Control Systems

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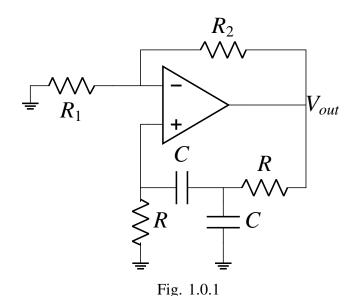
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1 Feedback Circuits

Abstract—The objective of this manual is to introduce control system design at an elementary level.

1 FEEDBACK CIRCUITS

1.0.1. For the Wein-bridge oscillator of Fig 1.0.1, use the expression for loop gain in Eq 1.0.3.5 to find the poles of the closed-loop system. Give the expression for the pole, Q and use it to show that to locate the poles in the right half of s plane, $\frac{R_2}{R_1}$ must be selected to be greater than 2.



1.0.2. Compare the basic structure for a sinusoidal oscillator with Wein-bridge oscillator and give expressions for G and H.

Solution:

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• Comparring Fig 1.0.1 and Fig 1.0.2, we get

$$G = 1 + \frac{R_2}{R_1} \tag{1.0.2.1}$$

$$H = \frac{Z_p}{Z_p + Z_s} \tag{1.0.2.2}$$

where.

$$Z_p = \frac{R}{RSC + 1} \tag{1.0.2.3}$$

$$Z_s = \frac{RSC + 1}{SC}$$
 (1.0.2.4)

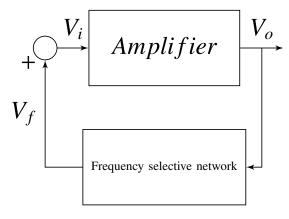


Fig. 1.0.2

1.0.3. Give the expression for loop gain for Weinbridge oscillator.

Solution:

$$T(s) = A(s)\beta(s)$$
 (1.0.3.1)

$$T(s) = \frac{1 + \frac{R_2}{R_1}}{1 + Z_s Y_p}$$
 (1.0.3.2)

$$T(s) = \frac{1 + \frac{R_2}{R_1}}{1 + (\frac{sRC+1}{sC})(\frac{sRC+1}{R})}$$
(1.0.3.3)

$$T(s) = \frac{1 + \frac{R_2}{R_1}}{1 + \frac{s^2 R^2 C^2 + sRC + sRC + 1}{sRC}}$$

$$T(s) = \frac{1 + \frac{R_2}{R_1}}{3 + sCR + \frac{1}{sCR}}$$
(1.0.3.4)

$$T(s) = \frac{1 + \frac{R_2}{R_1}}{3 + sCR + \frac{1}{sCR}}$$
 (1.0.3.5)

1.0.4. Write the characteristic equation for Wein-

bridge oscillator.

Solution:

$$1 - T(s) = 0 \qquad (1.0.4.1)$$

$$1 - \frac{1 + \frac{R_2}{R_1}}{3 + sCR + \frac{1}{sCR}} = 0 \qquad (1.0.4.2)$$

$$3 + sRC + \frac{1}{sCR} = 1 + \frac{R_2}{R_1}$$
 (1.0.4.3)

$$3 - 1 + sRC + \frac{1}{sRC} - \frac{R_2}{R_1} = 0 \qquad (1.0.4.4)$$

$$2s + s^2RC + \frac{1}{RC} - s\frac{R_2}{R_1} = 0 (1.0.4.5)$$

$$s^2RC + s(2 - \frac{R_2}{R_1}) + \frac{1}{RC} = 0$$
 (1.0.4.6)

$$s^2 + s \frac{1}{RC} (2 - \frac{R_2}{R_1}) + \frac{1}{R^2 C^2} = 0$$
 (1.0.4.7)

1.0.5. Write the general expression for the characteristic equation.

Solution:

$$s^2 + s\frac{\omega_0}{O} + \omega_0^2 = 0 ag{1.0.5.1}$$

1.0.6. State the **Barkhausen criterion** for sustained oscillations with frequency ω_0 .

Solution:

$$T(j\omega_0) = G(j\omega_0)H(j\omega_0) = 1$$
 (1.0.6.1)

- That is, at ω_0 the phase of the loop gain should be zero and the magnitude of loop gain should be 1.
- Only for a ∞ gain,system will produce a finite output for zero input.
- 1.0.7. Give the definition of **Quality factor**(Q) and explain its significance.

Solution:

- It is a parameter of an oscillatory system expressing the relationship between stored energy and energy dissipation.
- The "purity" of output sine waves will be a function of the selectivity feedback network.
- That is, higher the value of Q for frequency selective network, the less the harmonic content of sine wave produced.
- 1.0.8. Compare the equations 1.0.4.7 and 1.0.5.1 and give expressions for Q and ω_0

Solution:

$$\omega_0^2 = \frac{1}{R^2 C^2} \tag{1.0.8.1}$$

$$\omega_0 = \frac{1}{RC} \frac{\omega_0}{Q} = \frac{1}{RC} (2 - \frac{R_2}{R_1})$$
 (1.0.8.2)

$$Q = \frac{1}{(2 - \frac{R_2}{P_c})} \tag{1.0.8.3}$$

(1.0.8.4)

(1.0.4.4) 1.0.9. Using Eq 1.0.8.3 calculate the value of $\frac{R_2}{R_1}$ for which poles lie on right hand of s-plane.

Solution:

Poles lie on imaginary axis for $Q = \infty$

$$2 - \frac{R_2}{R_1} = 0 \tag{1.0.9.1}$$

$$\frac{R_2}{R_1} = 2 \tag{1.0.9.2}$$

... For poles to lie on right hand side of s-plane

$$\frac{R_2}{R_1} > 2 \tag{1.0.9.3}$$

1.0.10. Verify the above calculations using a Python code.

Solution:

codes/ee18btech11044 3 1.py

- This figure shows how the location of poles vary if $\frac{R_2}{R_1}$ is varied for a fixed ω_0 .
- vary if $\frac{R_2}{R_1}$ is varied for a fixed ω_0 . • I have varied $\frac{R_2}{R_1}$ from -10 to 10.

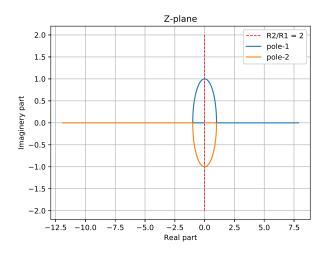


Fig. 1.0.10

1.0.11. Simulate the circuit shown in Fig 1.0.1 using spice simulators. Plot the output generated us-

ing python.

Solution:

You can find the netlist for the simulated circuit here:

spice/ee18btech11044.net

You can find the python script used to generate the output here:

codes/ee18btech11044_spice.py

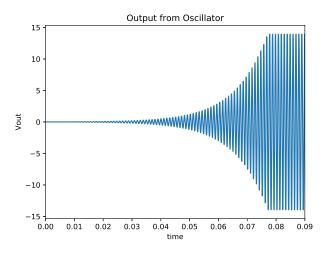


Fig. 1.0.11