1 Variables

2 root

	var	symbol	documentation	type	units	tokens	eqs
8	$F_{N,A}$	`F`	directed graph indicence matrix	network		[]	
1	t_N	`t`	time	frame	s	[]	
6	to_N	`to`	starting time	frame	s	[]	3
7	te_N	`te`	end time	frame	s	[]	4
3	*value*	`value`	numerical value	constant		[]	
4	*one*	`one`	numerical value 1	constant		[]	1
5	*null*	`null`	numerical value 0	constant		[]	2

3 System

	var	symbol	documentation	type	units	tokens	eqs
25	${\hat{x}^{A,\alpha}}_N$	`fx_A_alpha`	netflow of token A due to mechanism alpha	transport	ms^{-1}	[]	11
26	${\hat{x}^{A,\beta}}_N$	`fx_A_beta`	net flow of token A due to mechanism beta	transport	ms^{-1}	[]	12
27	${\hat{x}^{B,\gamma}}_N$	`fx_B_gamma`	netflow of token B due to mechanism gamma	transport	s^{-1}	[]	14
28	${\hat{x}^{B,\delta}}_N$	`fx_B_delta`	netflow of token B due to mechansim beta	transport	s^{-1}	[]	15
9	x_N	`x`	state token A	state	m	[]	20
10	y_N	`y`	state token B	state		[]	21
11	${x^o}_N$	`xo`	initial condition for state x	state	m	[]	5
12	${y^o}_N$	`yo`	initial condition for state y	state		[]	6
13	${K^{A,\alpha}}_A$	`K_A_alpha`	conductivity token A mechanism alpha	constant	s^{-1}	[]	
14	${K^{A,\beta}}_A$	`K_A_beta`	conductivity token A mechanism beta	constant	s^{-1}	[]	

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	var	symbol	documentation	type	units	tokens	eqs
15	${K^{B,\gamma}}_{A}$	K_B_gamma	conductivity token B mechanism gamma	constant	s^{-1}	[]	
16	${K^{B,\delta}}_{A}$	K_B_delta	conductivity token B mechanism delta	constant	s^{-1}	[]	
17	${M^{A,\alpha}}_{N}$	M_A_alpha	norming factor token A mechanism alpha	constant		[]	
18	${M^{A,\beta}}_{N}$	M_A_beta	norming factor token A mechanism beta	constant		[]	
19	${M^{B,\gamma}}_{N}$	M_B_gamma	norming factor token B mechanism gamma	constant		[]	
20	${M^{B,\delta}}_{N}$	M_B_delta	norming factor token B mechanism delta	constant		[]	
21	${\pi^{A,\alpha}}_{N}$	pi_A_alpha	effort for A mechanism alpha	secondaryState	m	[]	7
22	${\pi^{A,\beta}}_{N}$	pi_A_beta	effort for A mechanism beta	secondaryState	m	[]	8
23	${\pi^{B,\gamma}}_{N}$	pi_B_gamma	effort for B mechanism gamma	secondaryState		[]	9
24	${\pi^{B,\delta}}_{N}$	pi_B_delta	effort for B mechanism delta	secondaryState		[]	10
31	${\underline{\pi}^{A}}_{N}$	pi_A_stack	effort for token A stack	secondaryState	m	[]	24
32	${\underline{\pi}^{B}}_{N}$	pi_B_stack	effort for token B stack	secondaryState		[]	25
33	$\underline{\pi}^{A,B}$	pi_stack	effort for token A, B stack	secondaryState		[]	26
29	$\dot{x}_N$	dx	diferential balance for token A	differentialState	ms^{-1}	[]	16
30	$\dot{y}_N$	dy	differential balance for token B	differentialState	s^{-1}	[]	17

4 Properties

	var	symbol	documentation	type	units	tokens	eqs

5 Control

	var	symbol	documentation	type	units	tokens	eqs

6 System–Properties

	var	symbol	documentation	type	units	tokens	eqs

7 Properties–System

	var	symbol	documentation	type	units	tokens	eqs

8 System–Control

	var	symbol	documentation	type	units	tokens	eqs

9 Control–System

	var	symbol	documentation	type	units	tokens	eqs

10 Properties–Control

	var	symbol	documentation	type	units	tokens	eqs

11 Control–Properties

	var	symbol	documentation	type	units	tokens	eqs

12 Equations

12.1 Model equations

no	equation	documentation	layer
1	$one := \text{Instantiate}(value, value)$	numerical value 1	root
2	$null := \text{Instantiate}(value, value)$	numerical value 0	root
3	$to_N := \text{Instantiate}(t_N, value)$	starting time	root
4	$te_N := \text{Instantiate}(t_N, value)$	end time	root
5	${x^o}_N := \text{Instantiate}(x_N, value)$	initial condition for state x	System
6	${y^o}_N := \text{Instantiate}(y_N, value)$	initial condition for state y	System
7	${\pi^{A,\alpha}}_N := {M^{A,\alpha}}_N \,.\, x_N$	effort for B mechanism alpha	System
8	${\pi^{A,\beta}}_N := {M^{A,\beta}}_N \,.\, x_N$	effort for A mechanism beta	System
9	${\pi^{B,\gamma}}_N := {M^{B,\gamma}}_N \,.\, y_N$	effort for B mechanism gamma	System
10	${\pi^{B,\delta}}_N := {M^{B,\delta}}_N \,.\, y_N$	effort for B mechanism delta	System
11	${\hat{x}^{A,\alpha}}_N := F_{N,A} \overset{A}{\star} \left({K^{A,\alpha}}_A \,.\, F_{N,A} \overset{N}{\star} {\pi^{A,\alpha}}_N \right)$	netflow of token A due to mechanism alpha	System
12	${\hat{x}^{A,\beta}}_N := F_{N,A} \overset{A}{\star} \left({K^{A,\beta}}_A \,.\, F_{N,A} \overset{N}{\star} {\pi^{A,\beta}}_N \right)$	net flow of token A due to mechanism beta	System
14	${\hat{x}^{B,\gamma}}_N := F_{N,A} \overset{A}{\star} \left({K^{B,\gamma}}_A \,.\, F_{N,A} \overset{N}{\star} {\pi^{B,\gamma}}_N \right)$	netflow of token B due to mechanism gamma	System
15	${\hat{x}^{B,\delta}}_N := F_{N,A} \overset{A}{\star} \left({K^{B,\delta}}_A \,.\, F_{N,A} \overset{N}{\star} {\pi^{B,\delta}}_N \right)$	netflow of token B due to mechansim beta	System

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no	equation	documentation	layer
16	$\dot{x}_N := \hat{x}^{A,\alpha}{}_N + \hat{x}^{A,\beta}{}_N$	diferential balance for token A	System
17	$\dot{y}_N := \hat{x}^{B,\gamma}{}_N + \hat{x}^{B,\delta}{}_N$	differential balance for token B	System
20	$x_N := \int_{to_N}^{te_N} \dot{x}_N \ dt_N + x^o{}_N$	state token A	System
21	$y_N := \int_{to_N}^{te_N} \dot{y}_N \ dt_N + y^o{}_N$	state token B	System
24	$\underline{\pi}^A{}_N := \text{Stack}\left(\pi^{A,\alpha}{}_N, \pi^{A,\beta}{}_N\right)$	effort for token A stack	System
25	$\underline{\pi}^B{}_N := \text{Stack}\left(\pi^{B,\gamma}{}_N, \pi^{B,\delta}{}_N\right)$	effort for token B stack	System
26	$\underline{\pi}^{A,B} := \text{MixedStack}\left(\underline{\pi}^A{}_N, \underline{\pi}^B{}_N\right)$	effort for token A, B stack	System