

数学作业纸

科目 大物

华鑫纸品
Hua Xin Zhi Pin

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$$3-29. \because \text{当 } r < R_1, \oint_{R_1} \vec{H}_1 d\vec{l} = \frac{\pi r^2}{2\pi R_1^2} I$$

$$H_1 \cdot 2\pi r = \frac{\pi r^2}{2R_1^2} I$$

$$H_1 = \frac{rI}{2\pi R_1^2}$$

$$B_1 = \mu_1 H = \frac{\mu_1 r I}{2\pi R_1^2} \quad \text{方向顺时针}$$

$$\text{当 } R_1 < r < R_2 \quad \oint \vec{H}_2 d\vec{l} = I$$

$$H_2 = \frac{I}{2\pi r}$$

$$B_2 = \frac{\mu_2 I}{2\pi r} \quad \text{方向同 } B_1$$

$$r > R_2, H_3 = B_3 = \frac{I}{2\pi r} \quad \text{方向同 } B_1$$

$$3-30. \oint \vec{H} d\vec{l} = nIl$$

$$\vec{H}l = nIl$$

$$H = nI$$

$$B = \mu_0 \mu_r H = \frac{\mu_0 \mu_r n I}{2\pi r} \quad \text{方向遵循右手螺旋}$$

$$M = (\mu_r - 1) H = (\mu_r - 1) n I$$

$$\vec{j} = \vec{M} \times \vec{e}_n = (\mu_r - 1) n I \quad \text{方向沿介质切向}$$

$$4-1. \psi = 2\varPhi = 2 \int_a^{a+b} \frac{NI}{2\pi x} dx = \frac{NI}{2\pi} \ln \frac{a+b}{a}$$

$$\therefore E = - \frac{d\psi}{dt} = - \frac{\mu I_0 \omega}{\pi} \cos \omega t / n \frac{a+b}{a}$$

$$4-2. \because \psi = NBS = NB \cdot \pi R^2 \cos \theta$$

$$= NB \pi R^2 \cos \omega t$$

$$\therefore E = - NB \pi R^2 \omega \sin \omega t \quad E_{\max} = NB \pi R^2 \omega$$



设起始面线圈平面与 B 垂直，则 E_{\max} 出现在 $t = \frac{(2n-1)\pi}{2\omega}$ ($n=1, 2, 3, \dots$) 时

$$2P \sin \omega t = 1$$

▲



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$$4-4. \because B = \frac{N \cdot \cancel{A} \cdot \cancel{L}}{\cancel{r^2 \cdot \pi}} = \frac{N}{\cancel{L}} \cancel{A} \sin \cancel{\theta}$$

$$B = N \sin \omega t \frac{L}{r}$$

$$\therefore \Phi = BS = \frac{25N \sin \omega t \pi r^2}{L}$$

$$\Sigma = - \frac{25N \omega \pi r^2}{L} \cos \omega t$$

$$I = \frac{\Sigma}{R} = - \frac{25N \omega \pi r^2}{L R} \cos \omega t$$

$$\therefore I_{max} = \frac{25N \omega \pi r^2}{L R} \approx \frac{2.37 \times 10^7}{29.77} A.$$



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4-5. 将CD相连, 则 $\oint_L \vec{E}_i d\vec{l} = 0$. 即 $E = 0$

故 $E_{CB} + E_{CD} = 0$.

$$\therefore E_{CD} = - \int_{a-R}^{a+R} \frac{\mu_0 I}{2\pi x} \cdot V dx = - \frac{\mu_0 I V}{2\pi} \ln \frac{a+R}{a-R} \quad \text{故方向由 } D \rightarrow C.$$

$$\therefore E_{CB} = \frac{\mu_0 I V}{2\pi} \ln \frac{a+R}{a-R} \quad \text{方向由 } D \rightarrow C. \quad C \text{端电势高.}$$

4-7. $\because \mathcal{E} = \int_0^L B V \cos(\theta \frac{\pi}{2} - \theta) dl = \int_0^L B L \omega \sin^2 \theta dl = \frac{1}{2} B L^2 \omega \sin^2 \theta$

$$\therefore U_{OA} = -\mathcal{E} = -\frac{1}{2} B L^2 \omega \sin^2 \theta. \quad A \text{端电势更高}$$

4-8. (1) 由右手螺旋, 方向为 $A \rightarrow C \rightarrow D \rightarrow A \rightarrow O \rightarrow D \rightarrow C \rightarrow A$

(2) AOD不切割磁感线 $\mathcal{E}_{AOD} = 0$.

$$\mathcal{E}_{DCA} = - \frac{d\Phi}{dt} = -B \frac{ds}{dt} = -B \frac{d\left(\frac{\pi a^2}{2} \sin \omega t\right)}{dt} = -B \cdot \frac{\pi a^2 \omega}{2} \cos \omega t$$

$$t=0 \text{时}, \mathcal{E}_{DCA} = -B \cdot \frac{\pi a^2 \omega}{2} \quad \text{大小 } B \cdot \frac{\pi a^2 \omega}{2}$$



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$$4-9. (1) \because E = \int_C (\vec{v} \times \vec{B}) \cdot d\vec{l} = \oint_S v B_0 \frac{x \tan 30^\circ}{\tan 30^\circ} \cdot 2 = \frac{2\sqrt{3}}{3} v^2 B_0 t \quad \text{方向 } C \rightarrow D$$

$$(2) \because E_{\text{动}} = \frac{2\sqrt{3}}{3} v^2 B_0 t^2$$

$$E_{\text{感}} = - \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} = - \oint_S \vec{B}_0 \cdot \int_0^{x'} B_0 \cdot \frac{2x \tan 30^\circ}{\tan 30^\circ} dx' = \frac{\sqrt{3}}{3} B_0 x^2 = \frac{\sqrt{3}}{3} B_0 v^2 t^2$$

$$\therefore E = \frac{-\sqrt{3} B_0 x^2}{3} + \frac{2\sqrt{3}}{3} v^2 B_0 t^2 = \frac{\sqrt{3}}{3} v^2 B_0 t^2 \quad \text{方向由 } C \rightarrow D$$

$$4-10. \because \cancel{E_{\text{感}}} = E_{\text{动}} = \int_0^b (\vec{v} \times \vec{B}) dt = \int_0^b v \cdot \frac{\mu_0 I}{2\pi(a+x)} dx = - \frac{v \mu_0 I_0 e^{-\lambda t}}{2\pi} \ln \frac{a+b}{a}$$

以下斜上为正

 ~~$E_{\text{感}} = \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} =$~~

$$E_{\text{感}} = - \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} = - \int_0^b \frac{-\lambda \mu_0 e^{-\lambda t}}{2\pi(a+x)} \vec{B} \cdot d\vec{x} = - \frac{\lambda \mu_0 e^{-\lambda t} v t}{2\pi} \ln \frac{a+b}{a}$$

$$E = \frac{v \mu_0 I_0 e^{-\lambda t}}{2\pi} \ln \frac{a+b}{a} \left(\frac{\lambda t - 1}{a+b} \right)$$

当 $\lambda t > 1$ 方向自下向上 $\lambda t < 1$ 方向自上向下



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