

Probability and Random Variables

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Lecture Objectives

- Review probability and random variables
- Pre-requisite for discussion in rest of course

Probability

- Two philosophical viewpoints:
 - Frequentist
 - Probability of A: Fraction of outcomes A
 - Parameters are fixed and data are a repeatable random sample
 - n experiments, n_A have outcome A
 - $\lim_{n \rightarrow \infty} n_A/n = p_A$
 - Bayesian
 - Probability of A = Degree of belief that A is true
 - Suitably calibrated to betting odds
 - Unknown quantities treated probabilistically
 - data are fixed and known, parameters unknown also modeled probabilistically
 - Example: Probability that life came to earth on an asteroid
- We will lean toward the Bayesian camp

Probability Space

- Three elements:
 - Set of outcomes Ω
 - Events for which probability is assigned \mathcal{B}
 - A measure of probability $P()$
- Discrete Ω
 - Any subset of outcomes defines an event
- Non discrete Ω
 - Technical constraints “measurable”
 - Most events we think of non-problematic

Probability Space Example

Concept

- Random Experiment
- Outcomes
- Sample Space
- Events
- Probability

Example

- Throw of a Dice
- 1, 2, 3, 4, 5, 6
- $\{1, 2, 3, 4, 5, 6\}$
- $\{1\}, \{2,3\}, \{1,3,5\}, \dots$
- $P(\{2,3\}) = 2/6 = 1/3$
- $P(\{1\}) = 1/6, \dots$

Probability Axioms

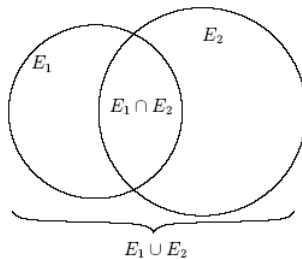
- E – Event
 - $0 \leq P(E) \leq 1$
 - $P(E^c) = 1 - P(E)$
 - $P(\Omega) = 1$
 - Disjoint Events E_i :
$$\mathcal{P} \left(\bigcup_i E_i \right) = \sum_i \mathcal{P}(E_i).$$
- Additional restrictions on what is allowable as a event in non-discrete case

Probability Properties I

$$\mathcal{P}(E^c) = 1 - \mathcal{P}(E)$$

$$\mathcal{P}(\phi) = 0$$

$$\mathcal{P}(E_1 \cup E_2) = \mathcal{P}(E_1) + \mathcal{P}(E_2) - \mathcal{P}(E_1 \cap E_2)$$



$$\mathcal{P}(\text{Odd number}) = 1 - \mathcal{P}(\text{Even number})$$

$$E_1 = \text{Multiple of 2, } \mathcal{P}(E_1) = \frac{1}{2}$$

$$E_2 = \text{Multiple of 3, } \mathcal{P}(E_2) = \frac{1}{3}$$

$$\mathcal{P}(E_1 \cup E_2) = P(\{1, 2, 3, 4, 6\}) = \frac{2}{3}$$

$$\mathcal{P}(E_1 \cap E_2) = P(\{6\}) = \frac{1}{6}$$

$$\frac{2}{3} = \frac{1}{2} + \frac{1}{3} - \frac{1}{6}$$

Conditional Probability

Conditional Probability

$$\mathcal{P}(E_1|E_2) = \text{Probability of } E_1 \text{ given } E_2 = \frac{\mathcal{P}(E_1 \cap E_2)}{\mathcal{P}(E_2)}$$

E_2 forms new universe

Bayes Rule

$$E_1 = \{5\} , E_2 = \text{throw} \geq 3 = \{ 3, 4, 5, 6 \}$$

$$\mathcal{P}(\{5\}|\{3, 4, 5, 6\}) = \frac{1}{4} = \frac{\frac{1}{6}}{\frac{4}{6}} = \frac{\mathcal{P}(\{5\})}{\mathcal{P}(\{3,4,5,6\})}$$

$\{3, 4, 5, 6\}$ is new “universe”

$$\text{Note } \mathcal{P}(\{3, 4, 5, 6\}|\{5\}) = 1$$

Statistical Independence

Statistical Independence

$$\mathcal{P}(E_1 \cap E_2) = \mathcal{P}(E_1) \mathcal{P}(E_2)$$

$$\Leftrightarrow \mathcal{P}(E_1 | E_2) = \mathcal{P}(E_1)$$

E_2 overlaps same fraction of E_1 as of Ω

$$E_1 = \text{throw} \geq 3 = \{3, 4, 5, 6\}$$

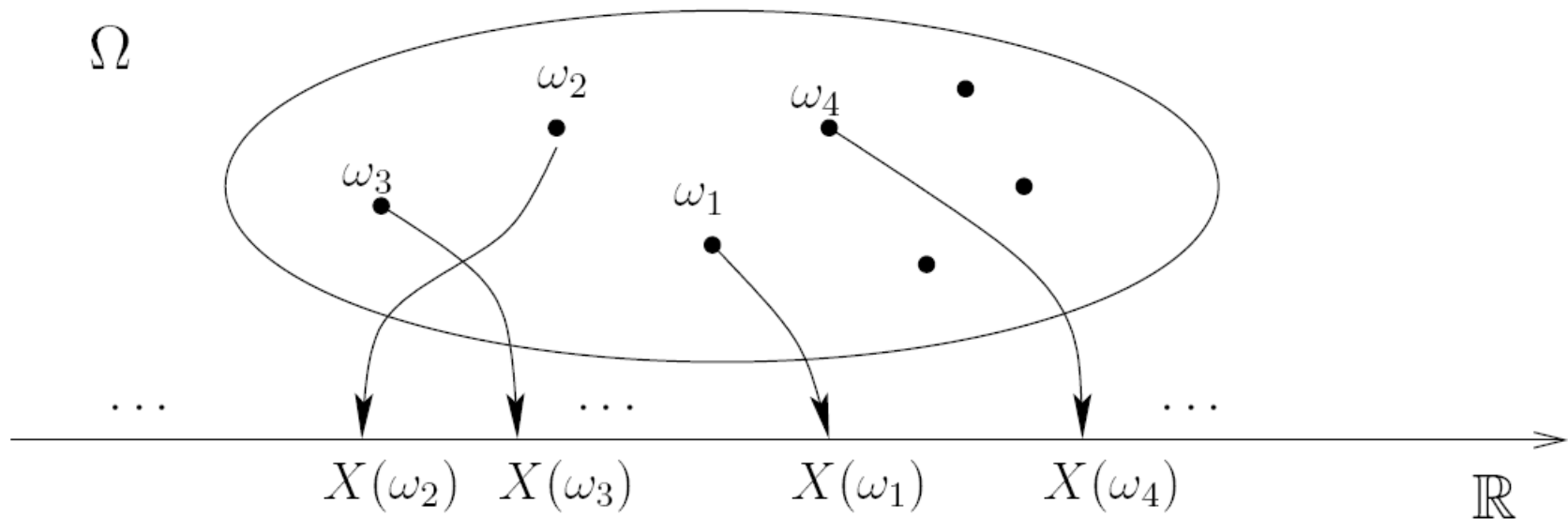
$$E_2 = \text{Odd Throw} = \{1, 3, 5\}, E_1 \cap E_2 = \{3, 5\}$$

$$\mathcal{P}(\{3, 4, 5, 6\}) = \frac{4}{6} = \frac{2}{3}, \mathcal{P}(\{1, 3, 5\}) = \frac{3}{6} = \frac{1}{2}$$

$$\mathcal{P}(\{3, 5\}) = \frac{2}{6} = \left(\frac{2}{3}\right)\left(\frac{1}{2}\right) = \mathcal{P}(\{3, 4, 5, 6\}) \mathcal{P}(\{1, 3, 5\})$$

Random Variable

- A real number for each outcome of a random experiment

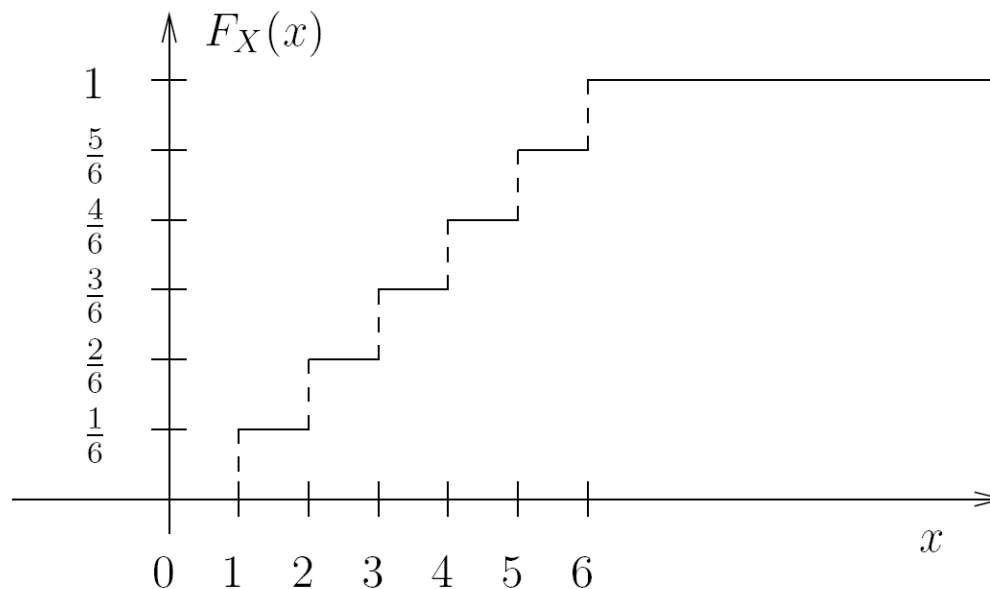


Cumulative Distribution Function

- Cumulative Distribution Function

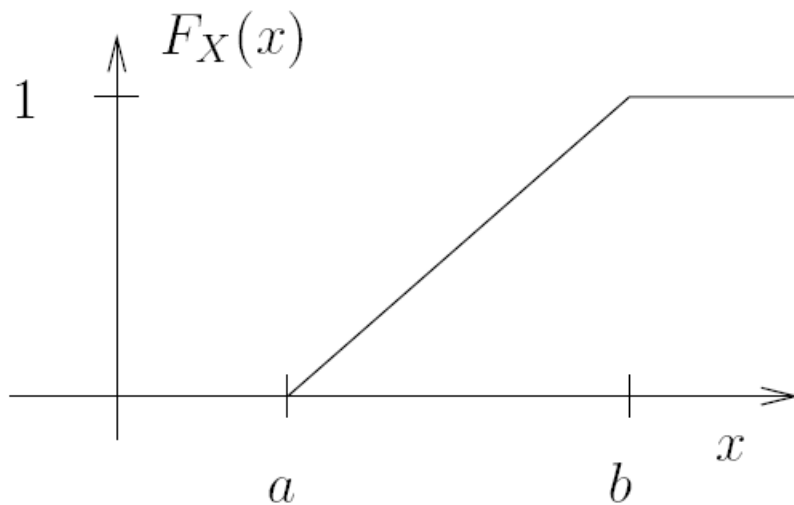
$$F_X(x) = \mathcal{P}(X \leq x)$$

- Dice throw

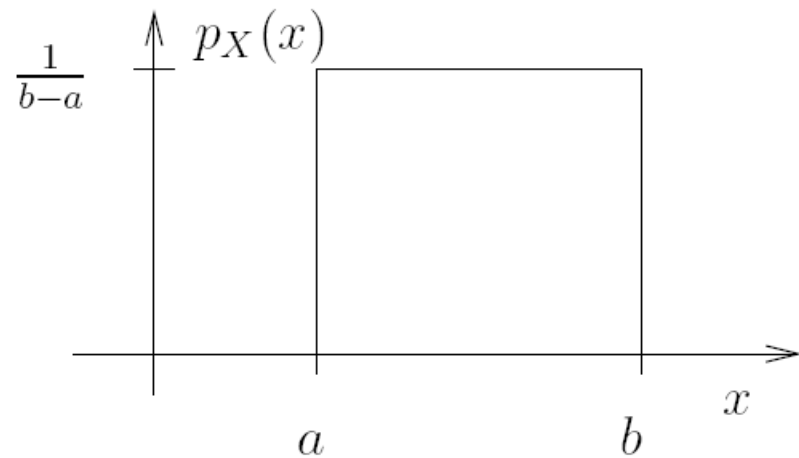


Probability Density Function

- PDF $p_X(X) = \frac{d}{dx}F_X(x)$
- Example: Uniform Random Variable



CDF



PDF

Statistical Averages (R.V.)

- Mean/Expected Value

$$m_X = E[X] \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} xp_X(x)dx$$

- nth Moment:

$$m_X^{(n)} = E[X^n] \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} x^n p_X(x)dx$$

- Variance/Standard Deviation:

$$\sigma_X^2 = E[(X - m_X)^2] \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} (x - m_X)^2 p_X(x)dx = E[X^2] - m_X^2$$

Characteristic Function

$$\psi_X(\nu) \stackrel{\text{def}}{=} E[e^{j\nu X}] = \int_{-\infty}^{\infty} p_X(x) e^{j\nu x} dx$$

- Fourier transform of pdf
- Utility: Computation of moments

$$m_X^n = \frac{1}{j^n} \frac{d^n \psi_X(\nu)}{d\nu^n} \Big|_{\nu=0}$$

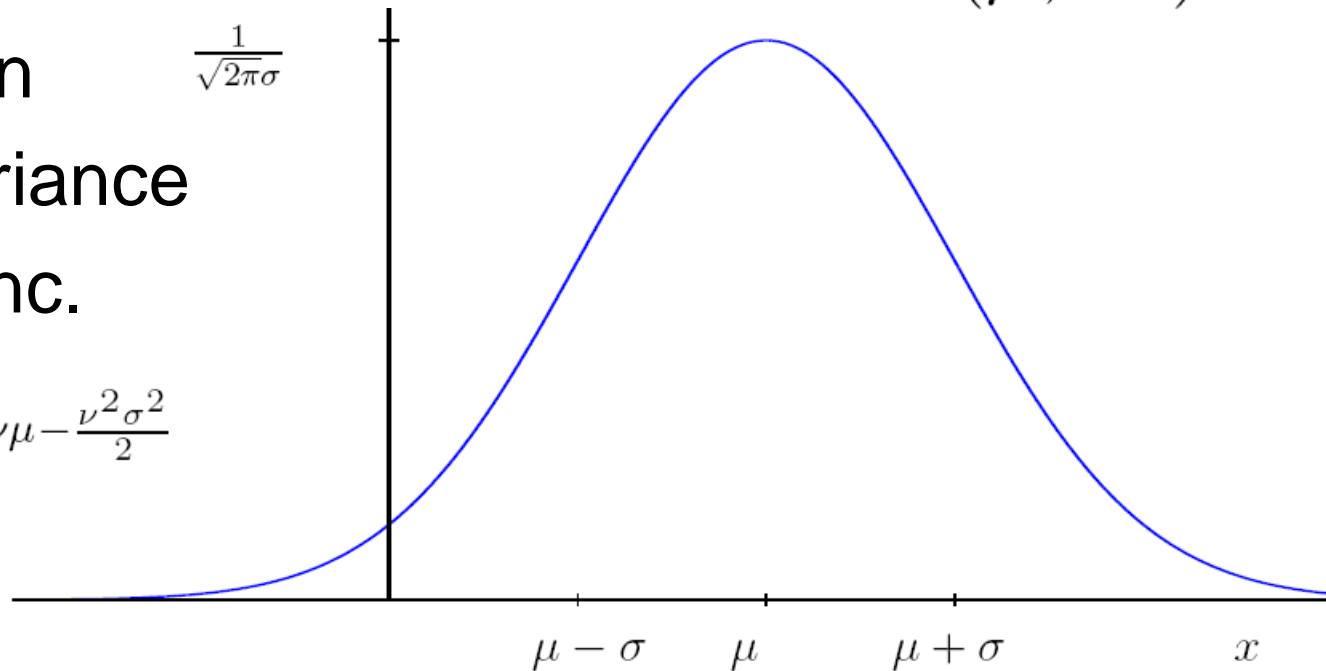
Gaussian Random Variable

- X: with pdf

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad \mathcal{N}(\mu, \sigma^2)$$

- μ - Mean
- σ^2 – Variance
- Char func.

$$\psi_X(\nu) = e^{j\nu\mu - \frac{\nu^2\sigma^2}{2}}$$

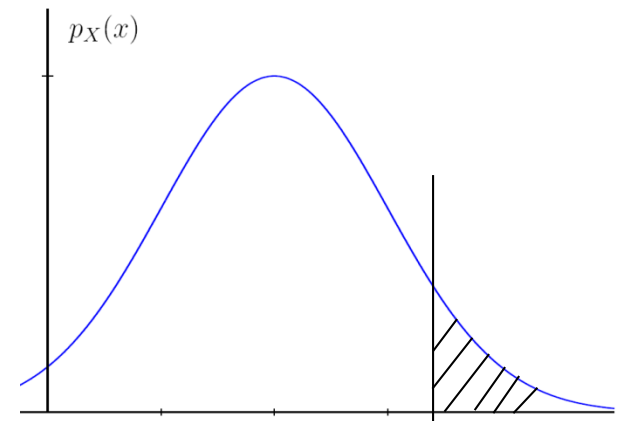


Normalized Gaussian RV

$$Y \sim \mathcal{N}(\mu, \sigma^2)$$

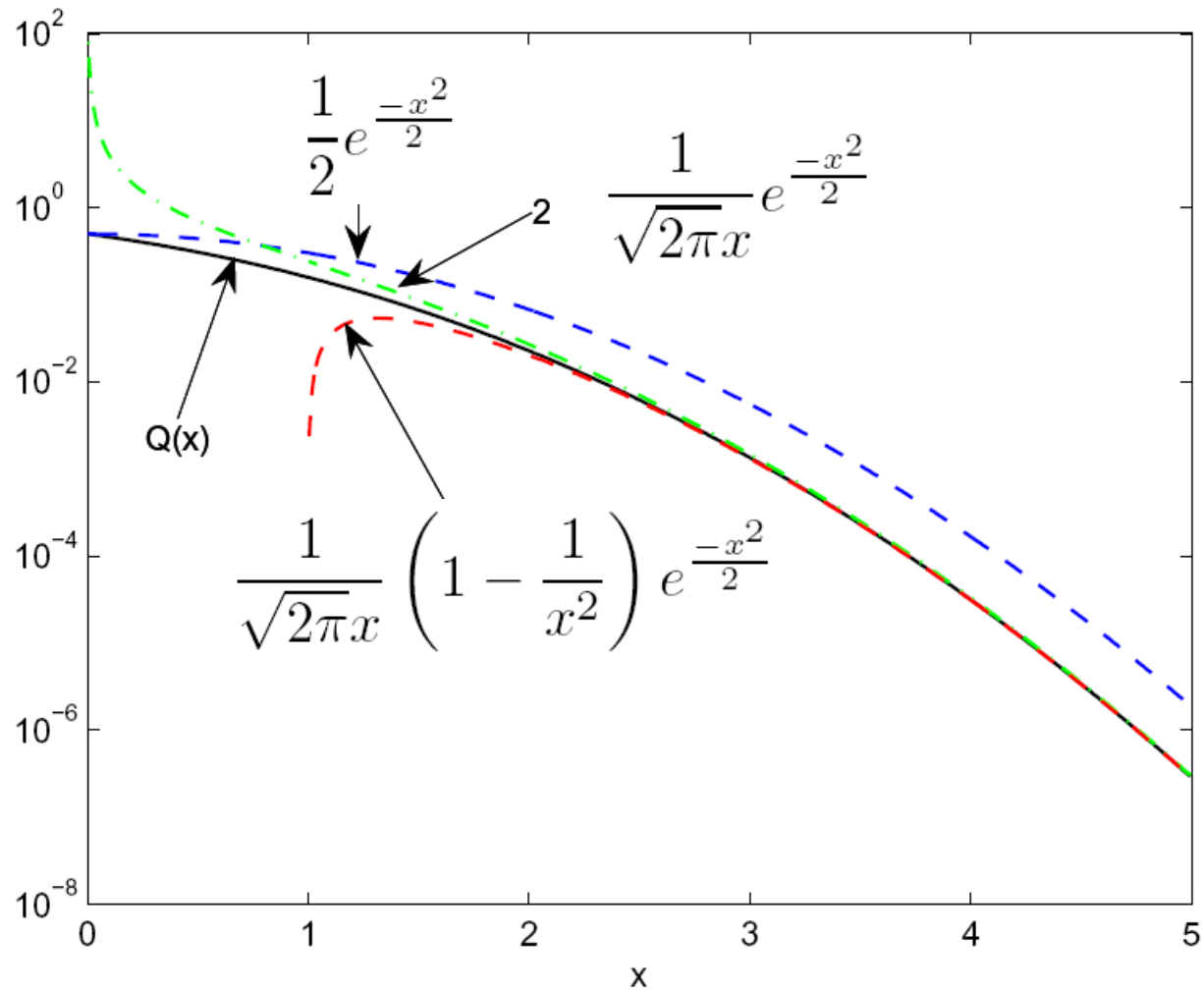
$$X = \frac{Y - \mu}{\sigma} \quad \text{is} \quad \mathcal{N}(0, 1)$$

- Normalized Gaussian RV
- Tail probability: Q-function



$$Q(x) = \mathcal{P}(X > x) = \int_x^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$$

Q-Function Bounds



Function of a RV

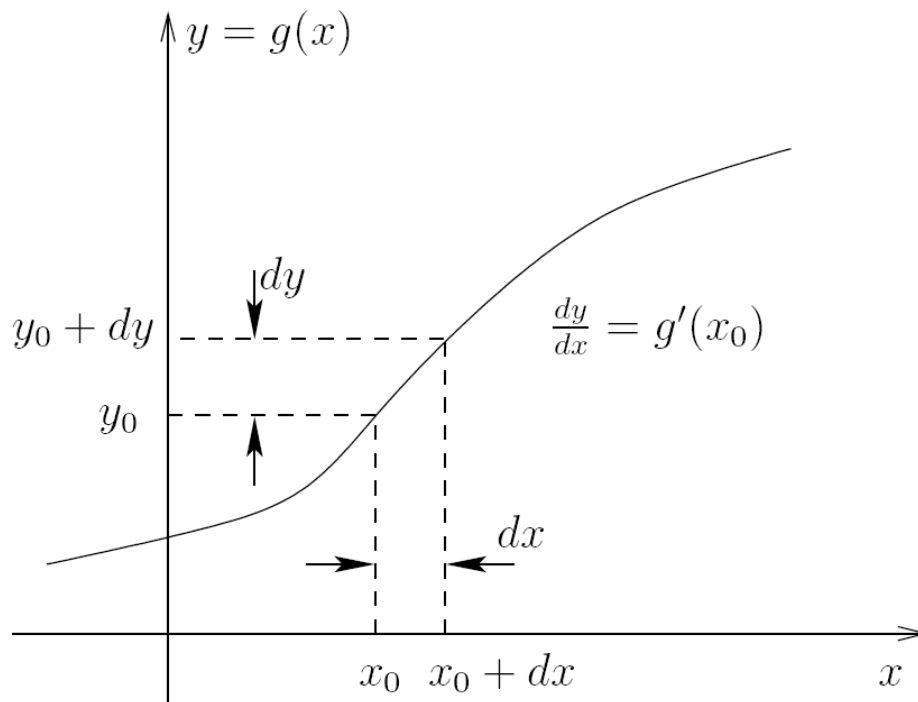
$$Y = g(X)$$

- A new random variable
 - fully characterized by X
- CDF:

$$F_Y(y) = \int_{\{x: g(x) \leq y\}} p_X(x) dx$$

Functions of a RV II

- Non-decreasing function



$$p_Y(y_0) = \frac{p_X(x_0)}{\frac{dy}{dx}} = \frac{p_X(x_0)}{g'(x_0)}$$

$$p_Y(y_0)dy = \mathcal{P}(\{y_0 \leq Y < y_0 + dy\}) = \mathcal{P}(\{x_0 \leq X < x_0 + dx\}) = p_X(x_0)dx$$

Functions of a RV III

- Countable number of solutions to $g(x)=y$, Say x_i
 - $g'(x_i)$ non-zero at each x_i

$$p_Y(y) = \sum_i \frac{p_X(x_i)}{|g'(x_i)|}$$

Example: RV Transformation I

$$X \sim \mathcal{N}(0, 1)$$

$$Y = aX + b$$

$$p_Y(y) = \frac{p_X\left(\frac{y-b}{a}\right)}{|a|} = \frac{1}{\sqrt{2\pi}|a|} e^{-\frac{(y-b)^2}{2|a|^2}}$$

Example: RV Transformation II

- X uniform over $[-\pi, \pi]$

$$f_X(x) = \begin{cases} \frac{1}{2\pi} & -\pi \leq x < \pi \\ 0 & \text{otherwise} \end{cases}$$

- $Y = X^2$

– $y=x^2$ has two solutions $\pm \sqrt{y}$

$$f_Y(y) = \sum_{x_i: g(x_i)=y} \frac{f_X(x_i)}{|g'(x_i)|} = \begin{cases} \frac{1}{2\pi\sqrt{y}} & 0 \leq y < \pi^2 \\ 0 & \text{otherwise} \end{cases}$$

RV Transformation: Application

- Computer generation of Random Variables with desired distributions
- Assignment 1: Addresses this problem

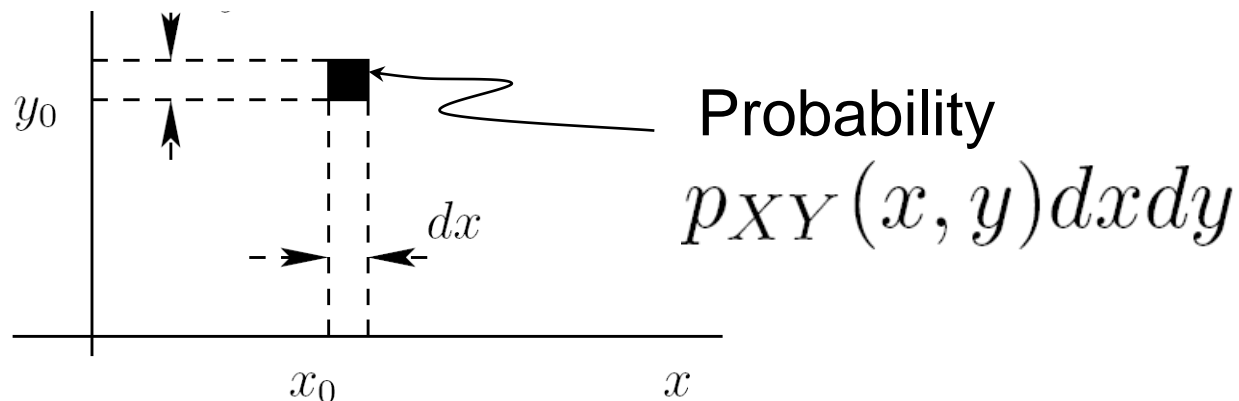
Two Random Variables

- Individual vs Joint Characterization
- Joint cdf

$$F_{XY}(x, y) = \mathcal{P}(X \leq x, Y \leq y)$$

- Joint pdf

$$p_{XY}(x, y) = \frac{\partial^2 F_{XY}(x, y)}{\partial x \partial y}$$



Joint/Marginal PDFs

- Marginals integral of joint pdfs

$$p_X(x) = \int_{-\infty}^{\infty} p_{XY}(x, y) dy.$$

$$p_Y(y) = \int_{-\infty}^{\infty} p_{XY}(x, y) dx.$$

Conditional PDF, Independence

$$p_{Y|X}(y|x) = \begin{cases} \frac{p_{XY}(x,y)}{p_X(x)} & p_X(x) \neq 0 \\ 0 & \text{otherwise} \end{cases}$$

- Statistically Independent

- $p_{Y|X}(y|x) = p_Y(y)$

- Equivalent:

$$p_{XY}(x, y) = p_Y(y)p_X(x)$$

Joint Statistics of 2 RVs

- Correlation: $E[XY]$
- Covariance

$$\text{cov}(X, Y) = E[(X - m_X)(Y - m_Y)]$$

– Correlation of “mean-removed” versions

- Correlation coefficient

$$\rho_{XY} = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y} \quad |\rho_{XY}| \leq 1$$

Uncorrelated and Independent RVs

- Uncorrelated: Covariance = 0
 - Equivalent conditions

$$E[XY] = E[X]E[Y]$$

$$\rho_{XY} = 0$$

- Independent implies uncorrelated not vice versa (important exception later)

Transformation of 2 RVs

- $Z = g(X, Y)$
 $W = h(X, Y)$ Transform of X, Y

- PDF of Z, W :

$$p_{ZW}(z, w) = \sum_i \frac{p_{XY}(x_i, y_i)}{|\det(J(x_i, y_i))|}$$

– (x_i, y_i) solutions to $w=g(x,y)$; $z=h(x,y)$

– Jacobian: $J(x, y) = \begin{bmatrix} \frac{\partial g(x,y)}{\partial x} & \frac{\partial g(x,y)}{\partial y} \\ \frac{\partial h(x,y)}{\partial x} & \frac{\partial h(x,y)}{\partial y} \end{bmatrix}$

Example

- X, Y independent RVs uniform $[0, 1]$

$$Z = g(X, Y) = X + Y$$

$$W = h(X, Y) = X - Y$$

$$J(x, y) = \begin{bmatrix} \frac{\partial g(x, y)}{\partial x} & \frac{\partial g(x, y)}{\partial y} \\ \frac{\partial h(x, y)}{\partial x} & \frac{\partial h(x, y)}{\partial y} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\det(J(x, y)) = -2$$

Example (contd.)

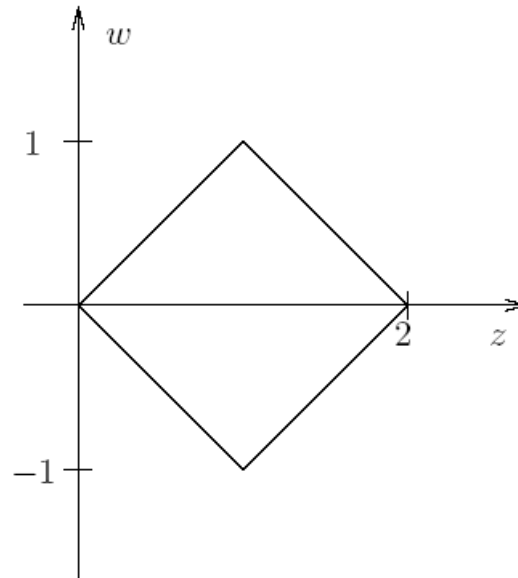
- Unique soln to $x + y = z, x - y = w$

$$x_1 = \frac{z+w}{2}, y_1 = \frac{z-w}{2}$$

$$\begin{aligned} p_{ZW}(z, w) &= \frac{p_{XY}(x_1, y_1)}{|\det(J(x_1, y_1))|} \\ &= \begin{cases} \frac{1}{2} & 0 \leq z + w \leq 2, 0 \leq z - w \leq 1 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

Example (contd.)

$$p_{ZW}(z, w)$$



- Uncorrelated but dependent
– Verify !

Example II

- X, Y independent identically distributed (iid) Gaussians $\mathcal{N}(0, \sigma^2)$
- Rectangular to polar conversion

$$R = \sqrt{X^2 + Y^2} \stackrel{\text{def}}{=} g(X, Y)$$

$$\Theta = \tan^{-1} \left(\frac{Y}{X} \right) \stackrel{\text{def}}{=} h(X, Y)$$

Example II (contd.)

$$\det(J(x, y)) = \frac{1}{\sqrt{x^2 + y^2}}$$

- Solution to $r = \sqrt{x^2 + y^2}, \theta = \tan^{-1} \left(\frac{y}{x} \right)$
 $x = r \cos(\theta) \quad y = r \sin(\theta)$

- Joint pdf of R, θ

$$p_{R\Theta}(r, \theta) = \frac{r}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}}$$

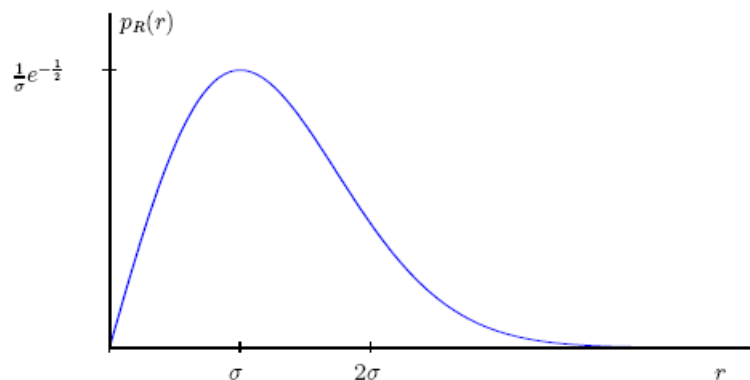
- Independent of θ

Example II (contd.)

- Marginal distribution of R

$$p_R(r) = \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} \quad r \geq 0.$$

- Rayleigh Distribution
 - Model for amplitude variations in mobile wireless applications



Multiple RVs

- n Random variables: X_1, X_2, \dots, X_n
- Random Vector:

$$\mathbf{X} = [X_1, X_2, \dots, X_n]^T$$

- Characterization

- Joint cdf: $F_{\mathbf{X}}(\mathbf{x}) = \mathcal{P}(\mathbf{X} \leq \mathbf{x})$

- Joint pdf: $p_{\mathbf{X}}(\mathbf{x}) = \frac{\partial^n F_{\mathbf{X}}(\mathbf{x})}{\partial x_1 \partial x_2 \cdots \partial x_n}$

Multiple RV Coordinate Transformation

$$\mathbf{X} = [X_1, X_2, \dots, X_n]^T, \quad \mathbf{Y} = [Y_1, Y_2, \dots, Y_n]^T$$

$$\mathbf{Y} = \mathbf{g}(\mathbf{X})$$

$$p_{\mathbf{Y}}(\mathbf{y}) = \sum_i \frac{p_{\mathbf{X}}(\mathbf{x}_i)}{|\det(\mathbf{J}(\mathbf{x}_i))|}$$

– \mathbf{x}_i solution to $\mathbf{g}(\mathbf{x}) = \mathbf{y}$ Jacobian:

$$\mathbf{J}(\mathbf{x}) = \begin{bmatrix} \frac{\partial g_1(\mathbf{x})}{\partial x_1} & \dots & \frac{\partial g_1(\mathbf{x})}{\partial x_n} \\ \vdots & \vdots & \vdots \\ \frac{\partial g_n(\mathbf{x})}{\partial x_1} & \dots & \frac{\partial g_n(\mathbf{x})}{\partial x_n} \end{bmatrix}$$

Jointly Gaussian RVs

- Joint pdf of form

$$p_{\mathbf{X}}(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^n \det \mathbf{C}}} \exp \left(-\frac{(\mathbf{x} - \mathbf{m})^T \mathbf{C}^{-1} (\mathbf{x} - \mathbf{m})}{2} \right)$$

- Mean $\mathbf{m} = E[X_1, X_2, \dots, X_n]$
- Covariance: $\mathbf{C} = E [(\mathbf{x} - \mathbf{m})(\mathbf{x} - \mathbf{m})^T]$
- Completely characterized by mean and covariance

Properties of Multivariate Gaussian Random Variables

- Any subset is also jointly Gaussian
- Linear transforms preserve Gaussianity
- Conditional distribution of some given the rest is Gaussian
- Jointly Gaussian + uncorrelated implies independent

Asymptotic Behavior of Infinite Collections of Random Variables

- Two main laws:
 - Law of large numbers
 - Central Limit Theorem

Law of Large Numbers (LLN)

- X_1, X_2, \dots Uncorrelated random variables, common mean m_X , finite variance

$$Y_n = \frac{1}{n} \sum_{i=1}^n X_i, \quad n = 1, 2, \dots$$

- Y_n converges to the mean as $n \rightarrow \infty$

$$\lim_{n \rightarrow \infty} \mathcal{P}(|Y_n - m_X| > \epsilon) = 0.$$

Central Limit Theorem

- X_1, X_2, \dots Independent identically distributed random variables, mean m_x , variance σ_x^2 (finite)

$$Y_n = \frac{1}{n} \sum_{i=1}^n X_i$$

- Converges to $\mathcal{N}(m, \frac{\sigma^2}{n})$ random variable as $n \rightarrow \infty$

Central Limit Theorem Significance

- Noise: often composed of smaller similar noise processes
 - CLT leads to Gaussian distribution
- Gaussian assumption common for several noise sources

Lecture Key Concepts

- Probability space
 - Universe of outcomes, Events, Probabilities
 - Independence
- Random Variables
 - Characterization by cdf/pdf
 - Joint pdf for multiple rvs
 - Transformations
- Law of Large Numbers
- Central Limit Theorem