

# Heterogenous-Agent Life-Cycle Models: Transitions

Dean Corbae  
(with thanks to Pavel Brendler and Kuan Liu)  
(Do not distribute without consent)

November 9, 2020

# Introduction

- We have so far learned how to compute stationary equilibria of life cycle models.
- However, comparing only outcomes of stationary equilibria would not provide us the full picture of the effects of a policy change (e.g. elimination of pay-as-you-go social security)
- Another important aspect of policy analysis is how the economy transits to a new stationary equilibrium consistent with the policy change, i.e. the transition path
- Here we learn how to compute the transition path from an equilibrium with social security to one without.

# The Concept of Transition

- Imagine that we are in the initial steady state at  $t = 0$  with social security tax rate  $\theta_0 > 0$ .
- The government makes an unexpected and credible announcement to eliminate the social security system from  $t = 1$  onward. This is what is sometimes called an “MIT shock”.
- This means that from  $t = 1$  onward, workers do not need to pay social security taxes (i.e.  $\theta_t = 0$  for  $t \geq 1$ ) and retirees lose their social security benefits (i.e.  $b_t = 0$  for  $t \geq 1$ ).
- Unlike the stationary equilibrium, the decision rules, the value functions, the cross-sectional distribution, and prices become calendar time  $t$  dependent until reaching the new steady state.
- This means in solving for the transition path, we need to add one more discrete finite state variable  $t$ .

# Preliminaries

- For illustration, assume an inelastic labor supply so  $L = 1$  (while Conesa/Krueger (1999) correctly parameterize a leisure choice with distortionary taxes, this simple example generates an upper bound welfare calculation when substitution effects outweigh income effects).
- Let the initial  $t = 0$  cross sectional distribution of agents and the initial value function be denoted by  $\Gamma_0(z, a, n; K_0^{ss})$  and  $V_0(z, a, n; K_0^{ss})$  which comes from the steady state with  $\theta_0 > 0$ .
- Assuming the economy reaches the new steady state at time  $T$ , denote the steady state cross sectional distn and value function by  $\Gamma_T(z, a, n; K_T^{ss})$  and  $V_T(z, a, n; K_T^{ss})$  with  $\theta_T = 0$ .
- Our job here is to find the equilibrium path of aggregate variables (e.g.  $K_t \rightarrow (r(K_t), w(K_t))$ ) when endogenous variables transition between  $t = 0$  and  $t = T$  with  $\theta_t = \theta_T = 0$  for  $t \geq 1$ .
- Note that we don't know how long it takes to get to  $T$  (in principle, it takes an infinite amount of time).

# Basic Steps to Solve for the Transition Path

- Taking  $T$  as given, we need a path of aggregate capital  $\{K_t^i\}_{t=0}^T$  where  $i$  denotes iteration number and  $K_0^i = K_0^{ss}$  and  $K_T^i = K_T^{ss}$
- With  $L = 1$  for example, this induces a path for prices:  $\{r_t^i, w_t^i\}_{t=0}^T$
- Since we know  $V_T(z, a, n; K_T^{ss})$ , we solve the household problem backwards from  $t = T - 1$  to  $t = 0$ . This induces a set of savings decision rules  $g_t^i(z, a, n; K_t^i)$  for  $t = 0, \dots, T - 1$  based on prices induced by  $\{K_t^i\}_{t=0}^T$ .
- Using  $g_t^i(z, a, n; K_t^i)$  and  $\Gamma_t^i(z, a, n; K_t^i)$ , calculate forward a new path for capital  $\{\hat{K}_t^{i+1}\}_{t=1}^T$  starting from  $t = 0$  (noting that since  $K_1^i \neq K_0^{ss} \rightarrow g_0^i(z, a, n; K_0^{ss}) \neq g_0^{ss}(z, a, n; K_0^{ss})$ ). Iterate on  $\{\hat{K}_t^{i+1}\}_{t=1}^T$  until convergence.
- Shooting forward, there is nothing that ensures  $\hat{K}_T^{i+1}$  is arbitrarily close to  $K_T^{ss}$ . Increase  $T$  until convergence.

## HH Problem at $t=T-1$ at iteration $i$

$$V_{T-1}^i(z, a, n; K_{T-1}^i) = \max_{\{c \geq 0, a' \geq a\}} u(c) + \beta s_{n+1} \mathbb{E}_{T-1} [V_T(z', a', n+1; K_T^{ss})]$$

s.t.

$$c + a' = a(1 + r(K_{T-1}^i)) + (1 - \theta_{T-1})e(z, n)w(K_{T-1}^i) + T + b_{n, T-1}(K_{T-1}^i)$$

$$a = 0 \text{ if } n = 1$$

$$a' \geq 0 \text{ if } n = N.$$

- Assuming a steady state at time  $T$ ,  $K_T^i = K_T^{ss}$  with  $\theta_T = 0$  and no matter what iteration  $i$  we are on,  $V_T(z', a', n+1; K_T^{ss})$  is the same.
- However, if  $K_{T-1}^i \neq K_T^{ss}$  (i.e. we are not already at the steady state), the solution to this problem induces

$$k_T^i = g_{T-1}^i(z, a, n; K_{T-1}^i) \neq g_T(z, a, n; K_T^{ss}). \quad (1)$$

## HH Problem between $t=T-2$ and $t=1$ at iteration $i$

$$V_t^i(z, a, n; K_t^i) = \max_{\{c \geq 0, a' \geq a\}} u(c) + \beta s_{n+1} \mathbb{E}_t [V_{t+1}^i(z', a', n+1; K_{t+1}^i)]$$

s.t.

$$c + a' = a(1 + r(K_t^i)) + (1 - \theta_t)e(z, n)w(K_t^i) + T + b_{n,t}(K_t^i)$$

$$a = 0 \text{ if } n = 1$$

$$a' \geq 0 \text{ if } n = N.$$

- The solution to this problem induces  $\{g_t^i(z, a, n; K_t^i)\}_{t=1}^{t=T-2}$ .

## HH Problem at $t=0$ at iteration $i$

$$V_0^i(z, a, n; K_0^{ss}, K_T^{ss}) = \max_{\{c \geq 0, a' \geq a\}} u(c) + \beta s_{n+1} \mathbb{E}_0 [V_1^i(z', a', n+1; K_1^i)]$$

s.t.

$$c + a' = a(1 + r(K_0^{ss})) + (1 - \theta_0)e(z, n)w(K_0^{ss}) + T + b_{n,t}(K_0^{ss})$$

$$a = 0 \text{ if } n = 1$$

$$a' \geq 0 \text{ if } n = N.$$

- Note that even though  $\theta_0 > 0$  and  $K_0^{ss}$  at  $t = 0$ , since  $\theta_1 = 0$  and  $K_1^i \neq K^{ss}$ ,  $V_0^i(z, a, j; K_0^{ss}, K_T^{ss})$  can be different from the steady state  $V_0(z, a, j; K_0^{ss})$  inducing  $g_0^i(z, a, n; K_0^{ss}) \neq g_0(z, a, n; K_0^{ss})$ .



# Algorithm

- 1 Choose the number of periods to reach the final steady state,  $T$ .  
For example, start with  $T = 20$
- 2 Given  $T$ , make an initial guess for the sequence  $\{K_t^{i=1}\}_{t=0}^T$  with  $K_0^1 = K_0^{SS}$  and  $K_T^1 = K_T^{SS}$ .
  - A good guess could simply be a linear function from  $K_0^{SS}$  to  $K_T^{SS}$  given by  $K_t^1 = K_0^{SS} + \Delta$ , where  $\Delta = [K_T^{SS} - K_0^{SS}]/T$
- 3 Given  $\{K_t^i\}_{t=0}^T$ , solve HH's dynamic programming problem backwards starting with  $t = T - 1$  obtaining decision rules  $g_t^i(z, a, n; K_t^i)$  for  $t = 0, \dots, T - 1$ .

## Algorithm - cont'd

- 4 Update the path of capital as follows: start with  $\Gamma_0(z, a, n; K_0^{ss})$  and use the decision rules  $g_t^i(z, a, n; K_t^i)$  to obtain  $\Gamma_t^{i+1}$  and  $\hat{K}_t^{i+1}$  for  $t = 0 \dots T$ . That is:

$$\Gamma_{t+1}^{i+1}(z', a', n; K_{t+1}^i) = H(\Gamma_t^{i+1}(z, a, n; K_t^i))$$

and

$$\hat{K}_{t+1}^{i+1} = \sum_{n=1}^N \sum_z \int_a g_t^i(z, a, n; K_t^i) \Gamma_t^i(z, a, n; K_t^i) da. \quad (2)$$

- 5 If  $\left\| \hat{K}_t^{i+1} - K_t^i \right\|_{\infty} < \epsilon_K$  for  $t = 0, \dots, T$  where  $\epsilon_K$  is your tolerance level, go to step 6. If not, update  $K_t^{i+1}$  as follows:

$$K_t^{i+1} = \rho K_t^i + (1 - \rho) \hat{K}_t^{i+1} \quad \forall t \text{ with some } \rho \in (0, 1)$$

and go to step 3 using the updated  $\{K_t^{i+1}\}_{t=0}^{T-1}$ .

## Algorithm Cont'd

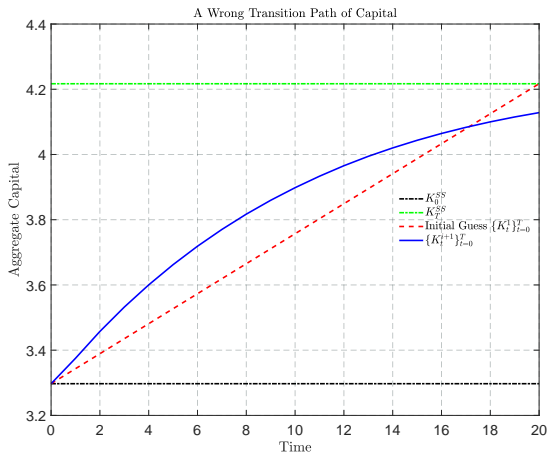
- ⑥ By (1) and (2), there is nothing to ensure that after step 5,  $\hat{K}_T^{i+1} = K_T^{SS}$ . If there is a  $t^* \leq T$  in the sequence such that:

$$\left\| \hat{K}_t^{i+1} - K_T^{SS} \right\| < \epsilon_T \quad \forall t \geq t^*$$

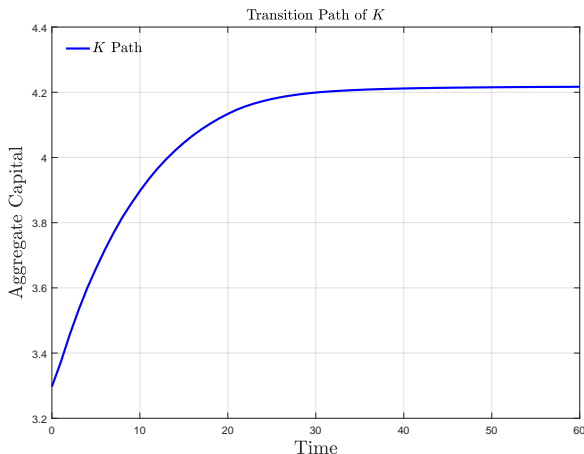
where  $\epsilon_T$  is your tolerance level, you have approximated the equilibrium path. If not, increase  $T$  and go back to step 2.

# A Wrong Transition Path of Capital

- Suppose we set  $T = 20$
- The resulting transition path shown below satisfies the criterion of step 5 in the algorithm; however it fails the criterion of step 6.



# The Equilibrium Transition Path of Capital



- If you get rid of social security, people need to save privately for retirement (i.e.  $K$  rises).

# Computing Welfare Gains/Losses with Transitions

We quantify the welfare change of the policy reform for an agent in state  $(z, a, n)$  relative to the initial steady state by asking:

- What fraction of per-period consumption would an agent in the steady state (with  $b > 0$ ) be willing to pay (if positive) or have to be paid (if negative) in all future periods to achieve the utility level associated with a transition to the final steady state (with  $b = 0$ )?
- Conesa/Krueger use the following utility function (we set  $\gamma = 1$  instead of  $\gamma = 0.42$  and  $\sigma = 2$ ):

$$u(c, l) = \frac{(c^\gamma(1-l)^{1-\gamma})^{1-\sigma}}{1-\sigma}$$

- We compute for each  $(z, a, n)$  the consumption equivalent  $\lambda(z, a, n)$  such that:

$$V_0(z, a, n; K_0^{SS}, K_T^{SS}) = \mathbb{E} \left[ \sum_{t=n}^N \beta^t \frac{[(1 + \lambda(z, a, n))c_t(z, a, n)]^{1-\sigma}}{1-\sigma} \middle| (z, a, n) \right]$$

where the lhs is the  $b = 0$  value and the rhs is the  $b > 0$  ss value.

## Computing CE with Transitions - cont.

- We can re-arrange the previous equation defining  $\lambda(z, a, n)$  as

$$\begin{aligned} V_0(z, a, n; K_0^{SS}, K_T^{SS}) &= \\ (1 + \lambda(z, a, n))^{(1-\sigma)} \mathbb{E} \left[ \sum_{t=n}^N \beta^t \frac{c_t(z, a, n)^{1-\sigma}}{1-\sigma} | (z, a, n) \right] \\ &= (1 + \lambda(z, a, n))^{(1-\sigma)} V_0(z, a, n; K_0^{SS}) \end{aligned}$$

- Hence we have

$$\begin{aligned} (1 + \lambda(z, a, n))^{(1-\sigma)} &= \frac{V_0(z, a, n; K_0^{SS}, K_T^{SS})}{V_0(z, a, n; K_0^{SS})} \Rightarrow \\ \lambda_{tran}(z, a, n) &= \left[ \frac{V_0(z, a, n; K_0^{SS}, K_T^{SS})}{V_0(z, a, n; K_0^{SS})} \right]^{\frac{1}{(1-\sigma)}} - 1 \end{aligned}$$

# Interpreting CE

- For example,  $\lambda_{tran}(z, a, n) = 0.1$  implies that eliminating social security increases the welfare of an individual in state  $(z, a, n)$  by an amount equivalent to receiving 10% higher consumption per period in the initial steady state for all future periods.
- Therefore  $\lambda_{tran}(z, a, n) \geq 0$  means that the agent is made better off by the reform and will thus vote for it; otherwise, the agent is made worse off by the reform and will vote against it.
- The total mass of population in the initial steady state who vote for the reform is given by

$$\sum_{n=1}^N \sum_z \int_a \Gamma_0^{SS}(z, a, n; K_0^{SS}) \times 1_{(\lambda_{tran}(z, a, n) \geq 0)} da$$



## CE across Steady States

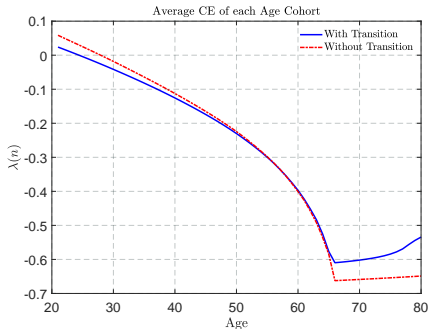
- We can also compute CE simply across the initial and the new steady states (i.e. without accounting for the transition path).
- This can be thought of CE in the counter-factual case where the economy jumps to the new steady state immediately after social security is abolished, unrealistically skipping the transition.
- Using the results for the initial and the new steady states and following the definition of CE given above, it is computed by:

$$\lambda_{SS}(z, a, n) = \left[ \frac{V_T(z, a, n; K_T^{SS})}{V_0(z, a, n; K_0^{SS})} \right]^{\frac{1}{(1-\sigma)}} - 1$$

# The Welfare Effect of the Transition Path I

- Let's first compare the average welfare gain/loss within each age cohorts **with** and **without** transition path.
- We use  $CE_{type}$  for  $type \in \{tran, SS\}$  as our measure of welfare gain/loss and its age cohort average given by

$$CE_{type}(n) = \sum_z \int_a \lambda_{type}(z, a, n) \frac{\Gamma_0^{SS}(z, a, n; K_0^{SS})}{\mu_n} da, \forall n$$



# What accounts for the welfare differences across age and SS versus Transition?

- The above figure establishes that there is:
  - Across age: the reform only makes agents under 25 years old better off ( $CE_{type}(n) > 0$ ).
  - Across type:
    - less (more) of a welfare gain (loss) accounting for the transition for younger agents.
    - less of a welfare loss accounting for the transition for the old.
- Why?
  - There are higher wages in the final steady state than in the transition boosting new steady state income for the young. ▶ Wage Path
  - There are lower interest rates in final new steady state than in the transition boosting transition interest income for the old. ▶ Interest Rate Path ▶ Decision Rules

# Aggregate Voting Differences

- Now we compare the total mass of population who vote for the reform **with** and **without** considering the transition path as given by:

$$\sum_{n=1}^N \sum_z \int_a \Gamma_0^{SS}(z, a, n; K_0^{SS}) \times 1_{(\lambda_{type}(z, a, n) \geq 0)} da$$

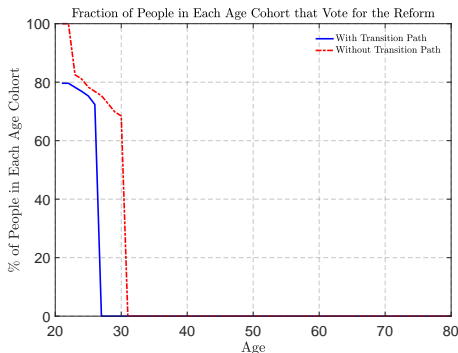
- Results:

Fraction of Population that Vote for the Reform	
<b>With</b> Transition	10.56%
<b>Without</b> Transition	16.29%

- This implies that we will *over-estimate* the welfare gain of the reform if we do not consider transition path.

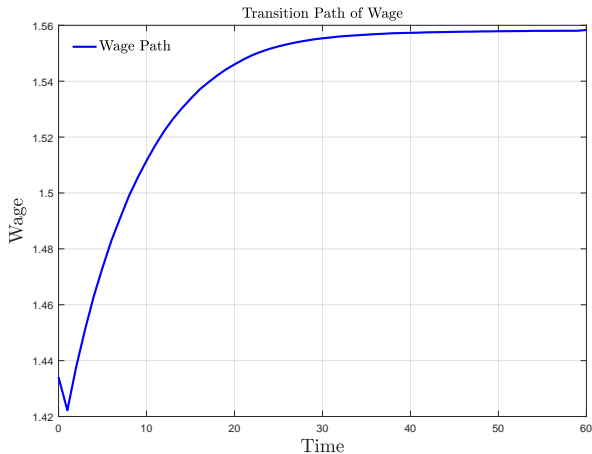
# Voting by Age Differences

- Finally, we compare the fraction of people in each age cohort that would vote for the reform **with** and **without** considering the transition path given by:  $\sum_z \int_a \frac{\Gamma_0^{SS}(z,a,n;K_0^{SS})}{\mu_n} \times \mathbf{1}_{(\lambda_{type}(z,a,n) \geq 0)} da, \forall n$



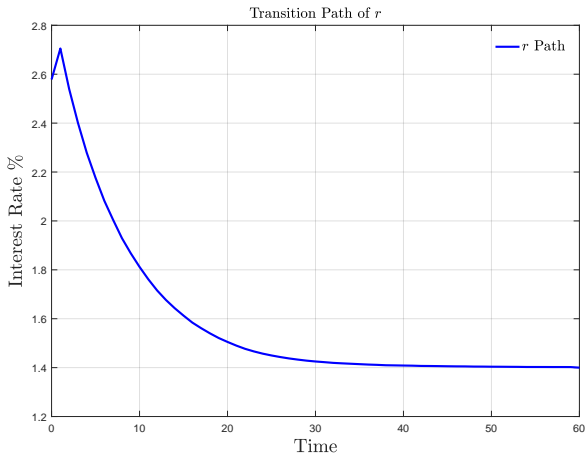
- As implied by the above figure, this measure suggests that by not considering the transition path, we (weakly) over-estimate welfare gains of the reform for every age group.

# The Equilibrium Transition Path of Wages



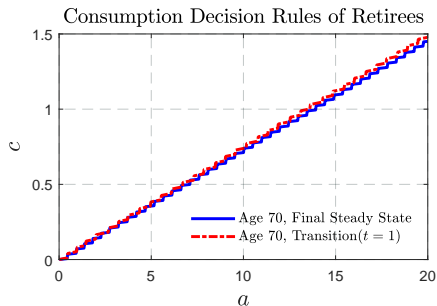
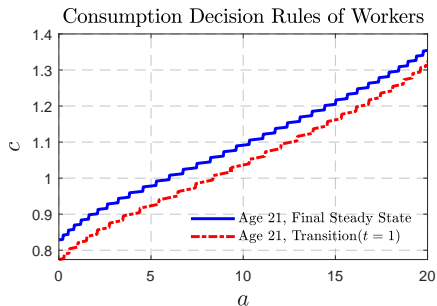
- Since  $w = (1 - \alpha)\left(\frac{K}{L}\right)^\alpha$  and  $K \uparrow$ , wages rise.

# The Equilibrium Transition Path of Interest Rates



- Since  $r = \alpha\left(\frac{L}{K}\right)^{1-\alpha}$  and  $K \uparrow$ , interest rates fall.

# Decision Rules Consumption for Young and Old



- 21 year olds consume less (save more) at start of transition than in steady state, the opposite of retirees.