

Gaussian::updateParam



```
graph LR; A[Gaussian::updateParam] --> B[Gaussian::quaternion2rotation]
```

A diagram showing a call from the function `Gaussian::updateParam` to the function `Gaussian::quaternion2rotation`. The first box is shaded gray and the second is white, both with black borders. A blue arrow points from the right side of the first box to the left side of the second box.

Gaussian::quaternion2rotation