

# An Introduction to Algorithms

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Intro



Complexity



Data Structure



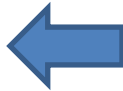
Trees



Hash Functions



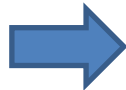
Sorting



Dynamic  
Programming




Greedy Algorithm



Misc Graph/Tree  
Algorithms

# Sorting Review

- Insertion Sort
  - $T(n) = \Theta(n^2)$
- Selection Sort
  - $T(n) = \Theta(n^2)$
- Merge Sort
  - $T(n) = \Theta(n \lg(n))$
- Heap Sort
  - $T(n) = \Theta(n \lg(n))$



*Seems pretty good.  
Can we do better?*

# Sorting

- Assumptions
  1. No (Prior) knowledge of the keys or numbers we are sorting on.
  2. Each key supports a comparison interface or operator.
  3. Each key is unique (just for convenience).

*Comparison Sorting*

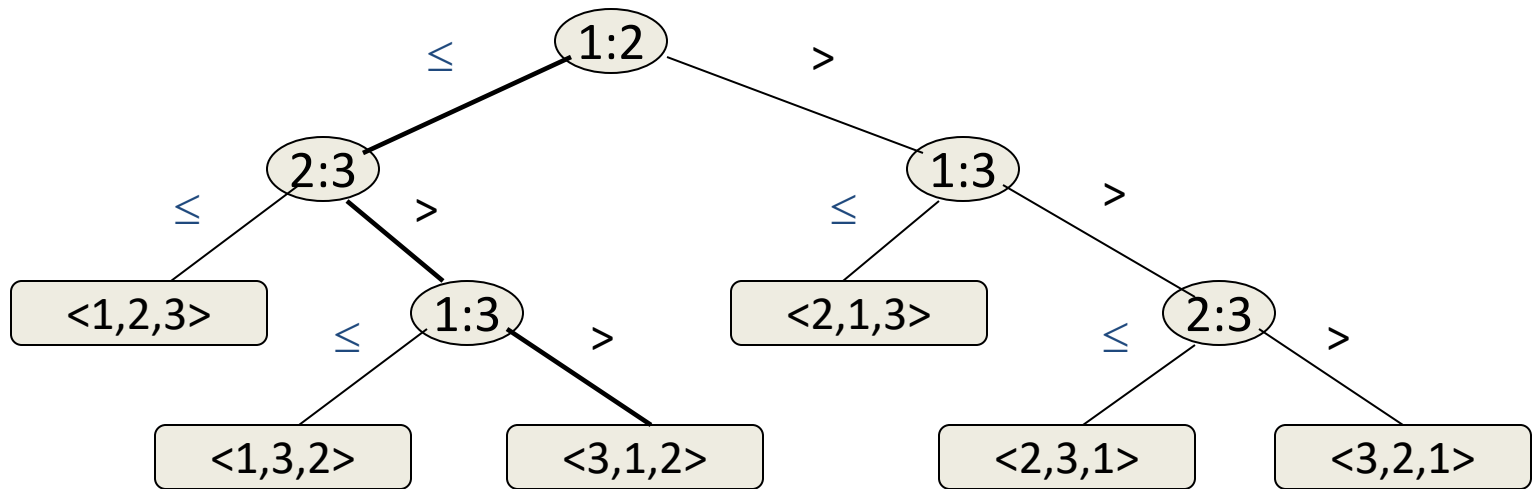
# Comparison Sorting

- Given a set of  $n$  values, there can be  $n!$  permutations of these values.
- So if we look at the behavior of the sorting algorithm over all possible  $n!$  inputs we can determine the worst-case complexity of the algorithm.

# Decision Tree

- Decision tree model
  - Full binary tree
    - A **proper binary tree** (or **2-tree**) is a tree in which every node other than the leaves has two children
  - Internal node represents a comparison.
    - Ignore control, movement, and all other operations, just see comparison
  - Each leaf represents one possible result (a permutation of the elements in sorted order).
  - The height of the tree (i.e., longest path) is the lower bound.

# Decision Tree Model



Internal node  $i:j$  indicates comparison between  $a_i$  and  $a_j$ .

suppose three elements  $\leq a_1, a_2, a_3 \leq$  with instance  $\langle 6, 8, 5 \rangle$

Leaf node  $\langle \pi(1), \pi(2), \pi(3) \rangle$  indicates ordering  $a_{\pi(1)} \leq a_{\pi(2)} \leq a_{\pi(3)}$ .

Path of **bold lines** indicates sorting path for  $\langle 6, 8, 5 \rangle$ .

There are total  $3!=6$  possible permutations (paths).

# Decision Tree Model

- The longest path is the worst case number of comparisons. The length of the longest path is the height of the decision tree.
- **Theorem 8.1:** Any comparison sort algorithm requires  $\Omega(n \lg n)$  comparisons in the worst case.
- **Proof:**
  - Suppose height of a decision tree is  $h$ , and number of paths (i.e., permutations) is  $n!$ .
  - Since a binary tree of height  $h$  has at most  $2^h$  leaves,
    - $n! \leq 2^h$ , so  $h \geq \lg(n!) \geq \Omega(n \lg n)$
- That is to say: **any comparison sort in the worst case needs at least  $n \lg n$  comparisons.**



# QuickSort Design

- Follows the **divide-and-conquer** paradigm.
- **Divide: Partition** (separate) the array  $A[p..r]$  into two (possibly empty) subarrays  $A[p..q-1]$  and  $A[q+1..r]$ .
  - Each element in  $A[p..q-1] < A[q]$ .
  - $A[q] <$  each element in  $A[q+1..r]$ .
  - Index  $q$  is computed as part of the partitioning procedure.
- **Conquer:** Sort the two subarrays by recursive calls to quicksort.
- **Combine:** The subarrays are sorted in place – no work is needed to combine them.
- How do the divide and combine steps of quicksort compare with those of merge sort?

# Pseudocode

Quicksort(A, p, r)

**if**  $p < r$  **then**

$q := \text{Partition}(A, p, r);$

$\text{Quicksort}(A, p, q - 1);$

$\text{Quicksort}(A, q + 1, r)$

Partition(A, p, r)

$x := A[r],$

$i := p - 1;$

**for**  $j := p$  **to**  $r - 1$  **do**

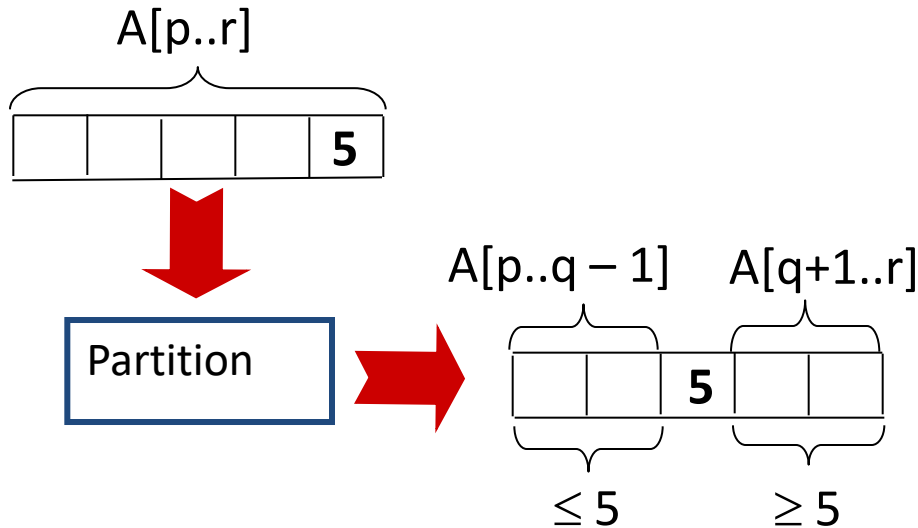
**if**  $A[j] \leq x$  **then**

$i := i + 1;$

$A[i] \leftrightarrow A[j]$

$A[i + 1] \leftrightarrow A[r];$

**return**  $i + 1$



# Example

initially:

$p$   $r$   
 2 5 8 3 9 4 1 7 10 **6**  
 $i$   $j$

**note:** pivot (x) = 6

next iteration:

2 5 8 3 9 4 1 7 10 6  
i j

**next iteration:**

2 5 8 3 9 4 1 7 10 6

i j

**next iteration:**

2 5 8 3 9 4 1 7 10 6

i j

next iteration:

2 5 3 8 9 4 1 7 10 6

i j

## Partition(A, p, r)

$$x := A[r],$$

```
i := p - 1;
```

```
for j := p to r - 1 do
```

**if  $A[j] \leq x$  then**

```
i := i + 1;
```

$$A[i] \leftrightarrow A[j]$$
$$A[i + 1] \leftrightarrow A[r];$$

```
return i + 1
```

# Example (Continued)

next iteration:      2 5 3 8 9 4 1 7 10 6

i j

**next iteration:**      2 5 3 8 9 4 1 7 10 6

i j

**next iteration:**      2 5 3 4 9 8 1 7 10 6

**i                      j**

**next iteration:**      2 5 3 4 1 8 9 7 10 6

$$i \qquad j$$

**next iteration:**      2 5 3 4 1 8 9 7 10 6

i j

**next iteration:**      2 5 3 4 1 8 9 7 10 6

**i** **j**

after final swap:    2 5 3 4 1 **6** 9 7 10 8

$$i \qquad j$$

## Partition(A, p, r)

$$x := A[r],$$

```
i := p - 1;
```

```
for j := p to r - 1 do
```

**if  $A[j] \leq x$  then**

```
i := i + 1;
```

$$A[i] \leftrightarrow A[j]$$
$$A[i + 1] \leftrightarrow A[r];$$

```
return i + 1
```

# Partitioning

- Select the **last element**  $A[r]$  in the subarray  $A[p..r]$  as the pivot – the element around which to partition.
- As the procedure executes, the array is partitioned into four (possibly empty) regions.
  1.  $A[p..i]$  — All entries in this region are  $< pivot$ .
  2.  $A[i+1..j-1]$  — All entries in this region are  $> pivot$ .
  3.  $A[r] = pivot$ .
  4.  $A[j..r-1]$  — Not known how they compare to  $pivot$ .

# Correctness of Partition

- Initialization:

- Before first iteration

- $A[p..i]$  and  $A[i+1..j-1]$  are empty – Conds. 1 and 2 are satisfied (trivially).
- $r$  is the index of the *pivot*
  - Cond. 3 is satisfied.

- Maintenance:

- Case 1:  $A[j] > x$

- Increment  $j$  only.

```
Partition(A, p, r)
```

```
   $x := A[r],$ 
```

```
   $i := p - 1;$ 
```

```
  for  $j := p$  to  $r - 1$  do
```

```
    if  $A[j] \leq x$  then
```

```
       $i := i + 1;$ 
```

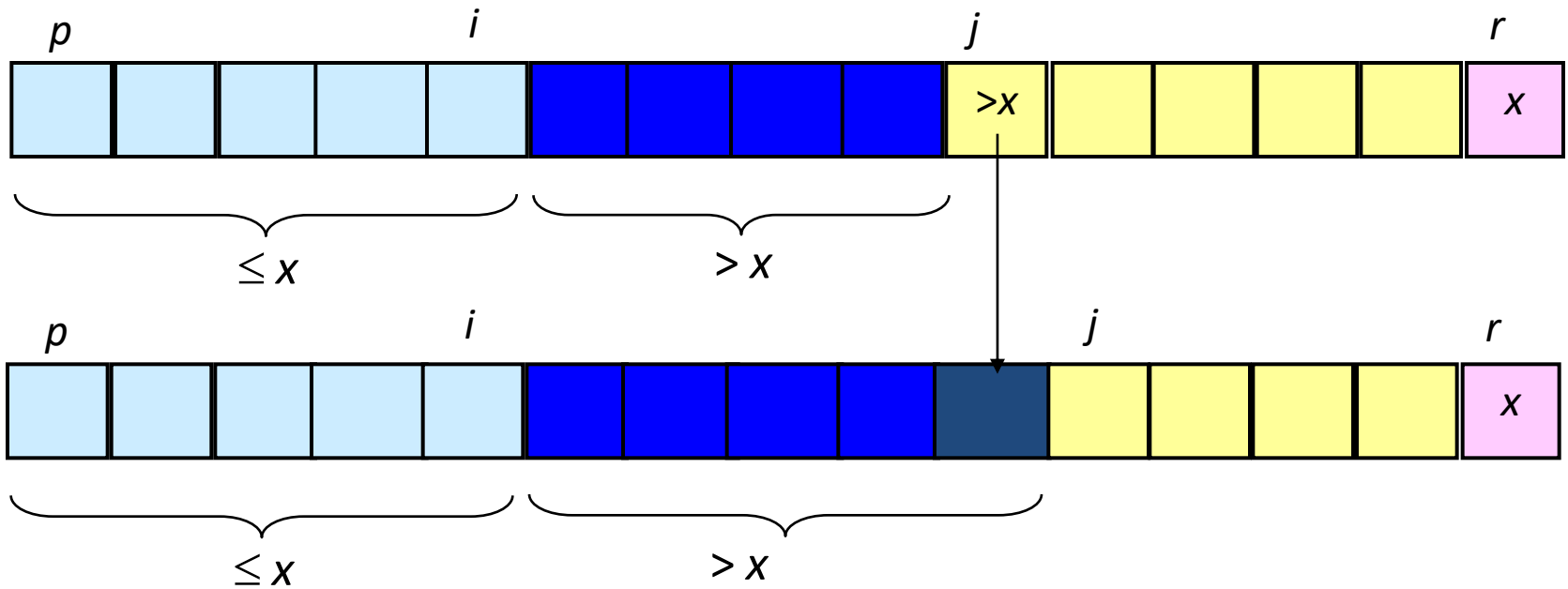
```
       $A[i] \leftrightarrow A[j]$ 
```

```
   $A[i + 1] \leftrightarrow A[r];$ 
```

```
  return  $i + 1$ 
```

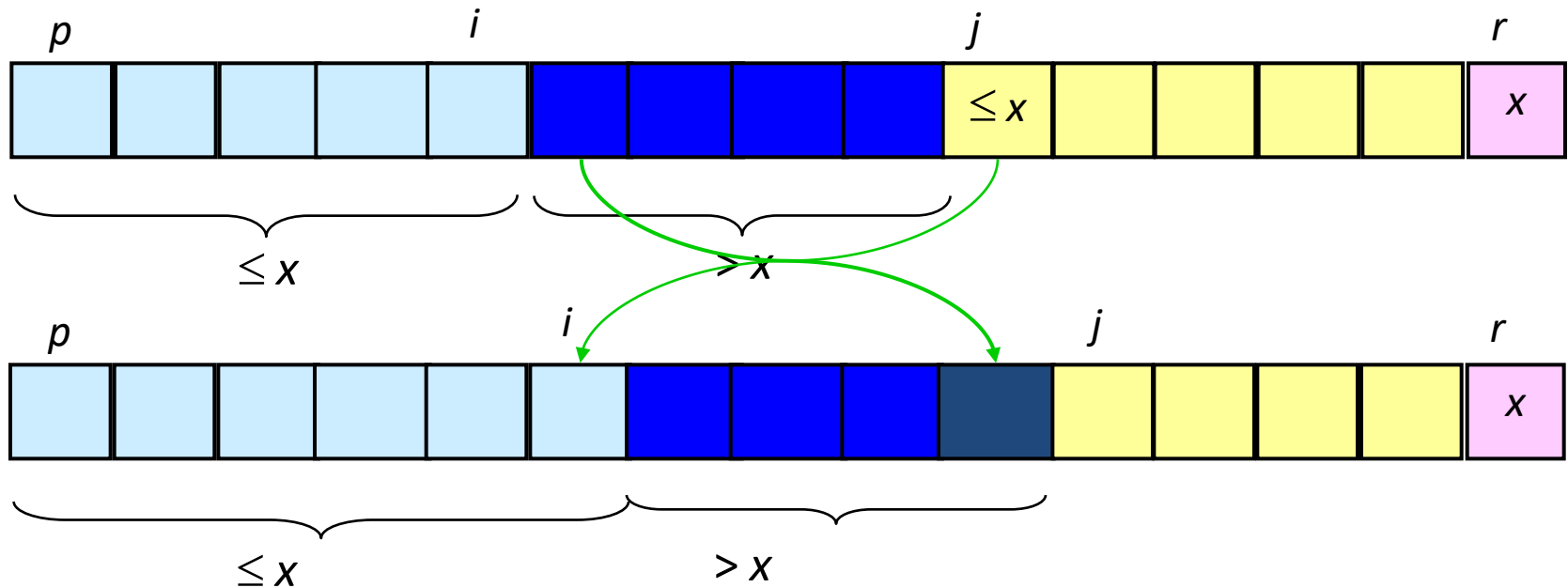
# Correctness of Partition

## Case 1:



# Correctness of Partition

- **Case 2:**  $A[j] \leq x$ 
  - Increment  $i$
  - Swap  $A[i]$  and  $A[j]$ 
    - Condition 1 is maintained.
- Increment  $j$ 
  - Condition 2 is maintained.
- $A[r]$  is unaltered.
  - Condition 3 is maintained.





# Correctness of Partition

- Termination:
  - When the loop terminates,  $j = r$ , so all elements in  $A$  are partitioned into one of the three cases:
    - $A[p..i] \leq \text{pivot}$
    - $A[i+1..j-1] > \text{pivot}$
    - $A[r] = \text{pivot}$
- The last two lines swap  $A[i+1]$  and  $A[r]$ .
  - *Pivot* moves from the end of the array to **between the two subarrays**.
  - Thus, procedure *partition* correctly performs the divide step.

# Complexity of Partition

- **PartitionTime( $n$ )** is given by the number of iterations in the *for* loop.
- $\Theta(n) : n = r - p + 1$ .

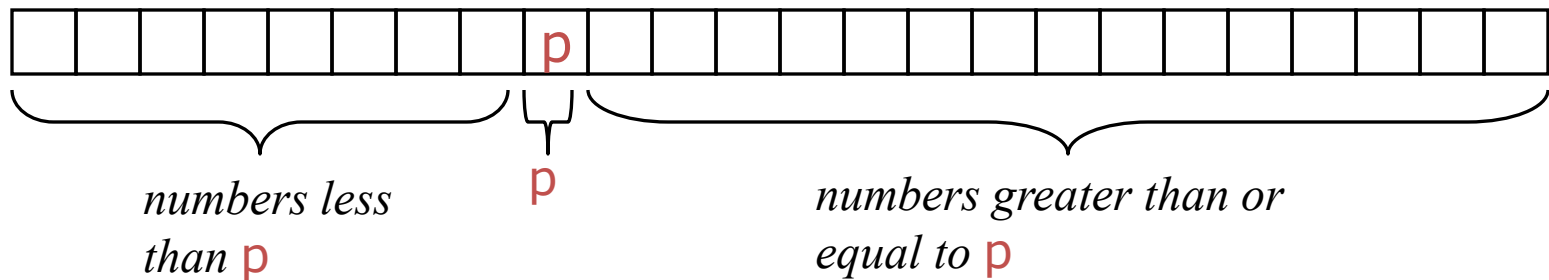
```
Partition(A, p, r)  
  x := A[r],  
  i := p - 1;  
  for j := p to r - 1 do  
    if A[j] ≤ x then  
      i := i + 1;  
      A[i] ↔ A[j]  
  A[i + 1] ↔ A[r];  
  return i + 1
```

# Quicksort Overview

- To sort  $a[\text{left} \dots \text{right}]$ :
  1. if  $\text{left} < \text{right}$ :
    - 1.1. Partition  $a[\text{left} \dots \text{right}]$  such that:
      - all  $a[\text{left} \dots p-1]$  are less than  $a[p]$ , and
      - all  $a[p+1 \dots \text{right}]$  are  $\geq a[p]$
    - 1.2. Quicksort  $a[\text{left} \dots p-1]$
    - 1.3. Quicksort  $a[p+1 \dots \text{right}]$
  2. Terminate

# Partitioning in Quicksort

- A key step in the Quicksort algorithm is **partitioning** the array
  - We choose some (any) number **p** in the array to use as a **pivot**
  - We **partition** the array into three parts:



# Alternative Partitioning

- Choose an array value (say, the first) to use as the pivot
- Starting from the left end, find the first element that is greater than or equal to the pivot
- Searching backward from the right end, find the first element that is less than the pivot
- Interchange (swap) these two elements
- Repeat, searching from where we left off, until done

# Alternative Partitioning

- To partition  $a[\text{left} \dots \text{right}]$ :
  1. Set  $\text{pivot} = a[\text{left}]$ ,  $l = \text{left} + 1$ ,  $r = \text{right}$ ;
  2. while  $l < r$ , do
    - 2.1. while  $l < \text{right} \ \& \ a[l] < \text{pivot}$  , set  $l = l + 1$
    - 2.2. while  $r > \text{left} \ \& \ a[r] \geq \text{pivot}$  , set  $r = r - 1$
    - 2.3. if  $l < r$ , swap  $a[l]$  and  $a[r]$
  3. Set  $a[\text{left}] = a[r]$ ,  $a[r] = \text{pivot}$
  4. Terminate

# Example of partitioning

- choose pivot: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- search: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- swap: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- search: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- swap: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- search: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- swap: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6
- search: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6
- swap with pivot: 1 3 3 1 2 2 3 4 4 9 8 9 6 5 6

# Partition Implementation (Java)

```
static int Partition(int[] a, int left, int right) {  
    int p = a[left], l = left + 1, r = right;  
    while (l < r) {  
        while (l < right && a[l] < p) l++;  
        while (r > left && a[r] >= p) r--;  
        if (l < r) {  
            int temp = a[l]; a[l] = a[r]; a[r] = temp;  
        }  
    }  
    a[left] = a[r];  
    a[r] = p;  
    return r;  
}
```



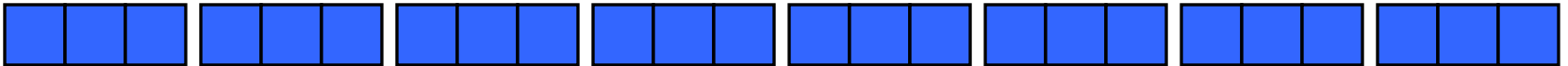
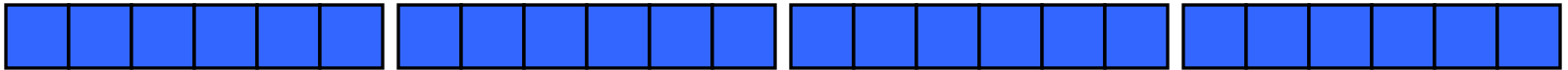
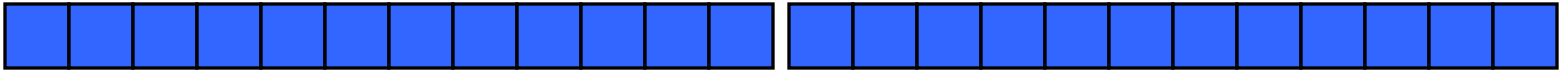
# Quicksort Implementation (Java)

```
static void Quicksort(int[] array, int left, int right) {  
    if (left < right) {  
        int p = Partition(array, left, right);  
        Quicksort(array, left, p - 1);  
        Quicksort(array, p + 1, right);  
    }  
}
```

## Analysis of quicksort—best case

- Suppose each partition operation divides the array almost exactly in half
- Then the depth of the recursion is  $\log_2 n$ 
  - Because that's how many times we can halve  $n$
- We note that
  - Each partition is linear over its subarray
  - All the partitions at one level cover the array

# Partitioning at various levels



# Best Case Analysis

- We cut the array size in half each time
- So the depth of the recursion is  $\log_2 n$
- At each level of the recursion, all the partitions at that level do work that is linear in  $n$
- $O(\log_2 n) * O(n) = O(n \log_2 n)$
- Hence in the best case, quicksort has time complexity  $O(n \log_2 n)$
- What about the worst case?

# Worst case

- In the worst case, partitioning always divides the size  $n$  array into these three parts:
  - A length one part, containing the pivot itself
  - A length zero part, and
  - A length  $n-1$  part, containing everything else
- We don't recur on the zero-length part
- Recurring on the length  $n-1$  part requires (in the worst case) recurring to depth  $n-1$

# Worst case partitioning



# Worst case for quicksort

- In the worst case, recursion may be n levels deep (for an array of size **n**)
- But the partitioning work done at each level is still **n**
- $O(n) * O(n) = \underline{O(n^2)}$
- So worst case for Quicksort is  $O(n^2)$
- When does this happen?
  - There are many arrangements that *could* make this happen
  - Here are two common cases:
    - When the array is already sorted
    - When the array is inversely sorted (sorted in the opposite order)

# Typical case for quicksort

- If the array is sorted to begin with, Quicksort is terrible:  $O(n^2)$
- It is possible to construct other bad cases
- However, Quicksort is usually  $O(n \log_2 n)$
- The constants are so good that Quicksort is generally the faster algorithm.
- Most real-world sorting is done by Quicksort



# Picking a better pivot

- Before, we picked the first element of the subarray to use as a pivot
  - If the array is already sorted, this results in  $O(n^2)$  behavior
  - It's no better if we pick the last element
- We could do an optimal quicksort (guaranteed  $O(n \log n)$ ) if we always picked a pivot value that exactly cuts the array in half
  - Such a value is called a **median**: half of the values in the array are larger, half are smaller
  - The easiest way to find the median is to sort the array and pick the value in the middle (!)

# Median of three

- Obviously, it doesn't make sense to sort the array in order to find the median to use as a pivot.
- Instead, compare just *three* elements of our (sub)array—the first, the last, and the middle
  - Take the *median* (middle value) of these three as the pivot
  - It's possible (but not easy) to construct cases which will make this technique  $O(n^2)$

# Quicksort for Small Arrays

- For very small arrays ( $N \leq 20$ ), quicksort does not perform as well as insertion sort
- A good cutoff range is  $N=10$
- Switching to insertion sort for small arrays can save about 15% in the running time

# Mergesort vs Quicksort

- Both run in  $O(n \lg n)$ 
  - Mergesort – always.
  - Quicksort – on average
- Compared with Quicksort, Mergesort has less number of comparisons but larger number of moving elements
- In Java, an element comparison is expensive but moving elements is cheap. Therefore, Mergesort is used in the standard Java library for generic sorting

# Mergesort vs Quicksort

In C++, copying objects can be expensive while comparing objects often is relatively cheap. Therefore, quicksort is the sorting routine commonly used in C++ libraries

# Partition Implementation (Java)



```
static int Partition(int[] a, int left, int right) {  
    int p = a[left], l = left + 1, r = right;  
    while (l < r) {  
        while (l < right && a[l] < p) l++;  
        while (r > left && a[r] >= p) r--;  
        if (l < r) {  
            int temp = a[l]; a[l] = a[r]; a[r] = temp;  
        }  
    }  
    a[left] = a[r];  
    a[r] = p;  
    return r;  
}
```

# Quicksort Implementation (Java)



```
static void Quicksort(int[] array, int left, int right) {  
    if (left < right) {  
        int p = Partition(array, left, right);  
        Quicksort(array, left, p - 1);  
        Quicksort(array, p + 1, right);  
    }  
}
```

`quickSort(arr, 0, 5)`

0	1	2	3	4	5
6	5	9	12	3	4



`quickSort(arr,0,5)`

`partition(arr,0,5)`

0	1	2	3	4	5
6	5	9	12	3	4

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

pivot= ?

0	1	2	3	4	5
6	5	9	12	3	4

Partition Initialization...

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

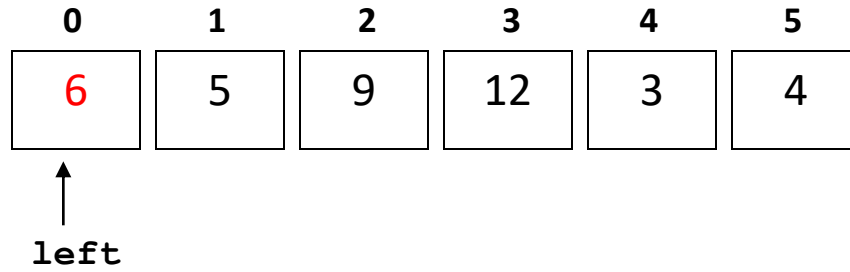
0	1	2	3	4	5
6	5	9	12	3	4

Partition Initialization...

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

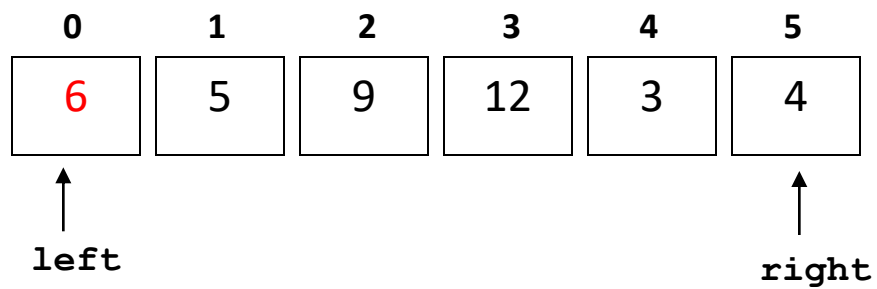


Partition Initialization...

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

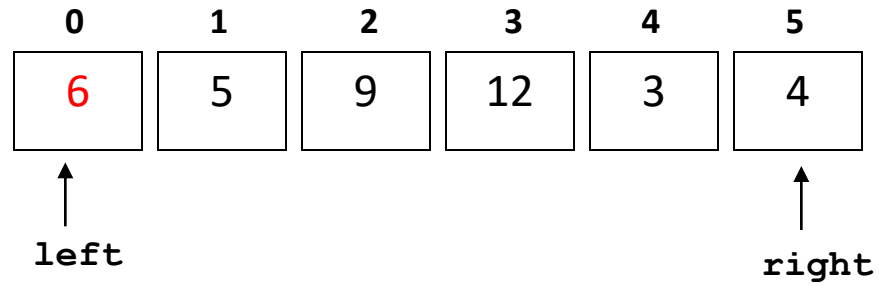


Partition Initialization...

```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

pivot=6

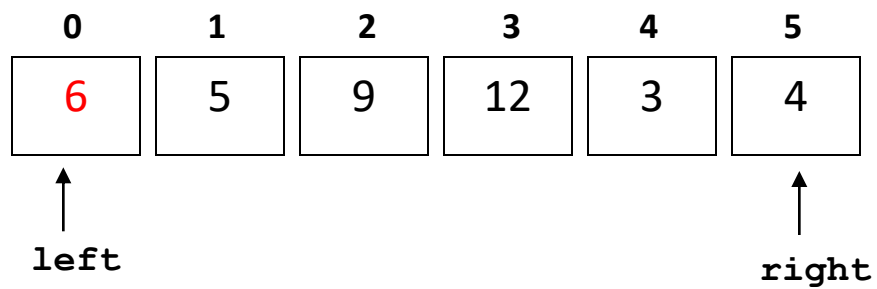


right moves to the left until  
value that should be to left  
of pivot...

```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

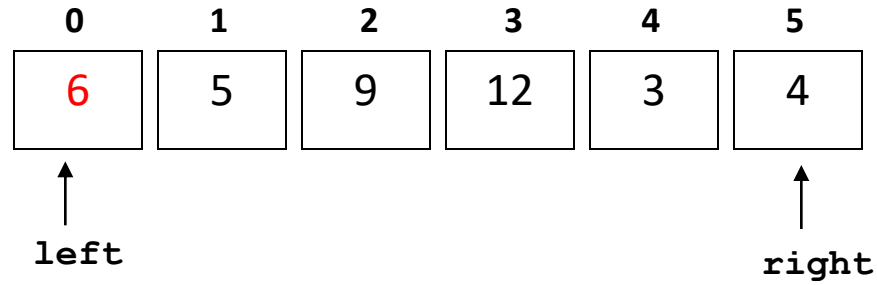
pivot=6



```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

pivot=6



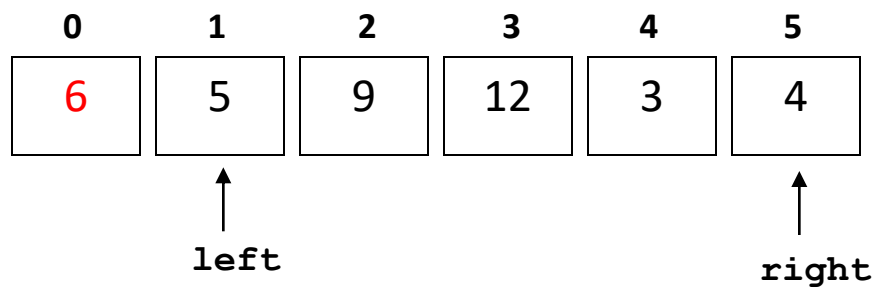
left moves to the right until  
value that should be to right  
of pivot...



`quickSort(arr,0,5)`

`partition(arr,0,5)`

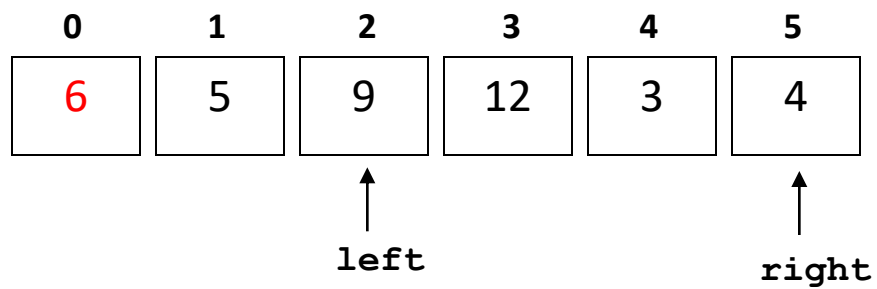
`pivot=6`



`quickSort(arr,0,5)`

`partition(arr,0,5)`

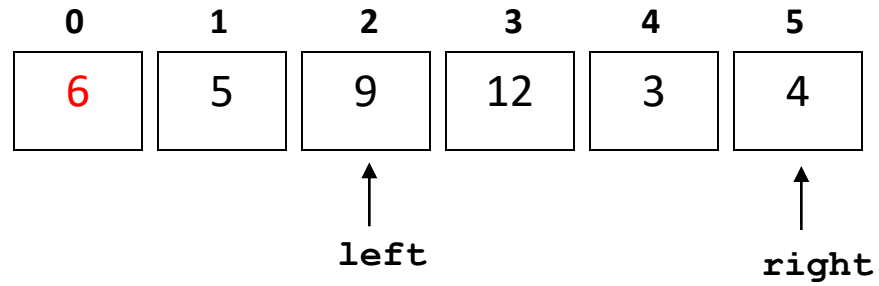
`pivot=6`



`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

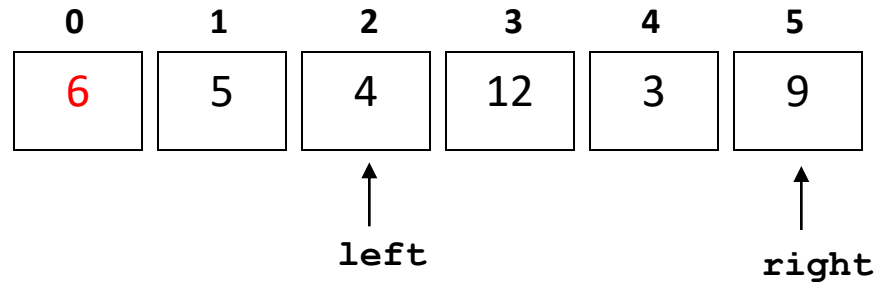


`swap arr[left] and arr[right]`

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

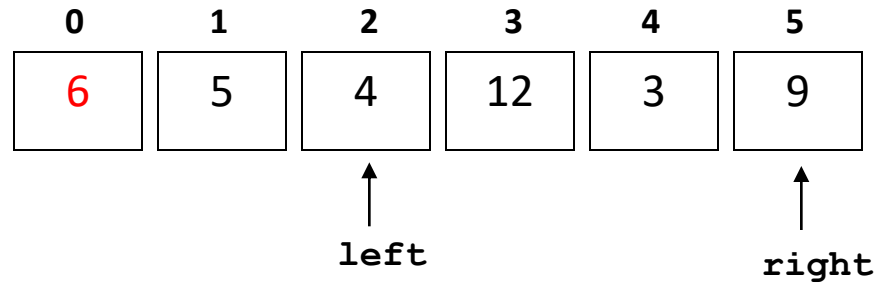


repeat right/left scan  
UNTIL left & right cross

```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

```
pivot=6
```

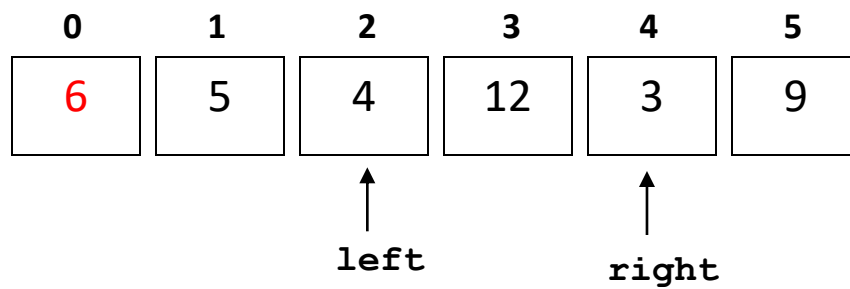


right moves to the left until  
value that should be to left  
of pivot...

`quickSort(arr,0,5)`

`partition(arr,0,5)`

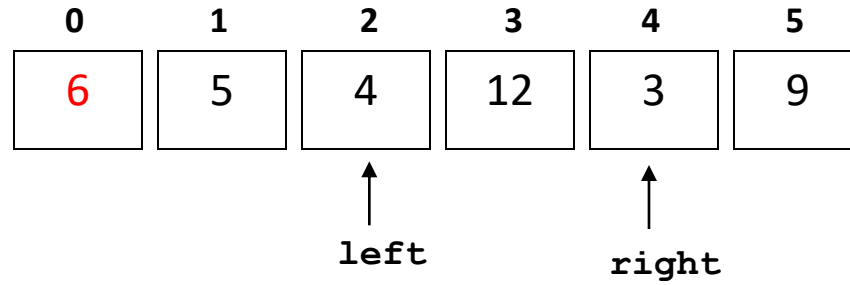
`pivot=6`



```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

```
pivot=6
```

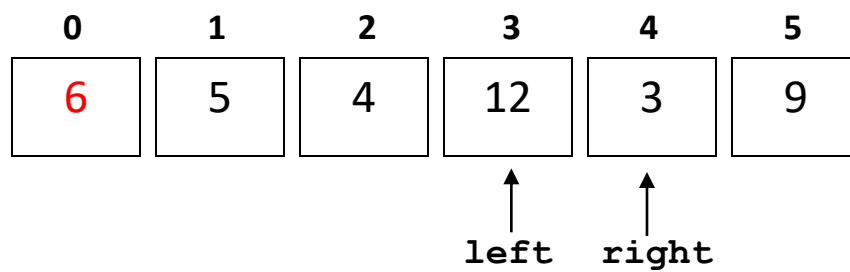


left moves to the right until  
value that should be to right  
of pivot...

`quickSort(arr,0,5)`

`partition(arr,0,5)`

`pivot=6`

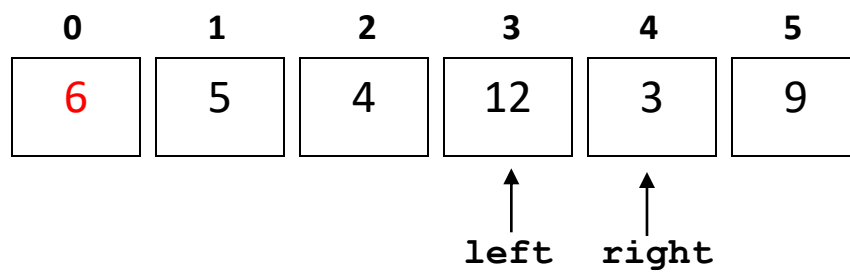




`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

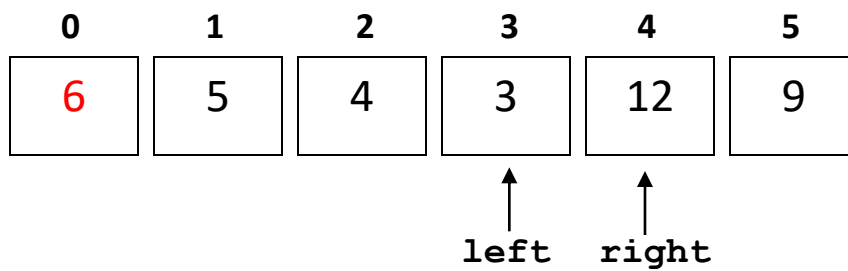


`swap arr[left] and arr[right]`

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

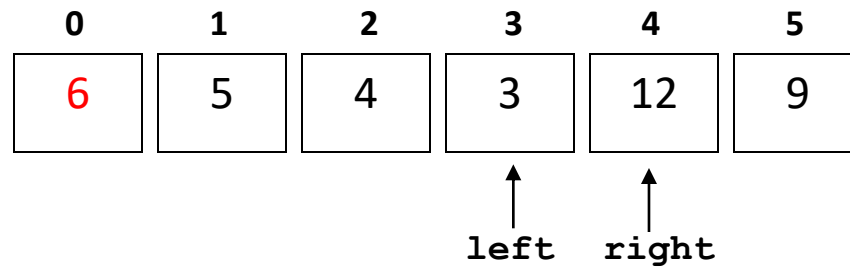


`swap arr[left] and arr[right]`

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

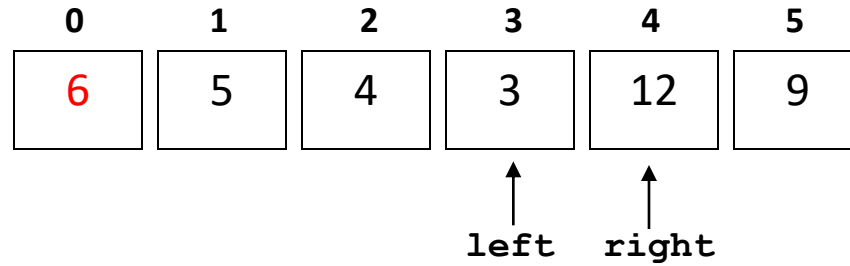


repeat right/left scan  
UNTIL left & right cross

```
quickSort(arr, 0, 5)
```

```
partition(arr, 0, 5)
```

```
pivot=6
```

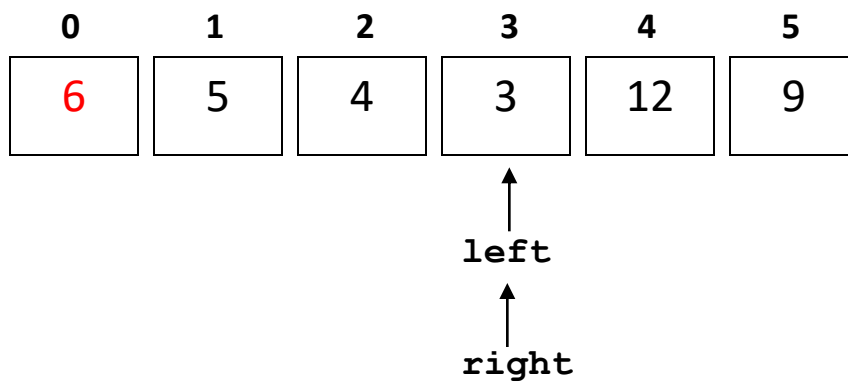


right moves to the left until  
value that should be to left  
of pivot...

`quickSort(arr,0,5)`

`partition(arr,0,5)`

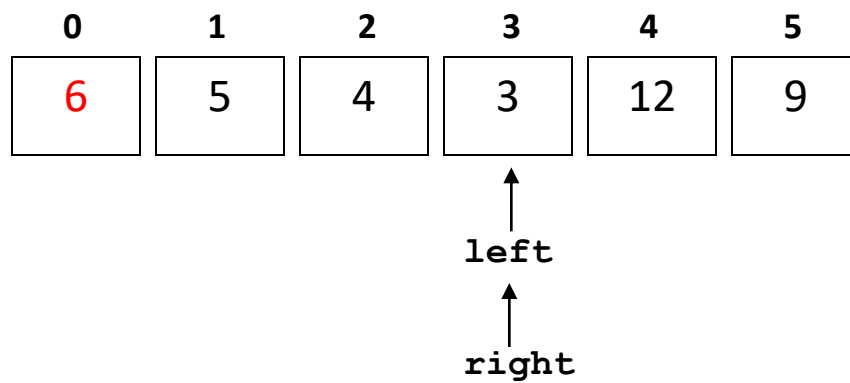
`pivot=6`



`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`

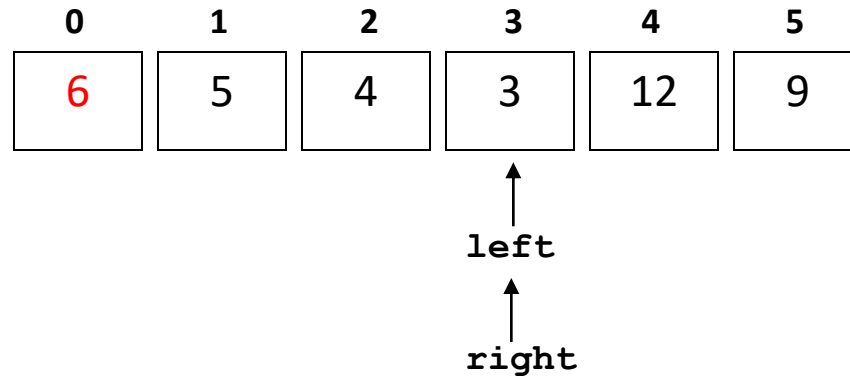


right & left CROSS!!!

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`



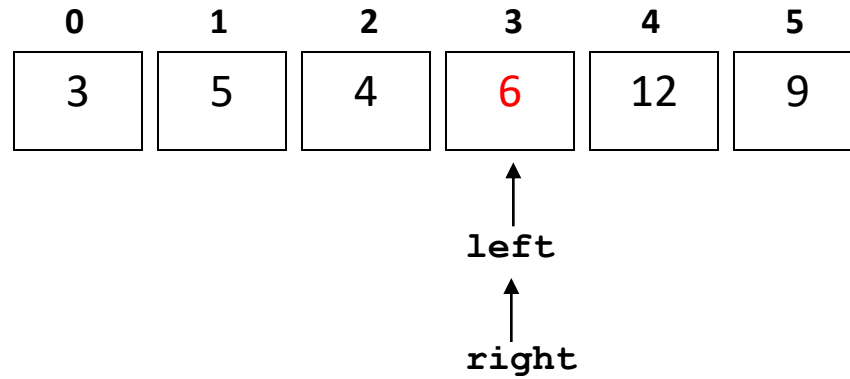
right & left CROSS!!!

1 - Swap pivot and arr[right]

`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`



right & left CROSS!!!

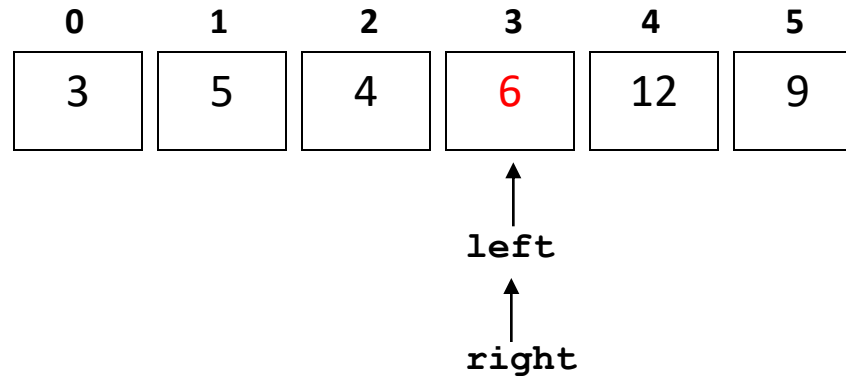
1 - Swap pivot and arr[right]



`quickSort(arr, 0, 5)`

`partition(arr, 0, 5)`

`pivot=6`



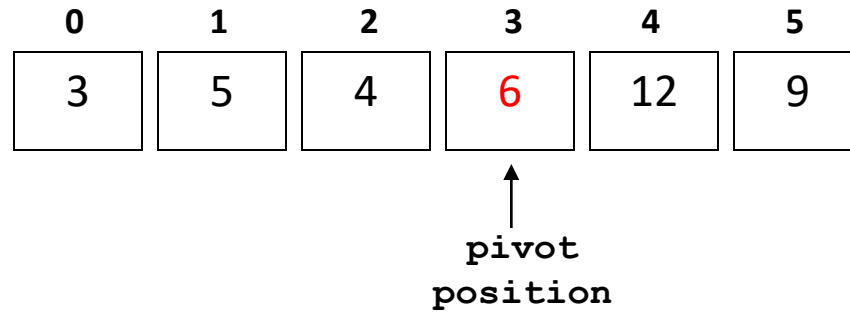
right & left CROSS!!!

1 - Swap pivot and arr[right]

2 - Return new location of pivot to caller

**return 3**

`quickSort(arr, 0, 5)`



Recursive calls to `quickSort()`  
using partitioned array...

`quickSort(arr, 0, 5)`

0	1	2	3	4	5
3	5	4	6	12	9

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

Partition Initialization...

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

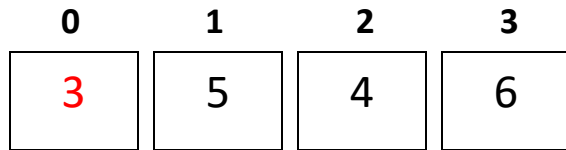
Partition Initialization...

`quickSort(arr, 0, 5)`

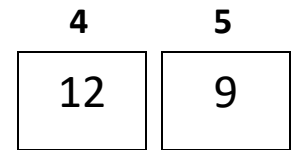
`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



↑  
`left`



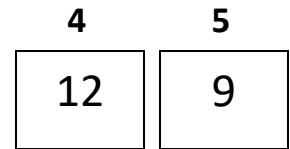
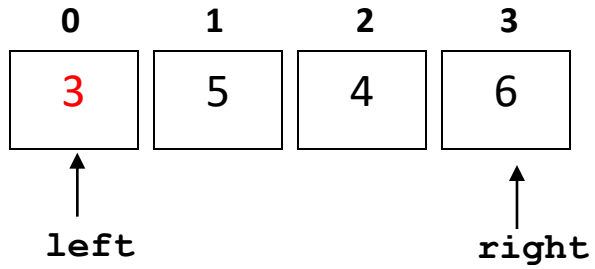
Partition Initialization...

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



Partition Initialization...

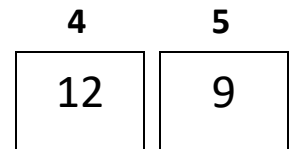
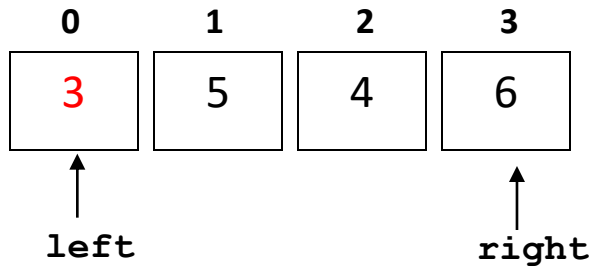


`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



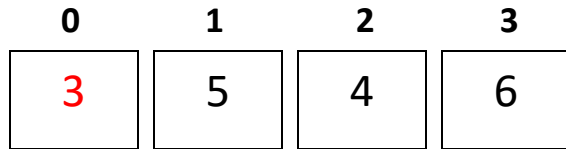
right moves to the left until  
value that should be to left  
of pivot...

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

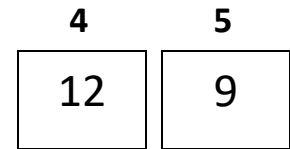
`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



↑  
`left`

↑  
`right`

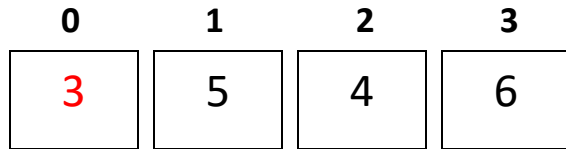


`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

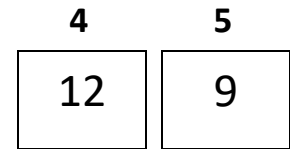
`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



↑  
left

↑  
right



`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

↑  
left

↑  
right

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

↑  
left

↑  
right

right & left CROSS!!!

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

↑  
left

↑  
right

right & left CROSS!!!

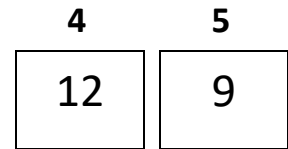
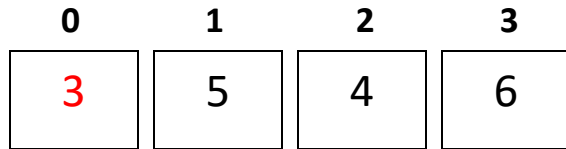
1 - Swap pivot and arr[right]

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`partition(arr, 0, 3)`

`quickSort(arr, 4, 5)`



↑  
left

↑  
right

right & left CROSS!!!

1 - Swap pivot and arr[right]

2 - Return new location of pivot to caller

`return 0`

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

0	1	2	3
3	5	4	6

4	5
12	9

Recursive calls to `quickSort()`  
using partitioned array...



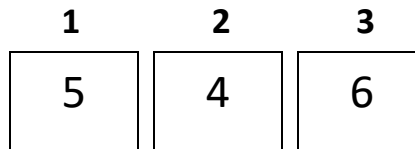
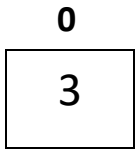
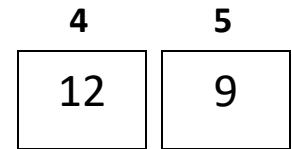
quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

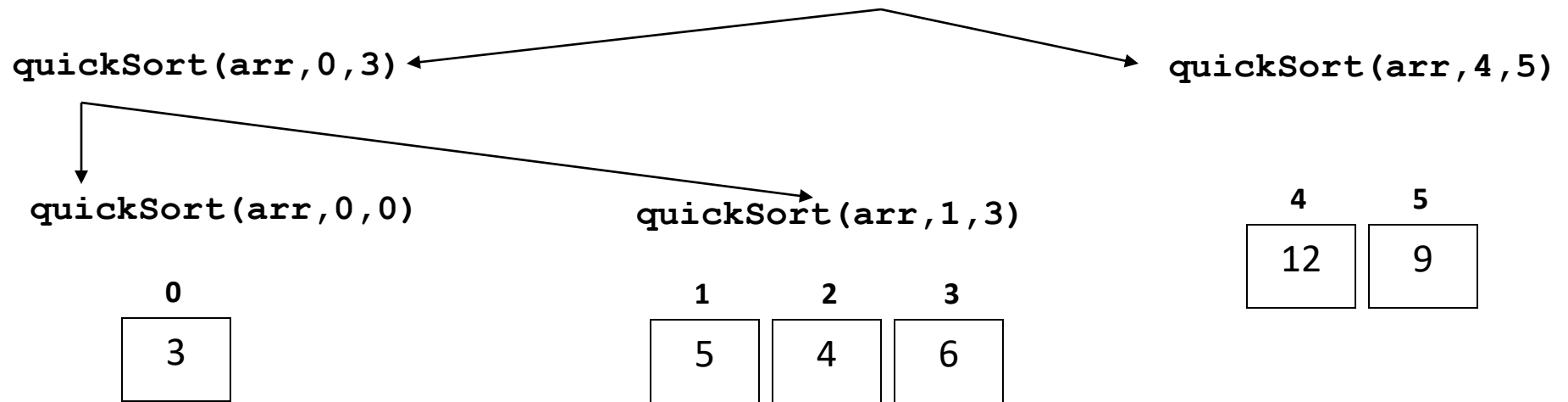
quickSort(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)



`quickSort(arr, 0, 5)`



Base case triggered...  
halting recursion.

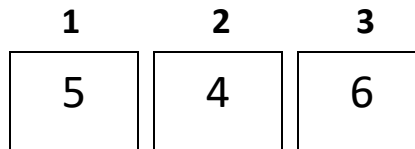
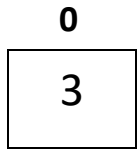
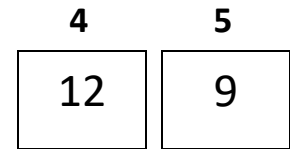
`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

`quickSort(arr, 0, 0)`

`quickSort(arr, 1, 3)`



Base Case: Return

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

`quickSort(arr, 0, 0)`

`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`

0  
3

1      2      3  
5      4      6

4      5  
12    9

Partition Initialization...

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

`quickSort(arr, 0, 0)`

`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`

0  
3

1 2 3  
5 4 6

4 5  
12 9

Partition Initialization...

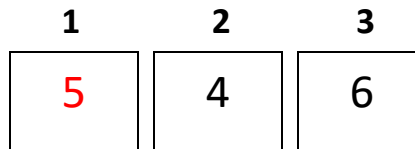
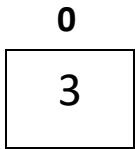
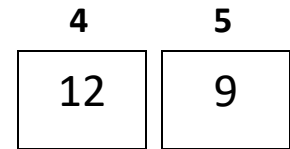
`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

`quickSort(arr, 0, 0)`

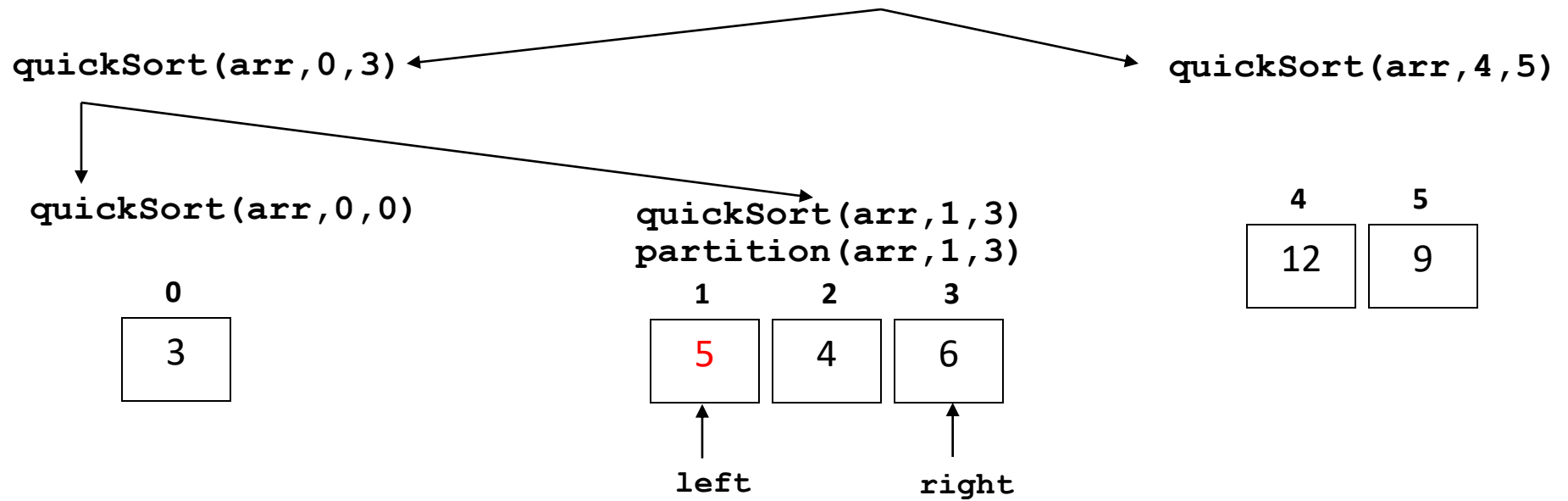
`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`



↑  
`left`

Partition Initialization...

`quickSort(arr, 0, 5)`



right moves to the left until  
value that should be to left  
of pivot...

`quickSort(arr, 0, 5)`

`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

`quickSort(arr, 0, 0)`

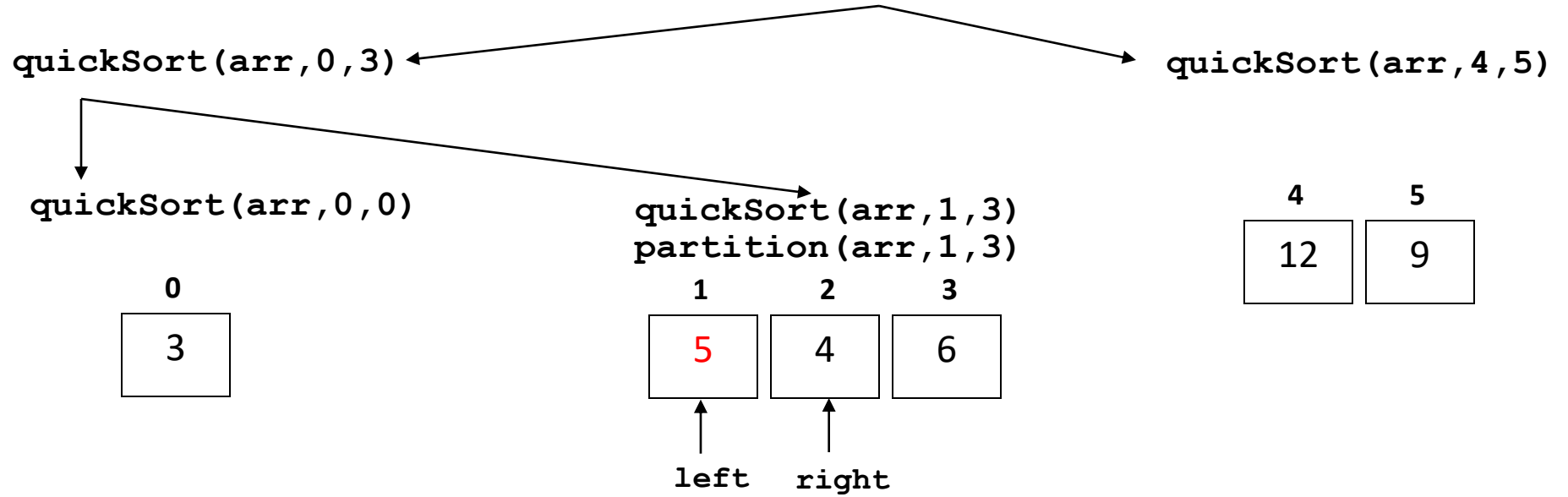
`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`

0  
3

1 2 3  
5 4 6

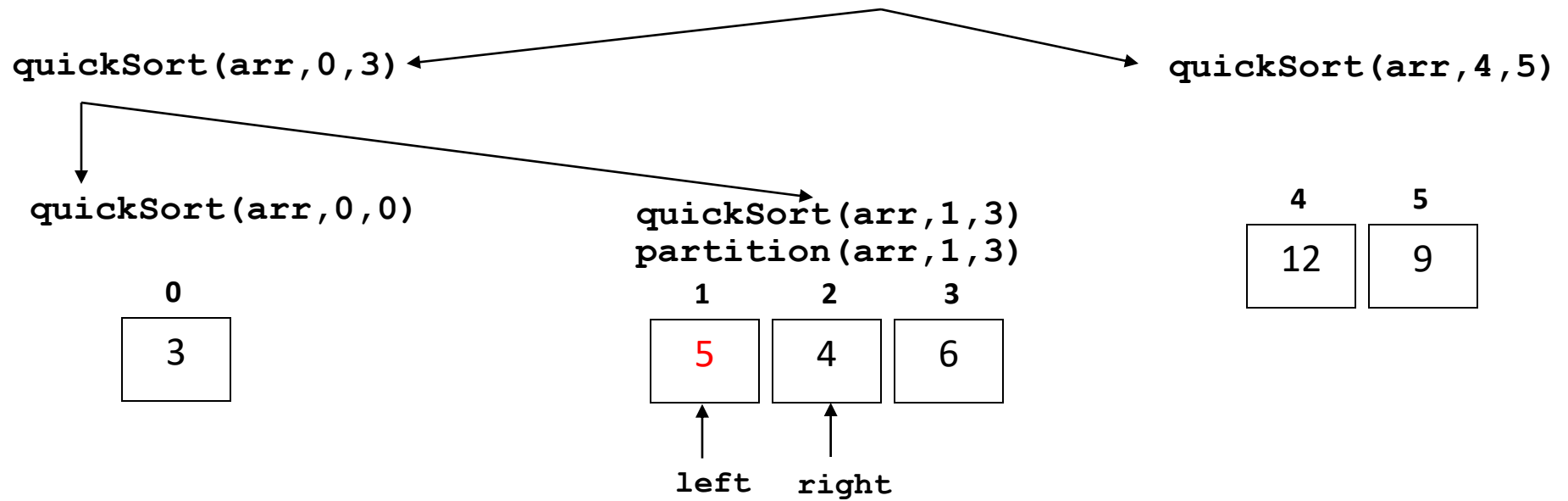
left right

4 5  
12 9





`quickSort(arr, 0, 5)`



left moves to the right until  
value that should be to right  
of pivot...

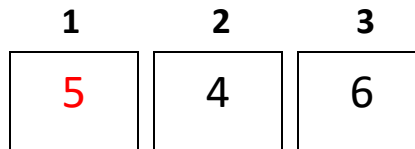
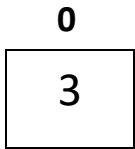
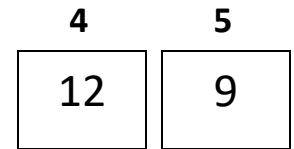
quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)  
partition(arr, 1, 3)



↑  
right  
↑  
left

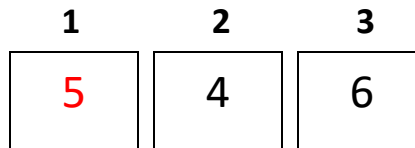
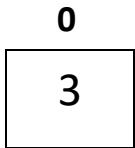
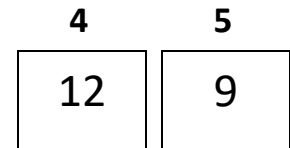
quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)  
partition(arr, 1, 3)



↑  
right

↑  
left

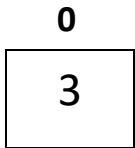
right & left CROSS!

`quickSort(arr, 0, 5)`

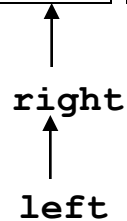
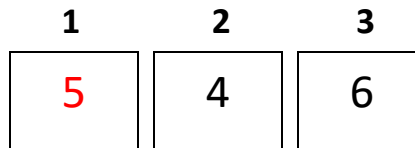
`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

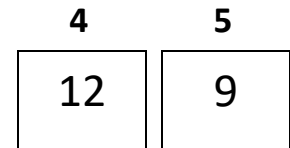
`quickSort(arr, 0, 0)`



`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`



right & left CROSS!  
1- swap pivot and arr[right]

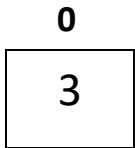


`quickSort(arr, 0, 5)`

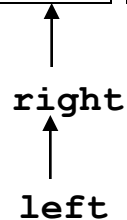
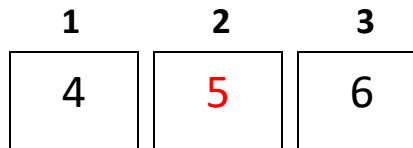
`quickSort(arr, 0, 3)`

`quickSort(arr, 4, 5)`

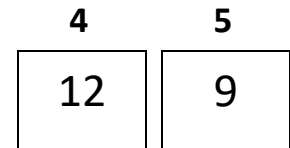
`quickSort(arr, 0, 0)`



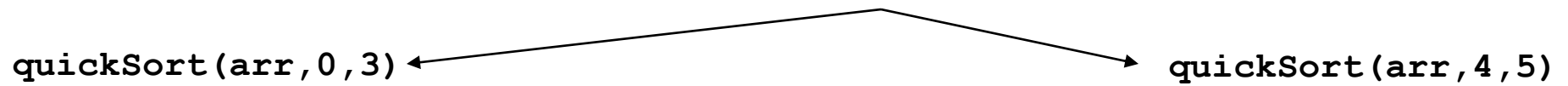
`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`



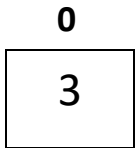
right & left CROSS!  
1- swap pivot and arr[right]



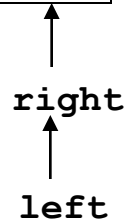
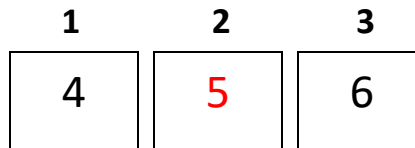
`quickSort(arr, 0, 5)`



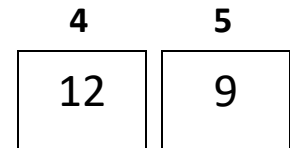
`quickSort(arr, 0, 0)`



`quickSort(arr, 1, 3)`  
`partition(arr, 1, 3)`



right & left CROSS!  
1- swap pivot and arr[right]  
2 – return new position of pivot



**return 2**

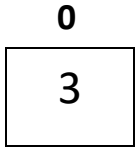
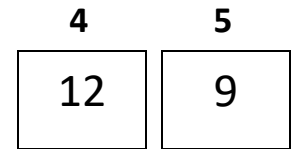
quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

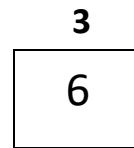
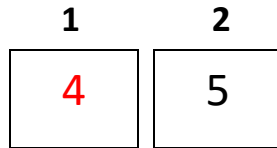
quickSort(arr, 0, 0)

quickSort(arr, 1, 3)



quickSort(arr, 1, 2)

quickSort(arr, 3, 3)



quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)

4

5

12

9

0

3

quickSort(arr, 1, 2)  
partition(arr, 1, 2)

quickSort(arr, 3, 3)

1

2

4

5

3

6



quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)

4

5

12

9

0

3

quickSort(arr, 1, 2)

quickSort(arr, 3, 3)

1

2

4

5

3

6

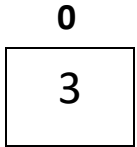
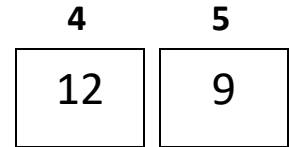
quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

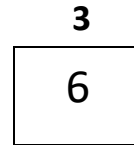
quickSort(arr, 0, 0)

quickSort(arr, 1, 3)



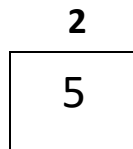
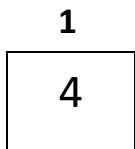
quickSort(arr, 1, 2)

quickSort(arr, 3, 3)



quickSort(arr, 1, 1)

quickSort(arr, 2, 2)



quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)  
partition(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)

4	5
12	9

0
3

quickSort(arr, 1, 2)

quickSort(arr, 3, 3)

3
6

quickSort(arr, 1, 1)

quickSort(arr, 2, 2)

1
4

2
5

quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)  
partition(arr, 4, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)

4	5
9	12

0
3

quickSort(arr, 1, 2)

quickSort(arr, 3, 3)

3
6

quickSort(arr, 1, 1)

quickSort(arr, 2, 2)

1
4

2
5

quickSort(arr, 0, 5)

quickSort(arr, 0, 3)

quickSort(arr, 4, 5)

quickSort(arr, 6, 5)

quickSort(arr, 0, 0)

quickSort(arr, 1, 3)

quickSort(arr, 4, 5)

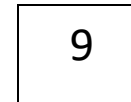
0



quickSort(arr, 1, 2)

quickSort(arr, 3, 3)

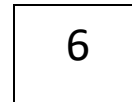
4



5



3



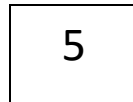
quickSort(arr, 1, 1)

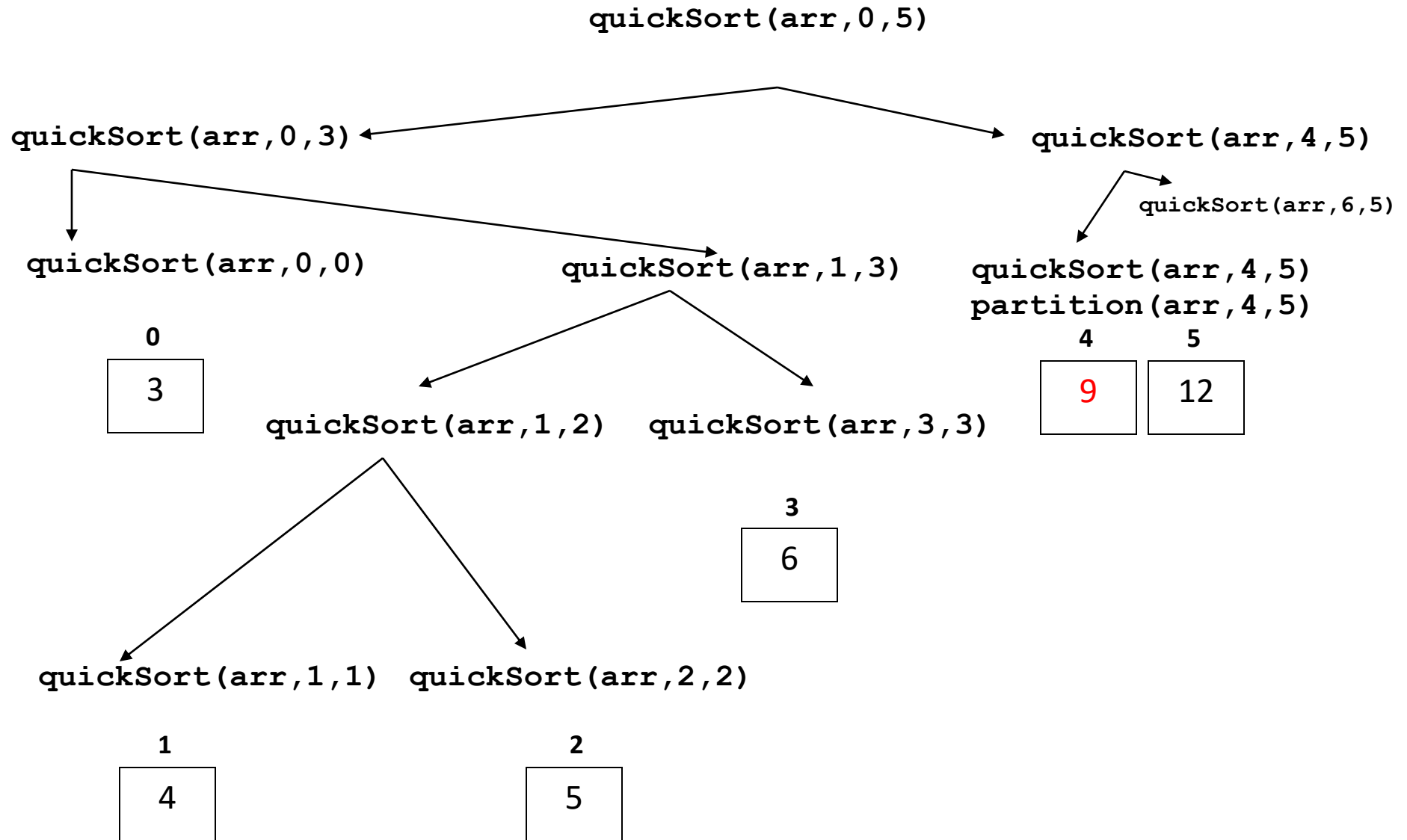
quickSort(arr, 2, 2)

1

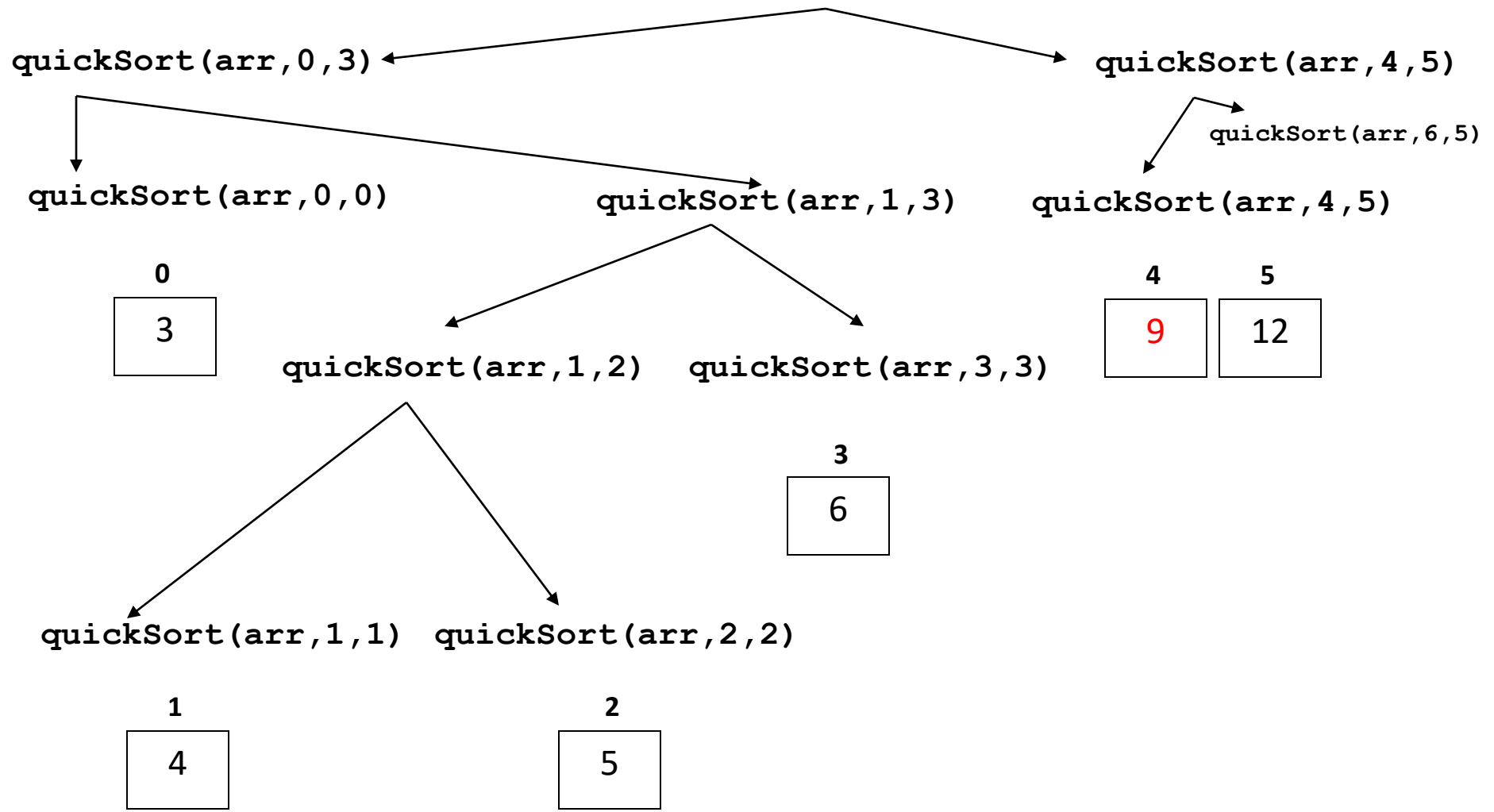


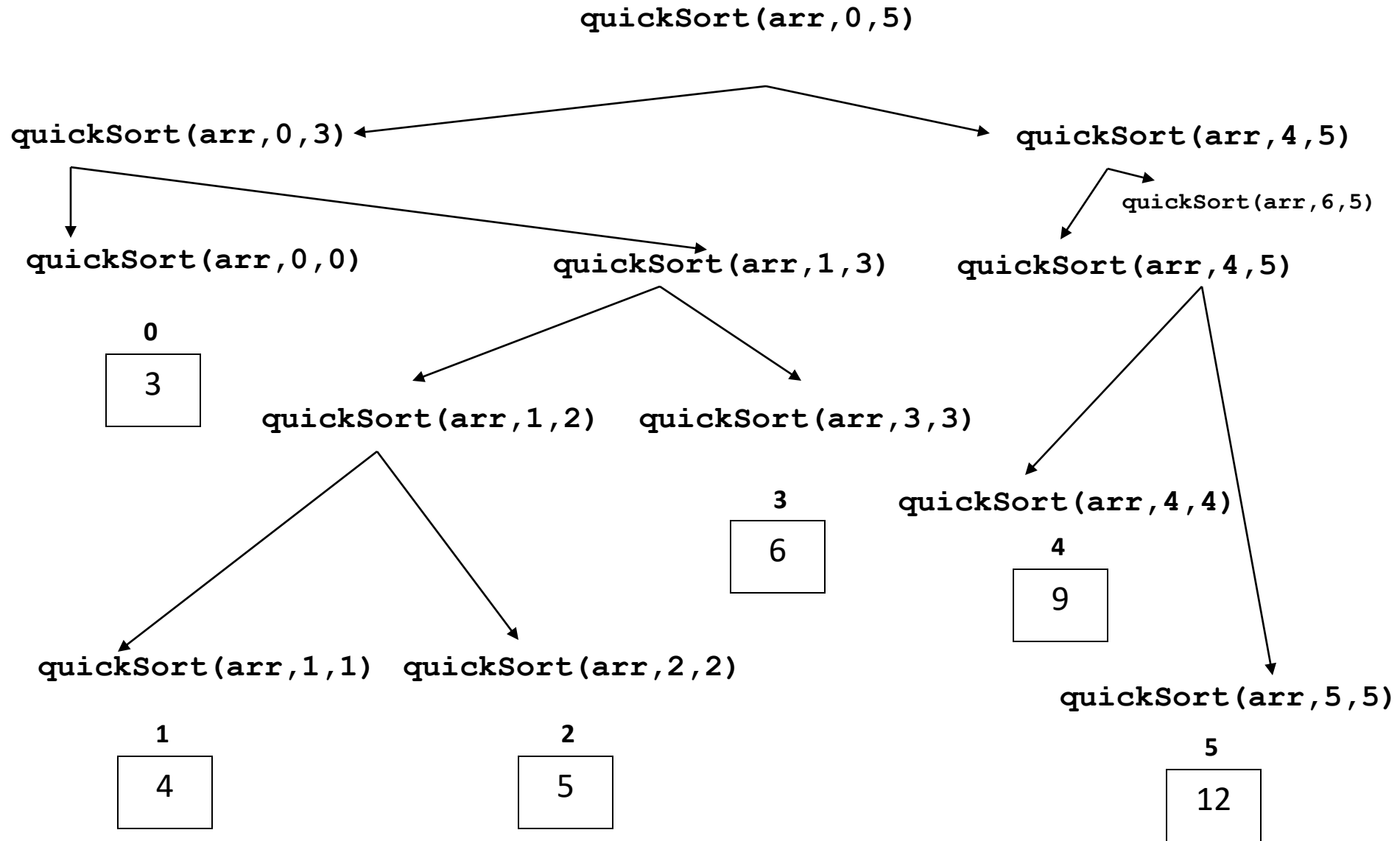
2





`quickSort(arr, 0, 5)`









**QUIZ  
TIME!**

# Quiz 1



**QUIZ  
TIME!**

- Suppose we are sorting an array of eight integers using quicksort, and we have just finished the first partitioning with the array looking like this: 2 5 1 7 9 12 11 10 Which statement is correct?
- A The pivot could be either the 7 or the 9.
- B The pivot could be the 7, but it is not the 9
- C The pivot is not the 7, but it could be the 9
- D Neither the 7 nor the 9 is the pivot.

# Quiz 2

- Let  $P$  be a QuickSort Program to sort numbers in ascending order using the first element as pivot. Let  $t_1$  and  $t_2$  be the number of comparisons made by  $P$  for the inputs  $\{1, 2, 3, 4, 5\}$  and  $\{4, 1, 5, 3, 2\}$  respectively. Which one of the following holds?
  - A  $t_1 = 5$
  - B  $t_1 < t_2$
  - C  $t_1 > t_2$
  - D  $t_1 = t_2$

# Quiz 3

- Discuss Which one of the following in place sorting algorithms needs the minimum number of swaps?

A

Quick sort

B

Insertion sort

C

Selection sort

D

Heap sort

# Quiz 4

- You have an array of  $n$  elements. Suppose you implement quick sort by always choosing the central element of the array as the pivot. Then the tightest upper bound for the worst case performance is ??

# Quiz 5

- The Quicksort algorithm we have seen in class is the following:

*QUICKSORT*( $A, p, r$ )

```
1  if  $p < r$ :  
2       $q \leftarrow \text{PARTITION}(A, p, r)$   
3      QUICKSORT( $A, p, q - 1$ )  
4      QUICKSORT( $A, q + 1, r$ )
```

*PARTITION*( $A, p, r$ )

```
1   $i \leftarrow p - 1$   
2  for  $j \leftarrow p$  to  $r - 1$   
3      if  $A[j] \leq A[r]$   
4           $i \leftarrow i + 1$   
5          exchange  $A[i] \leftrightarrow A[j]$   
6  exchange  $A[i + 1] \leftrightarrow A[r]$   
7  return  $i + 1$ 
```

## Quiz 5

### Continues...

5-1- Make the smallest possible change to the algorithm such that it would stop with a nearly-sorted array. This is accomplished by not sorting subarrays with  $k$  elements or less. Mark your change on the copy of the algorithm given above.

5-2 With the change you made in part 1, and  $k=3$ , how many recursive calls to Quicksort are required to nearly-sort the following array?

3	6	1	4	7	2	8	5
---	---	---	---	---	---	---	---

5-3- With the change you made in part 1,  $k = 3$ , and the array given in part 2, compute the final array obtained by Quicksort