

Gi-Cheon Kang

E-mail: gchnkang@gmail.com
Webpage: gicheonkang.com

CURRENT POSITION	Assistant Professor, Ajou University Department of Software and Computer Engineering Directing Human-Centered Embodied Intelligence (HEI) Lab	2026 –
EDUCATION	Seoul National University Ph.D. in Artificial Intelligence <i>Advisor:</i> Byoung-Tak Zhang <i>Thesis:</i> Embodied language agents for real-world robotic tasks: visually-grounded interaction & skill learning	2020 – 2025
	Seoul National University M.S. in Cognitive Science <i>Advisor:</i> Byoung-Tak Zhang	2018 – 2020
	Ajou University B.Eng. in Software and Computer Engineering	2011 – 2018
INTERESTS	Machine Learning, Robot Learning, Embodied & Multimodal AI <ul style="list-style-type: none">• Foundation Models for Robotics: Developing generalist robots by leveraging web-scale knowledge from foundation models• Human-Robot Interaction: Establishing natural, multimodal (verbal & non-verbal) interaction for shared autonomy• Lifelong Robot Learning: Continual skill learning and adaptation through interaction with the real world and humans	
FORMER POSITIONS	Postdoctoral Fellow , SNU AI Institute <i>Project:</i> Vision-language-action (VLA) models for robot manipulation	2025 – 2026
	Student Researcher , NAVER AI <i>Project:</i> Semi-supervised learning for visual dialog	Summer 2022
	Research Assistant , Seoul National University <i>Project:</i> Machine learning for multimodal and embodied AI	2020 – 2025
	Research Intern , SK T-Brain <i>Project:</i> Discovering sparse structures in visual dialog	Winter 2020
HONORS & AWARDS	RSS Pioneers Top 33 early-career researchers in robotics worldwide (acceptance rate: 14%) Youlchon AI Star Fellowship Awarded to 10 PhD students for excellence in core AI research IPAI Ph.D. Fellowship Daeha Scholarship 3rd Place, Visual Dialog Challenge @ CVPR 2019 Software-Centered University Hackathon, Prize from Microsoft Korea Yeoju Honor Scholarship	2025 2024 2024 2022 2019 2017 2016

SELECTED PUBLICATIONS

(* denotes equal contribution)

PEER-REVIEWED CONFERENCE PAPERS

[1] Continual Vision-and-Language Navigation

Seongjun Jeong, Gi-Cheon Kang, Seongho Choi, Joochan Kim, Byoung-Tak Zhang
The British Machine Vision Conference (BMVC), 2025

[2] CLIP-RT: Learning Language-Conditioned Robotic Policies from Natural Language Supervision

Gi-Cheon Kang*, Junghyun Kim*, Kyuhwan Shim, Jun Ki Lee, Byoung-Tak Zhang
Robotics: Science and Systems (RSS), 2025 (Oral)

[3] Socratic Planner: Self-QA-Based Zero-Shot Planning for Embodied Instruction Following

Suyeon Shin, Sujin Jeon*, Junghyun Kim*, Gi-Cheon Kang*, Byoung-Tak Zhang
IEEE International Conference on Robotics and Automation (ICRA), 2025

[4] PGA: Personalizing Grasping Agents with Single Human-Robot Interaction

Junghyun Kim, Gi-Cheon Kang*, Jaein Kim*, Seoyoon Yang, Minjoon Jung, Byoung-Tak Zhang
IEEE/RSJ International Conference on Intelligent Robots and Systems, (IROS), 2024

[5] PROGrasp: Pragmatic Human-Robot Communication for Object Grasping

Gi-Cheon Kang, Junghyun Kim, Jaein Kim, Byoung-Tak Zhang
IEEE International Conference on Robotics and Automation (ICRA), 2024 (Oral)

[6] The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training

Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang
IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2023

[7] GVCCI: Lifelong Learning of Visual Grounding for Language-Guided Robotic Manipulation

Junghyun Kim, Gi-Cheon Kang*, Jaein Kim*, Suyeon Shin, Byoung-Tak Zhang
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023 (Oral)

[8] Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer

Gi-Cheon Kang, Junseok Park, Hwaran Lee, Byoung-Tak Zhang*, Jin-Hwa Kim*
Findings of Empirical Methods in Natural Language Processing (EMNLP Findings), 2021

[9] Attend What You Need: Motion-Appearance Synergistic Networks for Video Question Answering

Ahjeong Seo, Gi-Cheon Kang, Joonhan Park, Byoung-Tak Zhang
Annual Meeting of the Association for Computational Linguistics (ACL), 2021

[10] Label Propagation Adaptive Resonance Theory for Semi-Supervised Continuous Learning

Taehyeong Kim, Injune Hwang, Gi-Cheon Kang, Won-Seok Choi, Hyunseo Kim, Byoung-Tak Zhang
IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2020

[11] Dual Attention Networks for Visual Reference Resolution in Visual Dialog

Gi-Cheon Kang, Jaeseo Lim, Byoung-Tak Zhang
Conference on Empirical Methods in Natural Language Processing (EMNLP), 2019
ICCV Workshop on Video Turing Test (VTT), 2019 (Spotlight)

WORKSHOP PAPERS

- [12] **Language-Driven Robotics: Learning and Interaction**
Gi-Cheon Kang
RSS Pioneers Workshop (RSSW), 2025
- [13] **Generative Self-training Improves Pre-training for Visual Dialog**
Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang
ICML Workshop on Pre-training: Perspectives, Pitfalls, and Paths Forward (ICMLW), 2022
- [14] **Improving Robustness to Texture Bias via Shape-focused Augmentation**
Sangjun Lee, Inwoo Hwang, Gi-Cheon Kang, Byoung-Tak Zhang
CVPR Workshop on Human-centered Intelligent Services: Safety and Trustworthy (CVPRW), 2022
- [15] **C^3 : Contrastive Learning for Cross-domain Correspondence in Few-shot Image Generation**
Hyukgi Lee, Gi-Cheon Kang, Chang-Hoon Jeong, Hanwool Sul, Byoung-Tak Zhang
NeurIPS Workshop on Controllable Generative Modeling in Language and Vision (NeurIPSW), 2021
- [16] **Contextualized Bilinear Attention Networks**
Gi-Cheon Kang, Seonil Son, Byoung-Tak Zhang
ECCV Workshop on VizWiz Grand Challenge (ECCVW), 2018

SERVICES	Reviewing	
	Conference on Neural Information Processing Systems (NeurIPS)	2023 – 2025
	International Conference on Machine Learning (ICML)	2024 – 2025
	International Conference on Learning Representations (ICLR)	2024 – 2026
	IEEE Transactions on Robotics (T-RO)	2025
	IEEE Robotics and Automation Letters (RA-L)	2024
	IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	2024
	AAAI Conference on Artificial Intelligence (AAAI)	2025
	ACL Rolling Review (ARR)	2024 – 2025
	Annual Meeting of the Association for Computational Linguistics (ACL)	2023 – 2024
	Empirical Methods in Natural Language Processing (EMNLP)	2022 – 2023

INVITED TALKS		
	<i>Vision-Language-Action Models for General-Purpose Robot Manipulation</i> Dept. of Immersive Media Engineering, Sungkyunkwan University Graduate School of AI, UNIST	Nov. 2025 Oct. 2025
	<i>CLIP-RT: Learning Language-Conditioned Robotic Policies from Natural Language Supervision</i> Robotics: Science and Systems (RSS)	June 2025
	<i>Foundation Models for Robotics: Learning and Interaction</i> Robotics: Science and Systems (RSS) Pioneers Workshop	June 2025
	<i>Vision-Language-Action Models for Robotic Manipulation</i> Korea Robotics Society (KROS) Workshop on Mobile Manipulation	May 2025
	<i>PROGrasp: Pragmatic Human-Robot Communication for Object Grasping</i> IEEE International Conference on Robotics and Automation (ICRA)	May 2024
	<i>The Evolution of Language Models: From Basic NLP to ChatGPT and Beyond</i> Dept. of Energy Resources Engineering, Seoul National University	Nov. 2023

The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training
IEEE RO-MAN Workshop on Learning by Asking for Intelligent Robots and Agents Aug. 2023

Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer
KSC 2021—Top-tier Conference Paper Presentation Session
Annual Conference on Human and Cognitive Language Technology

Dec. 2021
Oct. 2021

Dual Attention Networks for Visual Reference Resolution in Visual Dialog
ICCV 2019 - Video Turing Test Workshop
SK Telecom AI Center

Nov. 2019
Sept. 2019

EXTRA	BI Lab Tennis Club	2023 – 2025
CURRICULAR	Military Service in Republic of Korea Army	2012 – 2014
ACTIVITIES		