

# EE4400 Tut 1 Q1

$$\begin{array}{l}
 f(x, w) = \vec{x}^T \vec{w} \\
 \text{Target } f = [1 \ x_1] \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} = w_0 + w_1 x_1
 \end{array}
 \quad \left| \frac{\partial f}{\partial w} = x \right.$$

~~$x$~~   
 ~~$y$~~   
 ~~$\# - \#$~~

$$\begin{pmatrix} x \\ 1 \\ 1980 \\ 2018 \end{pmatrix} \quad \begin{pmatrix} y \\ \# - \# \end{pmatrix}$$

$$E = \frac{1}{2} (y - f)^2$$

$$\begin{aligned}
 \frac{\partial E}{\partial w} &= \frac{\partial E}{\partial f} \cdot \frac{\partial f}{\partial w} \\
 &= (y - f)(-1)x \\
 &= (f - y)x
 \end{aligned}$$


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$$\Delta w = -\frac{\partial E}{\partial w} = \underline{(y - f)x}$$

eta

note that  $x$  is a vector

## EE4400 - Tutorial 1, Question 1

```
In [15]: # 1 import pandas as pd
# 2 import matplotlib.pyplot as plt
# 3 import numpy as np
```

```
In [16]: # 1 def exp_cost_gradient(X, w, y):
# 2     # Compute prediction, cost and gradient based on mean square error Loss
# 3     pred_y = X @ w
# 4     cost   = np.sum((y - pred_y)*(y - pred_y))
# 5     gradient = -(y - pred_y) @ X
# 6     # print(gradient)
# 7     # print(cost)
# 8     return pred_y, cost, gradient
```

```
In [17]: # Load data
df = pd.read_csv('government-expenditure-on-education.csv')
expenditure = df['total_expenditure_on_education'].to_numpy()
years = df['year'].to_numpy()

# create normalized variables
max_expenditure = max(expenditure)
max_year = max(years)
min_year = min(years)

y = expenditure/max_expenditure
X = np.ones([len(y), 2])
X[:, 1] = (years-min_year)/(max_year-min_year)
#X[:, 1] = np.arange(0,1,0.1)

# Gradient descent
learning_rate = 0.01
w = np.array([0,0])
pred_y, cost, gradient = exp_cost_gradient(X, w, y)
num_iters = 200;
cost_vec = np.zeros(num_iters)
print('Initial Cost =', cost)
for i in range(0, num_iters):

    # update w
    w = w - learning_rate*gradient

    # compute updated cost and new gradient
    pred_y, cost, gradient = exp_cost_gradient(X, w, y)
    cost_vec[i] = cost

    if(i % 20 == 0):
        print('Iter', i, ': cost =', cost)

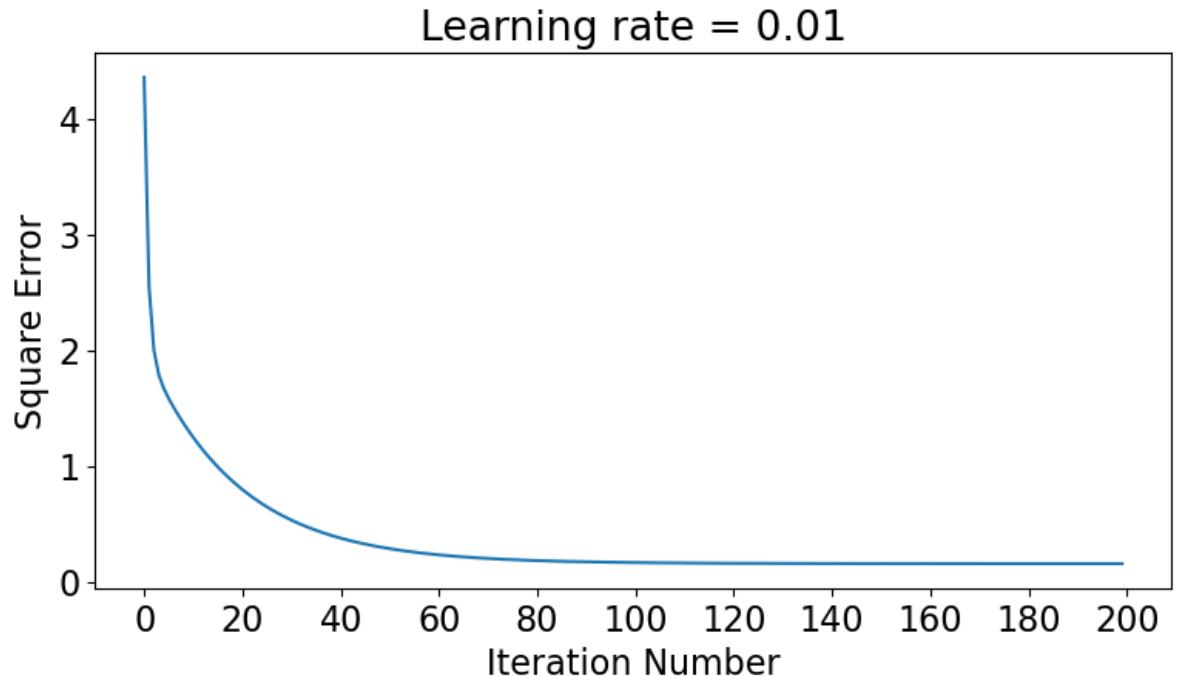
pred_y, cost, gradient = exp_cost_gradient(X, w, y)
print('Final Cost =', cost)
```

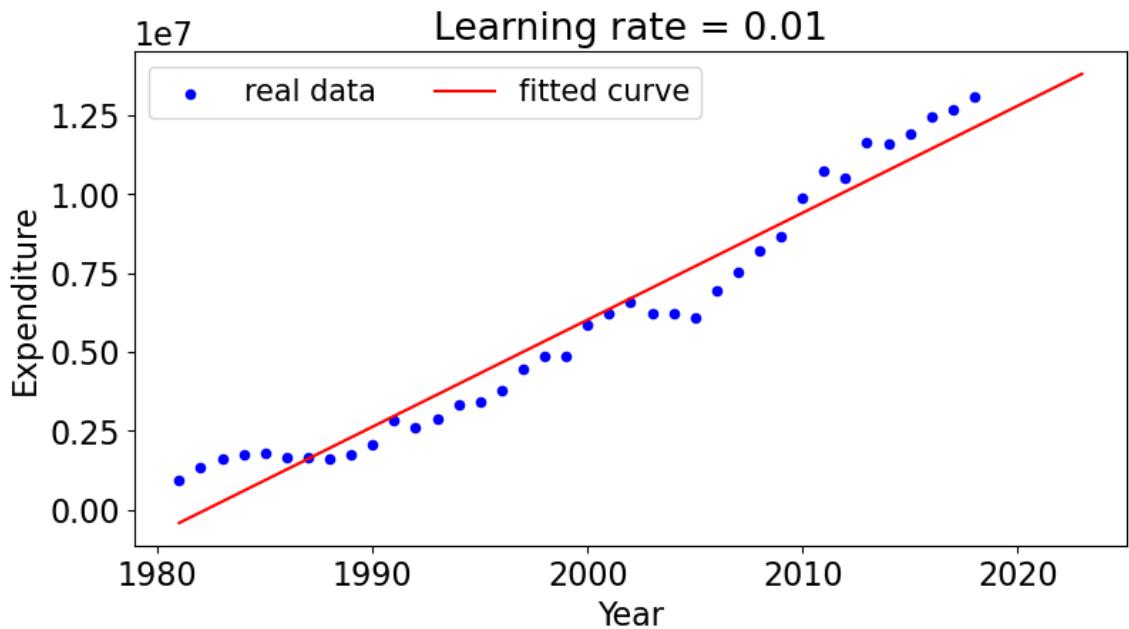
```
Initial Cost = 10.837516320395803
Iter 0 : cost = 4.3543130851728815
Iter 20 : cost = 0.7976577410102698
Iter 40 : cost = 0.37869717216854304
Iter 60 : cost = 0.234492466616192
Iter 80 : cost = 0.18485773091454086
Iter 100 : cost = 0.16777363522753555
Iter 120 : cost = 0.16189335156495857
Iter 140 : cost = 0.1598693792935628
Iter 160 : cost = 0.15917273539159435
Iter 180 : cost = 0.15893295309170388
Final Cost = 0.1588527935553728
```

In [18]:

```
1 # Plot cost function values over iterations
2 plt.figure(0, figsize=[9,4.5])
3 plt.rcParams.update({'font.size': 16})
4 plt.plot(np.arange(0, num_iters, 1), cost_vec)
5 plt.xlabel('Iteration Number')
6 plt.ylabel('Square Error')
7 plt.xticks(np.arange(0, num_iters+1, 20))
8 plt.title('Learning rate = ' + str(learning_rate))
9 #plt.savefig('FigTut1Cost' + str(learning_rate) + '.eps')
10
11 # Extrapolate until year 2023
12 ext_years = np.arange(min_year, 2024, 1)
13 ext_X = np.ones([len(ext_years), 2])
14 ext_X[:, 1] = (ext_years-min_year)/(max_year-min_year)
15 pred_y = ext_X @ w # model-dependent
16
17 # Plot extrapolation
18 plt.figure(1, figsize=[9,4.5])
19 plt.rcParams.update({'font.size': 16})
20 plt.scatter(years, expenditure, s=20, marker='o', c='blue', label='real data')
21 plt.plot(ext_years, pred_y * max_expenditure, c='red', label='fitted curve')
22 plt.xlabel('Year')
23 plt.ylabel('Expenditure')
24 plt.title('Learning rate = ' + str(learning_rate))
25 plt.legend(loc='upper left', ncol=3, fontsize=15)
```

Out[18]: <matplotlib.legend.Legend at 0x1aa72f39130>





**NUS Engineering EE4400**  
**Tutorial 1 Q2: Back Propagation**  
(CK Tham, ECE NUS)

I. Formulas

1. General

$$g(x) = \frac{1}{1 + e^{-x}}$$

$$g'(x) = g(x) * (1 - g(x))$$

2. Backward Pass

$$E = \frac{1}{2} \sum_k (d_k - y_k)^2$$

$$\frac{\partial E}{\partial y_k} = (y_k - d_k)$$

(a) Output Layer - node  $k$

$$E = \frac{1}{2} \sum_k (d_k - y_k)^2 \text{ across all output nodes (for 1 training pattern)}$$

$$y_k = g(\text{net}_k) \text{ where } \text{net}_k = \sum_j w_{jk} y_j$$

$$\frac{\partial E}{\partial y_k} = (y_k - d_k)$$

$$\delta_k = \frac{\partial E}{\partial \text{net}_k} = \frac{\partial E}{\partial y_k} \cdot \frac{\partial y_k}{\partial \text{net}_k} = (y_k - d_k) \cdot g'(\text{net}_k)$$

$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial E}{\partial \text{net}_k} \cdot \frac{\partial \text{net}_k}{\partial w_{jk}} = \delta_k \cdot y_j$$

$$\Delta w_{jk} = -\eta \frac{\partial E}{\partial w_{jk}}$$

(b) Hidden Layer - node  $j$  (summation of  $\delta_k$  over output nodes  $k$ )

$$\frac{\partial E}{\partial y_j} = \sum_k \left( \frac{\partial E}{\partial \text{net}_k} \cdot \frac{\partial \text{net}_k}{\partial y_j} \right) = \sum_k (\delta_k \cdot w_{jk})$$

$$\delta_j = \frac{\partial E}{\partial \text{net}_j} = \frac{\partial E}{\partial y_j} \cdot \frac{\partial y_j}{\partial \text{net}_j} = \frac{\partial E}{\partial y_j} \cdot g'(\text{net}_j)$$

$$\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial \text{net}_j} \cdot \frac{\partial \text{net}_j}{\partial w_{ij}} = \delta_j \cdot y_i$$

$$\Delta w_{ij} = -\eta \frac{\partial E}{\partial w_{ij}}$$

## II. Application to Specific Scenario

### 1. Forward Pass

$$\begin{aligned}
net_{h1} &= w_1 * i_1 + w_2 * i_2 + b_1 = 0.360 \\
y_{h1} &= g(net_{h1}) = 0.589 \\
net_{h2} &= w_3 * i_1 + w_4 * i_2 + b_2 = 0.881 \\
y_{h2} &= g(net_{h2}) = 0.707 \\
net_{o1} &= w_5 * y_{h1} + w_6 * y_{h2} + b_3 = 0.447 \\
y_{o1} &= g(net_{o1}) = 0.610 \\
net_{o2} &= w_7 * y_{h1} + w_8 * y_{h2} + b_4 = 0.408 \\
y_{o2} &= g(net_{o2}) = 0.601
\end{aligned}$$

### 2. Backward Pass

#### (a) Error

$$E_{total} = \frac{1}{2} \sum_k (d_k - y_k)^2 = 0.209$$

where  $d_k = target_{ok}$  and  $y_k = y_{ok}$

#### (b) Output Layer

##### (i) Weight $w_5$ between node h1 and node o1

$$\begin{aligned}
\frac{\partial E}{\partial y_{o1}} &= (y_{o1} - d_{o1}) = -0.340 \\
\delta_{o1} &= \frac{\partial E}{\partial net_{o1}} = \frac{\partial E}{\partial y_{o1}} \cdot \frac{\partial y_{o1}}{\partial net_{o1}} = (y_{o1} - d_{o1}) \cdot g'(net_{o1}) = -0.081 \\
\frac{\partial E}{\partial w_5} &= \frac{\partial E}{\partial net_{o1}} \cdot \frac{\partial net_{o1}}{\partial w_5} = \delta_{o1} \cdot y_{h1} = -0.048 \\
\Delta w_5 &= -\eta \frac{\partial E}{\partial w_5} = 0.005
\end{aligned}$$

##### (ii) Weight $w_7$ between node h1 and node o2

$$\begin{aligned}
\frac{\partial E}{\partial y_{o2}} &= (y_{o2} - d_{o2}) = 0.551 \\
\delta_{o2} &= \frac{\partial E}{\partial net_{o2}} = \frac{\partial E}{\partial y_{o2}} \cdot \frac{\partial y_{o2}}{\partial net_{o2}} = (y_{o2} - d_{o2}) \cdot g'(net_{o2}) = 0.132 \\
\frac{\partial E}{\partial w_7} &= \frac{\partial E}{\partial net_{o2}} \cdot \frac{\partial net_{o2}}{\partial w_7} = \delta_{o2} \cdot y_{h1} = 0.078 \\
\Delta w_7 &= -\eta \frac{\partial E}{\partial w_7} = -0.008
\end{aligned}$$

(c) Hidden Layer

For node h1, summation of  $\delta_k$  over output nodes  $k$ , i.e. o1 and o2.

(i) Weight  $w_1$  between input i1 and node h1

$$\begin{aligned}\frac{\partial E}{\partial y_{h1}} &= \sum_k \left( \frac{\partial E}{\partial net_k} \cdot \frac{\partial net_k}{\partial y_{h1}} \right) = \sum_k (\delta_k \cdot w_{jk}) = 0.019 \\ \delta_{h1} &= \frac{\partial E}{\partial net_{h1}} = \frac{\partial E}{\partial y_{h1}} \cdot \frac{\partial y_{h1}}{\partial net_{h1}} = \frac{\partial E}{\partial y_{h1}} \cdot g'(net_{h1}) = 0.005 \\ \frac{\partial E}{\partial w_1} &= \frac{\partial E}{\partial net_{h1}} \cdot \frac{\partial net_{h1}}{\partial w_1} = \delta_{h1} \cdot y_{i1} = 4.703 \times 10^{-4} \\ \Delta w_1 &= -\eta \frac{\partial E}{\partial w_1} = -4.703 \times 10^{-5}\end{aligned}$$