
Software Platforms for Automotive Systems

Lecture 1: Introduction

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What do you know about cars?

- How many processors are there in a modern car?
- What is an ECU and an OEM?
- How many kilometers of cable are there?
- How long is the product life cycle of a car?
- How many lines of codes?

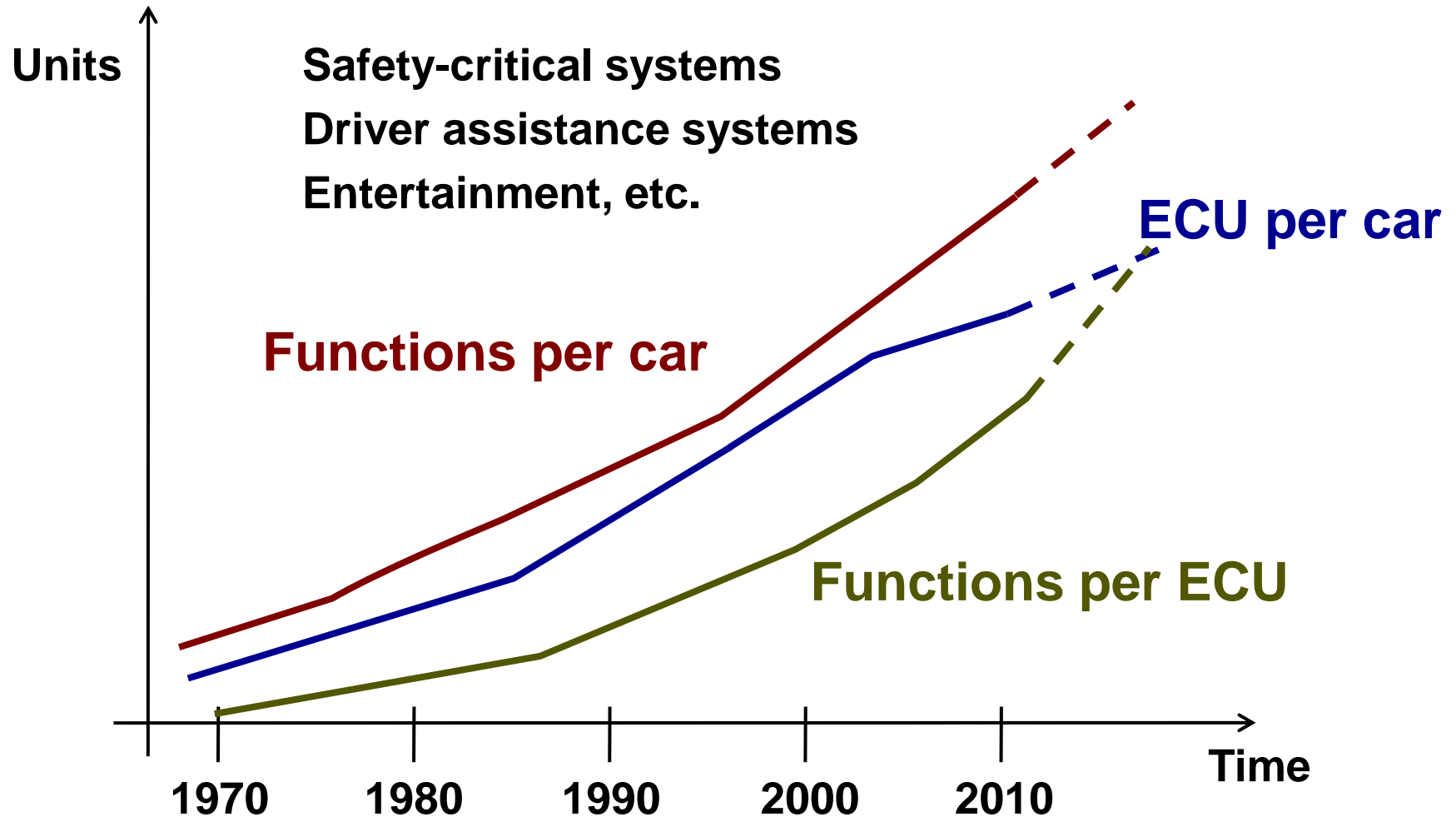


Source: Audi AG

Automotive Companies

- **OEM: Original Equipment Manufacturer**
 - Companies which develop cars
 - BMW, Audi, Toyota, Ford, etc.
- **Tier 1 providers (develop automotive systems)**
 - Bosch, Continental, Delphi, etc.
- **Tier 2 providers (develop processors chips, etc.)**
 - Freescale, Infineon, etc.
- **Tool providers (develop automotive software tools)**
 - dSpace, Vektor, Mentor Graphics, etc.

Trend in Automotive Systems



The Automotive E/E Architecture

- **All electrical/electronic (E/E) components in a car**
 - **Currently it has a high complexity and a high cost**
 - **Around 100 electronic control units (ECUs)**
 - **Around 10 buses and over 4 Km cable**
 - **Domain-specific technologies, e.g., LIN, FlexRay, etc.**
 - **Over 100 million lines of code**
- **Carrier of most innovation in today's cars**
- **Software has a crucial role**
 - **Trend to even more functionality and complexity**
 - **Need for portability and reusability of software**

Requirements on Car's E/E Systems

- **Harsh environmental conditions**
 - Wide temperature range, high humidity and vibration
 - Electromagnetic interference (EMI)
- **Reliability and availability**
 - Providing required functions in specified time interval
- **Functional Safety**
 - Avoiding potential hazards for passengers and others
- **Relatively long product life cycles**
 - Around 20 to 25 years

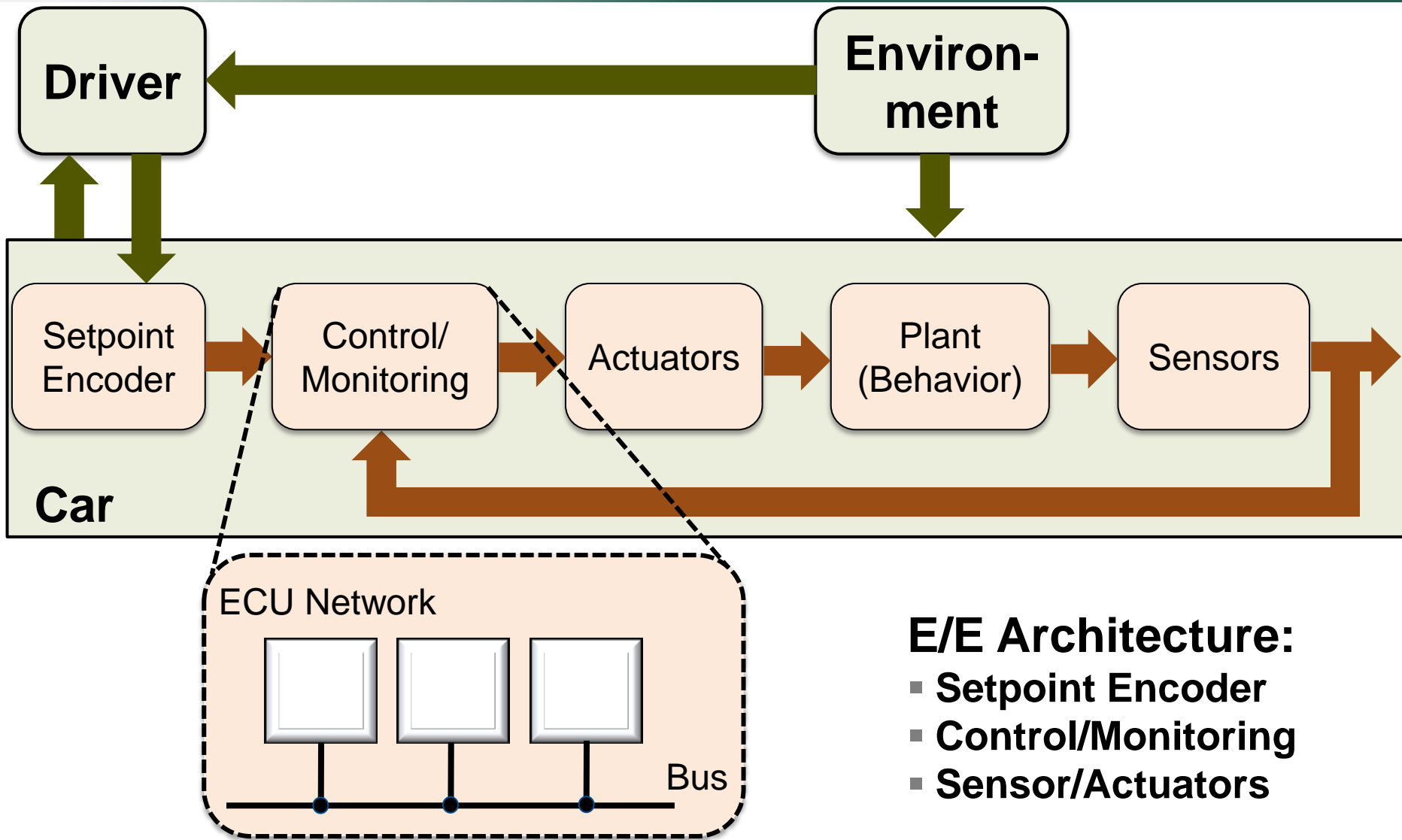
Automotive Software Engineering

- An attempt of definition:

“Systematic use of techniques and tools that support the design and development process with the aim of mastering complexity and achieving efficient and reliable software for the automotive domain.”

- **Efficient in the sense of resources and reusability**
 - ECUs need to be cost-effective and have limited resources
 - A high reusability of software saves costs
- **Reliable because of safety-critical applications**
 - Brakes, airbags, electronic stability program (ESP), etc.
 - Real-time behavior is required most of the time

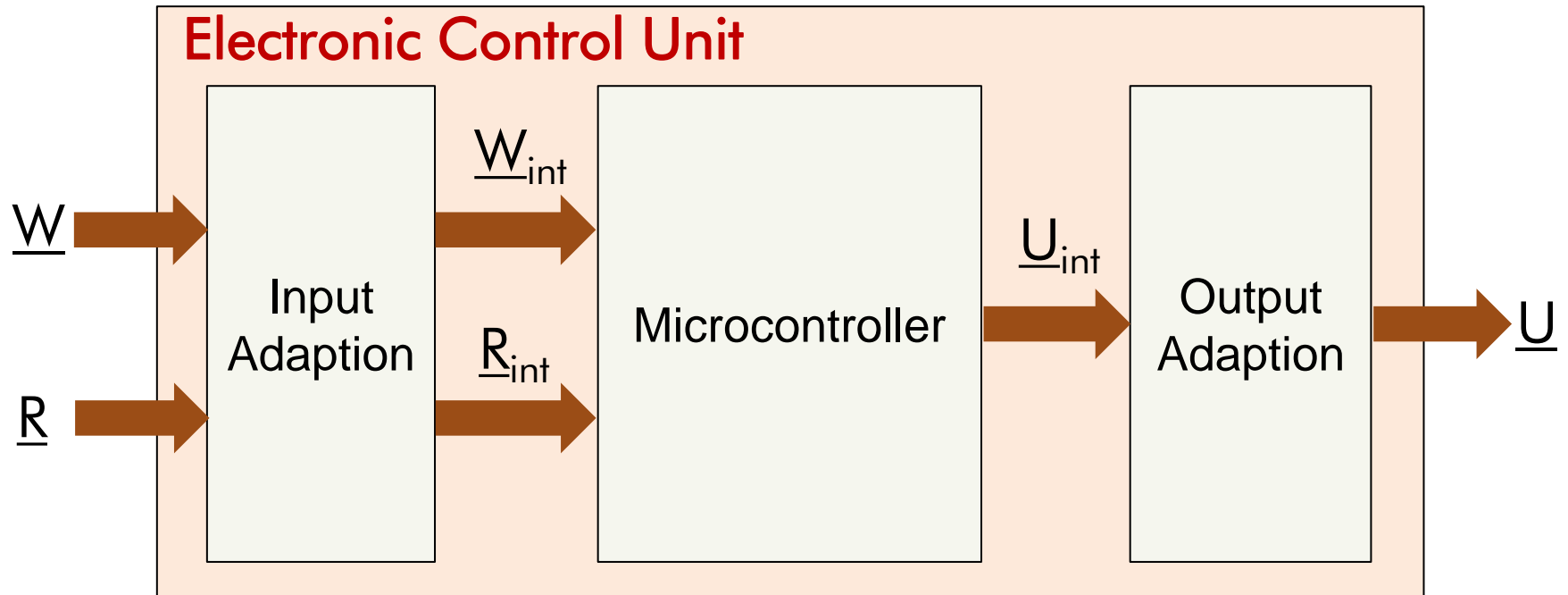
The Driver-Car-Environment System



E/E Architecture:

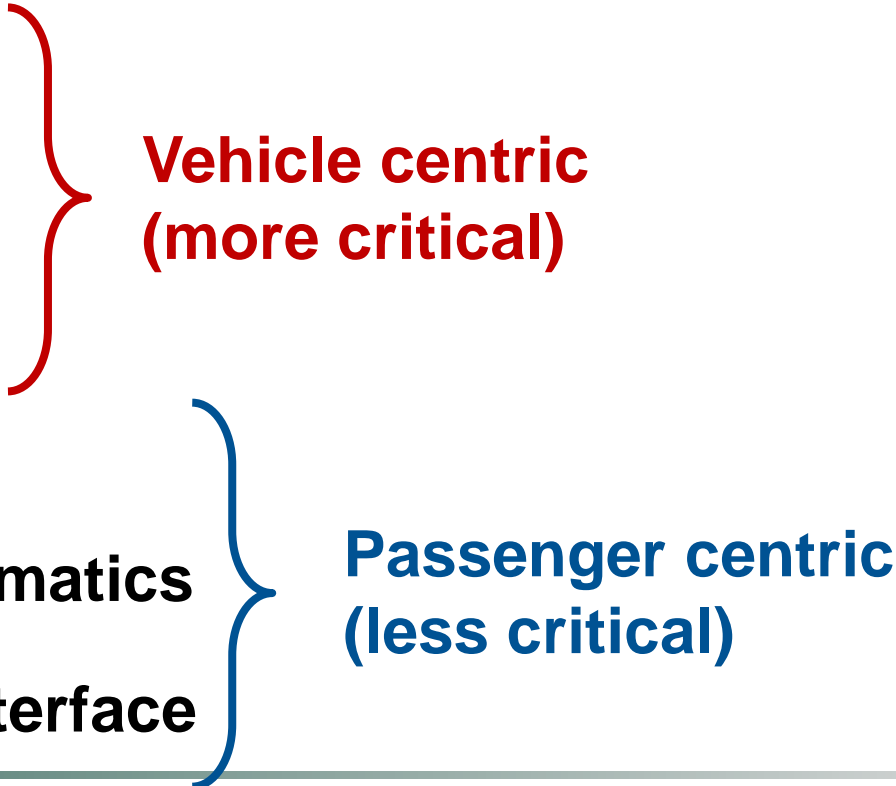
- Setpoint Encoder
- Control/Monitoring
- Sensor/Actuators

What's an ECU?



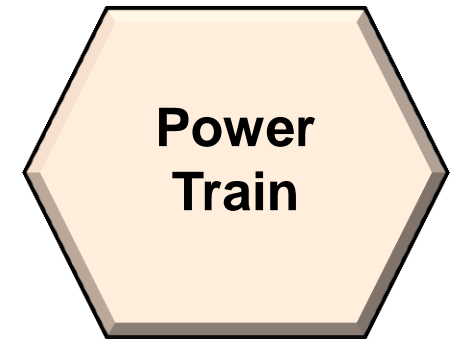
- Input/output adaption
 - Translate voltage and current levels

Automotive Functional Domains

- Functions are divided into 6 main domains
 - Manage complexity of the overall system
 - Different requirements and different technologies
 - Power Train
 - Chassis
 - Safety (passive)
 - Body/Comfort
 - Multimedia/Telematics
 - Man Machine Interface
- Vehicle centric
(more critical)**
- Passenger centric
(less critical)**
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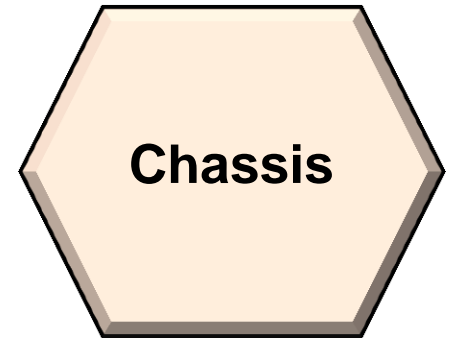
Power Train

- **Concerns the following**
 - Engine, gearbox, driveshaft, crankshaft, etc.
- **Sensors**
 - Throttle position, battery voltage, etc.
- **Actuators**
 - Throttle, ignition plugs, fuel injectors, etc.
- **On-board communication**
 - HS-CAN (High Speed-Controller Area Network)
- **Engine management, gearbox control, etc.**



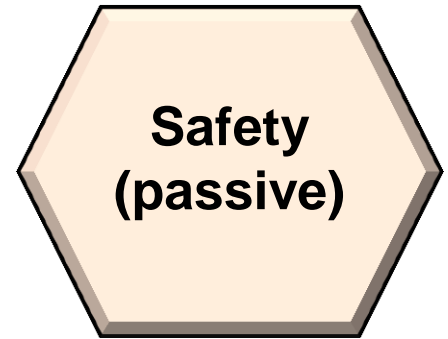
Chassis

- **Concerns the following**
 - Front and back axles, brakes, wheels, etc.
- **Sensors**
 - Wheels' rotational speed, yaw and steer angle, etc.
- **Actuators**
 - Individual brakes at wheels, etc.
- **On-board communication**
 - HS-CAN (High Speed-Controller Area Network)
- **Anti-blocking system, electronic stability program, etc.**



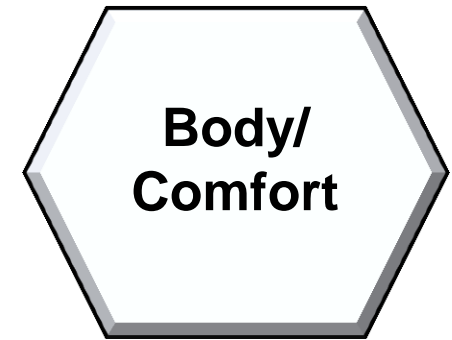
Safety (Passive)

- **Concerns the following**
 - Airbags, seatbelt, etc.
- **Sensors**
 - Collision detectors, seat occupancy, etc.
- **Actuators**
 - Airbag inflation, etc.
- **On-board communication**
 - LS-CAN (Low Speed-Controller Area Network)
- **Airbag control, seatbelt tightener, etc.**



Body/Comfort

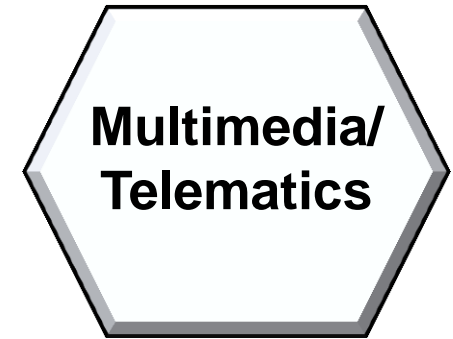
- **Concerns the following**
 - Side mirrors, seats, steering wheel, etc.
- **Sensors**
 - Rain sensor, temperature sensor, etc.
- **Actuators**
 - DC motor actuator for windows and mirrors, heating, etc.
- **On-board communication**
 - LS-CAN (Low Speed-Controller Area Network)
- **Parking assistant, electric windows, etc.**



Remaining Domains

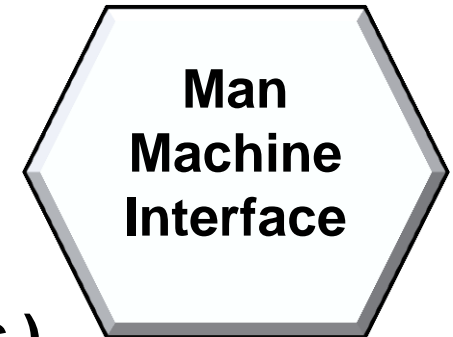
- **Multimedia/Telematics**

- Entertainment: Radio, Video, etc.
- Internet access
- Navigation



- **Man Machine Interface**

- Instrument panel
- Control panel (i.e., buttons, turn-switches, etc.)
- Voice command

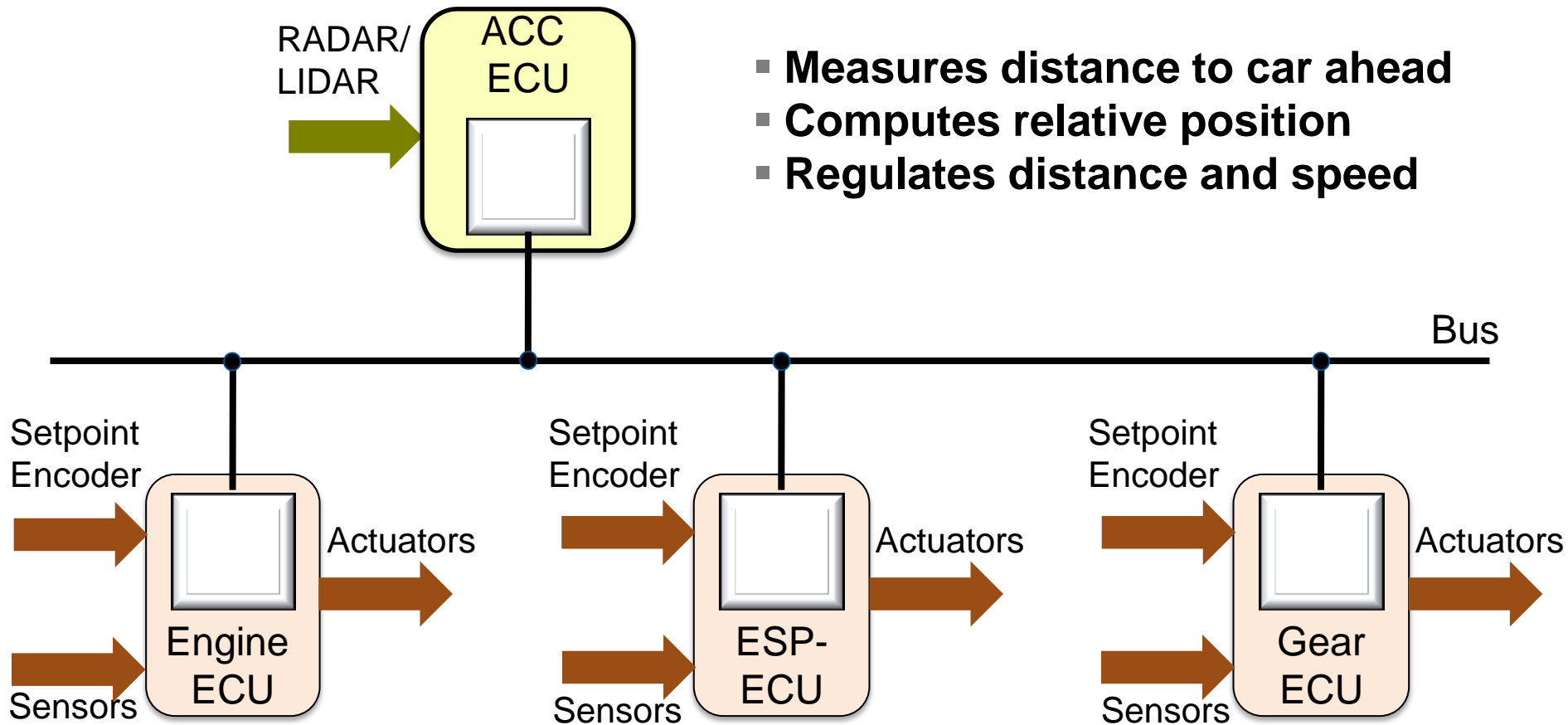


- **On-board communication**

- Mainly MOST (Media Oriented Systems Transport)

Cross-Domain Function

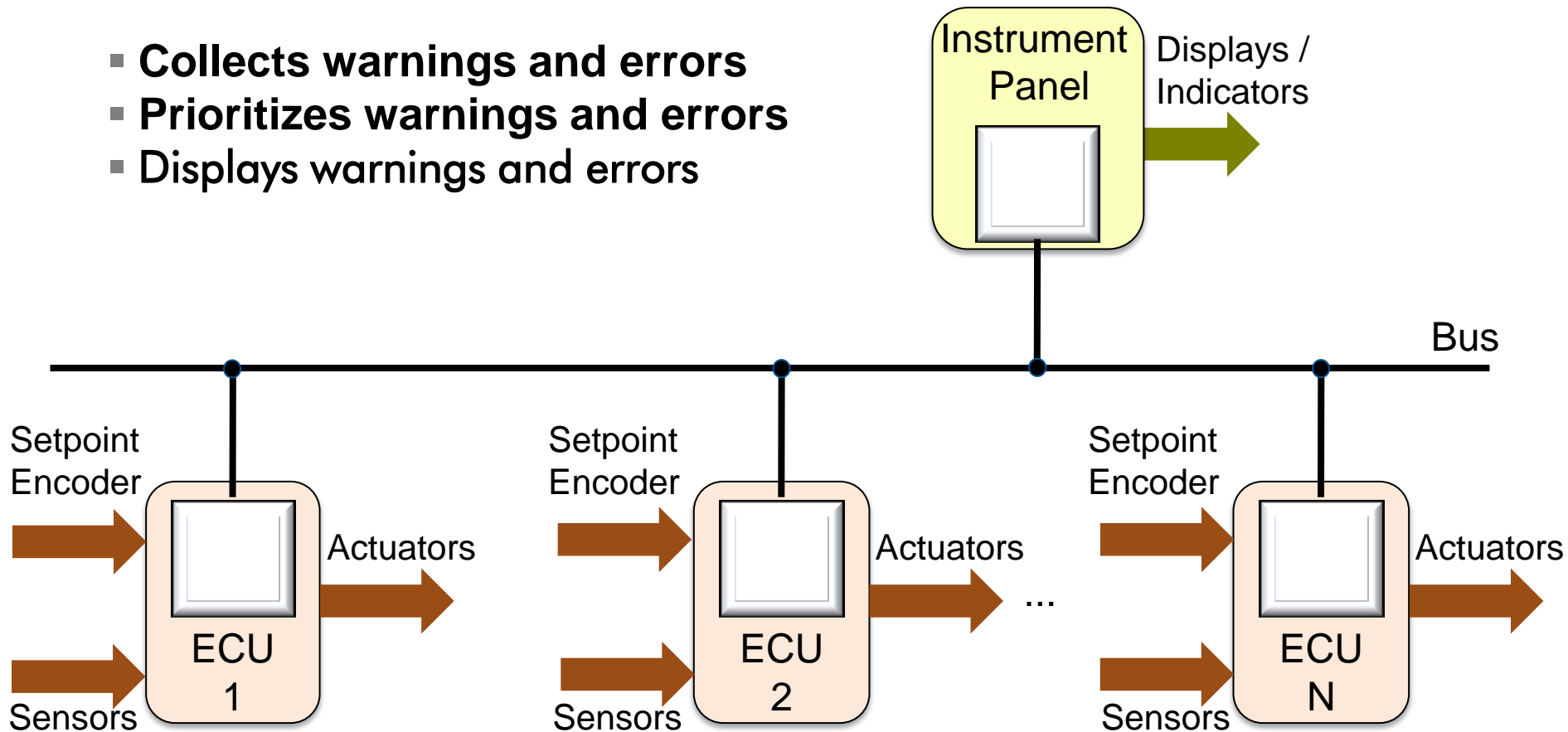
Adaptive cruise control (ACC):



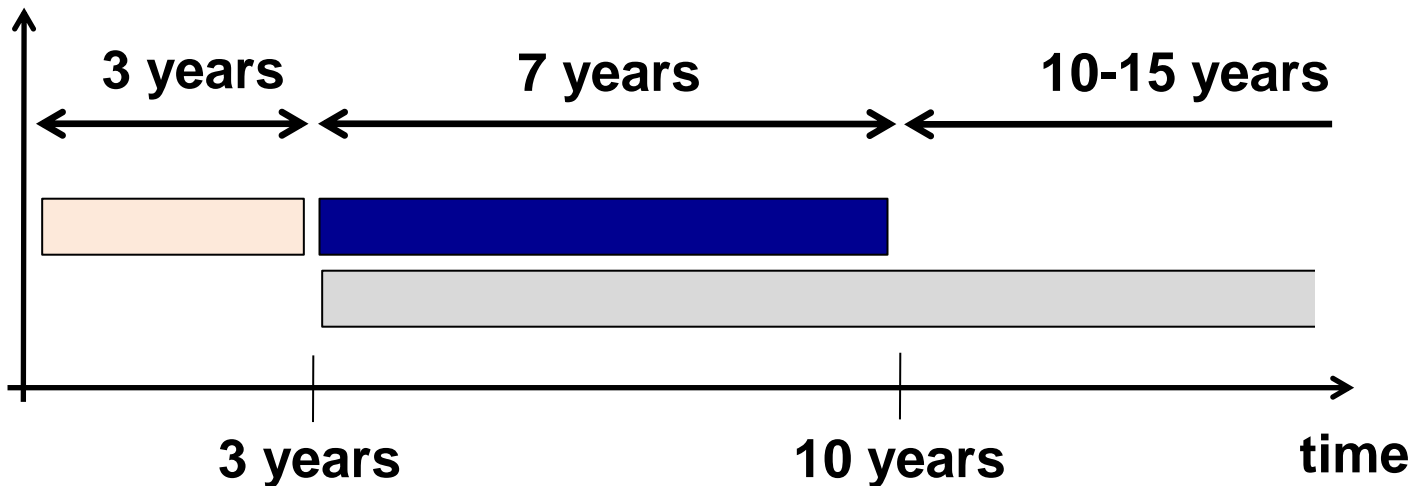
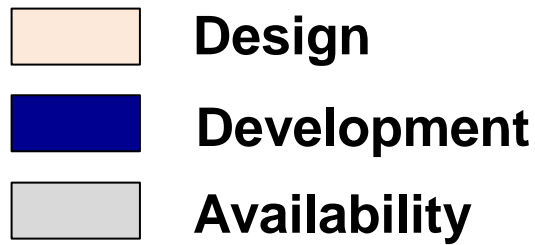
Cross-Domain Function

Instrument Panel Control

- **Collects warnings and errors**
- **Prioritizes warnings and errors**
- **Displays warnings and errors**



Product Life Cycle of a Car

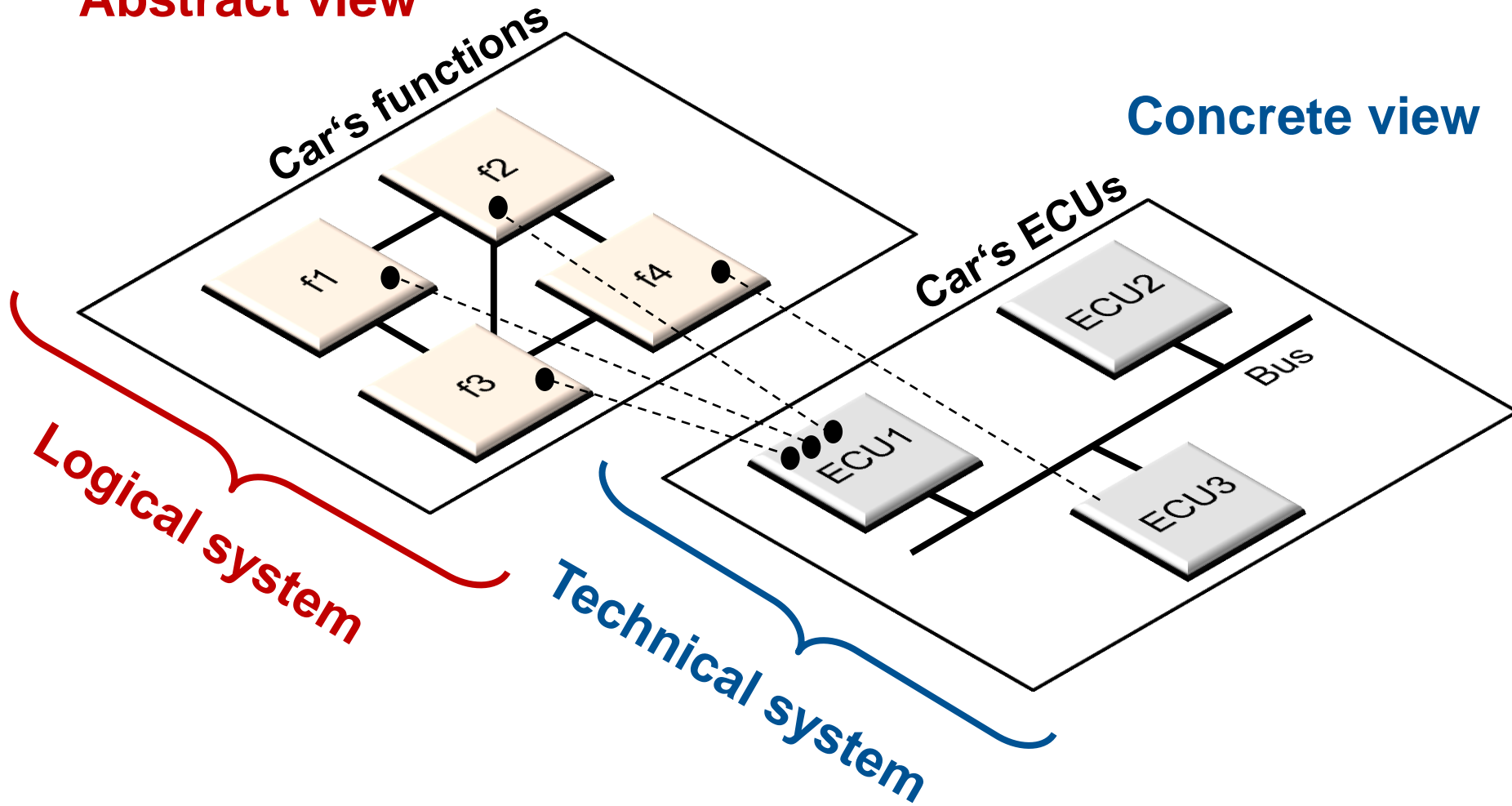


- Puts emphasis on the design
- Technology should be available
- Puts focus on software upgrades

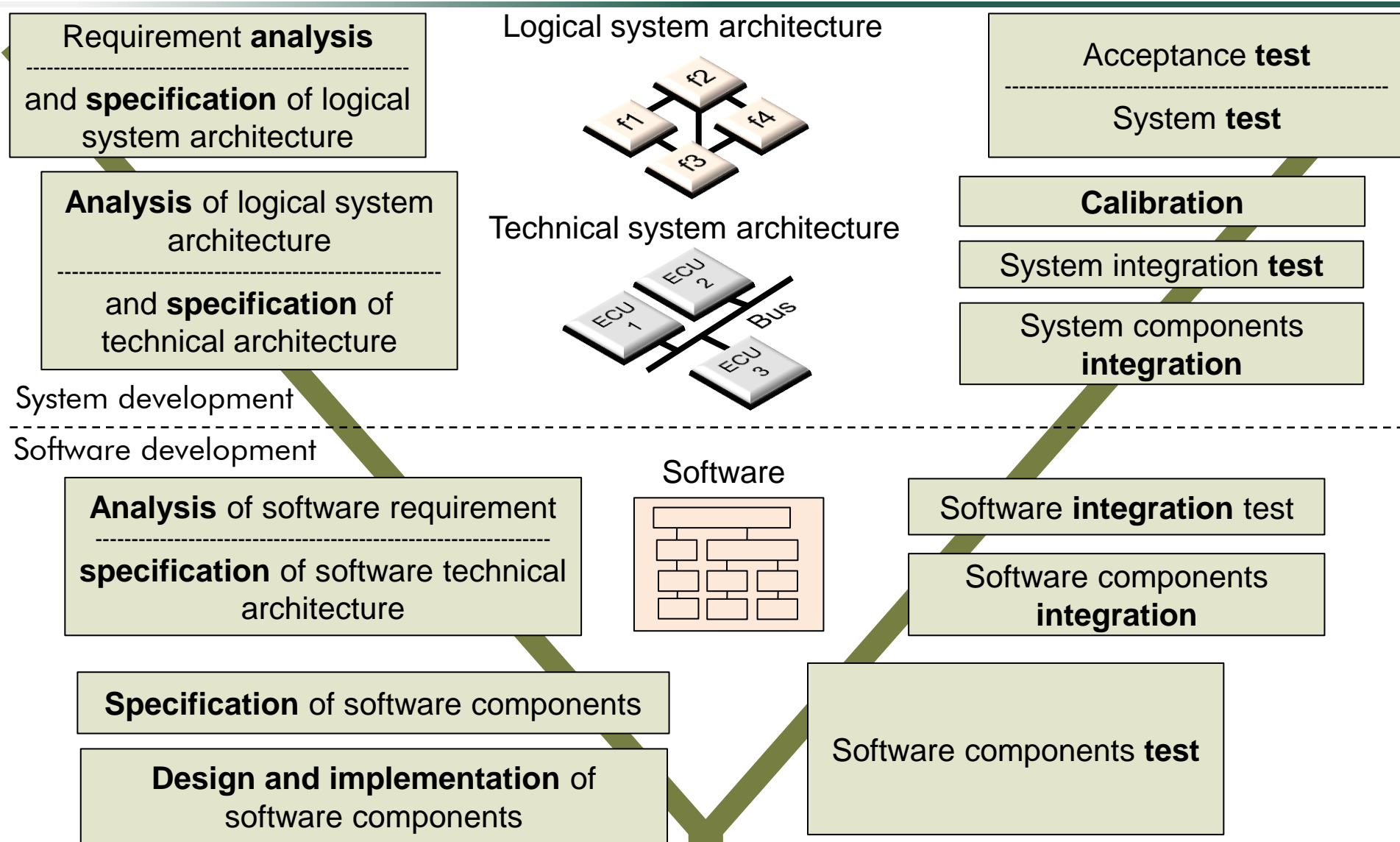
Functions and their Implementation

Abstract view

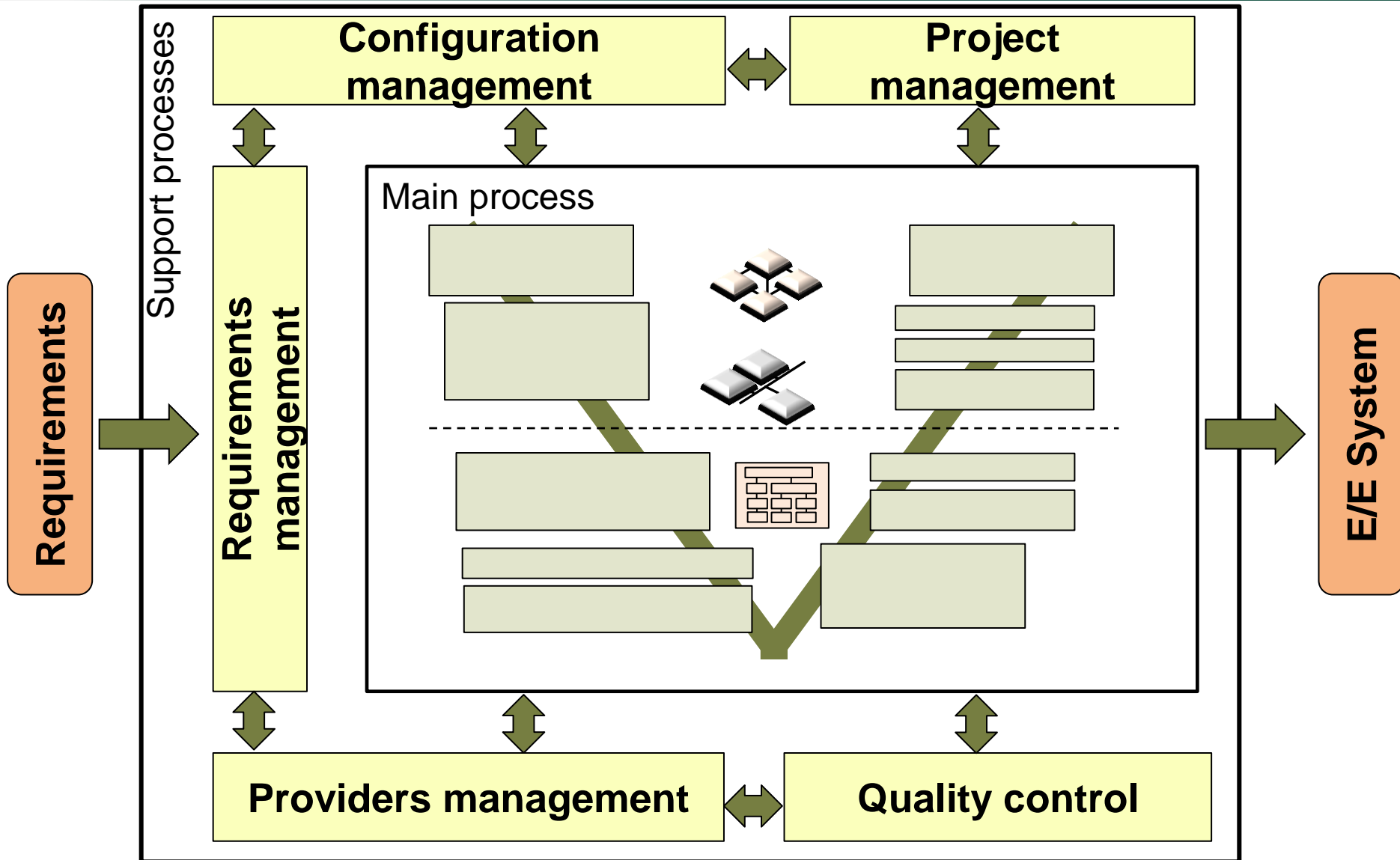
Concrete view



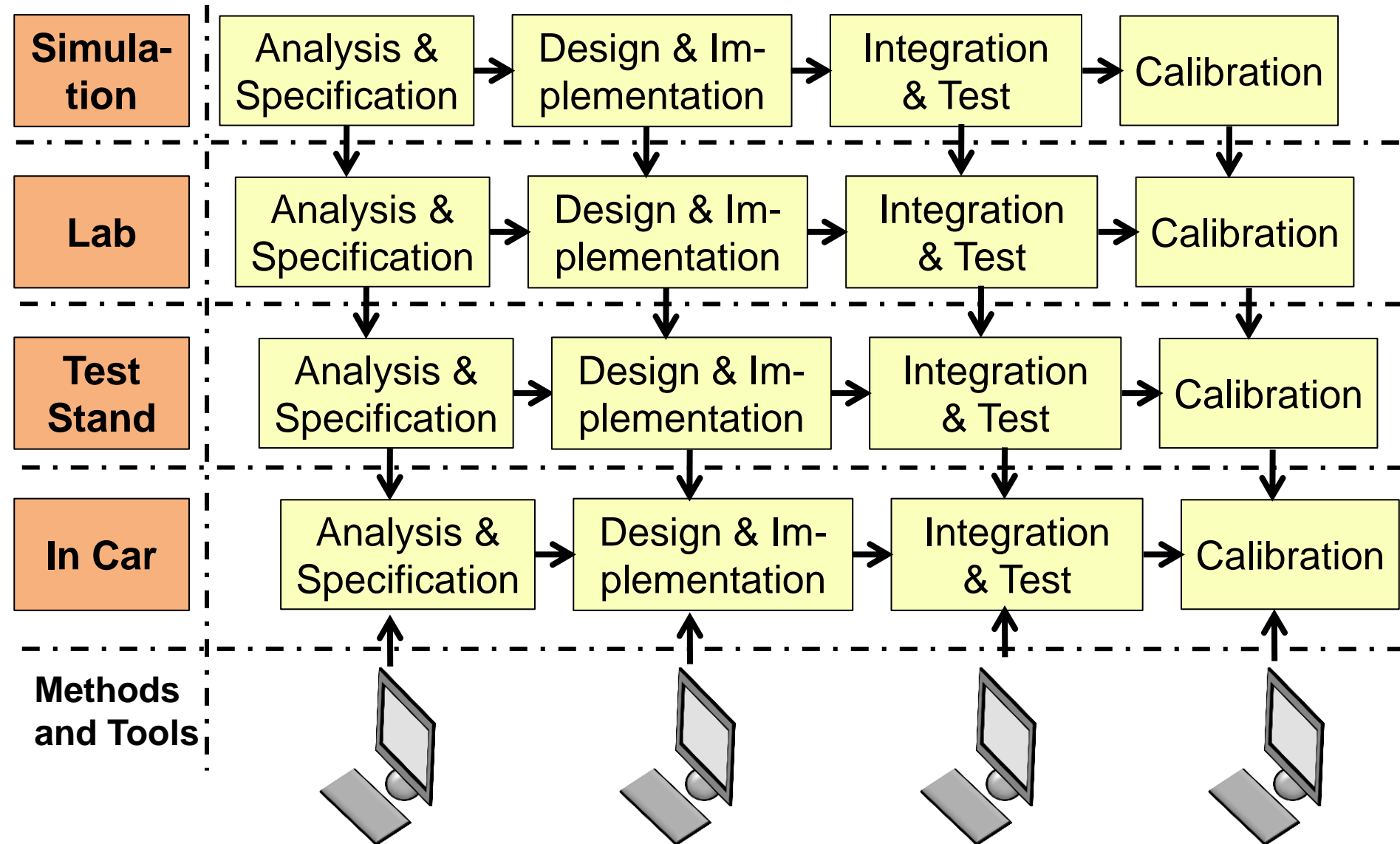
Main Development Process



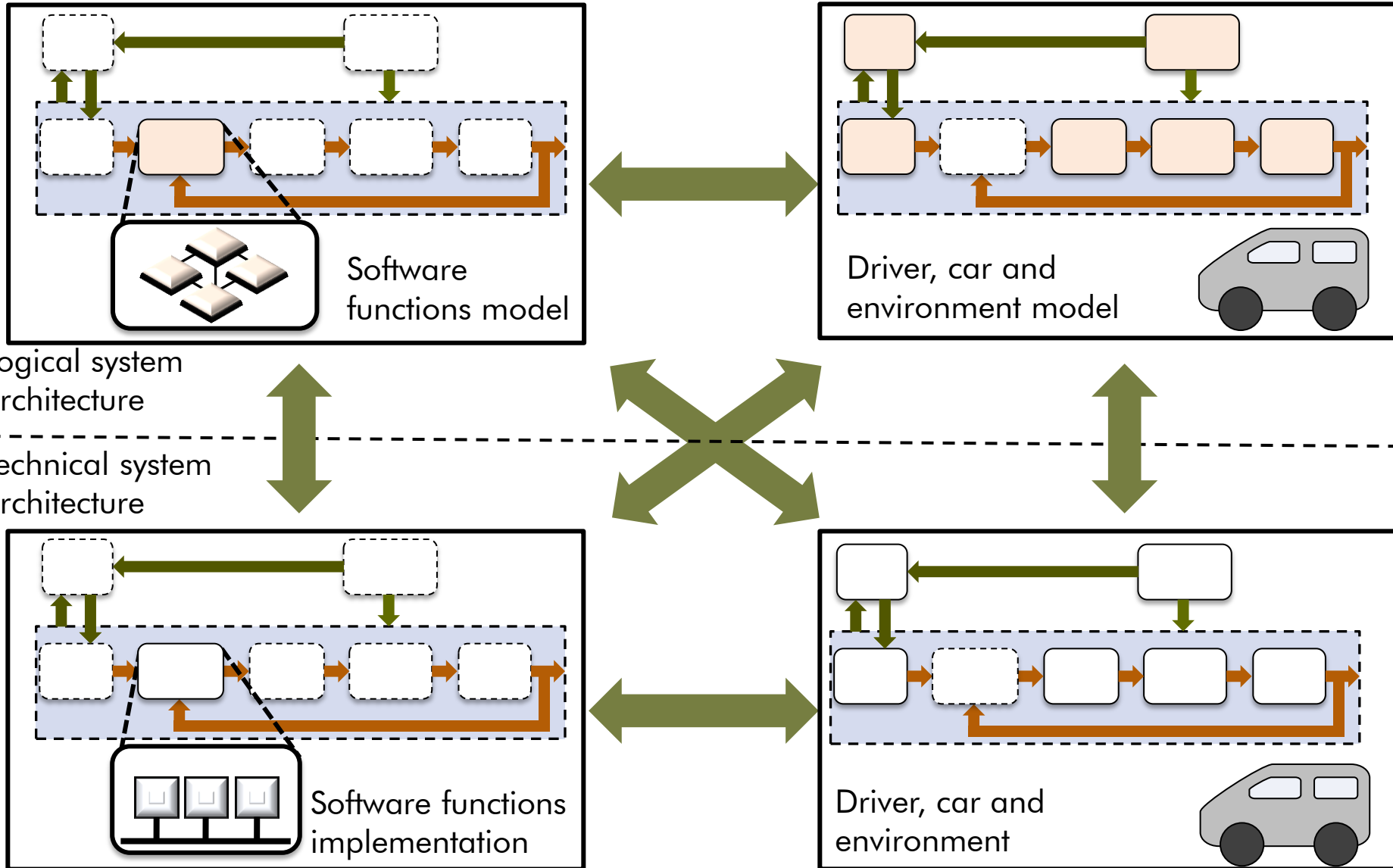
Support Development Process



Simultaneous Engineering

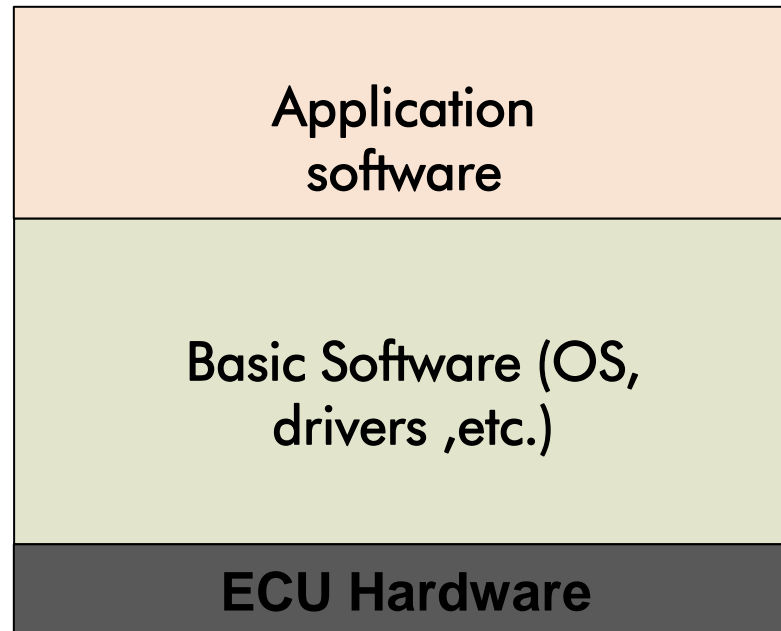


Model-Based Design & Development



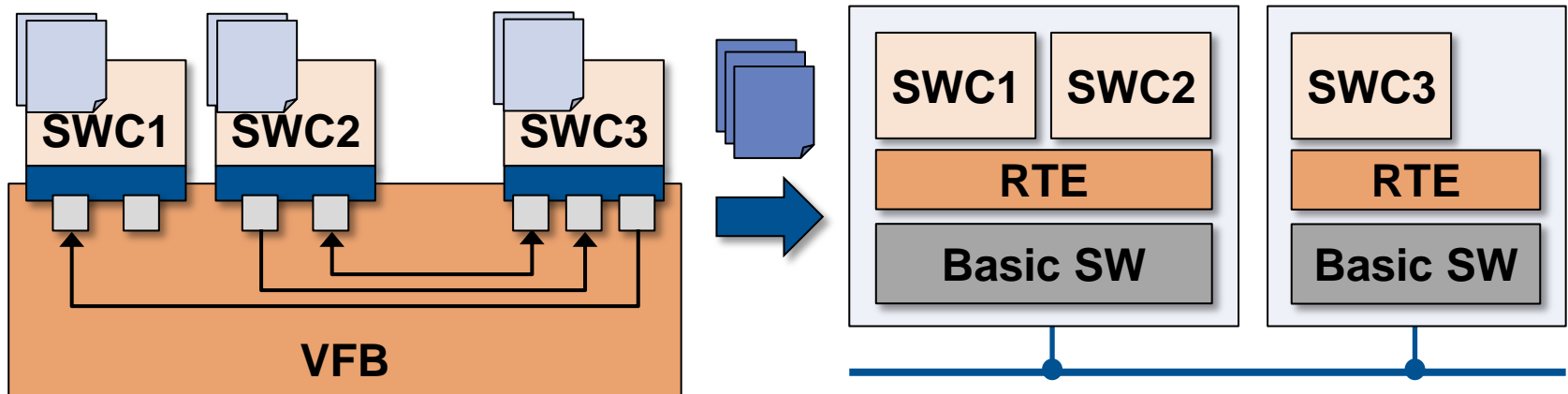
Traditional Software Architecture

- **Application software written for a given platform**
 - **Given operating system (OS), e.g., OSEK-OS**
 - **Given architecture, e.g., PowerPC, ARM, etc.**
 - **It is not portable to other ECUs**

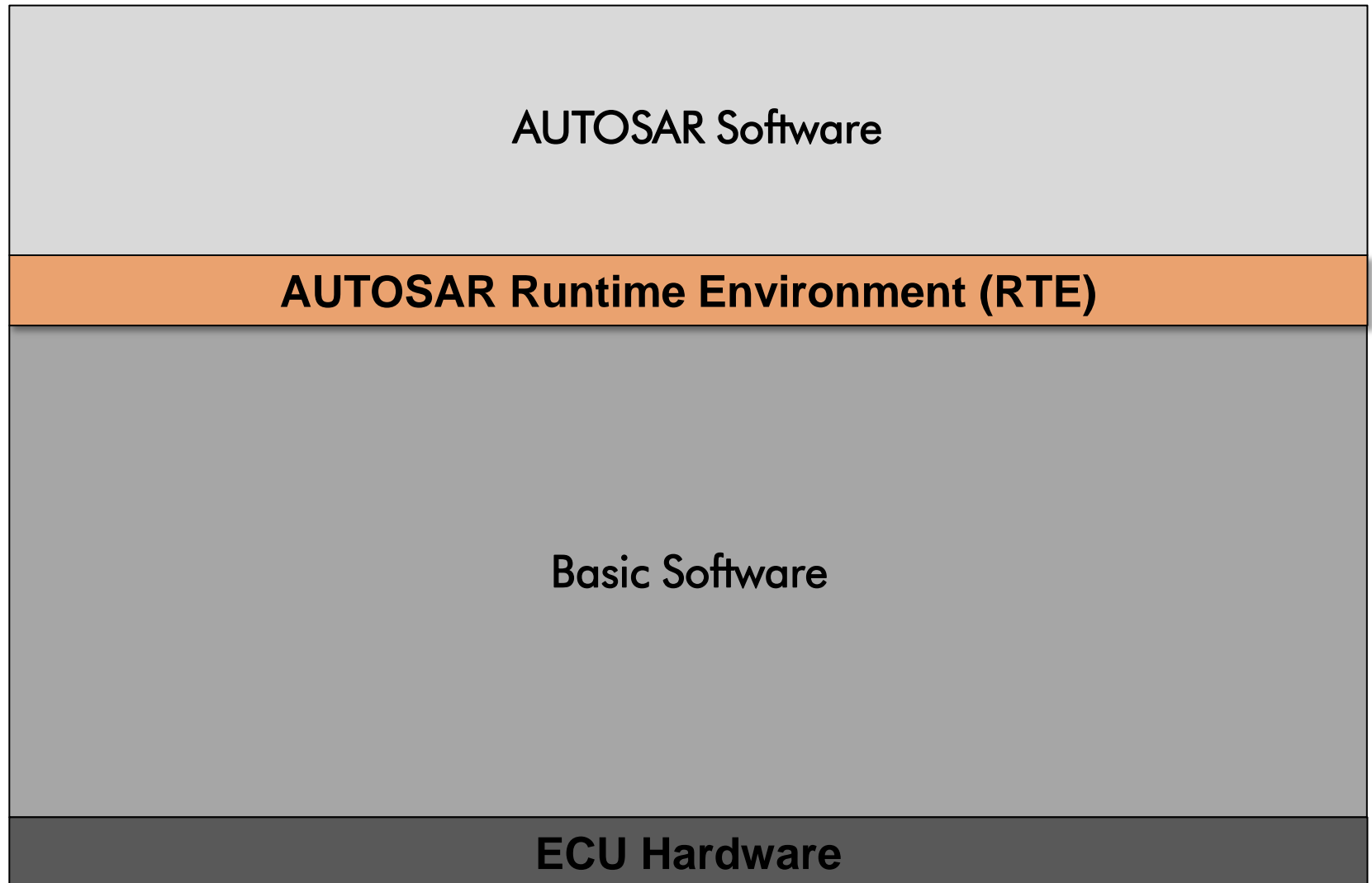


The AUTOSAR Standard

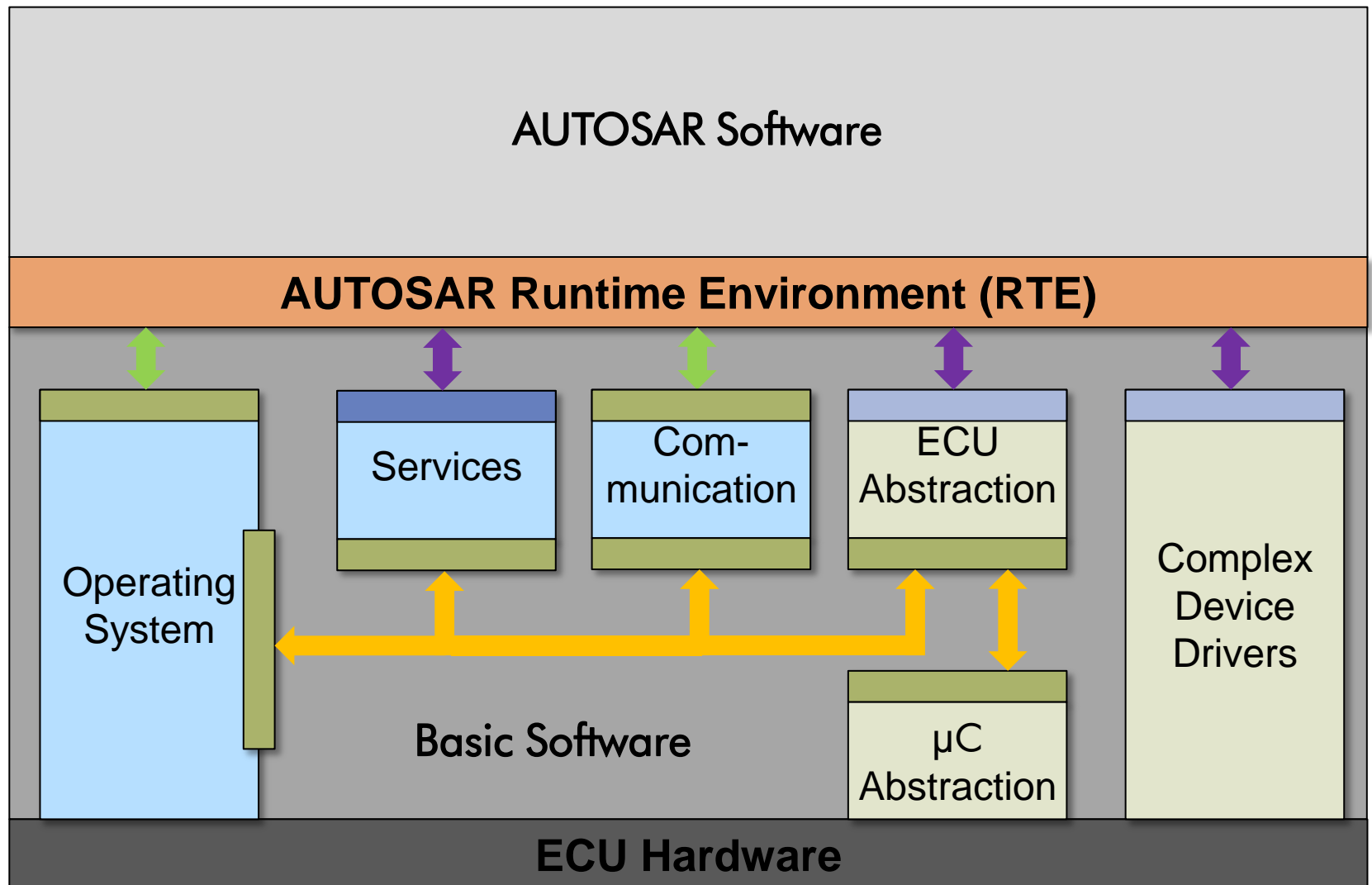
- **AUTomotive Open System Architecture**
 - Manage increasing E/E complexity
 - Improve flexibility and scalability
 - Improve quality and reliability of E/E systems
- **Software Component (SWC)**
- **Virtual Functional Bus (VFB)**



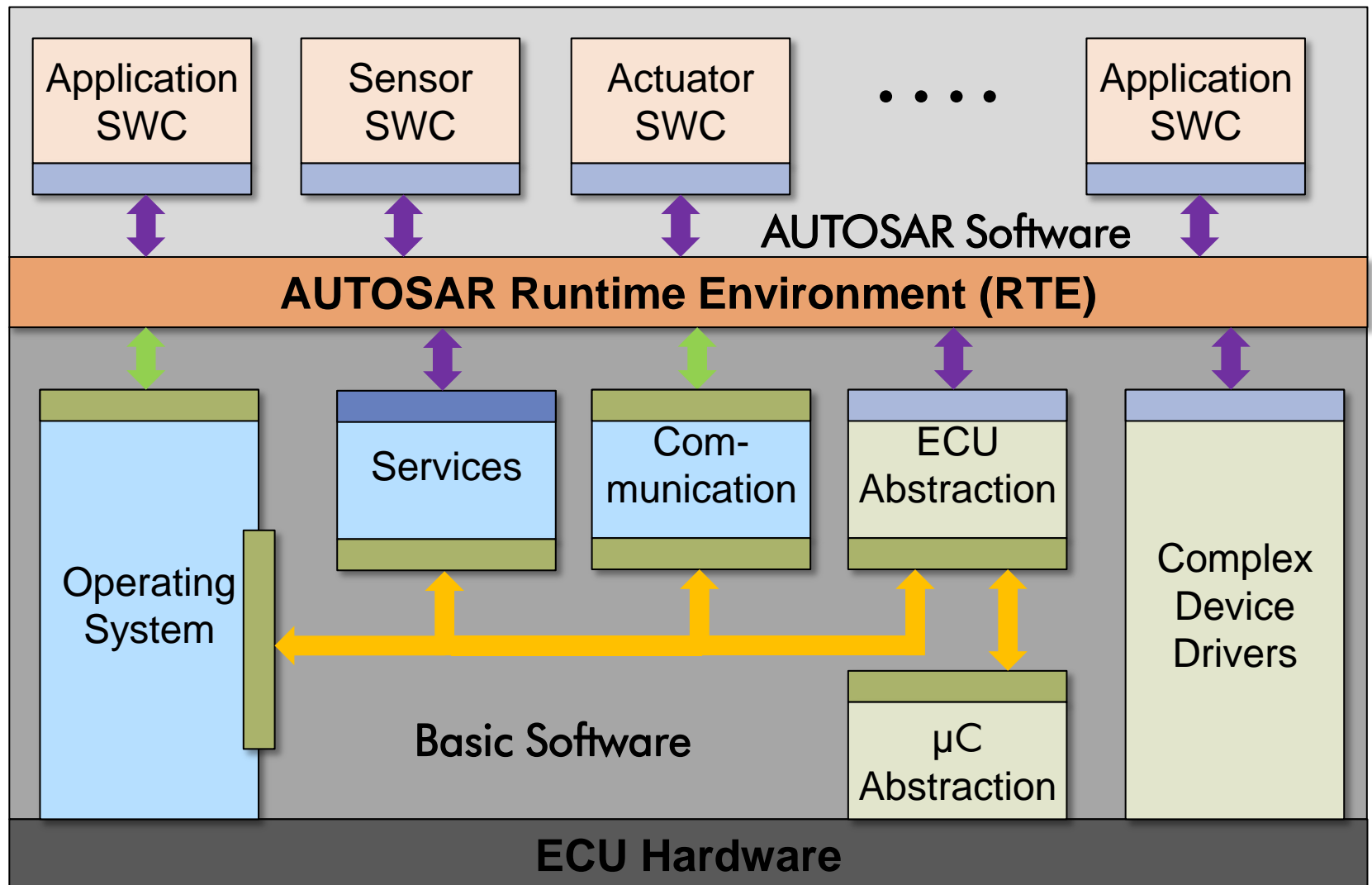
AUTOSAR Software Architecture



AUTOSAR Software Architecture



AUTOSAR Software Architecture



Summary

- **E/E architectures are highly complex**
 - Trend towards more functionality on fewer ECUs
 - Automotive Software need to be efficient and reliable
- **Functional Domains**
 - Vehicle centric: Power Train, Chassis and Safety
 - Passenger centric: Multimedia, Body/Comfort and MMI
- **Long product life cycles of around 25 years**
- **Design and development techniques**
- **The AUTOSAR standard**

Challenges in Automotive Systems

- **Migration to multi-core architectures**
 - Traditionally single core → **big issue for software**
- **Migration from distributed to centralized systems**
 - Need to reduce complexity → **big issue for software**
- **Variant-oriented applications**
 - Sport, comfort variants, etc. → **big issue for software**
- **Car-to-X communication → big issue for software**
- **Electric vehicles, alternative power-train solutions**
- **Autonomous cars → very big issue for software**

What did you learn about cars?

- **How many processors are there in a modern car?**
 - **Around 100 different processors**
- **What is an ECU and an OEM?**
 - **ECU= Electronic Control Unit**
 - **OEM= Original Equipment Manufacturer**
- **How many kilometers of cable are there? → 4 Km**
- **How long is the product life cycle of a car?**
 - **Around 20 to 25 years**
- **How many lines of codes? → Around 100 Million**

Organizational Issues

- **Lecture: every Thursday starting today**
 - From 15:30 hs until 17:00 hs
 - This room: 1/201
- **Different timings for tutorials (see OPAL)**
- **Slides and reading materials available over OPAL**
- **Accompanying book (available in the library):**
 - Title: “Automotive Software Engineering”
 - By J. Schäuffele and T. Zurawka, 4th Edition