

Mozart: A Mobile ToF System for Sensing in the Dark through Phase Manipulation

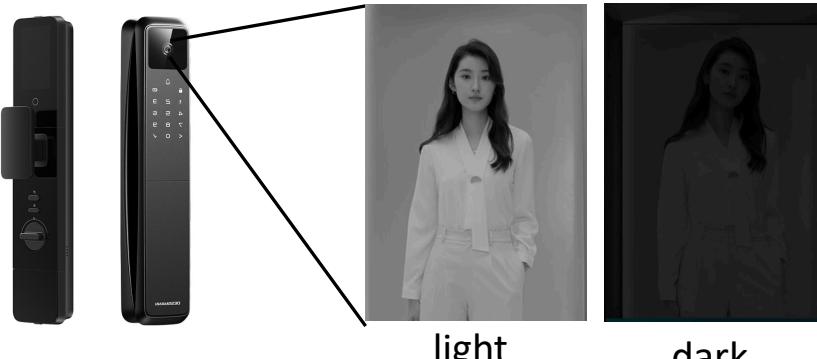
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² University of Michigan, Ann Arbor ³ Michigan State University



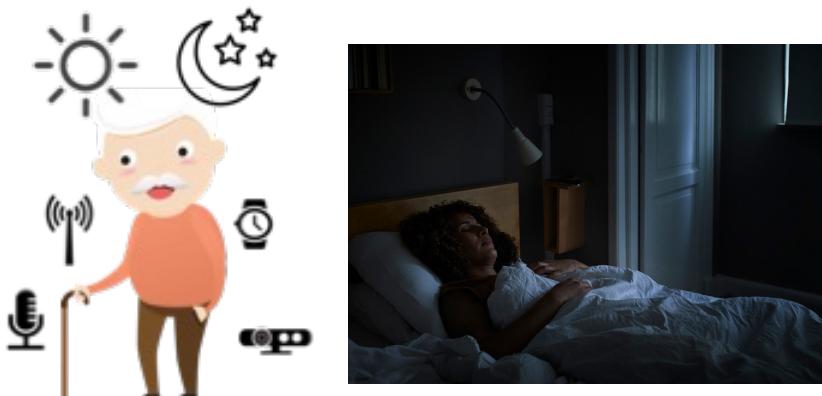
Sensing in the Dark: Applications



Smart door lock



Patrol robot



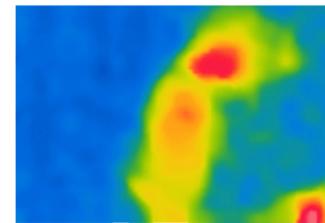
7/24 health monitoring



Security and surveillance

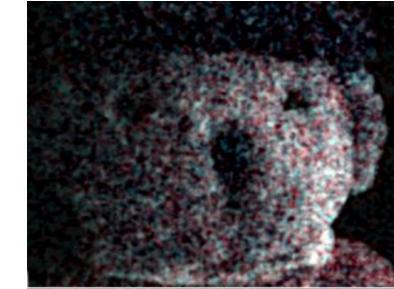
Sensing in the Dark: Current Solutions

Passive Sensing



Thermal camera

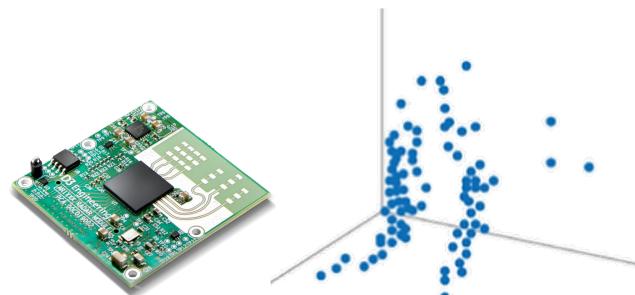
✗ low resolution



Enhanced RGB camera

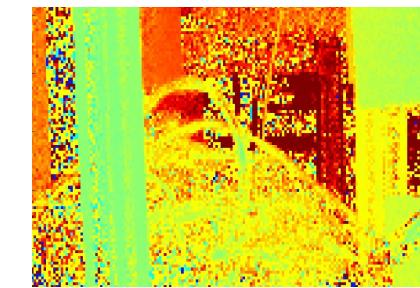
✗ high noise

Active Sensing



mmWave radar

✗ sparse point cloud



ToF depth camera

✗ low quality

Mozart: Sensing in the Dark with ToF Camera

ToF Cameras



Original Functionality
→



Depth Image

Mozart
→



Mozart Image

Key idea: exposing texture information from ToF cameras.

Designing Mozart: Challenges

- Improve texture resolution while retaining depth measurement.

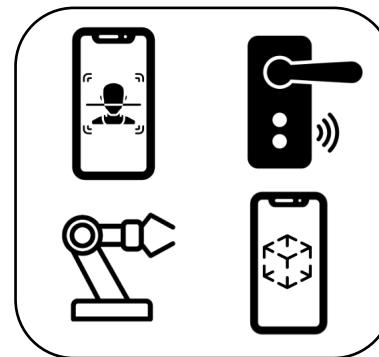
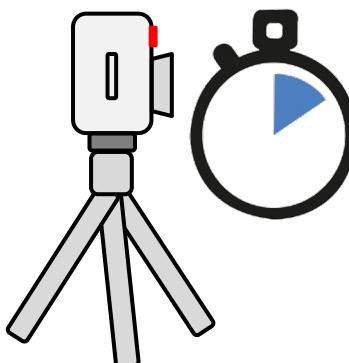


Mozart image



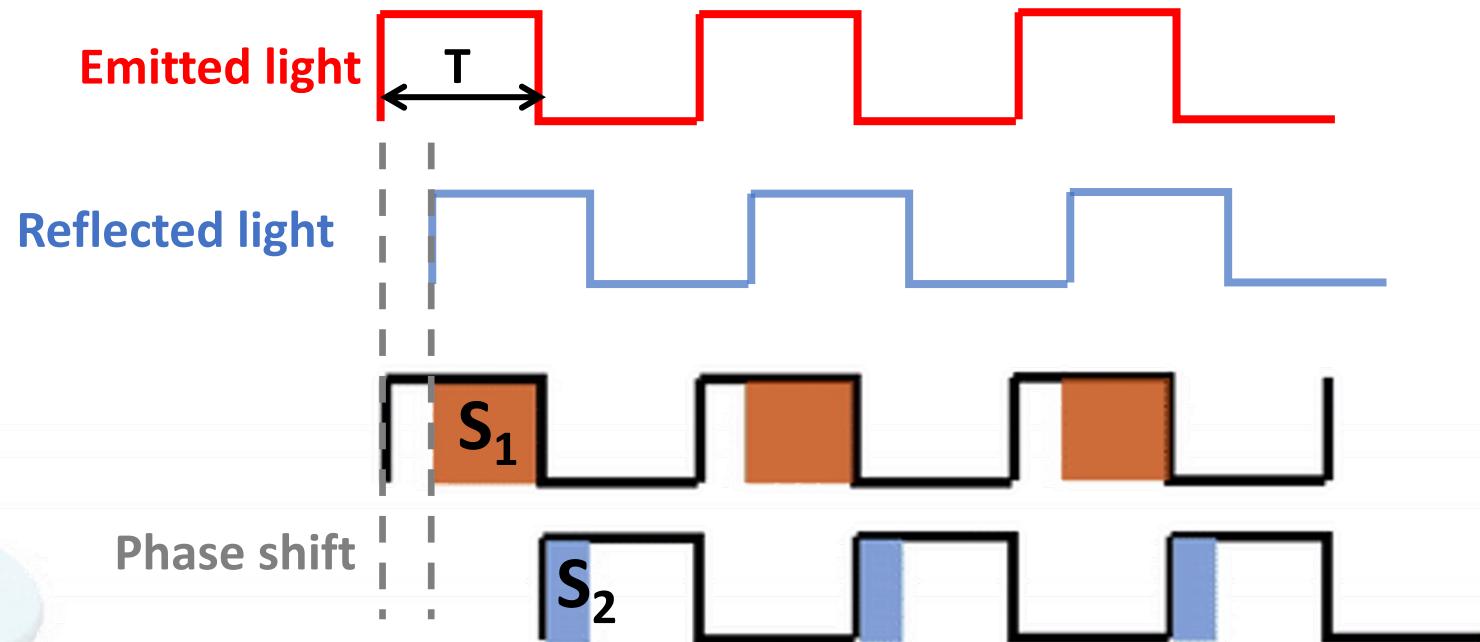
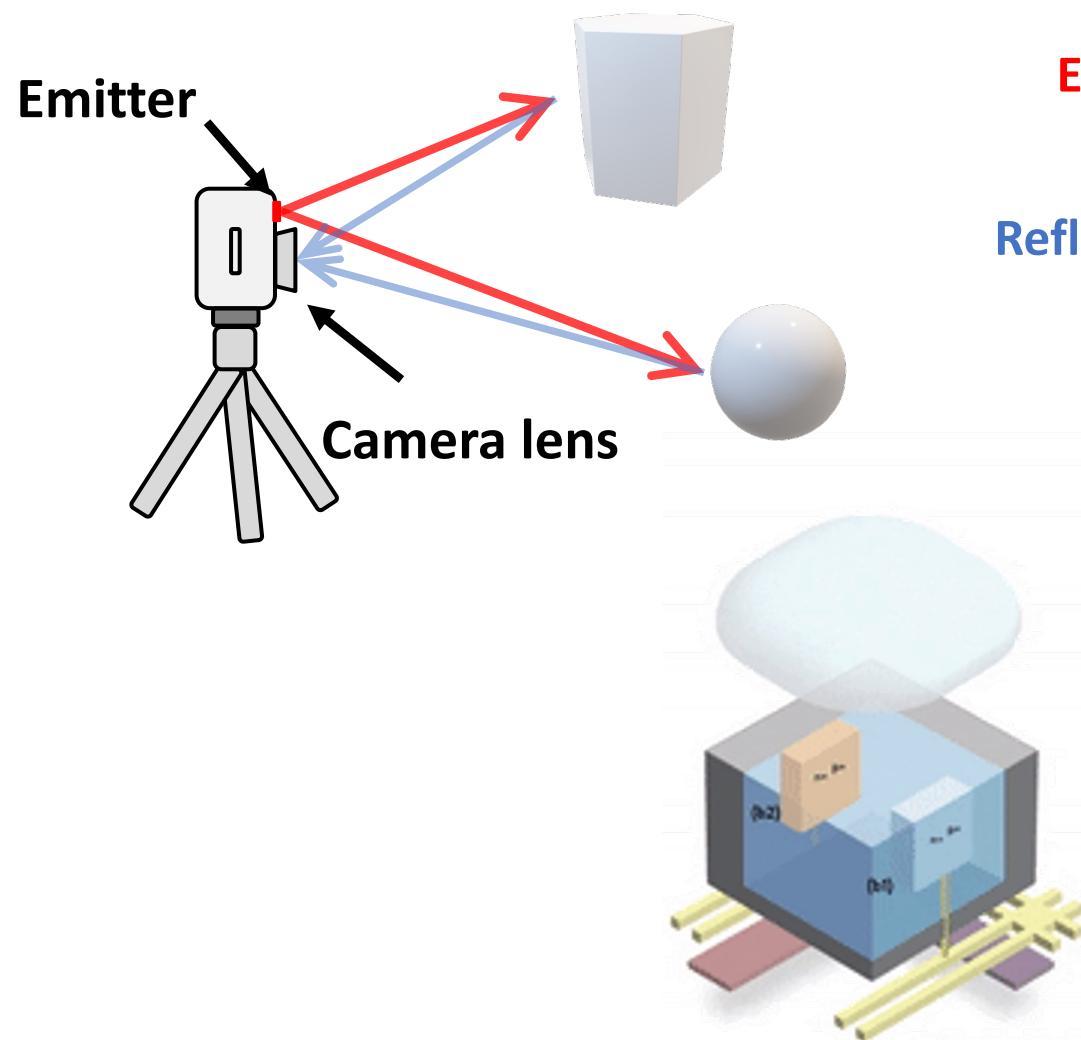
Depth image

- Generate high quality images in real time.



Real-time applications in
the dark

Understanding ToF Depth Sensing

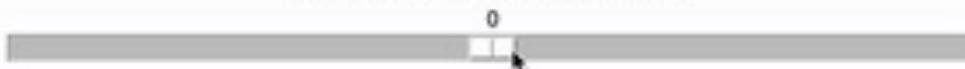


$$\text{distance} = \frac{S_2}{S_1 + S_2} \cdot \frac{cT}{2}$$

Expose Textures via Phase Manipulation



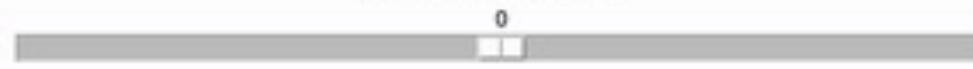
Normal depth map



ΔS_1



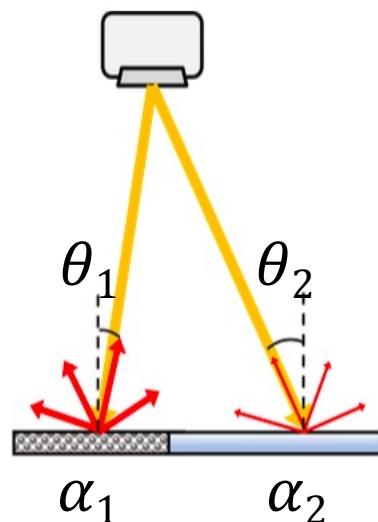
Mozart map



ΔS_2

Mozart: Physics Model for Exposing Textures

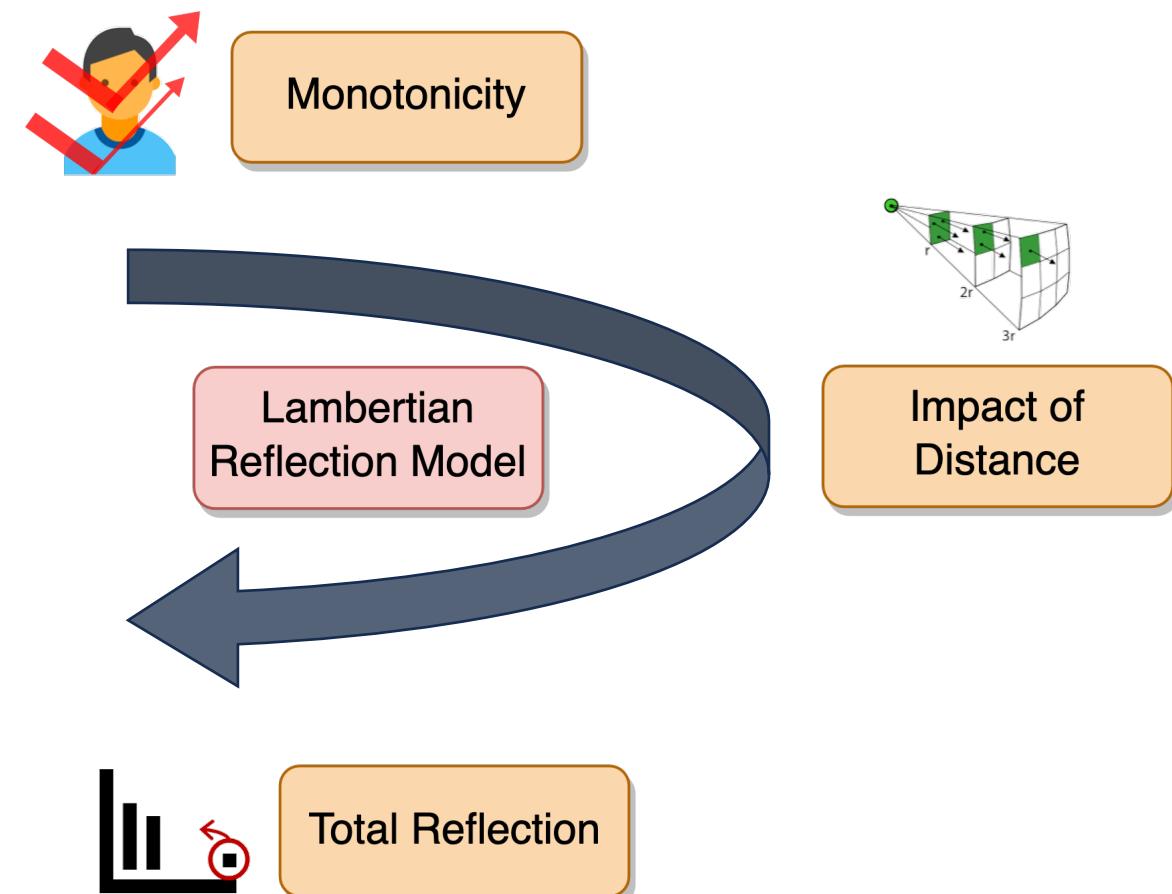
Lambertian reflection model



α : reflectivity
 θ : angle of incidence

Texture-related

$$\text{Albedo: } \beta = \alpha \cos \theta$$

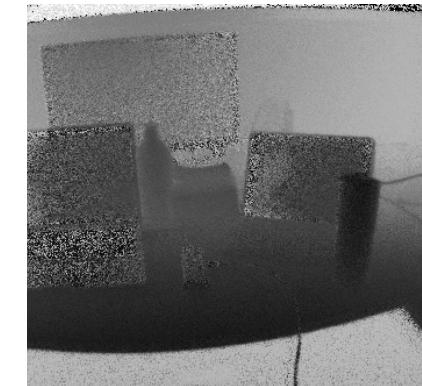
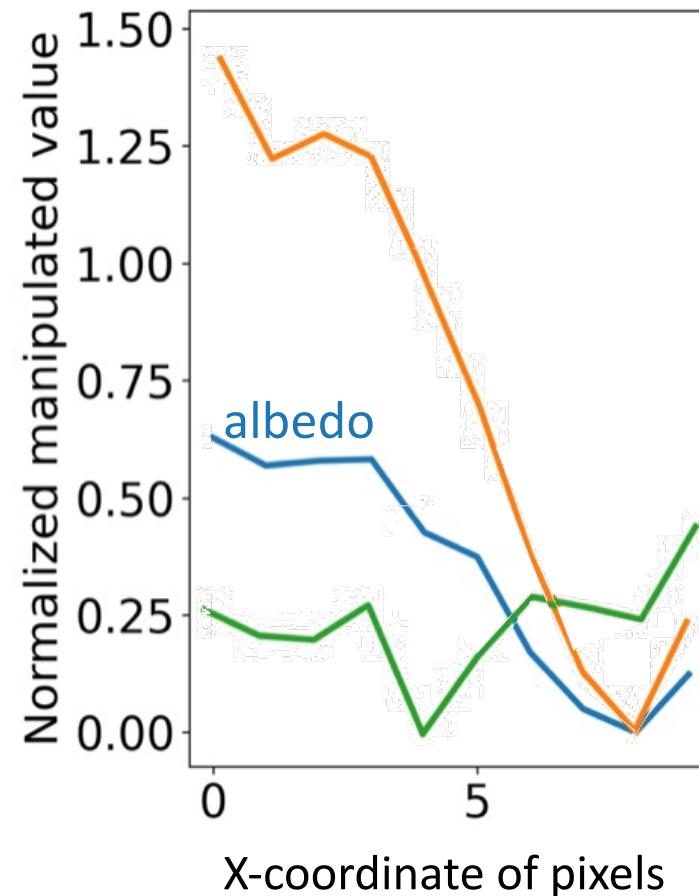


The phase components S_1 and S_2 can be represented by albedo β and distance d .

Observation 1: Monotonicity to Albedo



Monotonicity

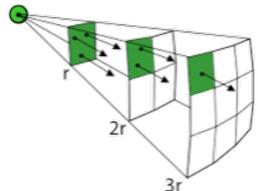


Non-monotonic to albedo



Monotonic to albedo

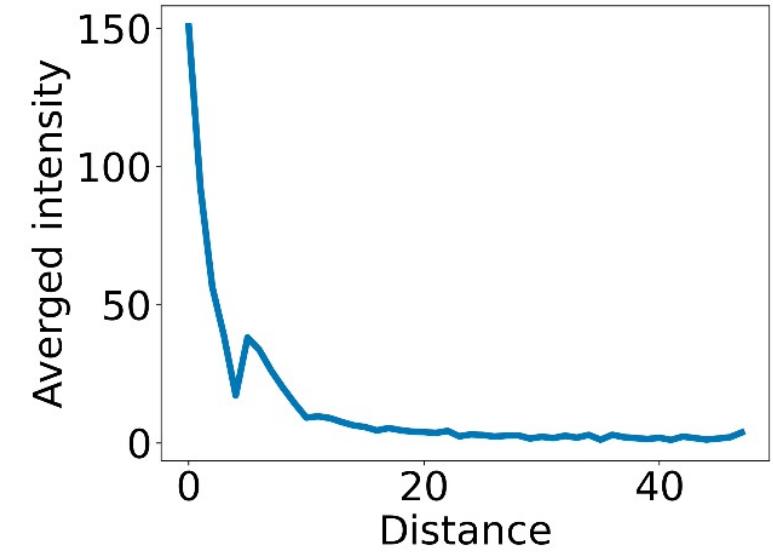
Observation 2: Impact of Distance



Impact
of
Distance



A typical image after phase manipulation



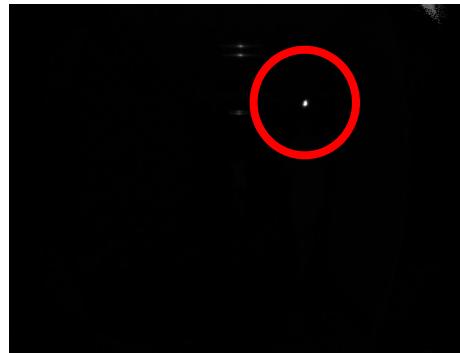
The phase components are reversely proportional to the square of distance.

Observation 3: Addressing Total Reflection



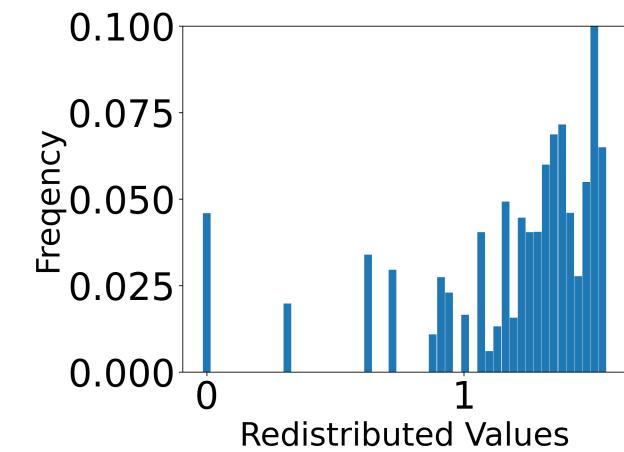
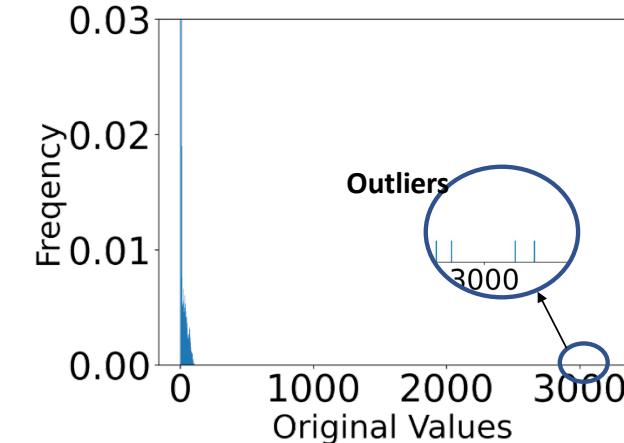
Total Reflection

With total reflection



Caused by objects like metals and glass

Total reflection mitigated

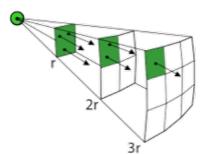


Mozart: Phase Manipulation Functions



Monotonicity

The phase manipulation functions must satisfy: $\frac{\partial f(S_1, S_2)}{\partial \beta} > 0$



Impact of Distance

Choose a $f(S_1, S_2)$ from the variants of $g(S_1, S_2) = \frac{S_2^2}{S_1 + S_2} = \frac{E_0}{8D^2} \cdot \beta$

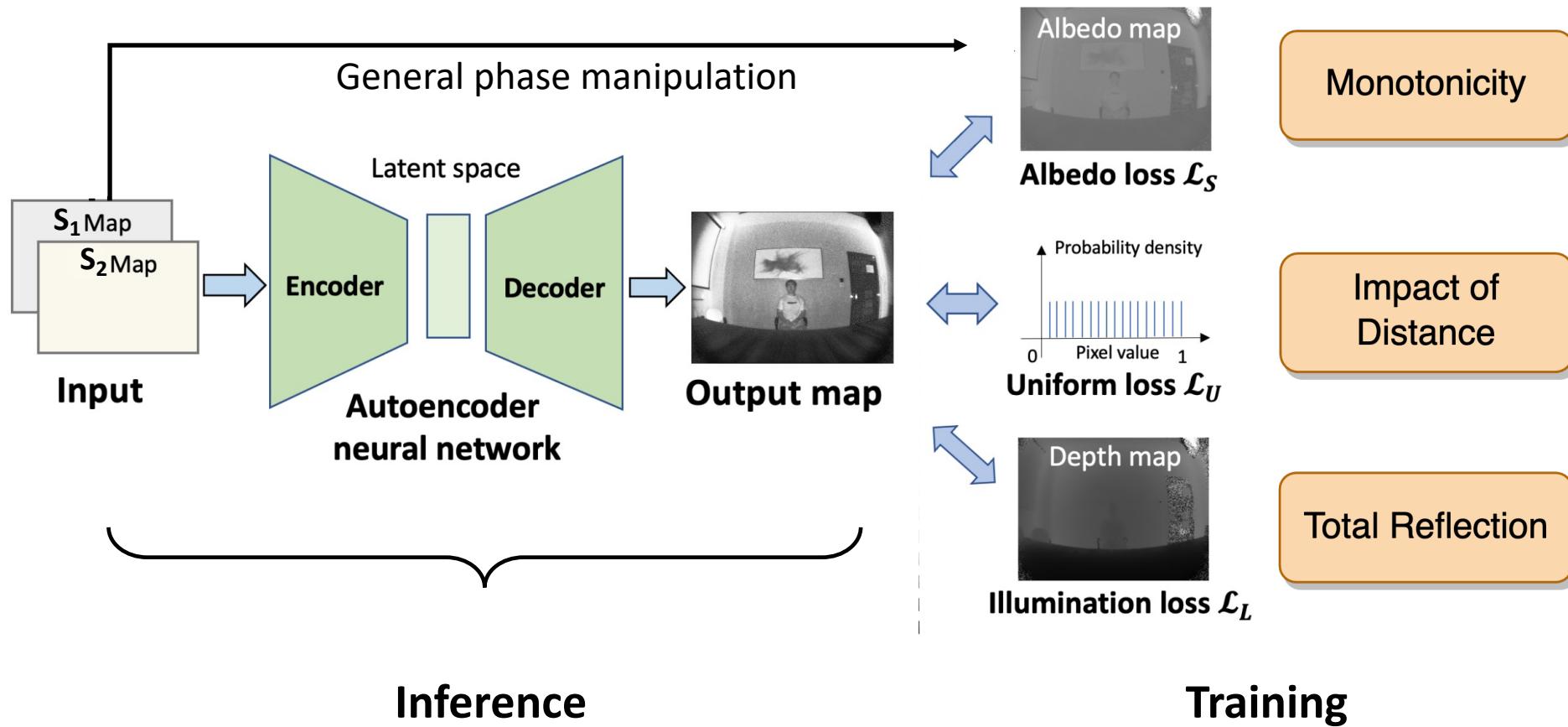


Total Reflection

Nest the redistribution function $r(S)$ outside $f(S_1, S_2)$

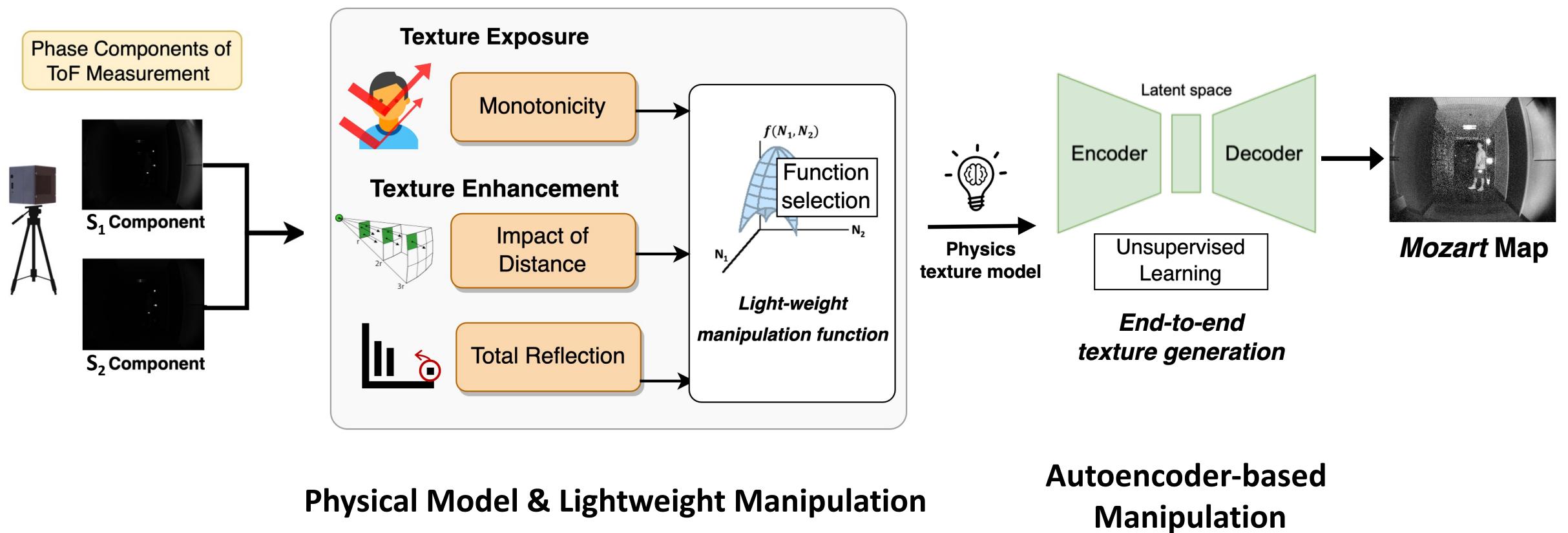
Lightweight, but requires domain expertise.

Mozart: ML-based Phase Manipulation



$$\mathcal{L} = \lambda_s \mathcal{L}_S + \lambda_l \mathcal{L}_L + \lambda_u \mathcal{L}_U$$

Mozart: Put it all together

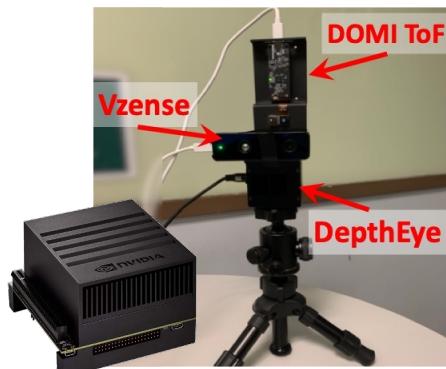


System Implementation & Dataset

- Various platform



Samsung S20Ultra &
HUAWEI Mate30 Pro
(ARCore / AREngine)



Standalone ToF cameras with
Nvidia Jetson Xavier

- Self-collected Dataset



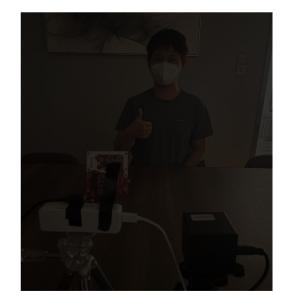
Human tracking

👤 9 📄 8000



Face recognition

👤 12 📄 15000



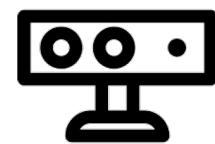
Gesture recognition

👤 12 💪 20

- Baselines (Five modalities)



IR



Depth



Radar

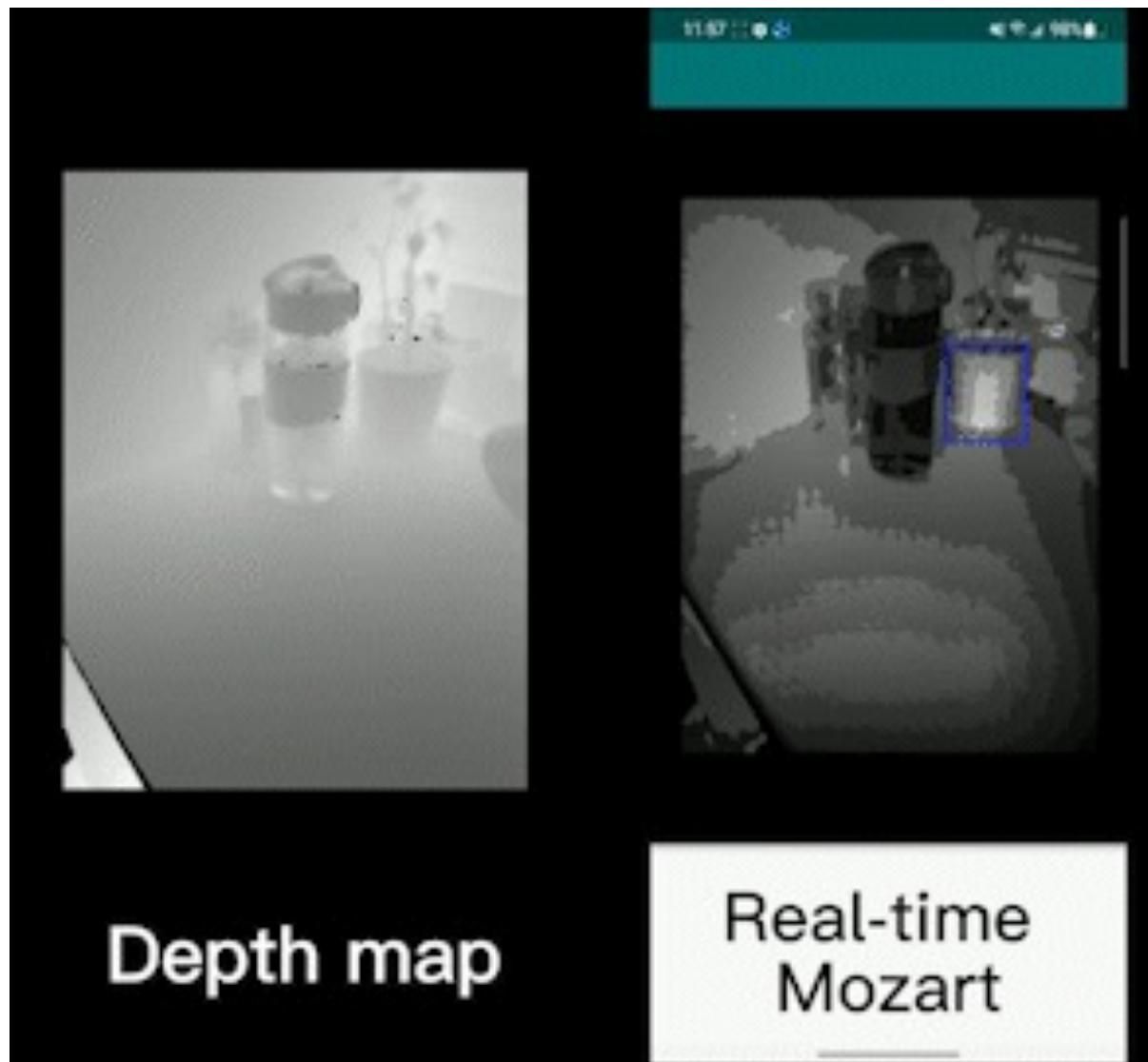


RGB



Enhanced RGB

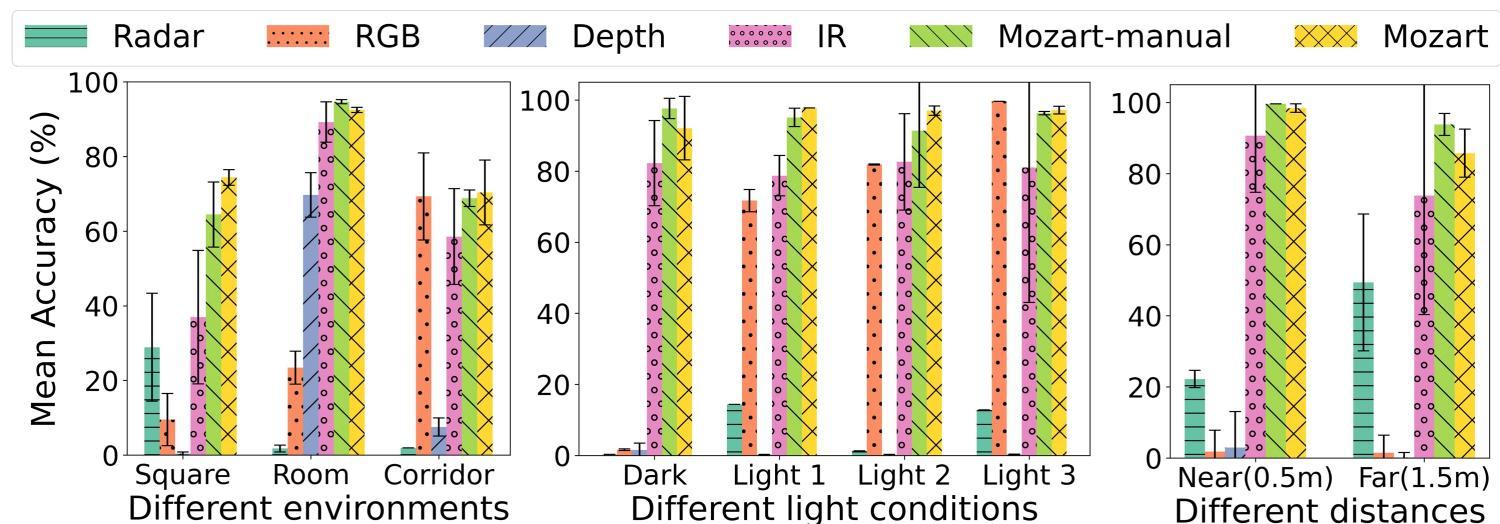
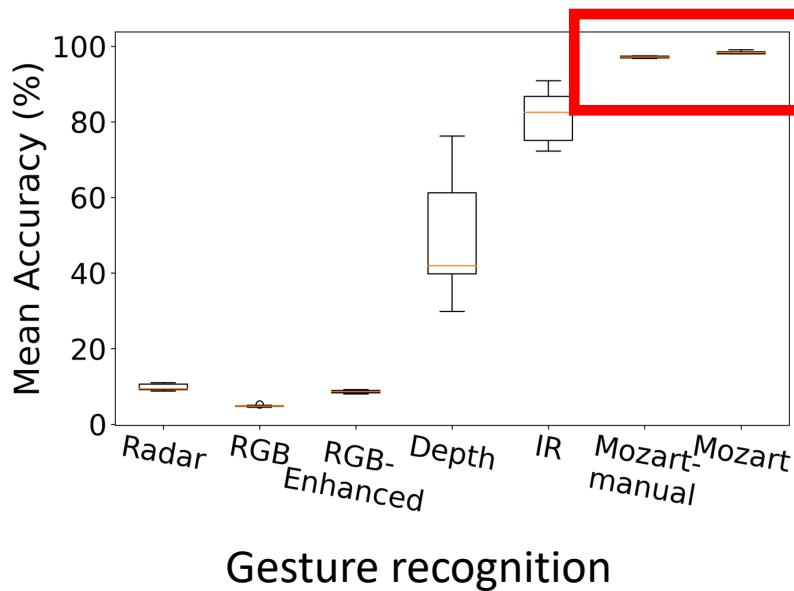
A Real-time Demo



Object detection rate:

- view of Depth: 7%
- the dark
 - Mozart: 89%

Comparison with Different Modalities

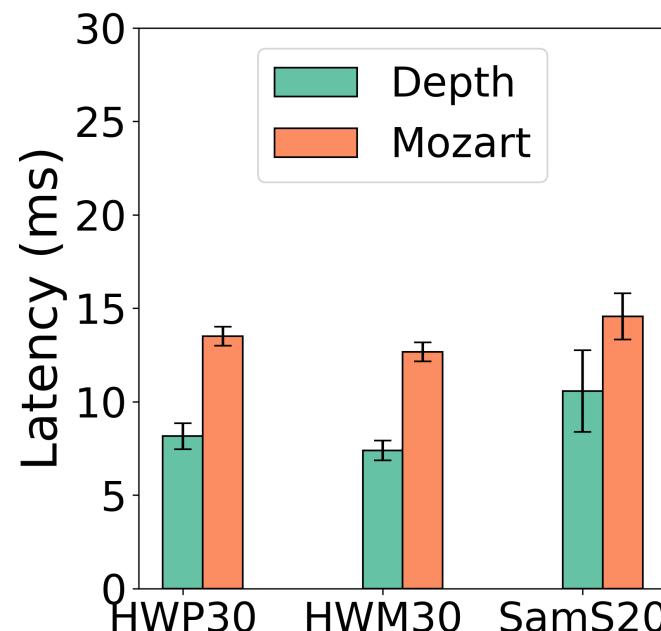


Mozart outperforms RGB, Radar, and depth images by **93.4%**, **88.46%**, and **45.76%**, respectively.

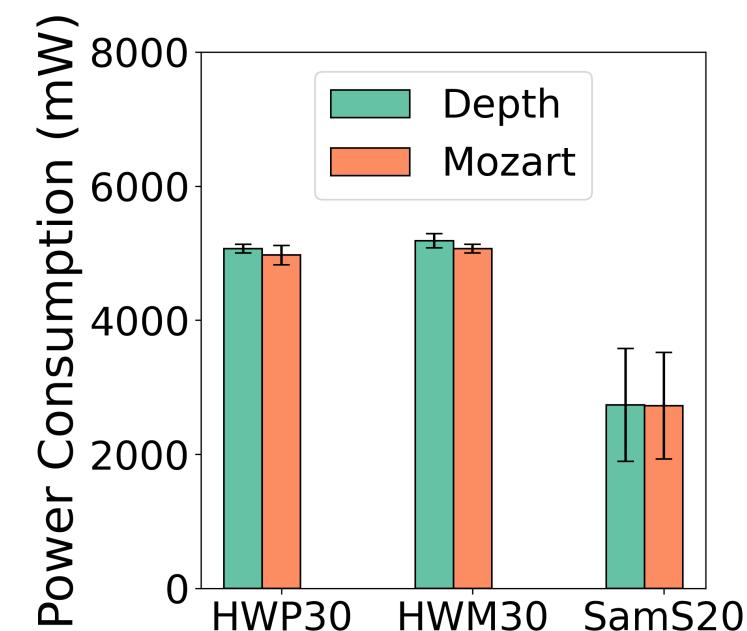
Mozart is robust to various environments, light conditions, and distances.

Overhead on Smartphones

➤ Latency



➤ Power consumption



- Achieve more than **30 fps** on smartphones

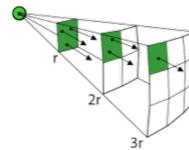
- Does not significantly increase overhead

Conclusion

- *Mozart*: a novel system for sensing in the dark using ToF cameras.
 - First-principle physical models to expose high-resolution textures from ToF cameras.



Monotonicity



Impact of Distance



Total Reflection

- Future work

- Apply Mozart maps in multi-modality vision algorithms
- Enable new mobile sensing and vision systems

Thanks!

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- <http://aiot.ie.cuhk.edu.hk>



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