Dimensionality reduction methods

Objective: Reduce number of dins. without Why? loose vital information/representation

- Compression in the data.

- Visualization X - D Z

- Curse of dimenSionality
LD N ~ 51

XER ZER

d < n

Two categories:

Feature Selection

- Selects certain features without transforming them

Frature extraction

- Creates new features bared on the original by some function.

Multidimensionality scaling (MDS)

In the category of feature extraction.

R Given N Sainples, we consider all distances

dis to be given using some metric (like Lz or L,)

LD MDS places there in a d-dim space so that these distances are preserved as best as prossible!

Gram matrix B: Contains all possible uner products between the N samples

MDS:
$$Y \cdot Y \approx X \cdot X^{\mathsf{T}}$$
, where
$$Y = \begin{bmatrix} y' & \longrightarrow \\ \vdots & & - p \end{bmatrix} \in \mathbb{R}^{\mathsf{N} \times \mathsf{d}}$$

To achieve these reduced dimensional y samples it can be shown that it amounts to

- a) Find the eigenvalues $\{\lambda_i\}_{i=1}^N$ of the Gram (3) matrix $\{\beta_i\}_{i=1}^N$ and corresponding eigenvectors $\{\beta_i\}_{i=1}^N$
- 6) Choose a subset of the d largest eigenvals.
- c) Construct a diagnal matrix $\Delta_{a}^{1/2}$ with. The NB! d largest eigenvals on the diagonal (sorted)
- d) Construct a matrix E_d , where the columns are the eigenvectors corresponding to the d largest eigenvals.

e) $y^{i} = (E_{d} \wedge A_{d})^{i}$, i = 1, ..., N (the rows)

Bunefits of Feature extraction:

- "Fast way of reducing complexity O(N3)
- Preserves the important information

Downsides:

- What do the new dims represent?

Frature Eduction can fix this "explainability"
problem.

Feature selection

- Keep relivant, remove irrelevant

LD Redundant, some features

correlates with others.

- Find best subset

LD Least number of features contributing

the most to the accuracy.

Fibruard relection: Add features one by one and check error towards validation ret.

Lo Stop when error is lowest.

PS: FS needs a supervised dataset $\{X^i, y^i\}_{i=1}^N$ this is not neccessary in feature extraction!

Drawbacks: - Can be costly computationally & impl. with crossodidation

- Do not neccessarily find all redundant features / best subsets.

- Needs labels - Selected features depends heavily on model (pred.

derstood task.

Benefits - Explainability

- Easily understood algorithm.

Dim. reduksjon metoder

Mål: Reducere antall dim. uten å miste vital informasjon/representasjon i data.

Why?: LD Compression Lo Visualisering Lo Computational complexity.

X -D Y X ERN, Y ERD n-din d-din n features

d features

1a) Feature Eduction : Selekterer noon features uten à transformere de

teature extraction: Layer mye features barent pa de opprimmelige wha, en funlisjon.

MDS: leategorien extraction

Baset på å bevære lik avstand mellom vektorene i Sample matrisene

X Sml. med Y

Austandsmål: Inda-produkt X: X;

Gran matrise: Bx = X. XT E IR NXN

Lo Innelialder alle "austandene" nullom alle samples

MDS:
$$\underline{Y} \cdot \underline{Y} \stackrel{\times}{=} \underbrace{X} \cdot \underline{X}^{T} dur$$

$$\underline{Y} = \begin{bmatrix} \underline{Y} & \underline{X} & \underline{X} & \underline{X} \\ \underline{Y} & \underline{X} & \underline{X} \end{bmatrix} \in \mathbb{R}^{N \times d}$$

Hoordon? Algoritme:

- a) finn egenverdien {\lambda_i} \lambda_i \rangle i \ran
- b) Velg it subset av de de storste eg. vadier of
 eg. velstorer { 7;3 i=1 { e i } i=1
- () Konstruer en diag. matrise 1/2 A d med de d storste di pa diag (soutest)
- d) Konstruer matrisa Ed hoor hollomene er eg. vebtoren titsvarende eg. vediene.
- e) $y_i = \left(\frac{E_d}{L_d} \frac{1}{2} \right)^i$ i = 1, ..., N (radene) $N \times d = d \times d$

Bruhs områder: Der avstander mellom features en en vihtig fahtor. å bevære

3

Formel slide 23

Indreprod.

(ndreprod.

austandomál

dij = ||xi - xj||^2 & Eublidok austandomál

$$C = I_{N} - \frac{1}{N} J_{N}, der I_{N} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ 0 & 0 &$$

$$\mathcal{F}_{N} = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ 1 & 1 & \cdots & 1 \\ \vdots & \vdots & \ddots & \ddots & 1 \end{pmatrix}$$

Derfra viden til å redusere til 2 dim. y, yz,..., yn ER²