C1: Conveyor

C2: Conveyor

② msgHereIs Glass(Glass)

① msgPopupDown(boolean down)

⑦ msgHereIsGlass(Glass)
//goes to C2 if popup
//at end of C1 otherwise
//messages C1

P: Popup

③ msgHereIs Glass(Glass)

⑥ msgJobDone(FinishedGlass)

msgBypass()
//used it no operation
//needed on glass

R: Robot

④ msgGlassReadyForWork(Glass)

WS: Workstation

msgJobDone(FinishedGlass)
⑤

//"Glass" as a parameter is an object of a shared class
// named Glass, holding all info about glass on line

W2-Subgroup2 Interactive Diagram
— Michael Boisvert
— Matthew Gumport
— Paulina Grcy