

Differential Privacy and its Application in Aggregation

Part 1 — Differential Privacy

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Motivation

- ▶ Consider a **trusted** party that holds a dataset of sensitive information (e.g. medical records, voter registration information, email usage) with the goal of providing **global, statistical information** about the data **publicly available**, while **preserving the privacy** of the users whose information the data set contains. Such a system is called a **statistical database**.
- ▶ The notion of indistinguishability, later termed **Differential Privacy**, formalizes the notion of "privacy" in statistical databases.

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- ▶ The notion of indistinguishability, later termed **Differential Privacy**, formalizes the notion of "privacy" in statistical databases.

Definition

ϵ -differential privacy

- ▶ The actions of the trusted server are modeled via a randomized algorithm \mathcal{A} . A randomized algorithm \mathcal{A} is ϵ -differentially private if for **all** datasets D_1 and D_2 that differ on **a single element** (i.e., data of one person), and all $S \subseteq \text{Range}(\mathcal{A})$,

$$\Pr[\mathcal{A}(D_1) \in S] \leq e^\epsilon \times \Pr[\mathcal{A}(D_2) \in S],$$

where the probability is taken over the coins of the algorithm and $\text{Range}(\mathcal{A})$ denotes the output range of the algorithm \mathcal{A} .

Description

- ▶ ϵ is the privacy parameter, e.g. if $\epsilon = 0.1$ then $e^\epsilon \approx 1.105$, if $\epsilon = 0.5$ then $e^\epsilon \approx 1.649$.

$$\Pr[\mathcal{A}(D_1) \in S] \leq e^\epsilon \times \Pr[\mathcal{A}(D_2) \in S]$$

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- ▶ This means that for any two datasets which are **close** to one another (that is, which differ on a single element) a given differentially private algorithm \mathcal{A} will behave **approximately the same** on both data sets.
- ▶ The definition gives a strong guarantee that **presence or absence** of an individual will not affect the final output of the query significantly.

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Diabetes example

- For example, assume we have a database of medical records D_1 where each record is a pair **(Name,X)**, where $\mathbf{X} \in \{0, 1\}$ denotes whether a person has diabetes or not. For example:

Name	Has Diabetes (X)
Ross	1
Monica	1
Joey	0
Phoebe	0
Chandler	1

- Now suppose a malicious user (often termed an adversary) wants to find whether Chandler has diabetes or not.

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What an adversary can do

- ▶ As a **side information** he knows in which row of the database Chandler resides.
- ▶ Now suppose the adversary is **only allowed** to use a particular form of query $Q(i)$ which returns the partial sum of first i rows of column **X** in the database.
- ▶ In order to find Chandler's diabetes status the adversary simply executes $Q(5) - Q(4)$.
- ▶ One striking feature this example highlights is: individual information can be compromised even **without** explicitly querying for the **specific** individual information.

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Differential privacy in the example

- ▶ Now we construct D_2 by replacing (Chandler,1) with (Chandler,0). Let $\mathcal{A} = Q(i)$.
- ▶ We say \mathcal{A} is ϵ -differentially private if it satisfies the definition:

$$\Pr[\mathcal{A}(D_1) \in S] \leq e^\epsilon \times \Pr[\mathcal{A}(D_2) \in S]$$

- ▶ S can be thought of as a singleton set (something like $\{3.5\}$, $\{4\}$ etc.) if the output function of \mathcal{A} is a Discrete Random Variable (i.e. has a probability mass function (pmf)).
- ▶ S can also be thought to be a small range of reals (something like $3.5 \leq \mathcal{A}(D_1) \leq 3.7$) if it is a Continuous Random Variable (i.e. has a probability density function (pdf)).

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Sensitivity

- ▶ The sensitivity (Δf) of a function $f : \mathcal{D} \rightarrow \mathbb{R}^d$ is

$$\Delta f = \max_{D_1, D_2} \|f(D_1) - f(D_2)\|_1$$

for all D_1, D_2 differing in **at most one element**, and $D_1, D_2 \in \mathcal{D}$.

- ▶ Clearly, if we change one of the entries in the database then the output of the query $Q(i)$ will change by at most one. So, the sensitivity of the query $Q(i)$ is **one**.
- ▶ It so happens that there are techniques (which are described below) using which we can create a differentially private algorithm for functions with low sensitivity.

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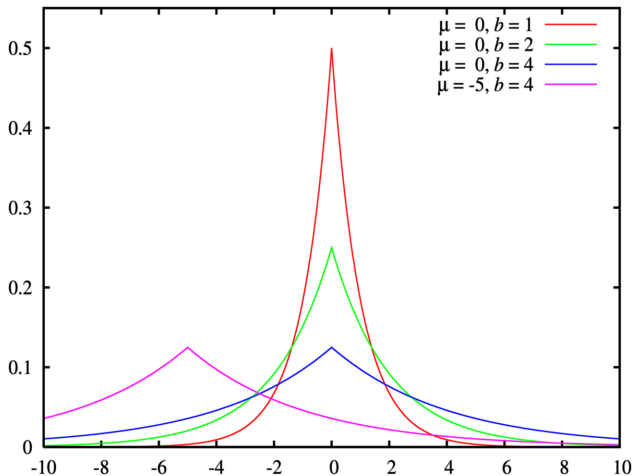
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Laplace Distribution

- ▶ Laplace distribution is a **continuous** probability distribution named after Pierre-Simon Laplace.
- ▶ It is also sometimes called the *double exponential distribution*, because it can be thought of as two exponential distributions (with an additional location parameter) spliced together back-to-back.

Laplace Distribution



Laplace Distribution Probability Density Function

Laplace Distribution

- Probability density function (PDF):

$$f(x|\mu, \lambda) = \frac{1}{2\lambda} e^{\left(-\frac{|x-\mu|}{\lambda}\right)} = \frac{1}{2\lambda} \begin{cases} e^{\left(-\frac{\mu-x}{\lambda}\right)} & \text{if } x < \mu \\ e^{\left(-\frac{x-\mu}{\lambda}\right)} & \text{if } x \geq \mu \end{cases}$$

- Here, μ is a **location parameter** and $\lambda \leq 0$ is a **scale parameter**. If $\mu = 0$ and $\lambda = 1$, the positive half-line is exactly an exponential distribution scaled by 1/2.
- PDF of exponential distribution:

$$f(x; \beta) = \begin{cases} \frac{1}{\beta} e^{-x/\beta}, & x \geq 0, \\ 0, & x < 0. \end{cases}$$

Laplace Noise

- ▶ Many differentially private algorithms rely on adding **controlled noise** to functions with **low sensitivity**.
- ▶ We will elaborate this point by taking a special kind of noise (whose kernel is a **Laplace distribution** i.e. the probability density function $\text{noise}(y) \propto e^{-|y|/\lambda}$, mean zero and standard deviation λ).
- ▶ Now in our case we define the output function of \mathcal{A} as a real valued function (called as the transcript output by \mathcal{A}) $\mathcal{T}_{\mathcal{A}}(x) = f(x) + Y$, where $Y \sim \text{Lap}(\lambda)$ and f is the original real valued query/function we plan to execute on the database.

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Laplace Noise

- ▶ Now clearly $\mathcal{T}_{\mathcal{A}}(x)$ can be considered to be a continuous random variable, where

$$\frac{\text{pdf}(\mathcal{T}_{\mathcal{A}, D_1}(x) = t)}{\text{pdf}(\mathcal{T}_{\mathcal{A}, D_2}(x) = t)} = \frac{\text{noise}(t - f(D_1))}{\text{noise}(t - f(D_2))}$$

which is at most $e^{\frac{|f(D_1) - f(D_2)|}{\lambda}} \leq e^{\frac{\Delta(f)}{\lambda}}$.

- ▶ We can consider $\frac{\Delta(f)}{\lambda}$ to be the privacy factor ϵ . Thus \mathcal{T} follows a differentially private mechanism (as can be seen from the definition).
- ▶ If we try to use this concept in our diabetes example then it follows from the above derived fact that in order to have \mathcal{A} as the ϵ -differential private algorithm we need to have $\lambda = 1/\epsilon$.

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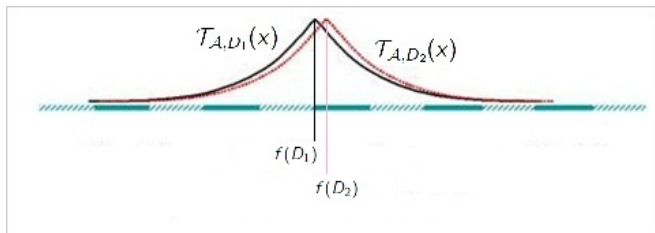
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Laplace Noise

- ▶ If $Y \sim \text{Lap}(0, \lambda)$, then

$$\mathcal{T}_{A,D_1}(x) = f(D_1) + Y \sim \text{Lap}(f(D_1), \lambda)$$

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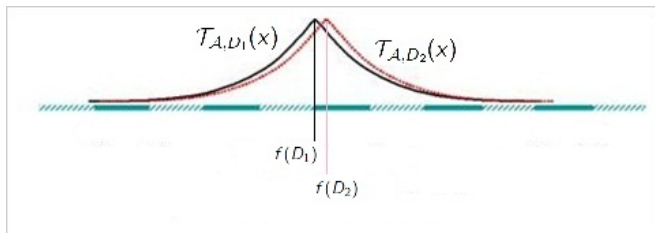
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- ▶ Thus we can achieve differential privacy by add adding Laplace noise to the output.

Sequential composition

- ▶ If we query an ϵ -differential privacy mechanism t times, and the randomization of the mechanism is independent for each query, then the result would be ϵt -differentially private.
- ▶ In the more general case, if there are n independent mechanisms: $\mathcal{M}_1, \dots, \mathcal{M}_n$, whose privacy guarantees are $\epsilon_1, \dots, \epsilon_n$ differential privacy, respectively, then any function g of them: $g(\mathcal{M}_1, \dots, \mathcal{M}_n)$ is $(\sum_{i=1}^n \epsilon_i)$ -differentially private.

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Parallel composition

- Furthermore, if the previous mechanisms are computed on **disjoint subsets** of the private database then the function g would be $(\max_i(\epsilon_i))$ -differentially private instead.

Group privacy

- ▶ In general, ϵ -differential privacy is designed to protect the privacy between **neighboring databases** which differ only in one row. This means that no adversary with arbitrary auxiliary information can know whether one particular participant submitted his information.
- ▶ However this is also extendable if we want to protect databases **differing in c rows**, which amounts to adversary with arbitrary auxiliary information can know whether c particular participants submitted their information.
- ▶ This can be achieved because if c items change, the probability dilation is bounded by $e^{\epsilon c}$ instead of e^ϵ , i.e. for D_1 and D_2 differing on c items:

$$\Pr[\mathcal{A}(D_1) \in S] \leq e^{(\epsilon c)} \times \Pr[\mathcal{A}(D_2) \in S]$$

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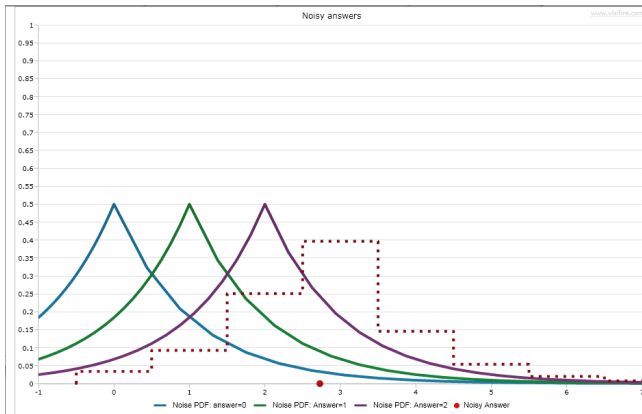
Group privacy

- ▶ Thus setting ϵ instead to ϵ/c achieves the desired result (protection of c items). In other words, instead of having each item ϵ -differentially private protected, now every group of c items is ϵ -differentially private protected (and each item is (ϵ/c) -differentially private protected).
- ▶ What's the drawback?

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- ▶ What's the drawback?

Group privacy



Epsilon

1.00

Ask Question

0

1

60.65 %

2

36.79 %



Group privacy

Proof idea:

- ▶ For three datasets D_1 , D_2 , and D_3 , such that D_1 and D_2 differ on one item, and D_2 and D_3 differ on one item (implicitly D_1 and D_3 differ on at most 2 items), the following holds for an ϵ -differentially private mechanism \mathcal{A} :

$$\Pr[\mathcal{A}(D_1) \in S] \leq \exp(\epsilon) \times \Pr[\mathcal{A}(D_2) \in S],$$

and

$$\Pr[\mathcal{A}(D_2) \in S] \leq \exp(\epsilon) \times \Pr[\mathcal{A}(D_3) \in S],$$

hence:

$$\begin{aligned} \Pr[\mathcal{A}(D_1) \in S] &\leq \exp(\epsilon) \times (\exp(\epsilon) \times \Pr[\mathcal{A}(D_3) \in S]) \\ &= \exp(2\epsilon) \times \Pr[\mathcal{A}(D_3) \in S] \end{aligned}$$

The proof can be extended to c instead of 2.

Conclusion & Discussion

- ▶ According to the sensitivity (Δf) of the statistical function, ϵ -differential privacy can be achieved in the statistical database by choosing appropriate λ of Laplace noise.
- ▶ In the next talk we will discuss how to achieve differential privacy in discrete functions, and how to use the technique in privacy-preserving aggregation.
- ▶ Discussion?

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