Practical Machine Learning Final Report: Exercise Prediction

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Introdution

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement – a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways.

Class A: exactly according to the specification (proper execution)

Class B: throwing the elbows to the front (common mistake)

Class C: lifting the dumbbell only halfway (common mistake)

Class D: lowering the dumbbell only halfway (common mistake)

Class F: Throwing the hips to the front (common mistake)

Goal of this Project:

The goal of this project is to predict the manner in which the exercise was performed (i.e., Class A, B, C, D, or F).

Load library

```
library(caret)

## Warning: package 'caret' was built under R version 4.0.3

## Loading required package: lattice

## Loading required package: ggplot2

library(rpart)
library(rpart.plot)
library(RColorBrewer)
library(rattle)

## Rattle: A free graphical interface for data science with R.

## Versión 5.3.0 Copyright (c) 2006-2018 Togaware Pty Ltd.

## Escriba 'rattle()' para agitar, sacudir y rotar sus datos.

library(e1071)
library(randomForest)
```

Warning: package 'randomForest' was built under R version 4.0.3

```
## randomForest 4.6-14
## Type rfNews() to see new features/changes/bug fixes.
##
## Attaching package: 'randomForest'
## The following object is masked from 'package:rattle':
##
## importance
## The following object is masked from 'package:ggplot2':
##
## margin
set.seed(1)
```

Download the data

Processing Data

Get the training and test

```
trainingRaw <- read.csv("./data/pml-training.csv")</pre>
testRaw <- read.csv("./data/pml-testing.csv")</pre>
dim(trainingRaw)
## [1] 19622
              160
dim(testRaw)
## [1] 20 160
str(trainingRaw)
                   19622 obs. of 160 variables:
## 'data.frame':
## $ X
                             : int 1 2 3 4 5 6 7 8 9 10 ...
## $ user_name
                                   "carlitos" "carlitos" "carlitos" ...
                             : chr
## $ raw timestamp part 1
                             : int
                                   1323084231 1323084231 1323084231 1323084232 1323084232 1323084232
## $ raw_timestamp_part_2
                             : int
                                   788290 808298 820366 120339 196328 304277 368296 440390 484323 484
## $ cvtd_timestamp
                             : chr
                                   "05/12/2011 11:23" "05/12/2011 11:23" "05/12/2011 11:23" "05/12/20
## $ new_window
                                   "no" "no" "no" "no" ...
                             : chr
## $ num_window
                                   11 11 11 12 12 12 12 12 12 12 ...
                             : int
## $ roll_belt
                                   1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
                             : num
## $ pitch_belt
                             : num
                                   8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                                   -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
                             : num
## $ total_accel_belt
                             : int
                                   3 3 3 3 3 3 3 3 3 3 ...
                                   ... ... ... ...
## $ kurtosis_roll_belt
                             : chr
                                   ... ... ... ...
## $ kurtosis_picth_belt
                             : chr
## $ kurtosis_yaw_belt
                             : chr
## $ skewness_roll_belt
                             : chr
                                   ... ... ... ...
## $ skewness_roll_belt.1
                             : chr
                                   0.01 \quad 0.01 \quad 0.01 \quad 0.01
## $ skewness_yaw_belt
                             : chr
## $ max_roll_belt
                             : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt
                                   NA NA NA NA NA NA NA NA NA ...
                             : int
                                   "" "" "" ...
## $ max yaw belt
                             : chr
## $ min_roll_belt
                             : num \, NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_belt
                             : int
                                   NA NA NA NA NA NA NA NA NA ...
                                   ... ... ...
                             : chr
## $ min_yaw_belt
##
   $ amplitude_roll_belt
                             : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
                             : int
                                   NA NA NA NA NA NA NA NA NA ...
                                   ...
  $ amplitude_yaw_belt
                             : chr
## $ var_total_accel_belt
                             : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt
                             : num
                                   NA NA NA NA NA NA NA NA NA ...
                             : num NA ...
## $ stddev_roll_belt
                             : num NA NA NA NA NA NA NA NA NA ...
## $ var_roll_belt
## $ avg_pitch_belt
                                   NA NA NA NA NA NA NA NA NA ...
                             : num
## $ stddev_pitch_belt
                             : num NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                             : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                             : num NA NA NA NA NA NA NA NA NA ...
                             : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt
## $ var_yaw_belt
                             : num NA NA NA NA NA NA NA NA NA ...
## $ gyros belt x
                             ## $ gyros_belt_y
                             : num 0 0 0 0 0.02 0 0 0 0 ...
## $ gyros_belt_z
                                   -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
                             : num
## $ accel_belt_x
                             : int -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel_belt_y
                             : int 4 4 5 3 2 4 3 4 2 4 ...
```

```
$ accel belt z
                                  22 22 23 21 24 21 21 21 24 22 ...
                           : int
## $ magnet_belt_x
                                  -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
                           : int
## $ magnet belt y
                           : int
                                  599 608 600 604 600 603 599 603 602 609 ...
## $ magnet_belt_z
                                  -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
                           : int
## $ roll arm
                           : num
                                  ## $ pitch arm
                                  22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
                           : num
   $ yaw arm
                           : num
                                  ##
   $ total accel arm
                           : int
                                  34 34 34 34 34 34 34 34 34 ...
##
   $ var accel arm
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ avg_roll_arm
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
   $ stddev_roll_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ var_roll_arm
                           : num
##
   $ avg_pitch_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_arm
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
   $ var_pitch_arm
                           : num
##
   $ avg_yaw_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ stddev_yaw_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ var yaw arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ gyros_arm_x
                                  : num
## $ gyros_arm_y
                           : num
                                  0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
## $ gyros_arm_z
                           : num
                                  -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
## $ accel_arm_x
                                  : int
## $ accel_arm_y
                                  109 110 110 111 111 111 111 111 109 110 ...
                           : int
## $ accel_arm_z
                                  -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                           : int
## $ magnet_arm_x
                           : int
                                  -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet_arm_y
                           : int
                                  337 337 344 344 337 342 336 338 341 334 ...
##
   $ magnet_arm_z
                                  516 513 513 512 506 513 509 510 518 516 ...
                           : int
                                  ... ... ... ...
   $ kurtosis_roll_arm
                           : chr
                                  ... ... ... ...
## $ kurtosis_picth_arm
                           : chr
                                  ... ... ... ...
   $ kurtosis_yaw_arm
                           : chr
##
   $ skewness_roll_arm
                           : chr
                           : chr
##
   $ skewness_pitch_arm
                                  ... ... ... ...
                                  ... ... ... ...
## $ skewness_yaw_arm
                           : chr
## $ max_roll_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ max_picth_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ max_yaw_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : int
## $ min roll arm
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_arm
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ min yaw arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : int
## $ amplitude_roll_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_arm
                           : num
## $ amplitude_yaw_arm
                                  NA NA NA NA NA NA NA NA NA ...
                           : int
## $ roll dumbbell
                           : num
                                  13.1 13.1 12.9 13.4 13.4 ...
## $ pitch_dumbbell
                                  -70.5 -70.6 -70.3 -70.4 -70.4 ...
                            : num
## $ yaw_dumbbell
                            : num
                                  -84.9 -84.7 -85.1 -84.9 -84.9 ...
                                  ... ... ... ...
##
                           : chr
   $ kurtosis_roll_dumbbell
                                  ... ... ... ...
##
   $ kurtosis_picth_dumbbell : chr
                                  ... ... ... ...
##
                            : chr
   $ kurtosis_yaw_dumbbell
                           : chr
                                  ... ... ... ...
   $ skewness_roll_dumbbell
                                  ... ... ... ...
## $ skewness_pitch_dumbbell : chr
                                  ## $ skewness_yaw_dumbbell
                           : chr
## $ max_roll_dumbbell
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
                                  NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                           : num
                                  ... ... ... ...
## $ max yaw dumbbell
                           : chr
```

```
## $ min_roll_dumbbell : num NA NA
## $ min_pitch_dumbbell : num NA NA
## $ min_yaw_dumbbell : chr "" "" "" ""
## $ amplitude_roll_dumbbell : num NA NA
## [list output truncated]
```

We note that the training dataset contains 19622 observations and 160 variables, and the test dataset contains 20 observations and 160 variables. The variable "classe" in the training set is the result to predict.

```
trainingRaw$classe <- as.factor(trainingRaw$classe)</pre>
#get cant o register for classe
summary (trainingRaw$classe)
##
      Α
           В
                 C
                       D
                             Ε
## 5580 3797 3422 3216 3607
\#NAindex \leftarrow apply(trainingRaw, 2, function(x) \{sum(is.na(x))\})
#trainingRaw <- trainingRaw[, which(NAindex == 0)]</pre>
\#NAindex \leftarrow apply(testRaw, 2, function(x) \{sum(is.na(x))\})
#testingRaw <- testRaw[, which(NAindex == 0)]</pre>
#str(trainingRaw)
#str(testingRaw)
```

preprocessing the variables

```
v <- which(lapply(trainingRaw, class) %in% "numeric")
preObj <-preProcess(trainingRaw[,v],method=c('knnImpute', 'center', 'scale'))
trainLess1 <- predict(preObj, trainingRaw[,v])
trainLess1$classe <- trainingRaw$classe
testLess1 <-predict(preObj,testRaw[,v])</pre>
```

Cross validations

Split the data into set for training and one set for cross validation.

```
set.seed(12031987)

inTrain = createDataPartition(trainLess1$classe, p = 3/4, list=FALSE)
training = trainLess1[inTrain,]
crossValidation = trainLess1[-inTrain,]
```

Model

```
Create the Train model using RF( random Forest)
```

```
modFit <- train(classe ~., method="rf", data=training, trControl=trainControl(method='cv'), number=5, a</pre>
```

Save the model

```
save(modFit,file="fit.R")
```

Accuracy

Check out the acurracy of the training set and cross-validation set

```
trainingPred <- predict(modFit, training)</pre>
confusionMatrix(trainingPred, training$classe)
## Confusion Matrix and Statistics
##
##
             Reference
## Prediction
                 Α
                      В
                            C
                                 D
                                      Ε
            A 4185
                       0
                                      0
##
                            0
                                 0
##
            В
                 0 2848
                            0
                                 0
                                      0
            С
##
                 0
                       0 2567
                                 0
                                      0
##
            D
                 0
                      0
                            0 2412
                                      0
##
            Ε
                       0
                            0
                                 0 2706
##
## Overall Statistics
##
##
                  Accuracy: 1
##
                    95% CI: (0.9997, 1)
##
       No Information Rate: 0.2843
       P-Value [Acc > NIR] : < 2.2e-16
##
##
                      Kappa: 1
##
##
##
   Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##
                         Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                           1.0000
                                    1.0000
                                              1.0000
                                                       1.0000
                                                                 1.0000
## Specificity
                           1.0000
                                    1.0000
                                              1.0000
                                                       1.0000
                                                                 1.0000
## Pos Pred Value
                                                       1.0000
                           1.0000
                                    1.0000
                                              1.0000
                                                                 1.0000
## Neg Pred Value
                           1.0000
                                   1.0000
                                              1.0000
                                                       1.0000
                                                                 1.0000
## Prevalence
                           0.2843
                                    0.1935
                                              0.1744
                                                       0.1639
                                                                 0.1839
## Detection Rate
                           0.2843
                                    0.1935
                                              0.1744
                                                       0.1639
                                                                 0.1839
## Detection Prevalence
                           0.2843
                                    0.1935
                                              0.1744
                                                       0.1639
                                                                 0.1839
## Balanced Accuracy
                           1.0000
                                    1.0000
                                              1.0000
                                                       1.0000
                                                                 1.0000
Cross Validation Set
cvPred <- predict(modFit, crossValidation)</pre>
confusionMatrix(cvPred, crossValidation$classe)
## Confusion Matrix and Statistics
##
##
             Reference
## Prediction
                            C
                                 D
                                      Ε
                 Α
                      В
            A 1387
##
                       5
                            1
                                 0
                                      1
                                      2
##
            В
                 4
                    936
                           10
                                 1
##
            С
                 0
                       8
                          833
                                 9
                                      4
##
            D
                 0
                       0
                                      4
                           10
                               793
##
            Ε
                       0
                            1
                                 1
                                    890
##
## Overall Statistics
##
```

Accuracy : 0.9867

##

```
95% CI: (0.9831, 0.9898)
##
       No Information Rate: 0.2845
##
       P-Value [Acc > NIR] : < 2.2e-16
##
##
##
                     Kappa : 0.9832
##
##
  Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##
                        Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                                 0.9863
                                            0.9743
                                                     0.9863
                                                              0.9878
                          0.9943
## Specificity
                          0.9980
                                   0.9957
                                            0.9948
                                                     0.9966
                                                              0.9985
## Pos Pred Value
                                                     0.9827
                                                              0.9933
                          0.9950
                                   0.9822
                                            0.9754
## Neg Pred Value
                          0.9977
                                   0.9967
                                            0.9946
                                                     0.9973
                                                              0.9973
## Prevalence
                          0.2845
                                   0.1935
                                            0.1743
                                                     0.1639
                                                              0.1837
## Detection Rate
                          0.2828
                                   0.1909
                                            0.1699
                                                     0.1617
                                                              0.1815
## Detection Prevalence
                                                     0.1646
                          0.2843
                                   0.1943
                                            0.1741
                                                              0.1827
## Balanced Accuracy
                          0.9961
                                   0.9910
                                            0.9845
                                                     0.9915
                                                              0.9931
```

results

We get the predictions in the actual test set

```
testingPred <- predict(modFit, testLess1)
testingPred</pre>
```

```
## [1] B A B A A E D B A A B C B A E E A B B B ## Levels: A B C D E
```