Master Research Report: Multilevel Multivariate Imputation by Chained Equations through Bayesian Additive Regression Trees

Methodology and Statistics for the Behavioural, Biomedical and Social Sciences

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1 Introduction

Incomplete data is a common challenge in many fields of research. Frequently, ad hoc strategies are used to deal with missing data, such as listwise deletion, pairwise deletion, mean imputation, and regression imputation. However, these strategies typically lead to erroneous inferences in realistic situations: estimates may be biased and variances inaccurate [Austin et al., 2021, Enders, 2017, Kang, 2013, van Buuren, 2018]. Rubin defined three types of missing data mechanisms: Missing Completely At Random (MCAR) where the cause of the missing data is unrelated to the unobserved or observed data, Missing At Random (MAR) where the missing data is related to the observed data, and Missing Not At Random (MNAR) where the missing data is related to unobserved data [Rubin, 1976].

Multiple imputation (MI) is considered a valid method for dealing with incomplete data, and allows us the separate the missing data problem from the analysis problem [Audigier et al., 2018, Austin et al., 2021, Burgette and Reiter, 2010, Enders, 2017, Grund et al., 2021, Hughes et al., 2014, Mistler and Enders, 2017, Van Buuren, 2007, van Buuren, 2018]. MI is used to impute each missing value in the dataset more than once given the observed data, considering necessary variation associated with the missingness problem. The multiply imputed datasets are analyzed, and the corresponding inferences are pooled according to Rubin's rules [Austin et al., 2021, Carpenter and Kenward, 2013, Rubin, 1987, van Buuren, 2018]. The imputation models should be at least as general as the analysis model and preferably all-encompassing: the concept of congeniality [Bartlett et al., 2015, Enders et al., 2018a, Grund et al., 2016, 2018b, Meng, 1994]. Otherwise, it will not capture every aspect of the data and the completed datasets cannot be properly analysed. So, when the complexity of data increases, specifying the imputation models becomes more difficult [Grund et al., 2018b, van Buuren, 2018]. MI has been implemented in a multilevel data context [Audigier et al., 2018, Dong and Mitani, 2023, Enders et al., 2020, 2018a,b, 2016, Grund et al., 2016, 2018a,b, 2021, Lüdtke et al., 2017, Mistler and Enders, 2017, Quartagno and Carpenter, 2022, Resche-Rigon and White, 2018, Taljaard et al., 2008, van Buuren, 2018], where this concept of congeniality becomes magnified. Multilevel data is hierarchically structured, where, for example, students are nested within schools [Hox and Roberts, 2011, Hox et al., 2017]. Multilevel models (MLM) are the recommended statistical technique to account for the specific dependencies [Hox and Roberts, 2011, Hox et al., 2017, Lüdtke et al., 2017]. It can contain both level-1, and level-2 variables, relating to the individual and class respectively, random intercepts, random slopes, and cross-level interactions [Hox and Roberts, 2011, Hox et al., 2017]. The complexity of the multilevel analysis model is built step-wise with non-linearities [Hox and Roberts, 2011, Hox et al., 2017]. Thus, when defining imputation models the hierarchical structure should be included, along with the complicated non-linearities from cross-level interactions. Since ignoring the multilevel structure will underestimate the Intra-Class Correlation (ICC) [Hox and Roberts, 2011, Lüdtke et al., 2017, Taljaard et al., 2008, van Buuren, 2018], which can be interpreted as the expected correlation between two randomly sampled individuals from the same group or the proportion of the total variance at level-2 [Gulliford et al., 2005, Hox and Roberts, 2011, Shieh, 2012]. So, defining these models is quite challenging [Burgette and Reiter, 2010, Hox and Roberts, 2011, van Buuren, 2018].

Generally, multiple imputation operates under two frameworks: joint modeling (JM) and fully conditional specification (FCS) [Enders et al., 2018a,b, Hughes et al., 2014, Mistler and Enders, 2017, van Buuren, 2018]. JM employs a multivariate data distribution and regresses incomplete on all complete variables for imputation. FCS, or chained equations, iteratively imputes one variable with missing values at a time through conditional univariate distributions regressing an incomplete variable on complete and previously imputed variables [Enders et al., 2018a,b, 2016, Grund et al., 2018a, Hughes et al., 2014, Mistler and Enders, 2017, van Buuren, 2018]. JM and FCS use multivariate and univariate linear mixed models respectively in a multilevel context [Enders et al., 2018a, Mistler and Enders, 2017, Resche-Rigon and White, 2018] to account for the hierarchical structure. Thus far, focus has been on multilevel JM and FCS including random intercepts and slopes, but no cross-level interactions Enders et al. [2020, 2018a,b, 2016], Grund et al. [2016, 2018a]. Overall, FCS is believed to be more flexible than JM [Audigier et al., 2018, Burgette and Reiter, 2010, Grund et al., 2018a, Van Buuren, 2007] and, thus, may be better suited for multilevel data. Grund et al. [2018b] recommend using FCS to impute a multilevel dataset with random intercepts, slopes and cross-level interactions or non-linear terms. FCS uses 'passive imputation' or treats interactions as 'just another variable' by defining a sperate imputation model. On the other hand, JM doesn't account for cross-level interactions at all [Grund et al., 2018b, van Buuren, 2018]. Still, imputation models including cross-level interaction or non-linear terms in FCS are still very complicated [Grund et al., 2018b, 2021].

Using non-parametric tree-based models might solve this problem. In a single-level imputation context,

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the use of tree-based, non-parametric models like regression trees, random forests, or Bayesian Additive Regression Trees (BART) simplified imputation models and performed better than parametric methods: the imputations showed better confidence interval coverage of the population parameters, lower variance and lower bias, especially in non-linear and interactive contexts [Burgette and Reiter, 2010, Silva and Gutman, 2022, Xu et al., 2016]. Waljee et al. [2013] also found lower imputation error when imputing with a random forest algorithm compared to MICE, KNN and mean imputation.

Tree-based models are non-parametric, meaning that they do not assume a specific data distribution. They can handle non-linear relationships and interactions between the predictor variables well, along with simultaneously handling continuous and categorical variables [Breiman et al., 1984, Burgette and Reiter, 2010, Chipman et al., 2010, Hill et al., 2020, James et al., 2021, Lin and Luo, 2019, Salditt et al., 2023]. BART models have been implemented in a multilevel prediction context. However, multilevel-BART models (M-BART) have predominantly been implemented with only random intercepts [Chen, 2020, Tan et al., 2016, Wagner et al., 2020, Wundervald et al., 2022]. In prediction context, Wagner et al. [2020] have found that this random intercept M-BART model provided better predictions with a lower Mean Squared Error (MSE) compared to a parametric MLM, Tan et al. [2016] found higher Area Under the Curve (AUC) values compared to a single level BART model and linear random intercept model, and Chen [2020] found better predictions and better coverage compared to parametric models and a single-level BART model. Other researchers modeled the random intercept as an extra split on each terminal node and found a lower MSE compared to a standard BART model and parametric MLMs [Wundervald et al., 2022]. Dorie et al. [2022] developed a multilevel BART model that included random intercepts and random slopes by combining BART with the Stan algorithm. Where the random parts are modeled by Stan. Their results showed that their algorithm 'stan4bart' showed better coverage of the population values and lower Root Mean Squared Error (RMSE) compared to BART models with varying intercept, BART models ignoring the multilevel structure, Bayesian Causal Forests (BCF), and parametric MLMs.

In spite of these promising findings, M-BART models have yet to be implemented in a multilevel multiple imputation context. Thus, my research question will be: *Can multivariate imputation by chained equations through a multilevel bayesian additive regression trees model improve the bias, variance and coverage of the estimates in a multilevel context compared to current practices?* Given the success of non-parametric models in single-level MI, I anticipate that employing M-BART models in a multilevel missing data context will reduce bias, accurately model variance, and improve estimate coverage compared to classical multilevel imputation through *2l.pmm, 2l.lmer, 2l.pan, 2l.jomo, rf* and single-level *pmm* and complete case analysis in the R-package MICE [Buuren and Groothuis-Oudshoorn, 2011].

The research report's sections will cover theoretical background, methods for evaluating M-BART models, preliminary results, and discussion of next steps.

2 Method

2.1 Theoretical background

2.1.1 Bayesian Additive Regression Trees (BART)

Bayesian Additive Regression Trees (BART) is a sum-of-trees model proposed by Chipman et al. [2010]. Regression trees are its building blocks [Chipman et al., 2010, Hill et al., 2020, James et al., 2021]. Regression trees divides the data into subgroups by recursively splitting the data into binary subgroups based on the predictors maximizing the homogeneity of the subgroups [Hastie, 2017, James et al., 2021, Salditt et al., 2023]. Recursive binary partitioning of the predictor space doesn't assume a specific data form, making this a non-parametric model [Hastie, 2017, James et al., 2021, Salditt et al., 2023] and allows regression trees to model non-linearities well and automatically [Burgette and Reiter, 2010, Hill et al., 2020].

Chipman et al. [2010] define the BART model as:

$$f(\mathbf{x}) = \sum_{k=1}^{m} g(\mathbf{x}; T_k, M_k), \tag{1.1}$$

$$f(\mathbf{x}) = g(\mathbf{x}, T_1, M_1) + g(\mathbf{x}_i, T_2, M_2) + \cdots + g(\mathbf{x}_i, T_m, M_m), \tag{1.2}$$

where $f(\mathbf{x})$ is the overall fit of the model: the sum of many regression trees, $\mathbf{x}$ are the predictor

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variables, T_k is the k-th tree and M_k is the collection of leaf parameters within the k-th tree [Chipman et al., 2010, Hill et al., 2020, James et al., 2021]. The data are assumed to arise from a model with additive normally distributed errors: $Y = \sum_{k=1}^{m} g(\mathbf{x}; T_k, M_k) + \epsilon, \epsilon \sim \mathcal{N}(0, \sigma^2)$. Next to the sum-of-trees model, BART also includes a regularization prior that constrains the size and fit of each tree so that each contributes only a small part to prevent overfitting [Chipman et al., 2010, Hill et al., 2020, James et al., 2021]. BARTs are estimated using the Bayesian back-fitting Markov Chain Monte Carlo (MCMC) algorithm. It updates individual trees, considering the remaining trees, their associated parameters, and the residual standard deviation (σ). It fits a new tree to the partial residuals, r_i, treating them as the data, by perturbing the tree from the previous iteration. It can either *grow*, *prune*, or *change* a tree. *Growing* means adding additional splits, *pruning* removes splits, and *changing* changes decision rules. The algorithm stops after the specified amount of iterations. The partial residuals are defined as:

$$r_i = y_i - \sum_{k' < k} \hat{f}_{k'}^{b}(x_i) - \sum_{k' > k} \hat{f}_{k'}^{b-1}(x_i), \tag{2}$$

where $\hat{f}_k^b(x_i)$ is the prediction of the kth tree in the bth iteration for person i.

2.1.2 Multilevel-BART (M-BART)

Chen [2020], Wagner et al. [2020] and Tan et al. [2016] define a multilevel-BART (M-BART) model including a random intercept building on the work of Lin and Luo [2019]. The M-BART algorithm breaks down the observed variable into fixed and random components. The fixed components are modeled by BART and the random components are modeled by a linear mixed effects model [Chen, 2020, Tan et al., 2016, Wagner et al., 2020]. The M-BART model including a random intercept can be identified as:

$$f(\mathbf{x}) = \sum_{k=1}^{m} g(\mathbf{x}; T_k, M_k) + \alpha_j, \tag{3}$$

where, now, $f(\mathbf{x})$ is the overal fit of the model incorporating random intercept α_j for cluster j.

2.2 Simulation study

For this research report, I will conduct a simulation study to examine the performance of three M-BART models in a multilevel prediction context compared to a sinlge-level BART model.

2.2.1 Data generating mechanism

The population data-generating mechanism will be based on the following MLM:

$$y_{ij} = \beta_{0j} + \beta_{1j}X_{1ij} + \beta_{2j}X_{2ij} + \beta_{3j}X_{3ij} + \beta_{4j}X_{4ij} + \beta_{5j}X_{5ij} + \beta_{6j}X_{6ij} + \beta_{7j}X_{7ij} + \epsilon_{ij}, \tag{4}$$
$$\beta_{0j} = \gamma_{00} + \gamma_{01}Z_{1j} + \upsilon_{0j}, \tag{4.1}$$
$$\beta_{1j} = \gamma_{10} + \gamma_{11}Z_{1j} + \upsilon_{1j}, \tag{4.2}$$
$$\beta_{2j} = \gamma_{20} + \gamma_{21}Z_{1j} + \upsilon_{2j}, \tag{4.3}$$
$$\beta_{3j} = \gamma_{30} + \gamma_{32}Z_{2j} + \upsilon_{3j}, \tag{4.4}$$
$$\beta_{4j} = \gamma_{40} + \upsilon_{4j}, \tag{4.5}$$
$$\beta_{5j} = \gamma_{50} + \upsilon_{5j}, \tag{4.6}$$
$$\beta_{6j} = \gamma_{60} + \upsilon_{6j}, \tag{4.7}$$
$$\beta_{7j} = \gamma_{70}, \tag{4.8}$$

where y_{ij} is a continuous level 1 outcome variable for person i in group j and Z_{1j} and Z_{2j} are continuous level-2 variables. The random intercept β_{0j} is determined by the grand mean γ_{00}, the group effect $\gamma_{01}Z_{1j}$ and the group-level random residuals υ_{0j}. The regression coefficients β_{1j}, β_{2j}, and β_{3j} for the continuous variables X_{1ij}, X_{2ij}, and X_{3ij} depend on the the intercepts γ_{10}, γ_{20}, and γ_{30}, the cross-level interactions $\gamma_{11}Z_{1j}$, $\gamma_{21}Z_{1j}$, and $\gamma_{32}Z_{2j}$, and the random slopes υ_{1j}, υ_{2j}, and υ_{3j}. The regression coefficients β_{4j}, β_{5j} and β_{6j} are determined by the intercepts γ_{40}, γ_{50} and γ_{60} and the random slopes υ_{4j}, υ_{5j} and υ_{6j}. The regression coefficient β_{7j} is determined by the intercept γ_{70}. The residuals and

random slopes v_{0j}, v_{1j}, v_{2j}, v_{3j}, v_{4j}, v_{5j}, and v_{6j} and ϵ_{ij} follow a zero-mean normal distribution. The variance of v_{0j}, the group-level random residuals, were scaled such that the specified ICC value was obtained. v_{1j}, v_{2j}, v_{3j}, v_{4j}, v_{5j}, and v_{6j} all have a variance of 1. ϵ_{ij} had a variance of 25. X_1, X_2, X_3, X_4, X_5, X_6 and X_7 are multivariate normally distributed: $\mathbf{X}_{ij} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, with $\boldsymbol{\mu} = (0, 0, 0, 0, 0, 0, 0)$ and $\boldsymbol{\Sigma} = \text{diag}(6.25, 9, 4, 11.56, 4, 2.5, 19.36)$ with no co-variances. The level-2 variables Z_1 and Z_2 are also multivariate normally distributed: $\mathbf{Z}_j \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, with $\boldsymbol{\mu} = (0, 0)$ and $(\boldsymbol{\Sigma}) = \text{diag}(1, 2.56)$ with no co-variances. The group-level effects (γ_{01} and $\gamma 02$) were set to .5, the cross-level interactions (γ_{11}, γ_{21}, and γ_{32}) were set to .35, and the overall intercept (γ_{00}) was set to 10. The within-group effect sizes (γ_{10}, γ_{20}, γ_{30}, γ_{40}, γ_{50}, γ_{60}, and γ_{70}) were varied in the simulations.

2.2.2 Simulation design

Table 1 shows the factors that will be varied in the simulation study. All these values are realistic in practice and/or previously proposed [Enders et al., 2020, 2018b, Grund et al., 2018b, Gulliford et al., 1999, Hox et al., 2017, Murray and Blitstein, 2003]. For each combination of varying parameters, 6 datasets will be simulated for each scenario to reduce computational time. 4 different models will be compared: a single level BART, single level

Table 1: Simulation design

Parameter	Values
Number of clusters (j)	30, 50
Within-cluster sample size (n_j)	5, 15, 35, 50
Intraclass Correlation (ICC)	0, .05, .3, .5
Within-group effect size (γ)	.2, .5, .8

BART with group-dummy's, a multilevel BART model incorporating a random intercept [Chen, 2020, Tan et al., 2016, Wagner et al., 2020, Wundervald et al., 2022], and a multilevel BART model combined with Stan to model the random parts of the models [Dorie et al., 2022]. The first three models will be performed with the package *dbarts* [Dorie, 2023a] and the last will performed with the package *stan4bart* [Dorie, 2023b] in R [R Core Team, 2023]. The default arguments from the function *rbart_vi* will be used for all models, as well as the default priors.

2.2.3 Evaluation

In this research report, the preliminary results will pertain to the evaluation of different BART models in terms of the relative bias and Mean Squared Error (MSE) of the estimates, which will be calculated as follows [Morris et al., 2019]:

$$Bias = \frac{1}{n_{\text{sim}}} \sum_{t=1}^{n_{\text{sim}}} (\hat{\theta}_t - \theta), \tag{5}$$

$$MSE = \frac{1}{n_{\text{sim}}} \sum_{t=1}^{n_{\text{sim}}} (\hat{\theta}_t - \theta)^2, \tag{6}$$

$$\tag{5a}$$

where $\hat{\theta}_t$ is the estimated parameter in simulation t, θ is the true value, and n_{sim} is the number of simulated datasets.

3 Results

The results of this research report are shown in figure 1 and 2. Figure 1 shows the average relative bias for all models, simulated datasets, every *ICC* value, and within-group effect size. On the x-axis we can see the different simulated datasets with their names specifying the total sample size, number of groups and group sizes. Figure 2 shows the average Mean Squared Error (MSE) for all models, datasets, *ICC* values, and within-group effect sizes (γ).

In figure 1 we can see that when there is no multilevel structure in the dataset, $ICC = 0$, the models perform similarly in terms of relative bias: overall, the bias is around zero. We can see a slight increase in relative bias when the total sample size is small for all γ. When we increase the ICC, $ICC > 0$, we can see a divide in the performance of the models. Even when $ICC = .05$, the single level BART model (bart) increases in relative bias. bart shows higher levels of relative bias when the total sample size is small. However, when the total sample size is large, *2500*, bart performs slightly better than the single level BART model including a group-dummy (gbart) for all γ. The same pattern is observed for the

other models: when $ICC = .05$, the relative bias decreases when the total sample size increases. This pattern is further continued when increasing the ICC: the relative bias decreases when the total sample size increases for both $ICC = .3$ and $ICC = .5$. However, when considering the stan4bart model, which models the random parts of the model in Stan and the fixed parts in BART, the relative bias stays considerably constant when increasing the ICC: the relative bias is higher when the total sample size is small, but it does not seem to significantly increase with higher ICC or higher γ. This cannot be said for the bart and gbart models, which show a slight increase in relative bias when increasing the ICC, especially in the lower total sample sizes. The rbart model, which incorporates a random intercept, shows a similar pattern as the stan4bart model, but with an overall higher relative bias.

Figure 1: Bias of the estimates for all simulated datasets, all ICC values, and differing within group effect sizes using four models. bart = single level BART model, gbart = single level BART model with group-dummys, rbart = multilevel BART model incorporating a random intercept, stan4bart = multilevel BART model combined with Stan to model the random parts of the models. dataset names show the total sample size, number of groups, and group size. Bias is based on 6 replicates for every dataset.

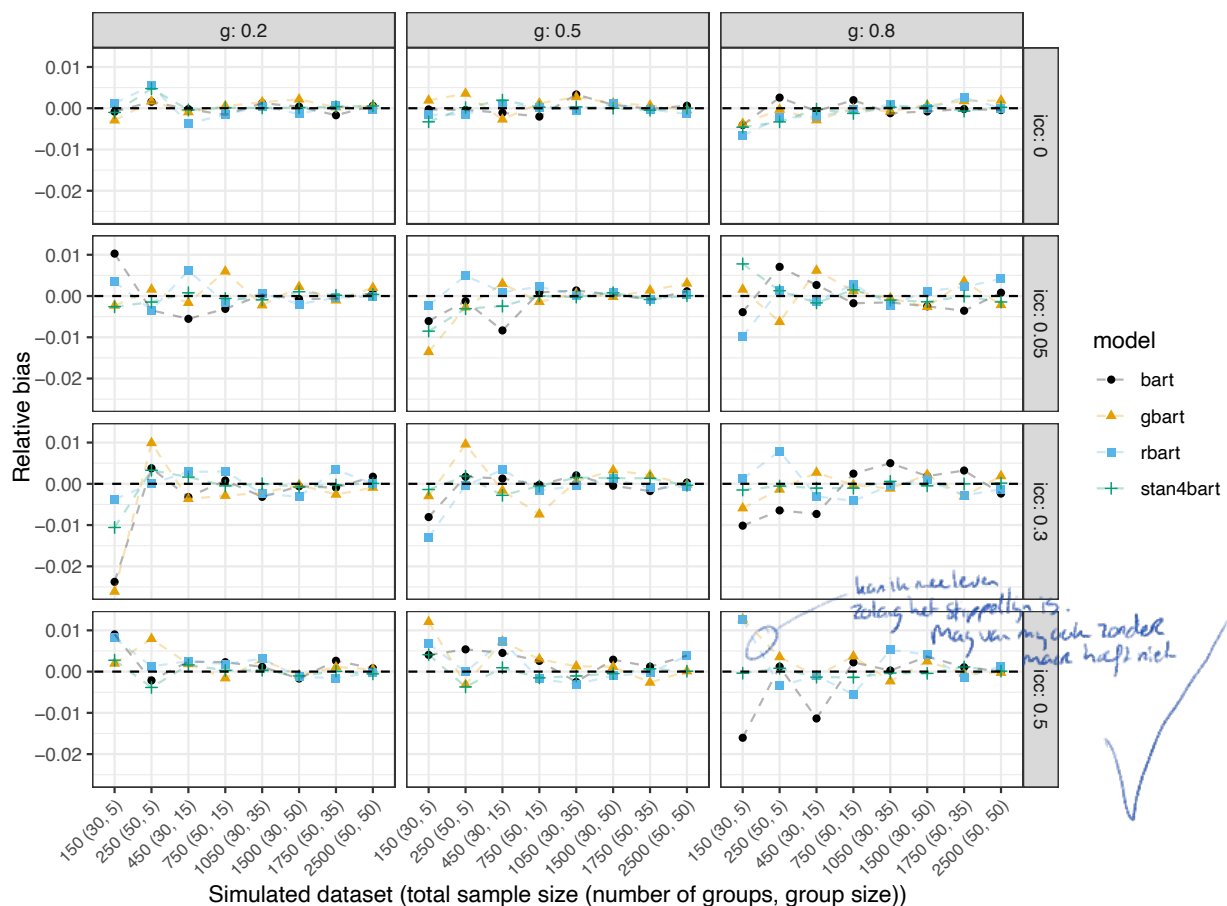Simulated dataset (total sample size (number of groups, group size))

Figure 2 shows a similar pattern as figure 1. When there is no multilevel structure in datasets, $ICC = 0$ the models perform well and almost exactly the same. When increasing the ICC, we can start to see a divide in the performance of the models. When $ICC = .05$ the models bart, gbart and rbart perform similarly, with gbart outperforming the other two models when the group sizes are 35 or larger. However, stan4bart consistently outperforms the other three models in terms of MSE. Increasing the ICC to .3, divides the performance of the models further: in small datasets bart now has the highest MSE with gbart performing only a little better. rbart performs better than bart and gbart, but when the datasets increase in size, it performs similar to bart. Again, gbart outperforms bart and rbart when the groups sizes are 35 or larger. stan4bart is still has the overall lowest MSE. Increasing the ICC further to .5 exaggerates these patterns. Over all ICC values, increasing γ increases the MSE of the models.

Figure 2: Mean Squared Error (MSE) of the estimates for all simulated datasets, all ICC values, and differing within group effect sizes using four models. bart = single level BART model, gbart = single level BART model with group-dummys, rbart = multilevel BART model incorporating a random intercept, stan4bart = multilevel BART model combined with Stan to model the random parts of the models. dataset names show the total sample size, number of groups, and group size. MSE is based on 6 replicates for every dataset.
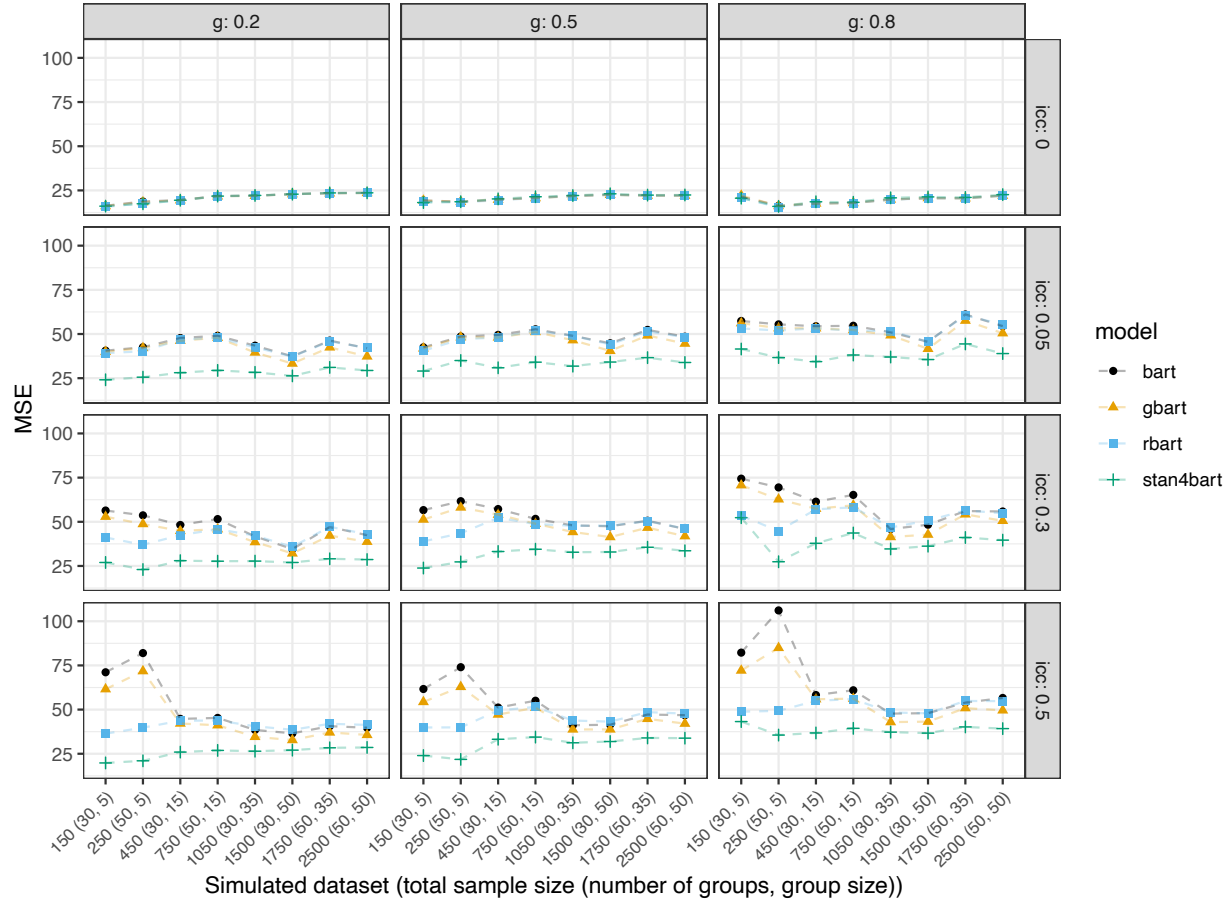
4 Discussion

In this research report I have investigated the performance of different BART models in terms of relative bias and MSE of the estimates. I considered four different models: a single-level BART model (bart), a single-level BART model including a group-dummy (gbart), a multilevel BART model including a random intercept (rbart), and a multilevel BART model combining Stan and BART (stan4bart). Chen [2020], Tan et al. [2016] and Wundervald et al. [2022] found that a BART model including a random intercept performed better than a single-level BART model, which is partly in agreement with my results: the MSE for the rbart showed more consistency, but when the total sample sizes were large, the model did not perform better than the bart and gbart models. The results indicate that the *stan4bart* model performs best out of the four models: it shows to lowest relative bias as well as the lowest MSE. These results are agreement with Dorie et al. [2022], who found that the *stan4bart* algorithm performed better in terms of coverage of the population values and RMSE compared to single-level BART models, BART models including a random intercept, Bayesian Causal Forests (BCF), and parametric MLMs.

Building on these results, I will implement the *stan4bart* as an imputation method within the package *MICE* [Buuren and Groothuis-Oudshoorn, 2011] in my thesis. I will compare the performance of the *stan4bart* model to other imputation methods: *2l.pmm, 2l.lmer, 2l.pan, 2l.jomo, rf* and single-level *pmm* and complete case analysis in the R-package MICE [Buuren and Groothuis-Oudshoorn, 2011]. They will be evaluated in terms of relative bias, modeled variance, and the 95% confidence interval coverage of the estimates [Ober-

Table 2: Simulation design for the thesis

Parameter	Values
Number of clusters (j)	30, 50
Within-cluster sample size (n_j)	5, 15, 35, 50
Intraclass Correlation (ICC)	0, .05, .3, .5
Missing data mechanism	MAR, MCAR
Amount of missingness	0%, 25%, 50%
Within-group effect size (γ)	.2, .5, .8

man and Vink, 2023]. The simulation design will be extended to include more parameters: the missing data mechanism and amount of missingness. The simulation design is shown in table 2. For each combination of paramteres, a 1000 replicated datasets will be generated.

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