

# AutB



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**Keyword**

P5

MB\_CyclicSetPoint

# Admin

## Evaluation

50 % 2 évaluations intermédiaires de 45'

Semaine 13, modules 00 à 04

Semaine 21, programmation robuste

50 % Examen de module semaines 26/27

# Admin

Reste

Semaine 20 Polynôme 5

Labo 6/7 (1)

Semaine 21 (Evaluation programmation robuste)

Labo 6/7 (2)

Semaine 22 Fête Dieu + Rapi (pas de cours)

Labo 6/7 (3)

Semaine 23 Retour Eval + fin

Labo 7/7 (lundi)

Labo 7/7 (mercredi)

Semaine 24 OPC UA + Généralités

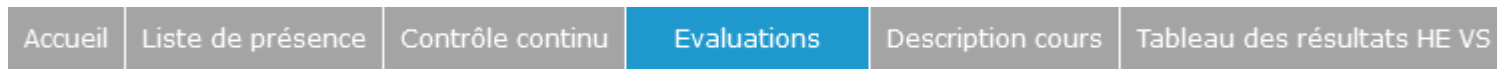
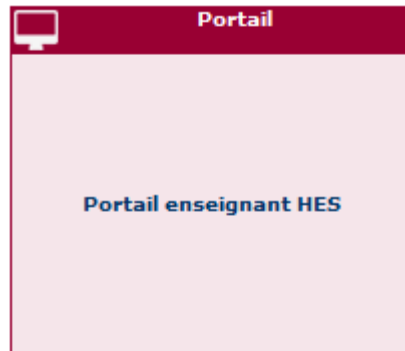
Labo 7/7 (mercredi)

Evaluation S21 45'→60'

Sujets: principalement MOD04, MOD05, MOD06 et MOD07

# Evaluation

Feedback Please !



# Régulateur PI

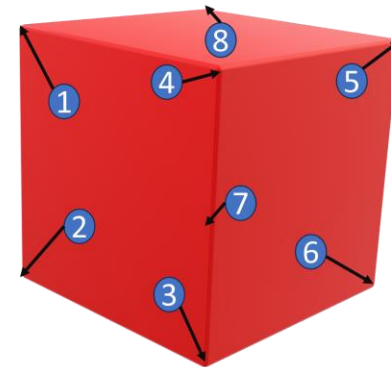
Exemple en AutB\_MOD\_07\_Mechatronics\_Soft  
**Function Block PI Regler.md**

# Use Case

**Robot**

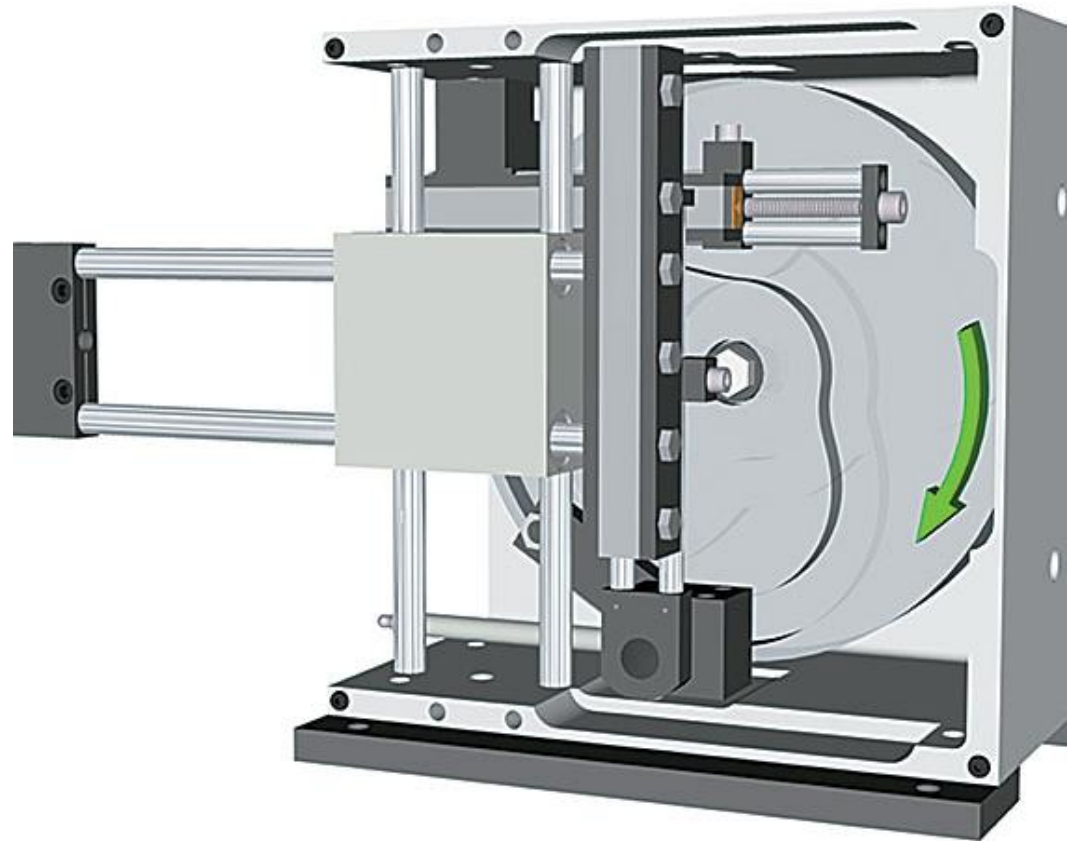


**Move XYZ from 1 to 6**



# Use case

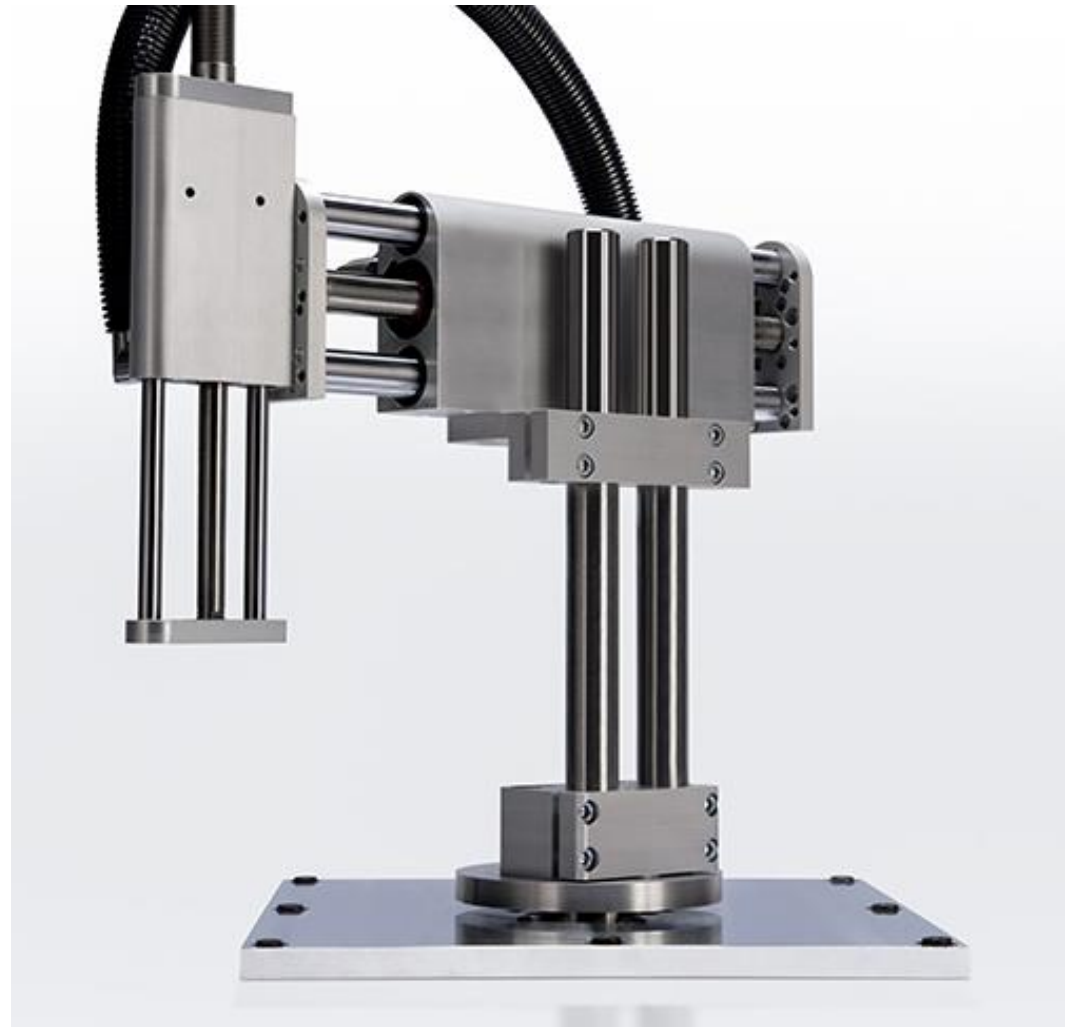
Replace mechanical cam by linear motors.



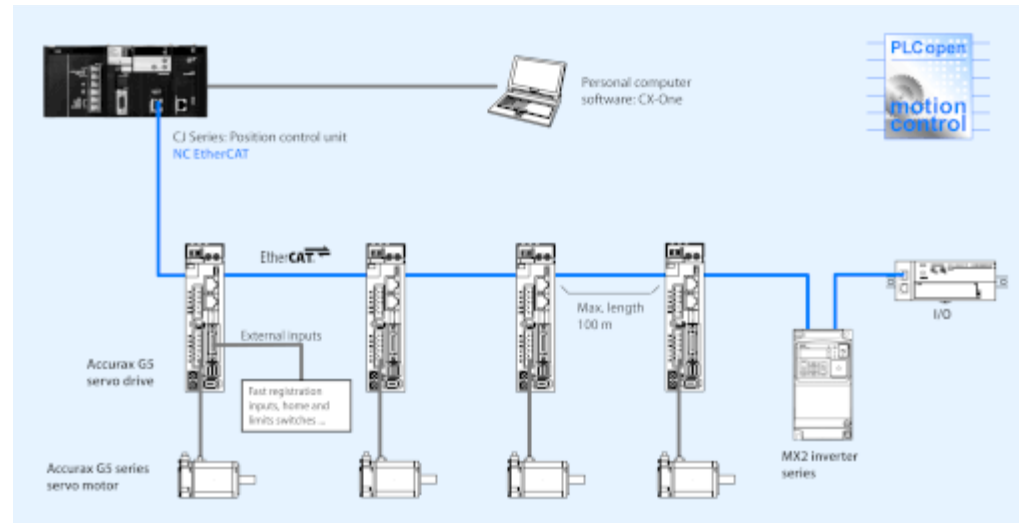


# Use case

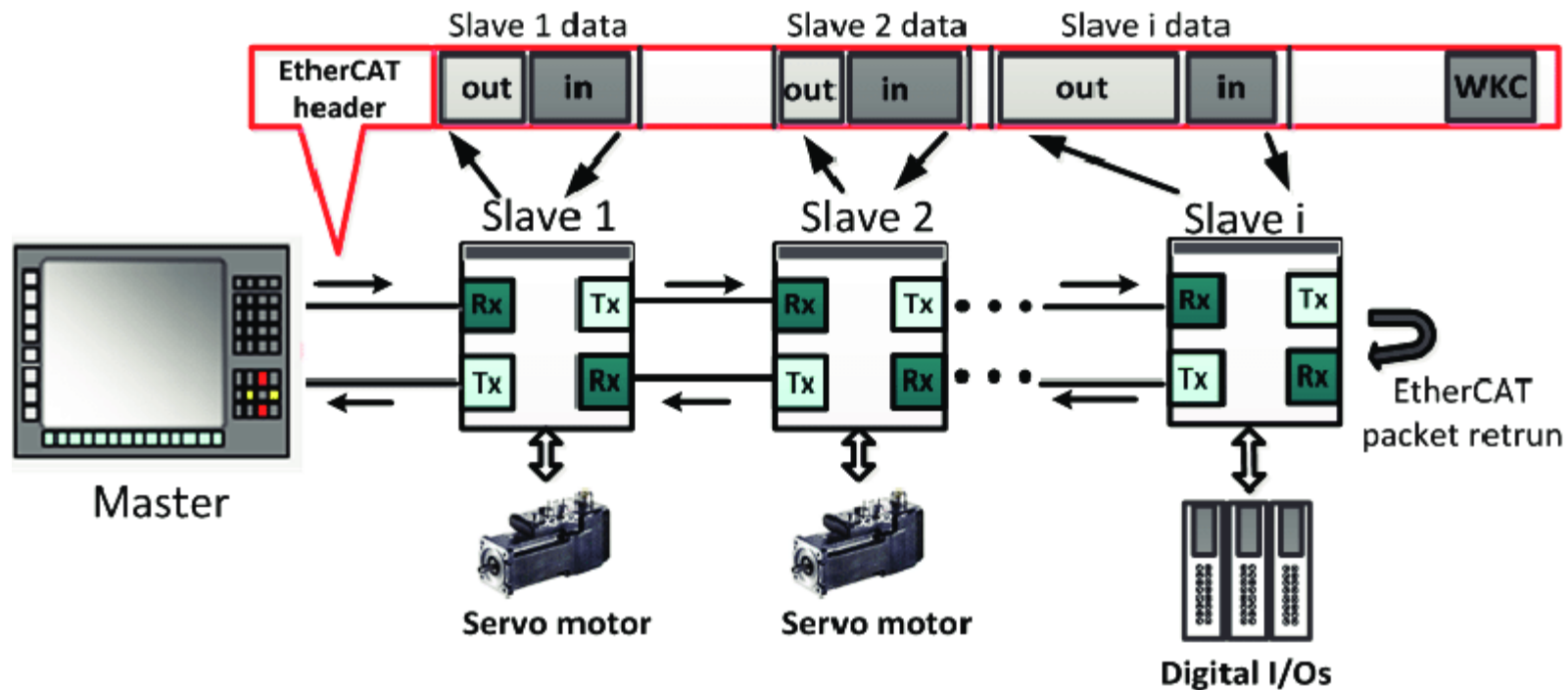
With linear motors



# Synchronise motors

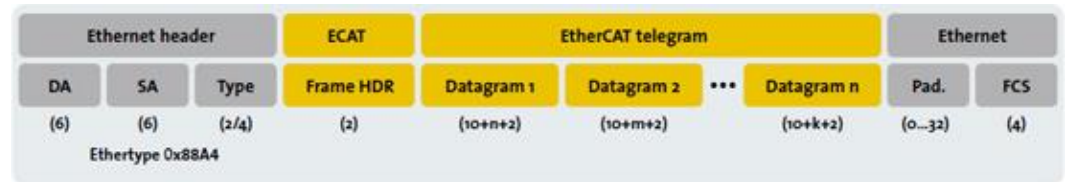


# Synchronise motors



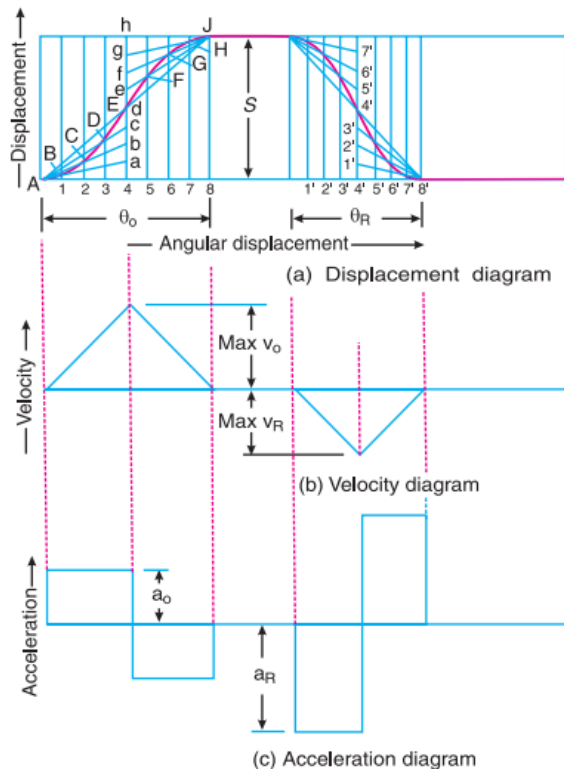
# Ethercat Frame

[More info about EtheCAT](#)



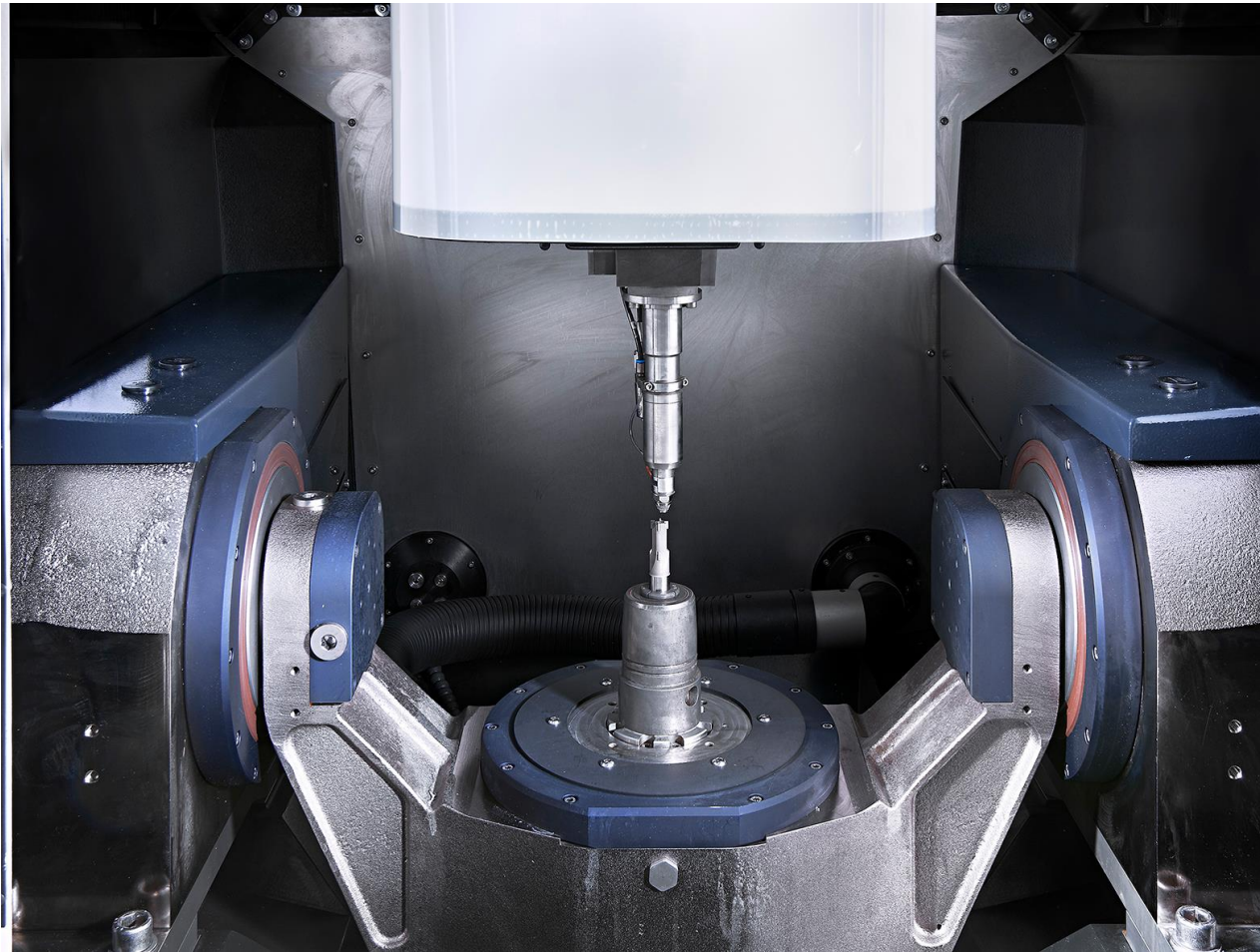
# Design Cam profile Old Style

## Source Schneider



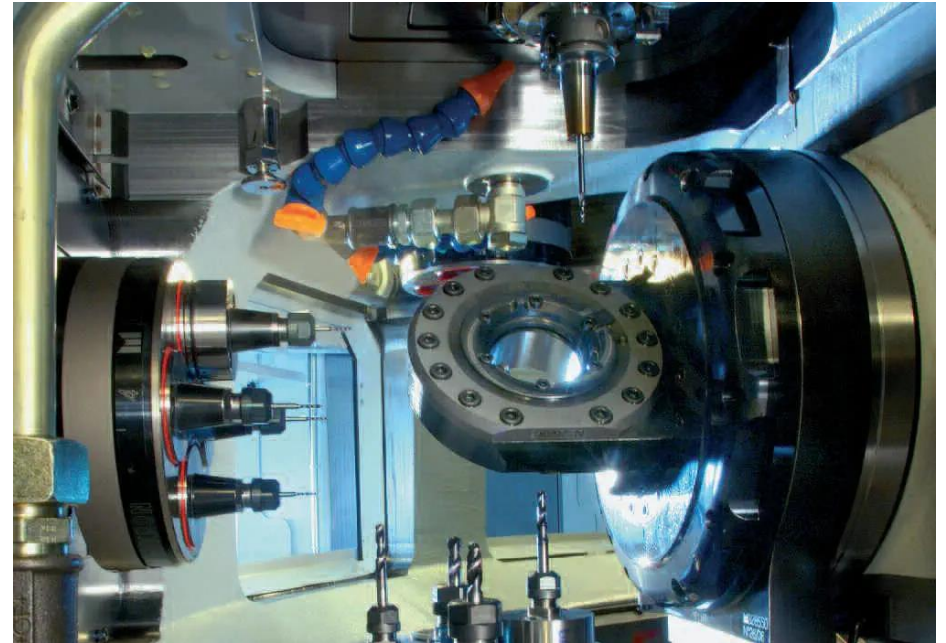
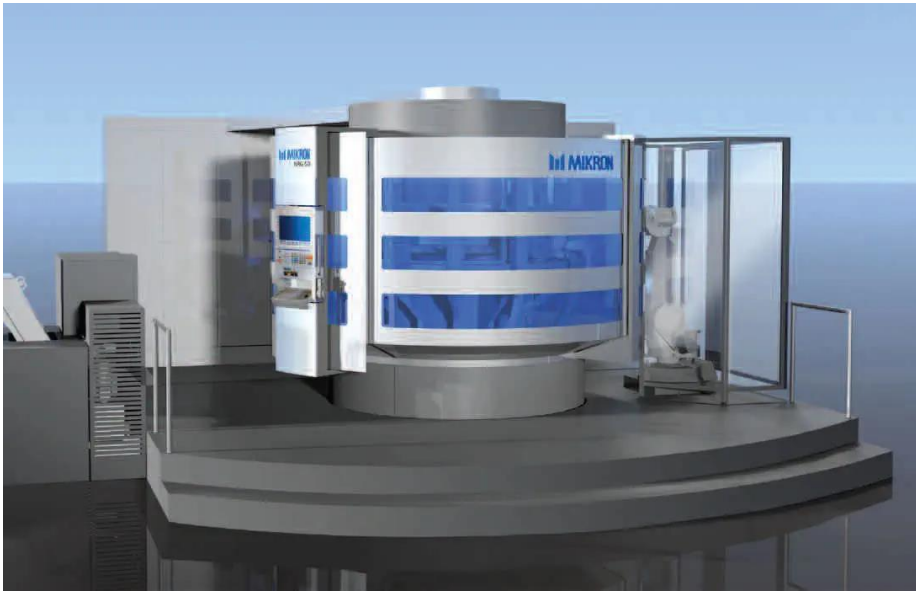
MC_CamIn	
Master Axis_Ref	BOOL InSync
Slave Axis_Ref	BOOL Busy
Execute BOOL	BOOL Active
CamTableID MC_CAM_ID	BOOL CommandAborted
BufferMode MC_Buffer_Mode	BOOL Error
Periodic BOOL	ET_Result ErrorId
MasterStartMode MC_Master_Start_Mode	BOOL EndOfProfile
SlaveStartMode MC_Slave_Start_Mode	TIME RampInDuration
RampInDirection MC_Direction	
VelocityOffsetRampIn LREAL	
AccelerationOffsetRampIn LREAL	
DecelerationOffsetRampIn LREAL	
JerkOffsetRampIn LREAL	

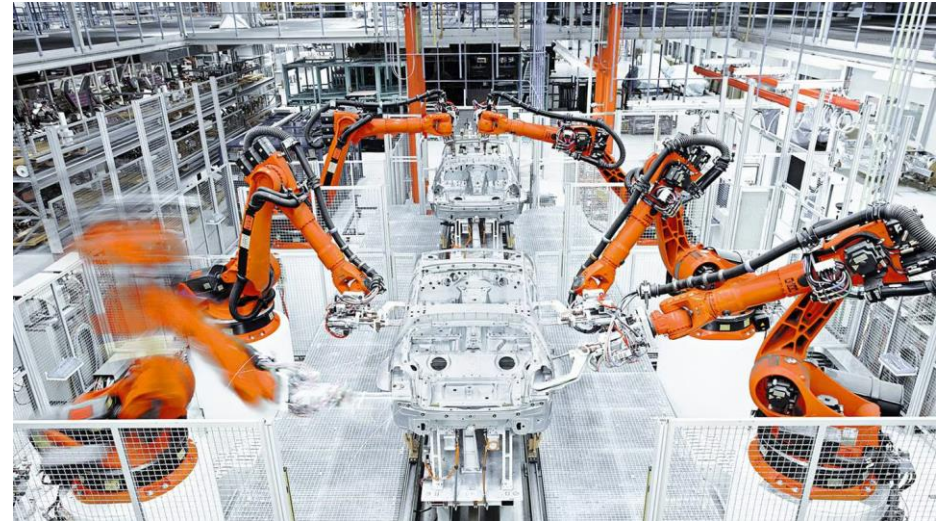
# Introduction to CNC





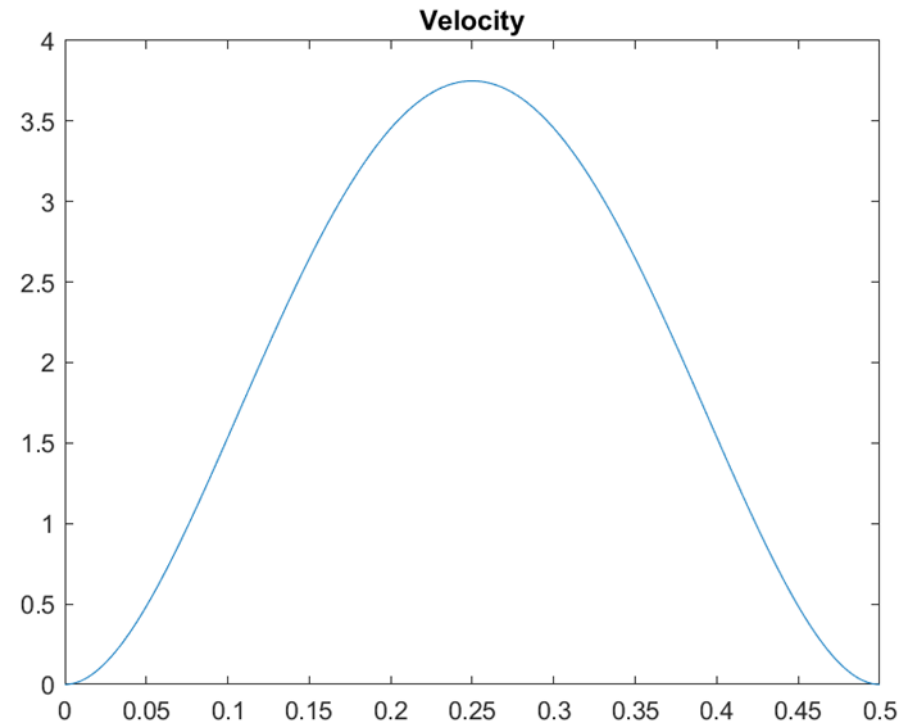
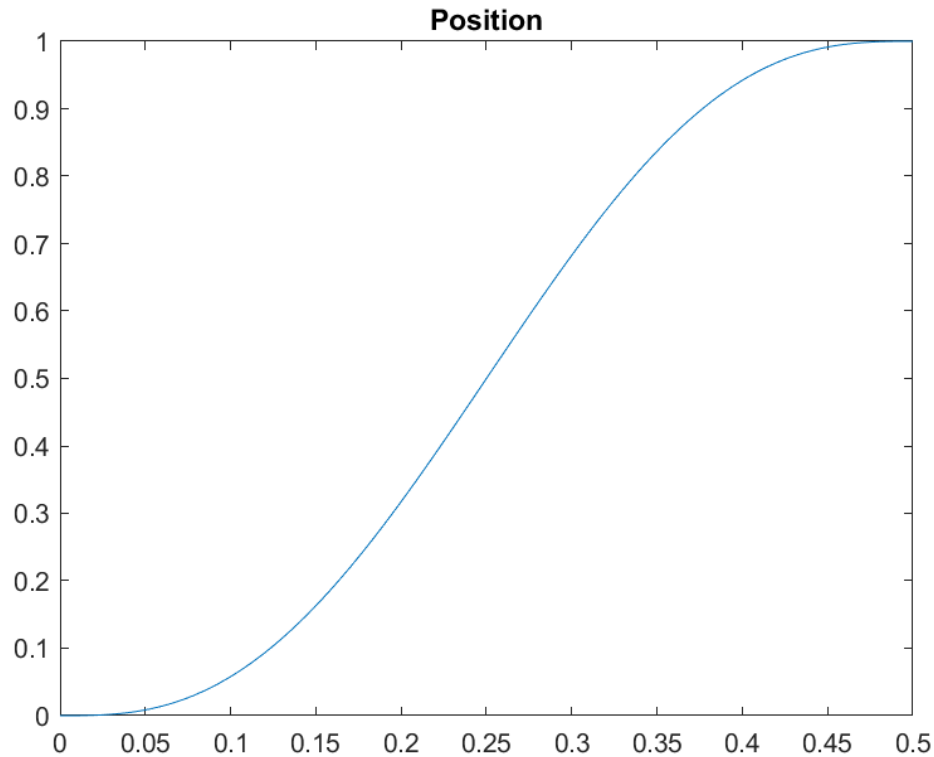
# Understand modular CNC



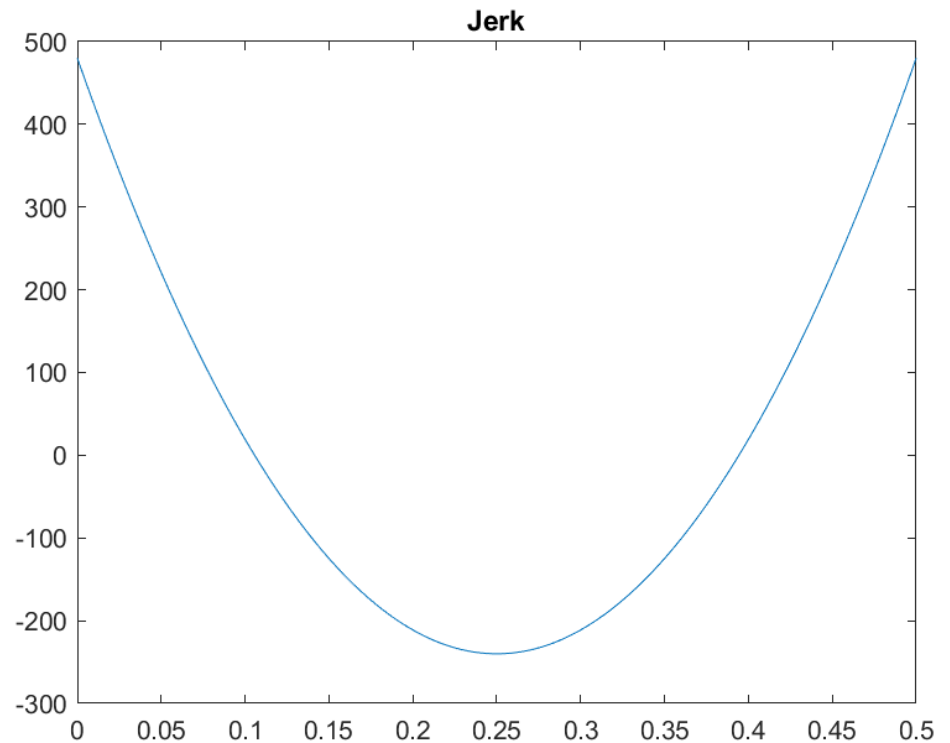
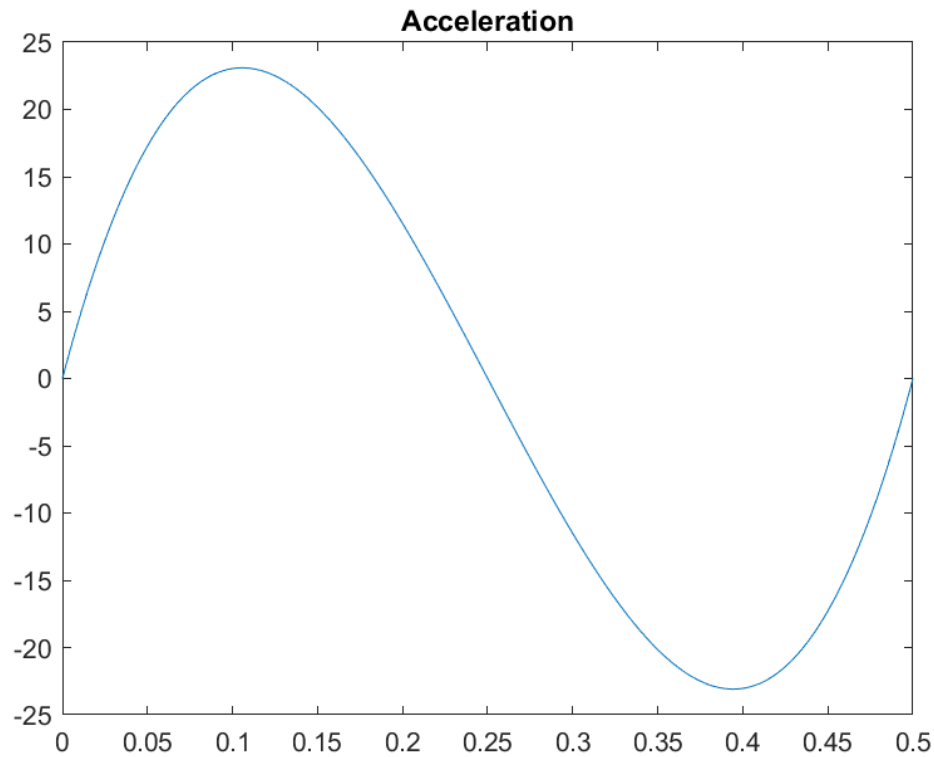




# Theoretical introduction with P5



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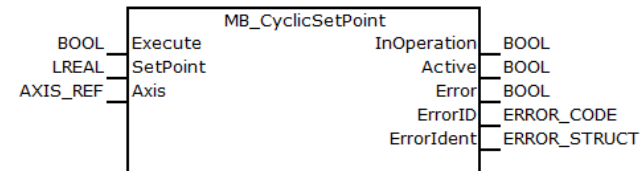
# MB\_CyclicSetPoint

Brief description

The function block

MB\_CyclicSetPoint cyclically sends the external command value of an axis without direct change at the drive.

Type: **Execute**



# Merci de votre attention

