

Object Proposals

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graph TD; A[Object Proposals] --> B[Window Scoring]; A --> C[Grouping Methods]; B --> D[Bounding Box]; C --> E[Merging Superpixels]; C --> F[Seed Segmentation]; E --> D; E --> G[Region]; F --> G;
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The diagram illustrates a workflow for object detection. It begins with 'Object Proposals' (green box), which branches into 'Window Scoring' (orange box) and 'Grouping Methods' (pink box). 'Window Scoring' leads to 'Bounding Box' (red box). 'Grouping Methods' leads to both 'Merging Superpixels' (gray box) and 'Seed Segmentation' (cyan box). 'Merging Superpixels' leads to both 'Bounding Box' and 'Region' (yellow box). 'Seed Segmentation' leads to 'Region'.

Window Scoring

Grouping Methods

Merging
Superpixels

Seed
Segmentation

Bounding Box

Region