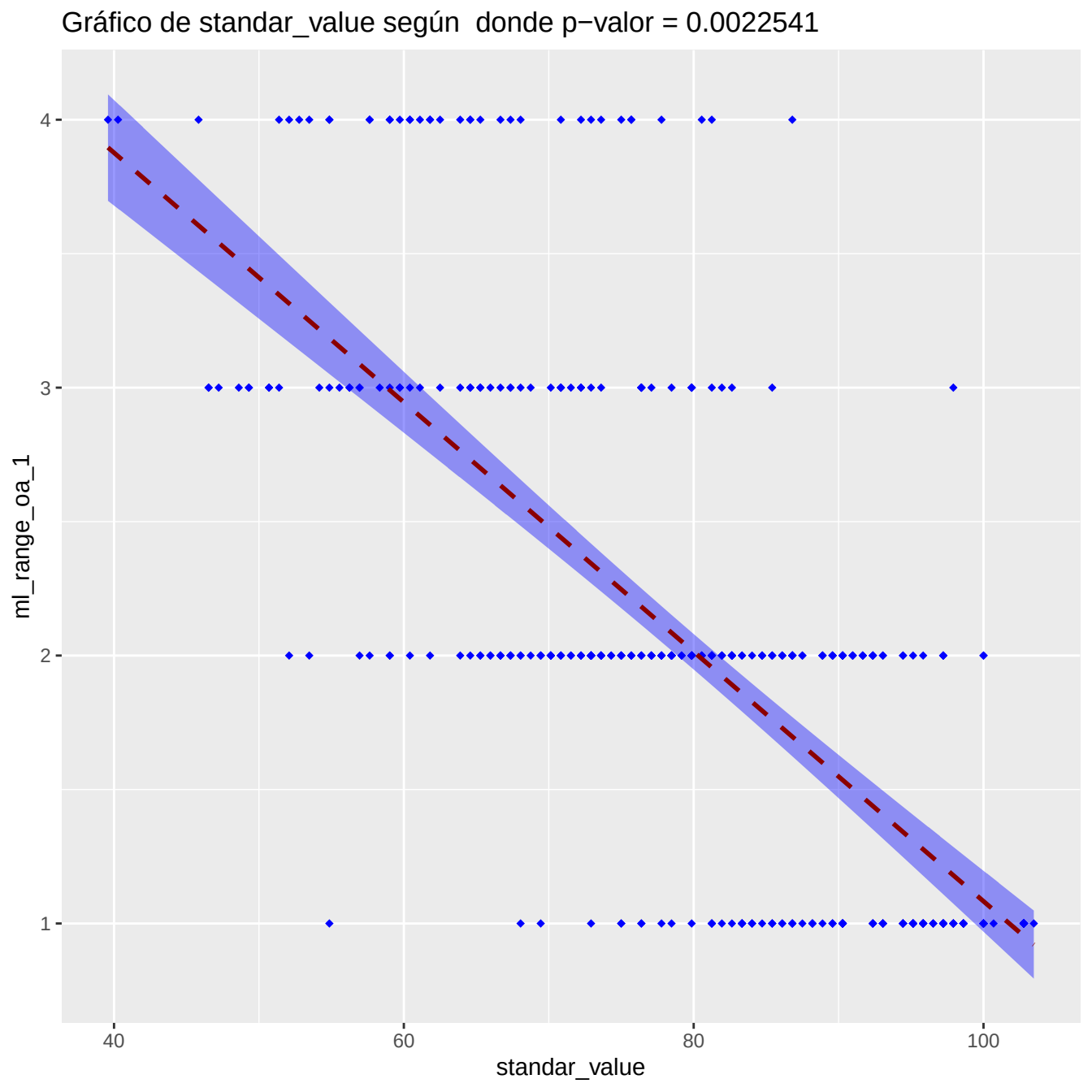
Gráfico de standar_value según donde p−valor = 0.0022541
ml_range_oa_1
4
3
2
1
40
60
80
100
standar_value

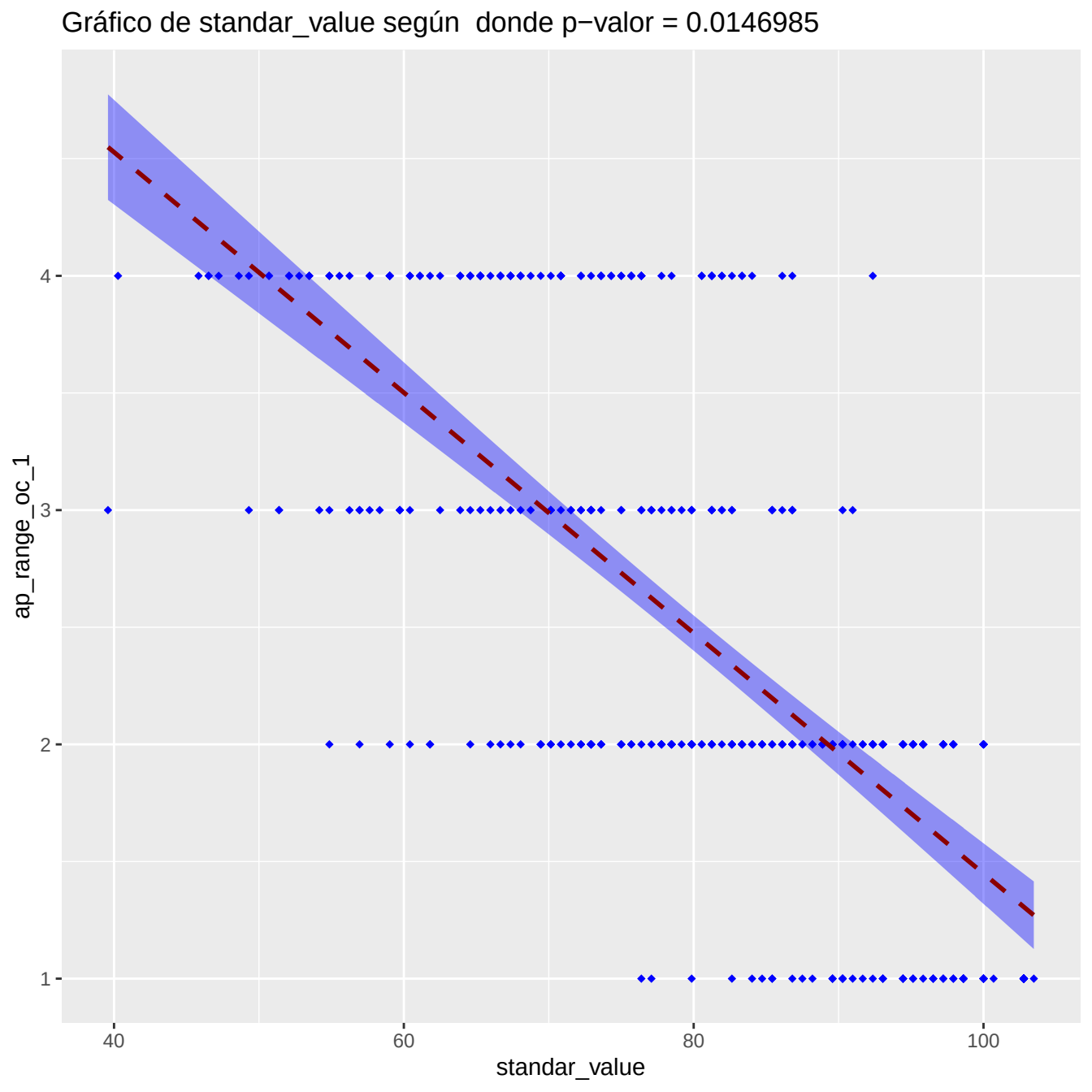
Gráfico de standar_value según donde p−valor = 0.0146985
ap_range_oc_1
4
3
2
1
40
60
80
100
standar_value

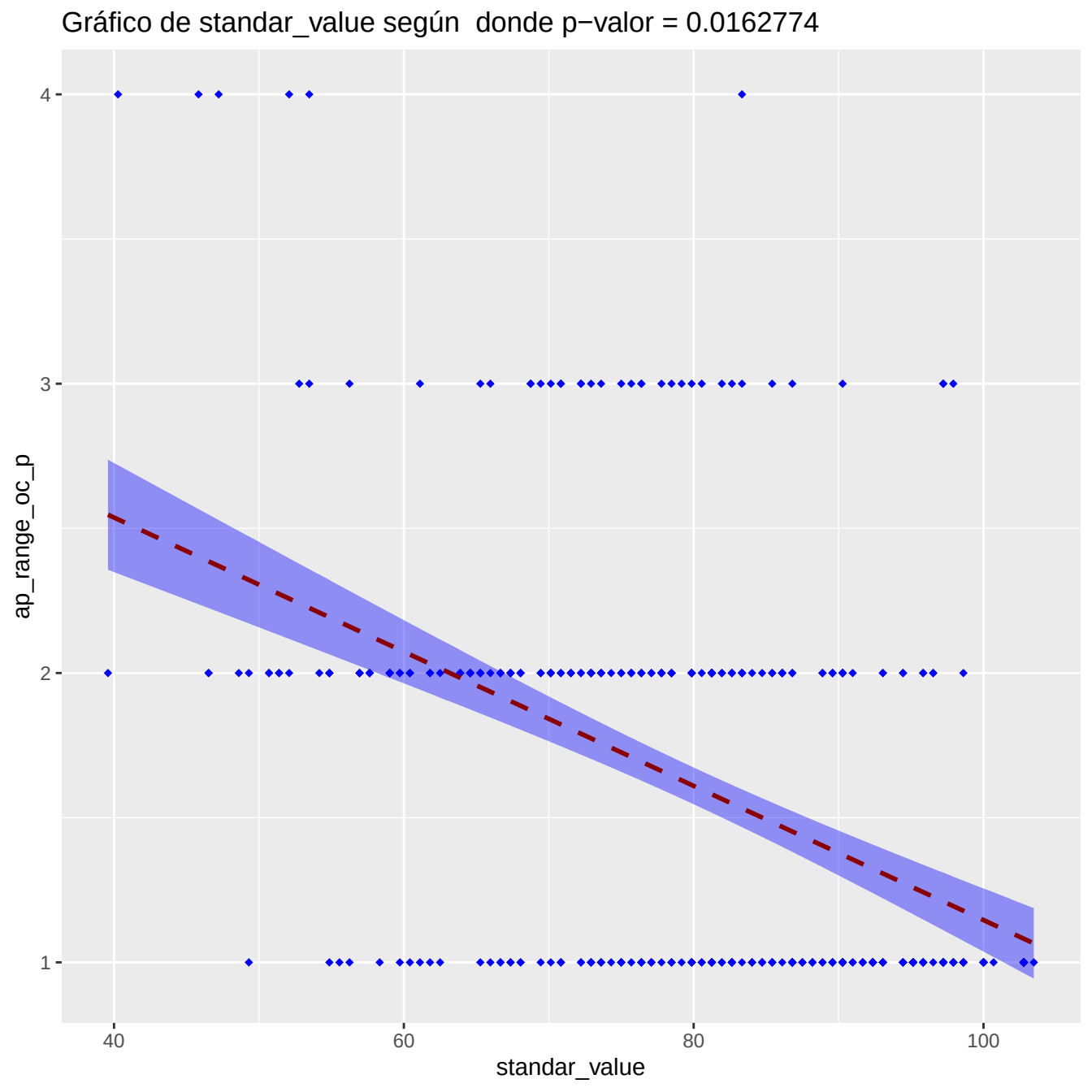
Gráfico de standar_value según donde p−valor = 0.0162774
ap_range_oc_p
4
3
2
1
40
60
80
100
standar_value

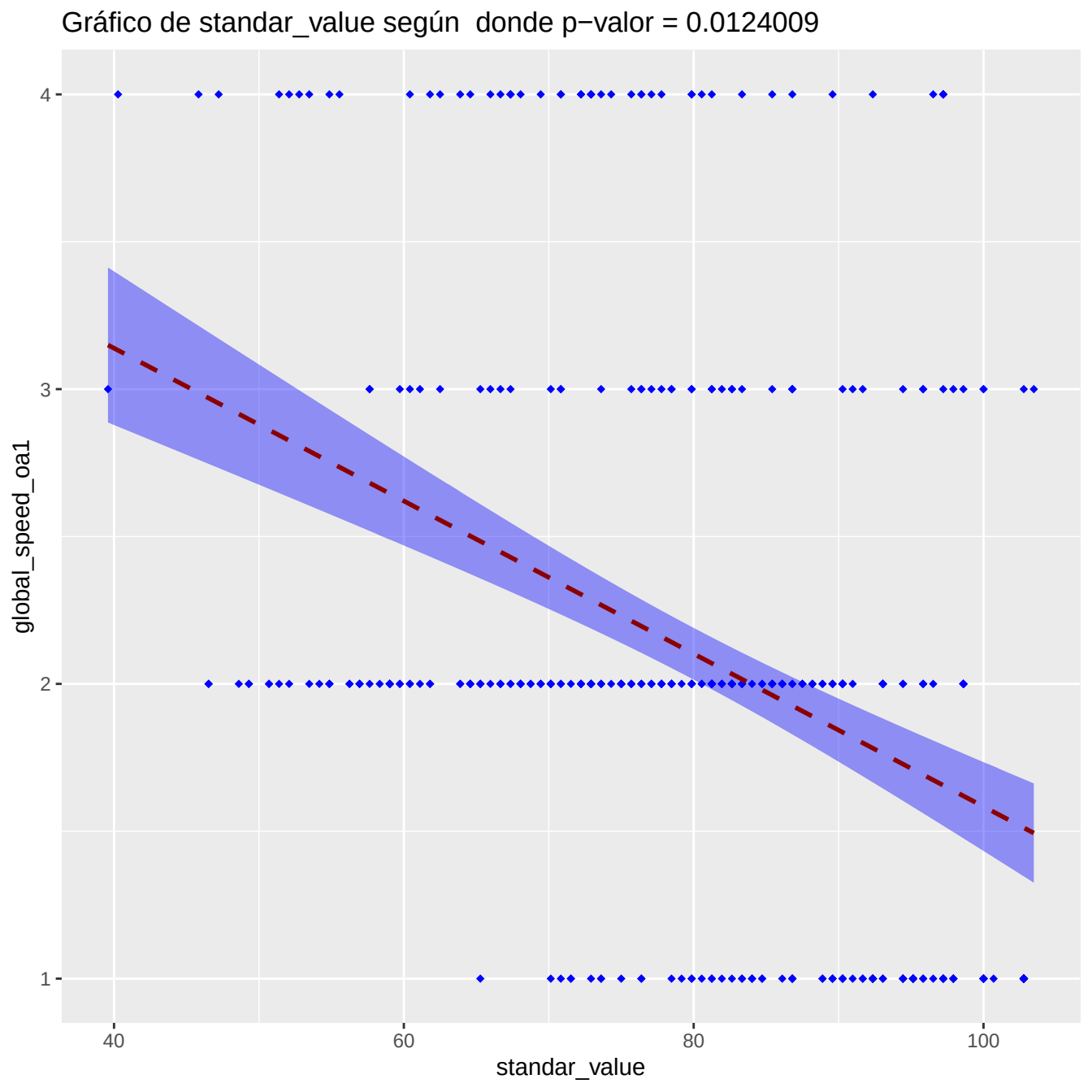
Gráfico de standar_value según donde p−valor = 0.0124009
global_speed_oa1
4
3
2
1
40
60
80
100
standar_value

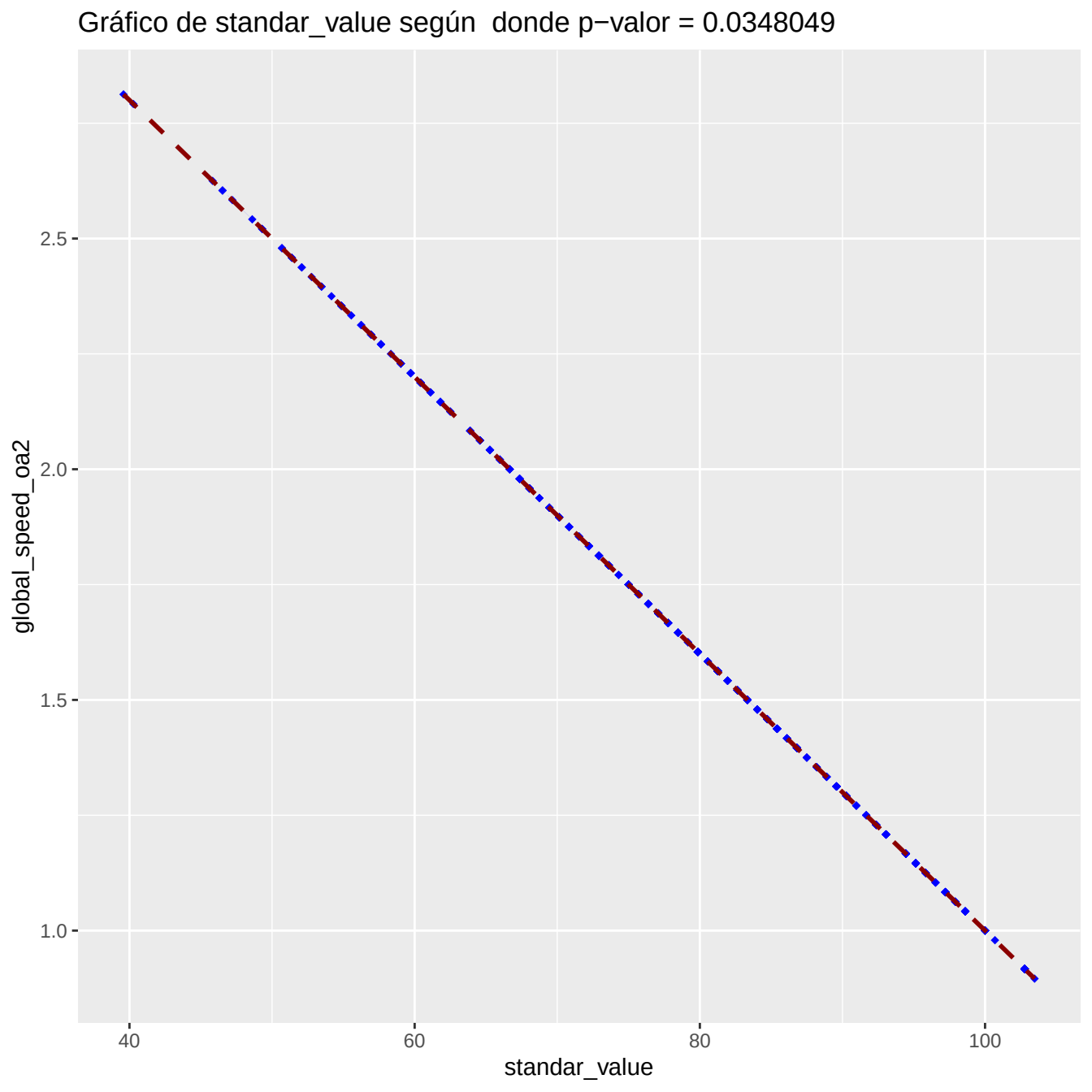
Gráfico de standar_value según donde p−valor = 0.0348049
global_speed_oa2
2.5
2.0
1.5
1.0
40
60
80
100
standar_value

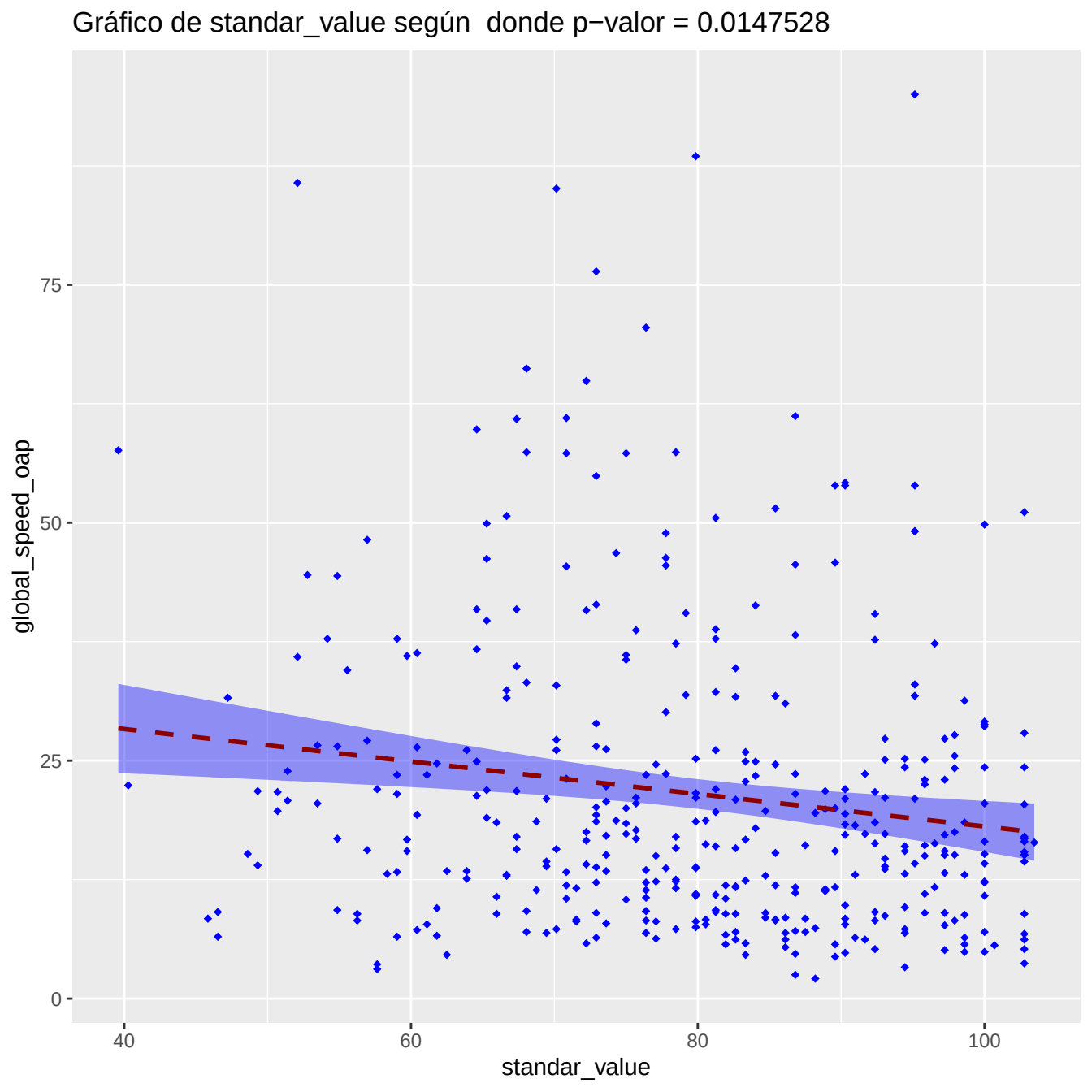
Gráfico de standar_value según donde p−valor = 0.0147528
global_speed_oap
75
50
25
0
40
60
80
100
standar_value

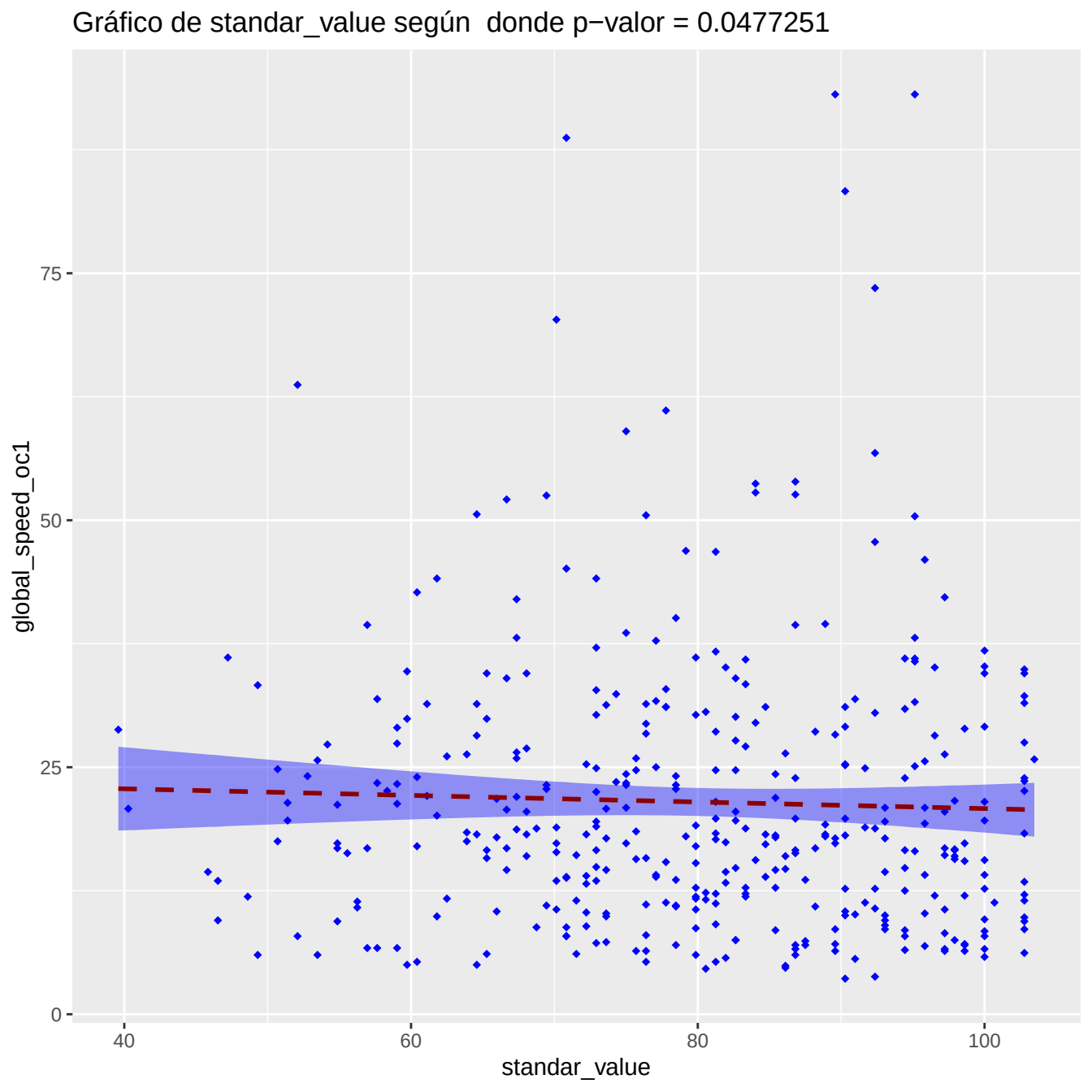
Gráfico de standar_value según donde p−valor = 0.0477251
global_speed_oc1
0
25
50
75
40
60
80
100
standar_value

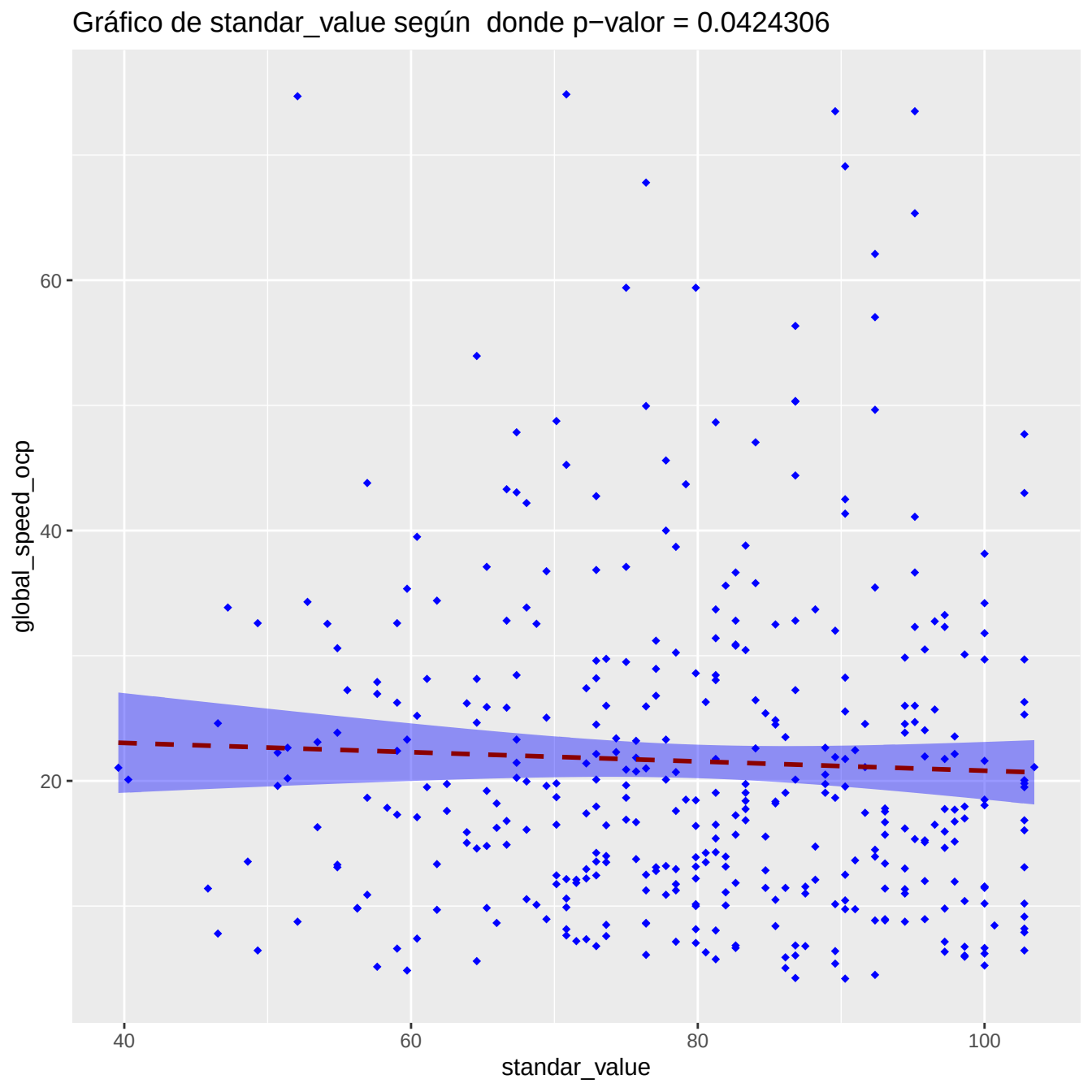
Gráfico de standar_value según donde p−valor = 0.0424306
global_speed_ocp
60
40
20
40
60
80
100
standar_value

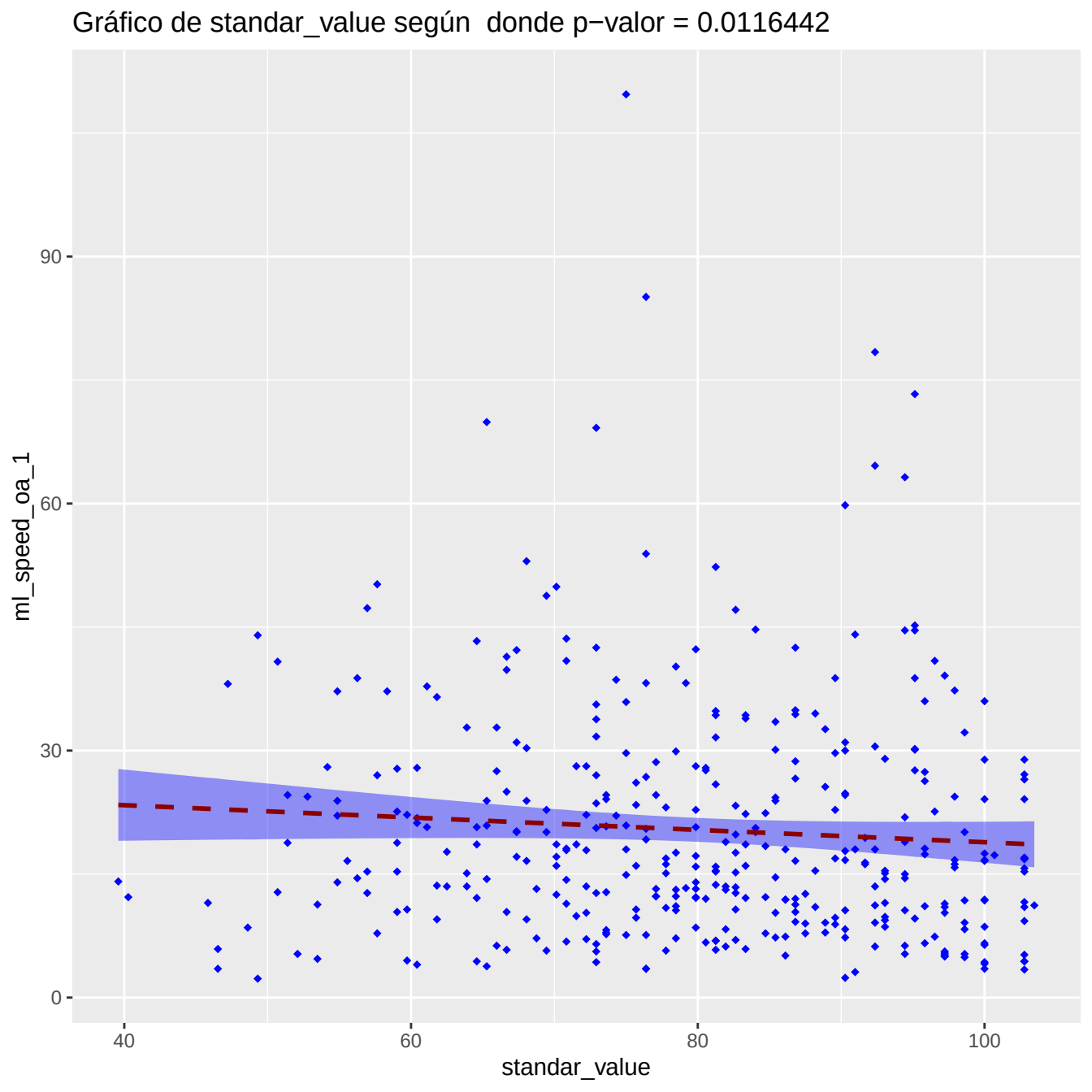
Gráfico de standar_value según donde p−valor = 0.0116442
ml_speed_oa_1
90
60
30
0
40
60
80
100
standar_value

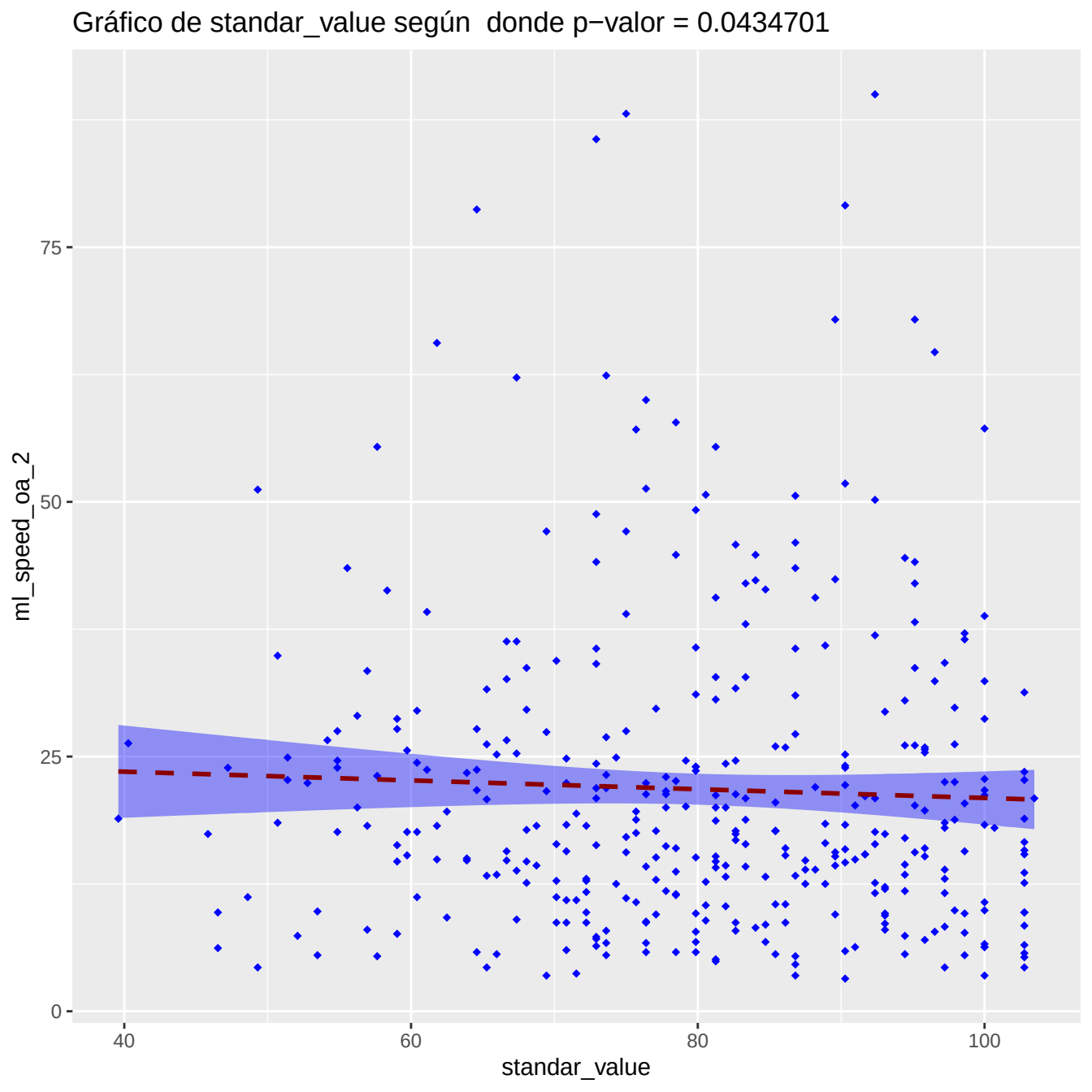
Gráfico de standar_value según donde p−valor = 0.0434701
ml_speed_oa_2
75
50
25
0
40
60
80
100
standar_value

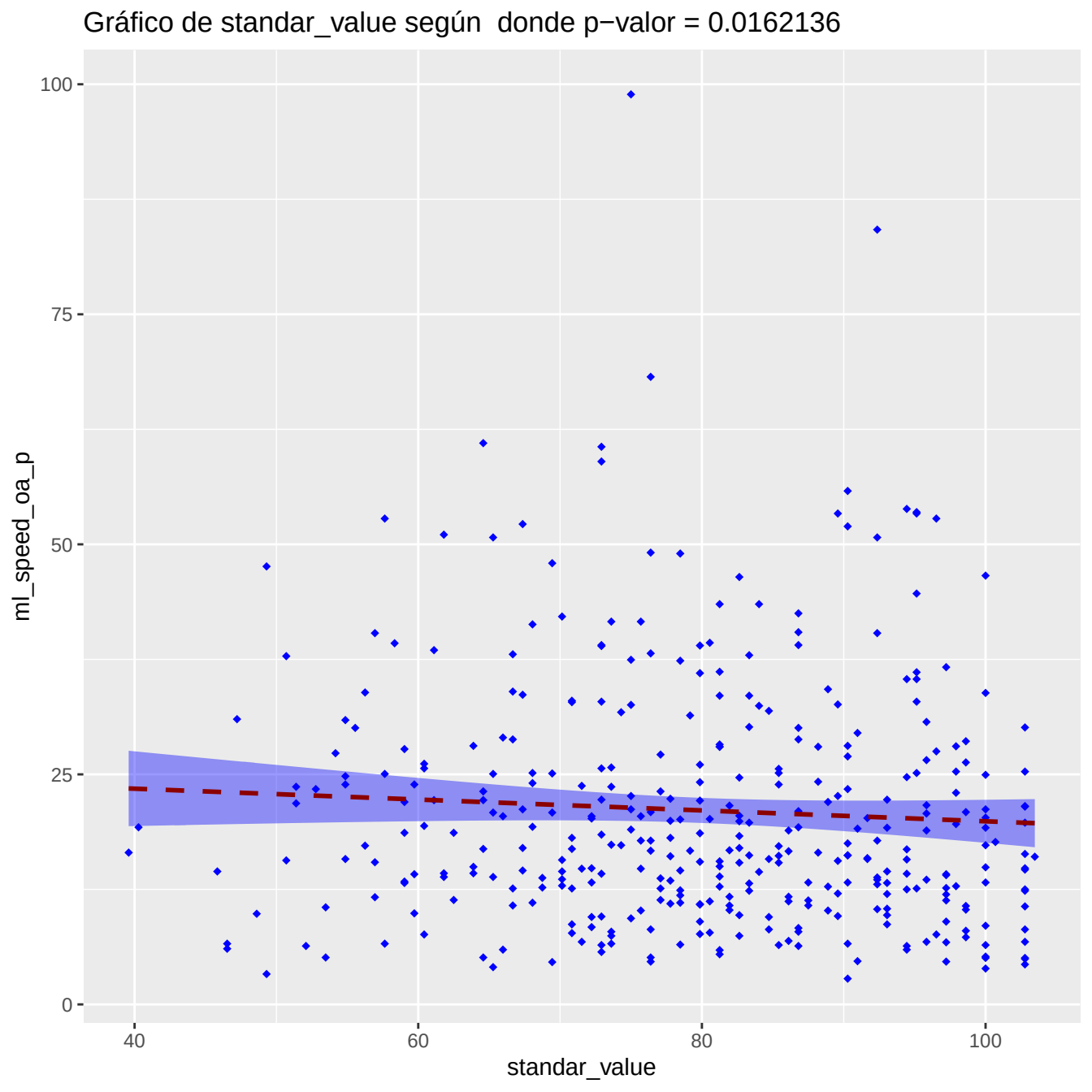
Gráfico de standar_value según donde p−valor = 0.0162136
ml_speed_oa_p
100
75
50
25
0
40
60
80
100
standar_value

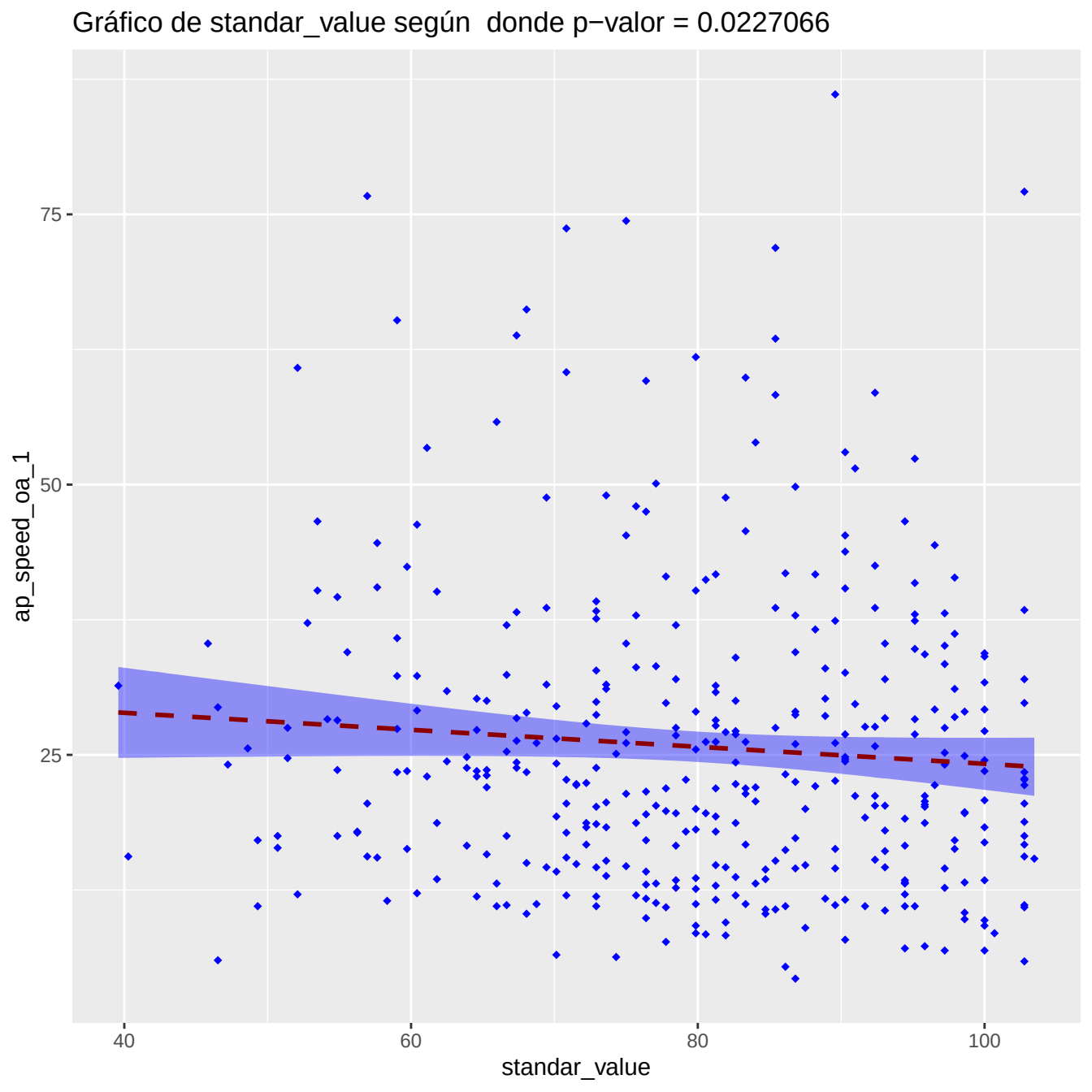
Gráfico de standar_value según donde p−valor = 0.0227066
ap_speed_oa_1
75
50
25
40
60
80
100
standar_value

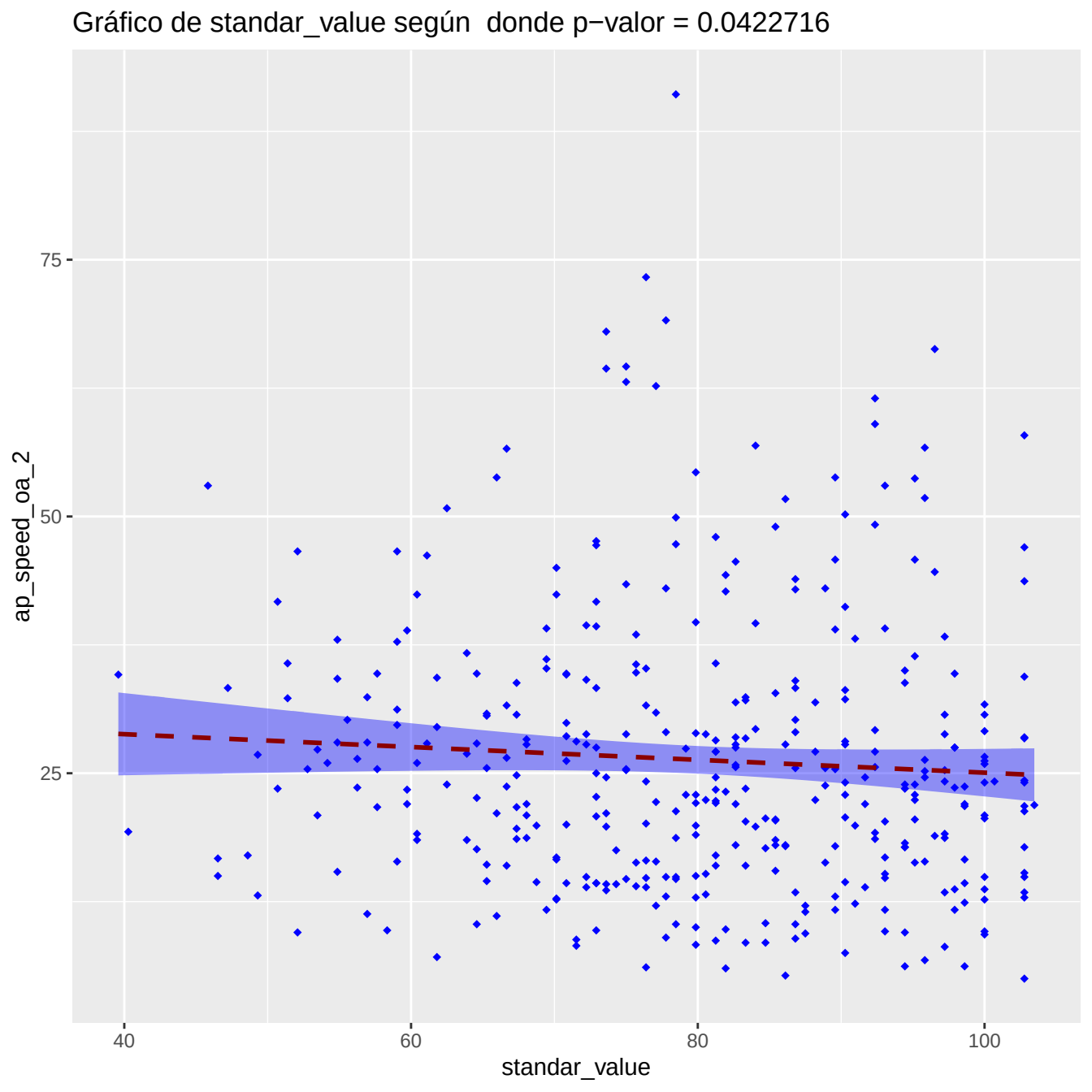
Gráfico de standar_value según donde p−valor = 0.0422716
ap_speed_oa_2
75
50
25
40
60
80
100
standar_value

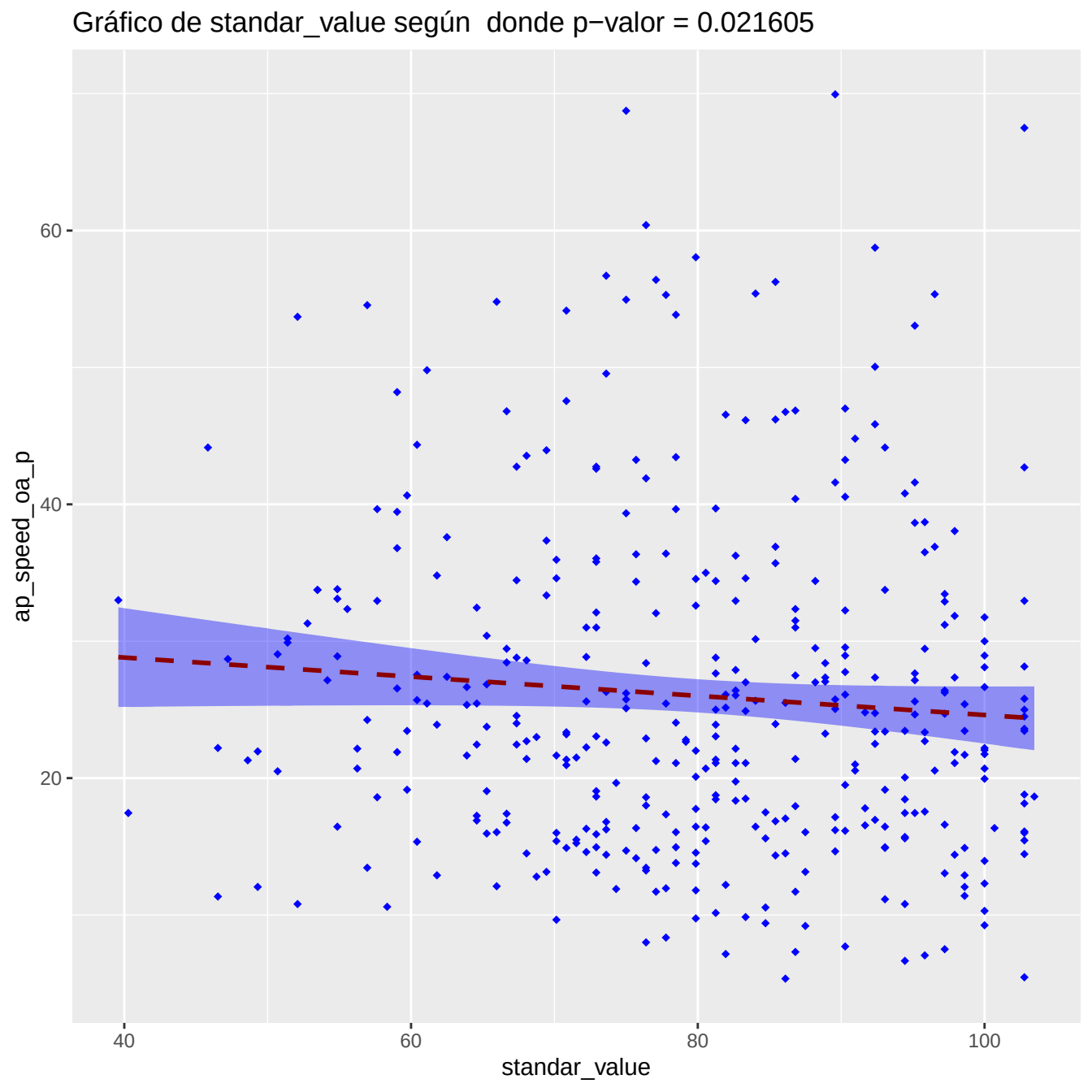
Gráfico de standar_value según donde p−valor = 0.021605
ap_speed_oa_p
60
40
20
40
60
80
100
standar_value

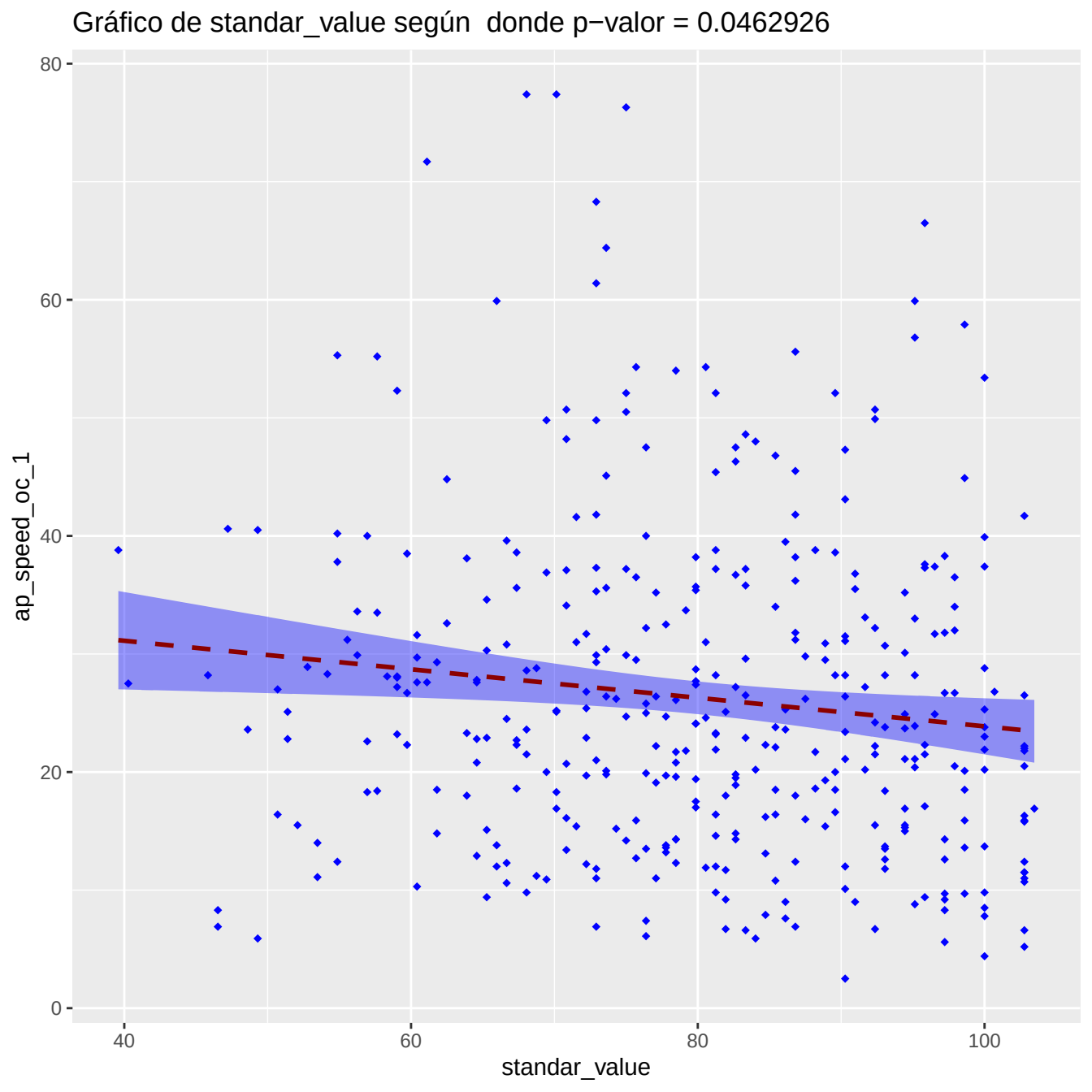
Gráfico de standar_value según donde p−valor = 0.0462926
ap_speed_oc_1
standar_value
0
20
40
60
80
40
60
80
100

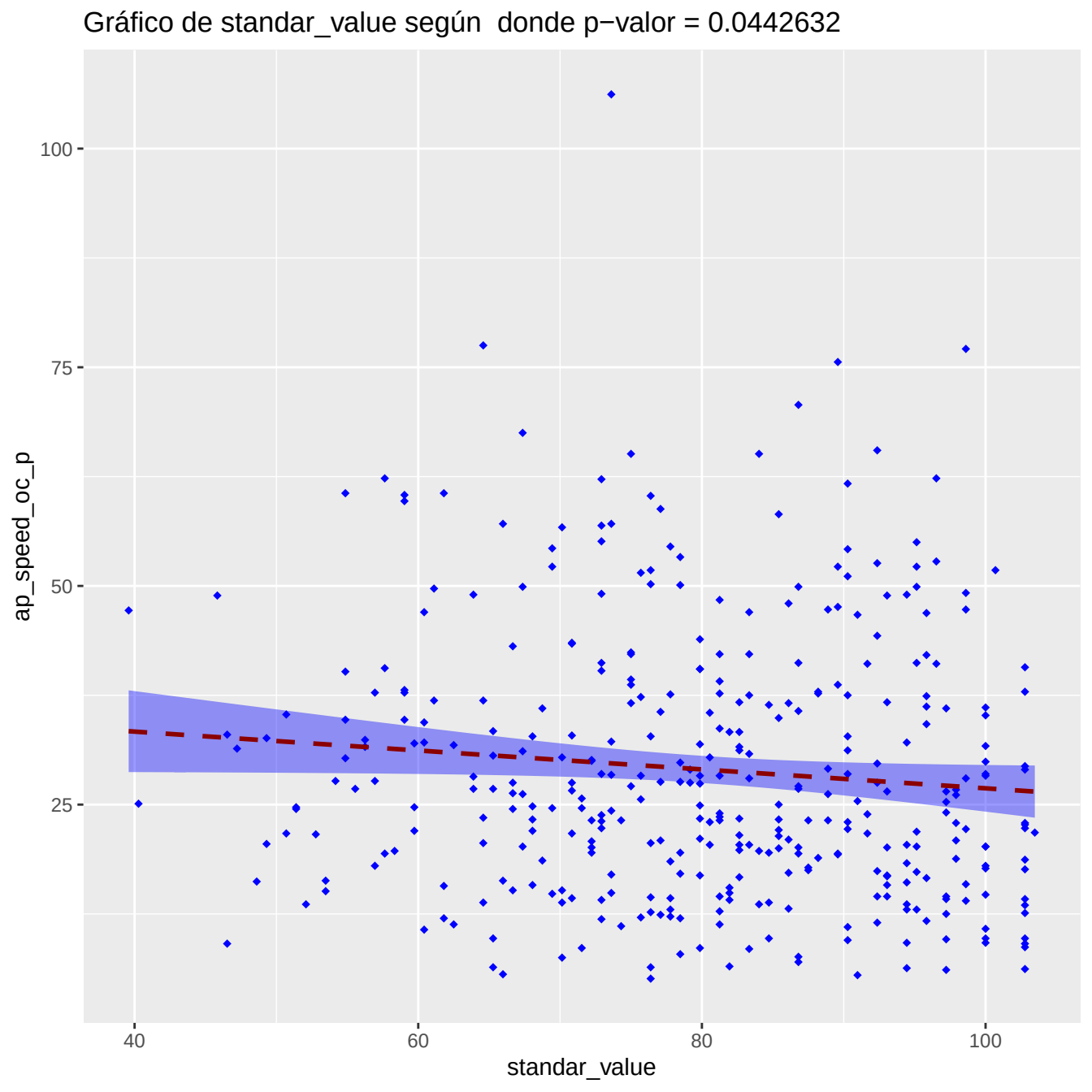
Gráfico de standar_value según donde p−valor = 0.0442632
ap_speed_oc_p
100
75
50
25
40
60
80
100
standar_value

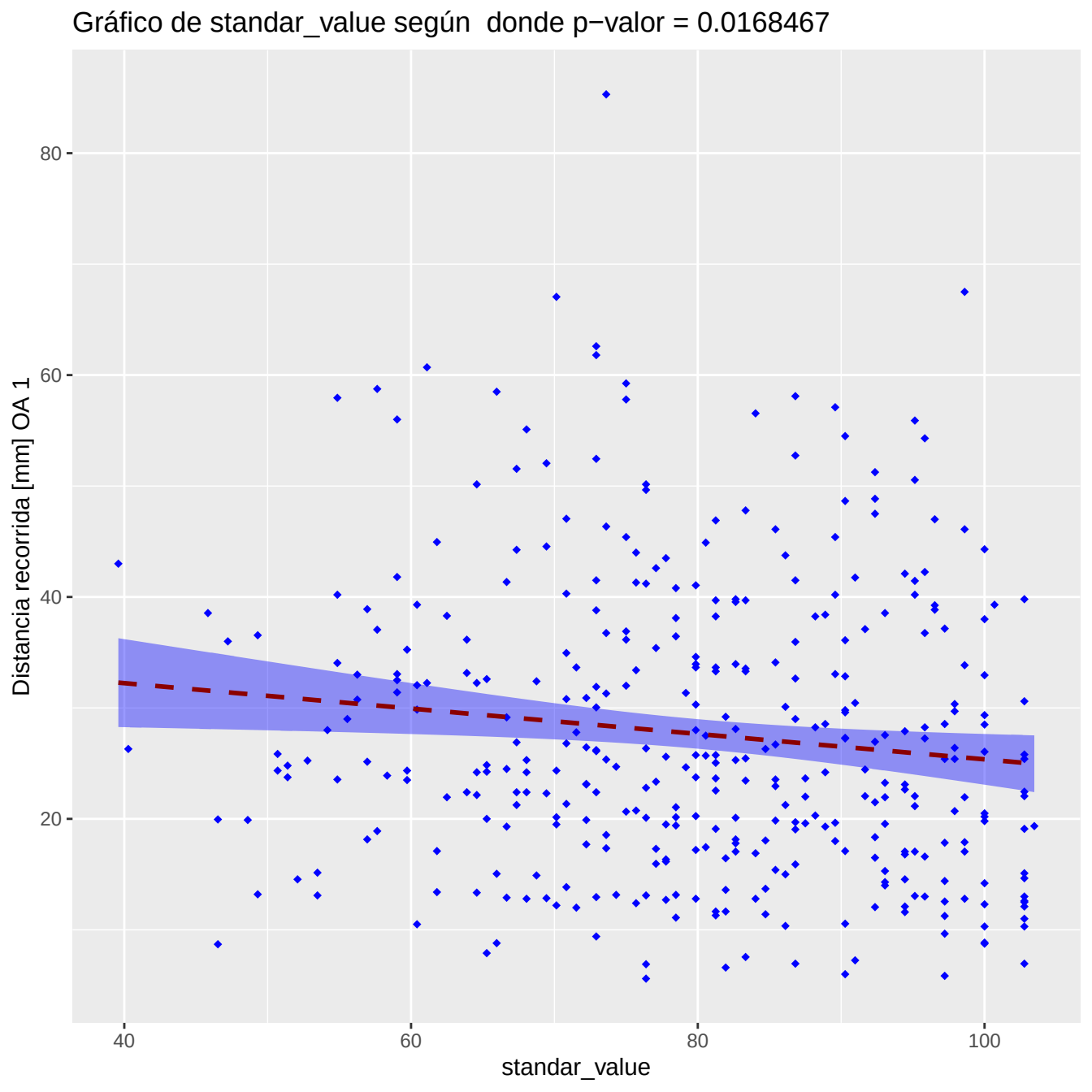
Gráfico de standar_value según donde p−valor = 0.0168467
Distancia recorrida [mm] OA 1
80
60
40
20
40
60
80
100
standar_value

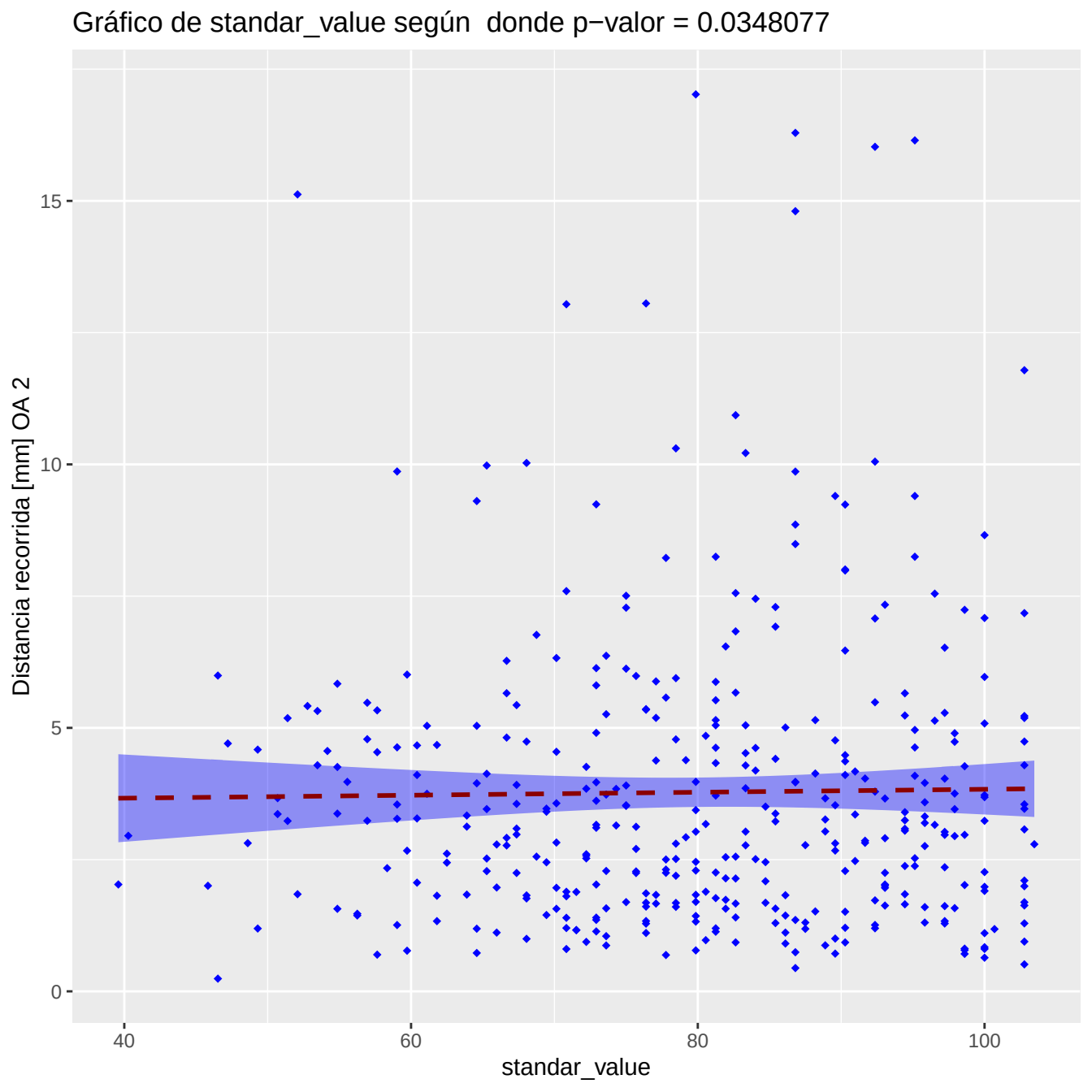
Gráfico de standar_value según donde p−valor = 0.0348077
Distancia recorrida [mm] OA 2
standar_value
0
5
10
15
40
60
80
100

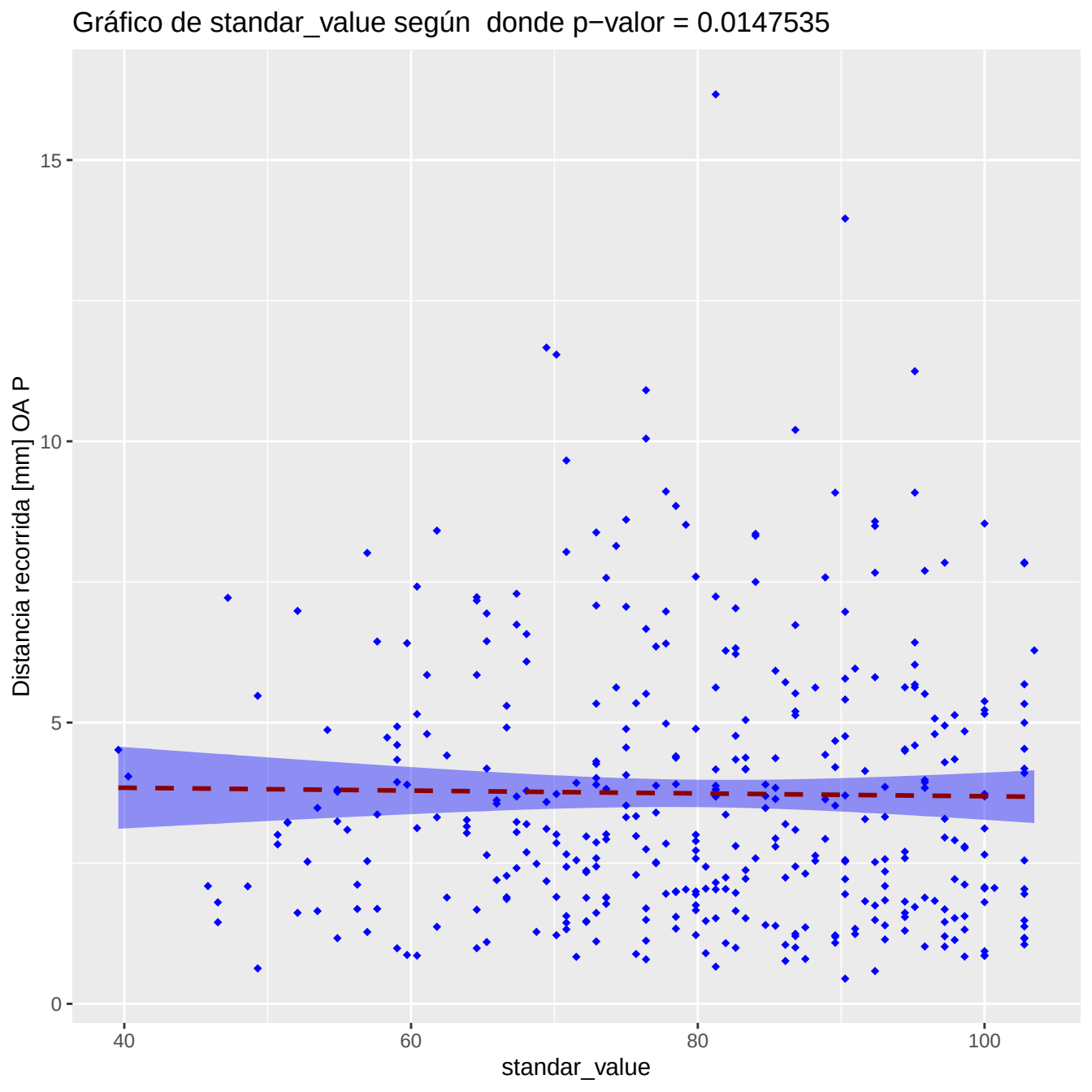
Gráfico de standar_value según donde p−valor = 0.0147535
Distancia recorrida [mm] OA P
15
10
5
0
40
60
80
100
standar_value

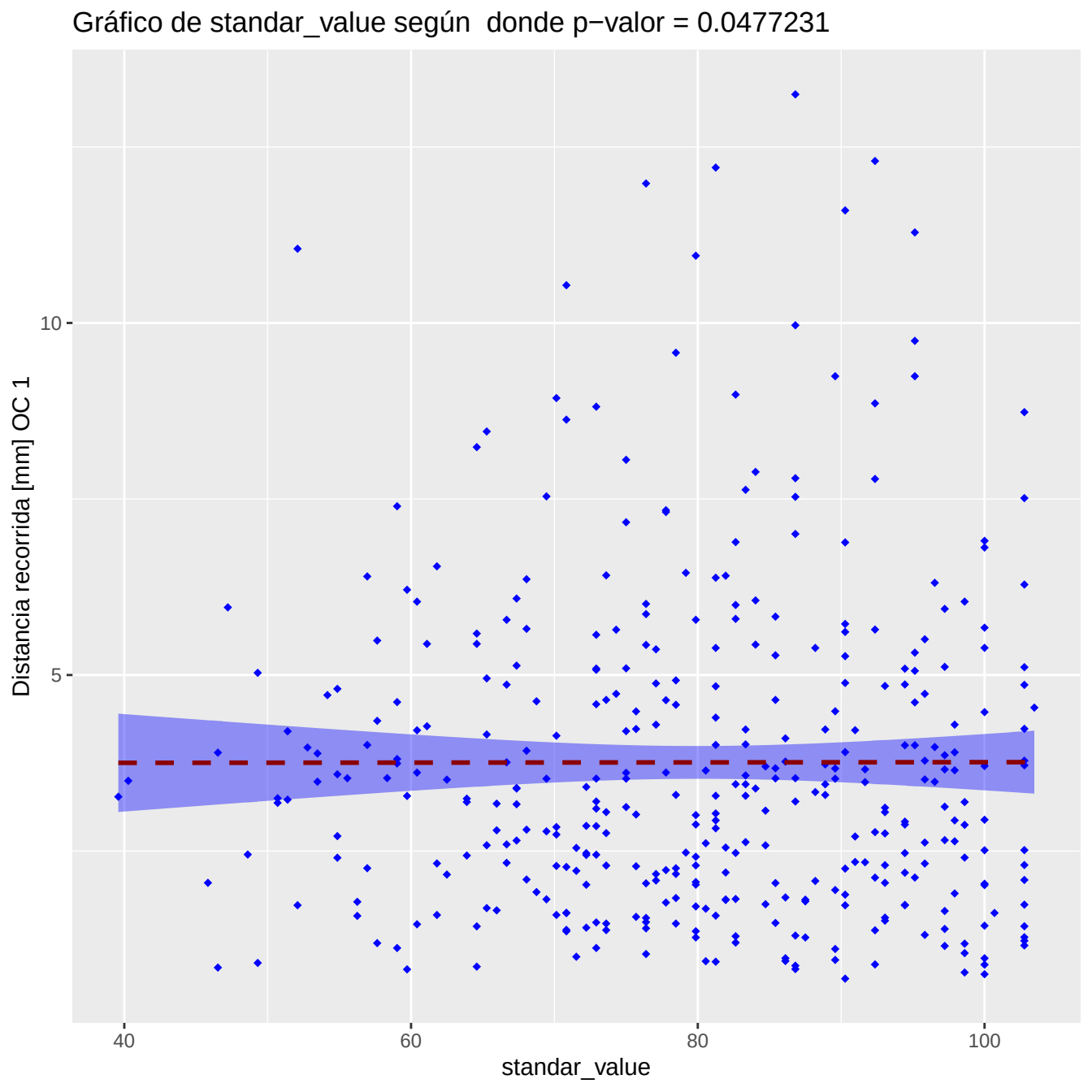
Gráfico de standar_value según donde p−valor = 0.0477231
Distancia recorrida [mm] OC 1
10
5
40
60
80
100
standar_value

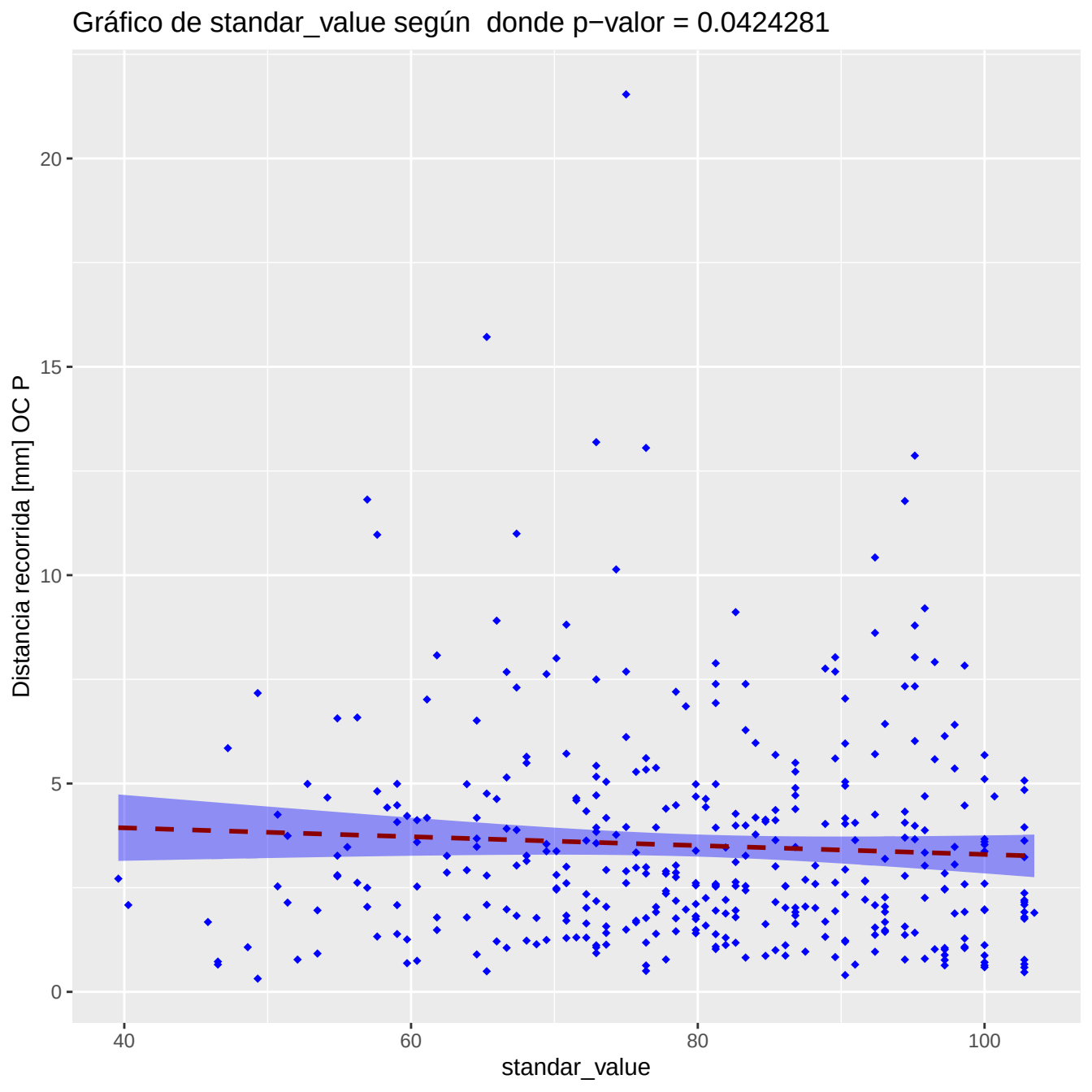
Gráfico de standar_value según donde p−valor = 0.0424281
Distancia recorrida [mm] OC P
0
5
10
15
20
40
60
80
100
standar_value