

3-29. \therefore 当 $r < R_1$. $\oint \vec{H}_1 d\vec{l} = \frac{2\pi r^2}{2\pi R_1^2} I$

$$H_1 \cdot 2\pi r = \frac{r^2}{R_1^2} I$$

$$H_1 = \frac{r I}{2\pi R_1^2}$$

$$B_1 = \mu_1 H_1 = \frac{\mu_1 r I}{2\pi R_1^2} \quad \text{方向顺时针}$$

当 $R_1 < r < R_2$ $\oint \vec{H}_2 d\vec{l} = I$

$$H_2 = \frac{I}{2\pi r}$$

$$B_2 = \frac{\mu_2 I}{2\pi r} \quad \text{方向同 } B_1$$

$r > R_2$. $H_3 = B_3 = \frac{I}{2\pi r}$

方向同 B_1

3-30. $\oint \vec{H} d\vec{l} = n I l$

$$H l = n I l$$

$$H = n I$$

$$B = \mu_0 \mu_r H = \mu_0 \mu_r n I \quad \text{方向遵循右手螺旋}$$

$$M = (\mu_r - 1) H = (\mu_r - 1) n I$$

$$\vec{j} = \vec{M} \times \vec{e}_n = (\mu_r - 1) n I \quad \text{方向沿介质面切向}$$

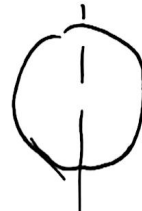
4-1. $\psi = 2\phi = 2 \int_a^{a+b} \frac{\mu I}{2\pi x} dx = \frac{\mu I l}{2\pi} \ln \frac{a+b}{a}$

$$\therefore \mathcal{E} = - \frac{d\psi}{dt} = - \frac{\mu I_0 l \omega}{2\pi} \cos \omega t \ln \frac{a+b}{a}$$

4-2. $\therefore \psi = NBS = NB \cdot \pi R^2 \cos \theta$

$$= NB \pi R^2 \cos \omega t$$

$$\therefore \mathcal{E} = NB \pi R^2 \omega \sin \omega t \quad \mathcal{E}_{\max} = NB \pi R^2 \omega$$



设起始面线圈平面与 B 垂直. 则 \mathcal{E}_{\max} 出现在 $t = \frac{(2n-1)\pi}{2\omega}$ ($n=1, 2, 3, \dots$) 时
 $\sin \omega t = 1$

$$4-4. \because B = \frac{\Phi}{S} = \frac{N \cdot I}{L} = \frac{N \sin \omega t}{L}$$

$$B = \mu n I = \frac{25 N \sin \omega t}{L}$$

$$\therefore \Phi = BS = \frac{25 N \sin \omega t \pi r^2}{L}$$

$$\mathcal{E} = - \frac{25 N \omega \pi r^2}{L} \cos \omega t$$

$$I = \frac{\mathcal{E}}{R} = - \frac{25 N \omega \pi r^2}{LR} \cos \omega t$$

$$\therefore I_{\max} = \frac{25 N \omega \pi r^2}{LR} \approx \frac{2.57 \times 10^{-2}}{29.77} A.$$



4-5. 将CD相连. 则 $\oint_L \vec{E} \cdot d\vec{l} = 0$. $\nabla \cdot \vec{E} = 0$

故 $E_{CB} + E_{CD} = 0$.

$$\therefore E_{CD} = \int_{a-R}^{a+R} \frac{\mu_0 I}{2\pi x} \cdot v dx = -\frac{\mu_0 I v}{2\pi} \ln \frac{a+R}{a-R} \quad \text{故方向由D} \rightarrow \text{C.}$$

$$\therefore E_{CD} = \frac{\mu_0 I v}{2\pi} \ln \frac{a+R}{a-R} \quad \text{方向由D} \rightarrow \text{C.} \quad \text{C端电势高.}$$

4-7. $\therefore \mathcal{E} = \int_0^l B v \cos(\theta \frac{r}{2} - \theta) dl = \int_0^l B l \omega \sin^2 \theta dl = \frac{1}{2} B l^2 \omega \sin^2 \theta$

$$\therefore U_{OA} = -\mathcal{E} = -\frac{1}{2} B l^2 \omega \sin^2 \theta. \quad \text{A端电势更高}$$

4-8. (1) 由右手螺旋. 方向. 为 ~~$A \rightarrow C \rightarrow D \rightarrow A$~~ $A \rightarrow O \rightarrow D \rightarrow C \rightarrow A$

(2) AOD不切割磁感线 $\mathcal{E}_{AOD} = 0$.

$$\mathcal{E}_{DCA} = -\frac{d\Phi}{dt} = -B \frac{dS}{dt} = -B \frac{d(\frac{ra^2}{2} \sin \omega t)}{dt} = -B \cdot \frac{ra^2 \omega}{2} \cos \omega t$$

$$t=0 \text{ 时, } \mathcal{E}_{DCA} = -B \cdot \frac{ra^2 \omega}{2} \quad \text{大小 } B \cdot \frac{ra^2 \omega}{2}$$



$$4-9. (1) \because \mathcal{E} = \int_C (\vec{v} \times \vec{B}) \cdot d\vec{l} = \int_0^x v B_0 \frac{x \tan 30^\circ}{\tan 30^\circ} \cdot 2 = \frac{2\sqrt{3}}{3} v^2 B_0 t \quad \text{方向 } C \rightarrow D$$

$$(2) \because \mathcal{E}_{\text{动}} = \frac{2\sqrt{3}}{3} v^2 B_0 t^2$$

$$\mathcal{E}_{\text{感}} = - \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} = - \oint_S \frac{\partial B_0}{\partial t} \cdot d\vec{S} = - \frac{\partial B_0}{\partial t} \int_0^x B_0 \frac{2x' \tan 30^\circ}{\tan 30^\circ} dx' = + \frac{\sqrt{3}}{3} B_0 x^2 = + \frac{\sqrt{3}}{3} B_0 v^2 t^2$$

$$\therefore \mathcal{E} = \frac{\sqrt{3}}{3} B_0 x^2 + \frac{2\sqrt{3}}{3} v^2 B_0 t^2 = \frac{\sqrt{3}}{3} v^2 B_0 t^2 \quad \text{方向由 } C \rightarrow D$$

$$4-10. \because \mathcal{E}_{\text{动}} = \int_0^b (\vec{v} \times \vec{B}) \cdot d\vec{l} = \int_0^b v \cdot \frac{\mu_0 I}{2\pi(a+x)} dx = - \frac{v \mu_0 I_0 e^{-\lambda t}}{2\pi} \ln \frac{a+b}{a}$$

以下列上为正

$$\mathcal{E}_{\text{感}} = - \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} = - \oint_S \frac{\partial B_0}{\partial t} \cdot d\vec{S} = - \frac{\partial B_0}{\partial t} \int_0^b B_0 dx = - \frac{\lambda \mu_0 I_0 e^{-\lambda t}}{2\pi} \ln \frac{a+b}{a}$$

$$\mathcal{E}_{\text{感}} = - \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} = - \int_0^b \frac{\lambda \mu_0 I_0 e^{-\lambda t}}{2\pi} \cdot v dt \cdot dx = + \frac{\lambda \mu_0 I_0 e^{-\lambda t} v t}{2\pi} \ln \frac{a+b}{a}$$

$$\mathcal{E} = \frac{v \mu_0 I_0 e^{-\lambda t}}{2\pi} \ln \frac{a+b}{a} (\lambda t - 1)$$

当 $\lambda t > 1$ 方向自下向上 $\lambda t < 1$ 方向自上向下

