

# Interior-Point Method for Nuclear Norm Approximation with Application to System Identification

Author: Zhang Liu and Lieven Vandenberghe  
Presentation by: Martin Hellkvist

May 7, 2019

# Summary

- ▶ Nuclear Norm:  $\|X\|_* = \text{sum of singular values}$
- ▶  $\min \|X\|_*$  typically has low rank solutions
  - ▶ Can be cast as Semidefinite Program (SDP)
- ▶  $\min \text{rank}(X)$  is NP-hard
  - ▶ System Identification
  - ▶ Machine Learning
  - ▶ Computer Vision
- ▶ Contribution:
  - ▶ Describe a more efficient interior-point method for high order problems with the structure that follows  $\|\cdot\|_*$

# Nuclear Norm Approximation Problem

$$\begin{aligned} & \text{minimize } \|\mathcal{A}(x) - B\|_* \\ & B \in \mathbb{R}^{p \times q} \\ & \mathcal{A}(x) = x_1 A_1 + x_2 A_2 + \cdots + x_n A_n \end{aligned} \tag{1}$$

Can be cast as

$$\begin{aligned} & \text{minimize } (\text{tr} U + \text{tr} V)/2 \\ & \text{subject to } \begin{bmatrix} U & (\mathcal{A}(x) - B)^T \\ \mathcal{A}(x) - B & V \end{bmatrix} \succeq 0 \end{aligned} \tag{2}$$

Where  $U = U^T \in \mathbb{R}^{q \times q}$  and  $V = V^T \in \mathbb{R}^{p \times p}$  are new variables, and the problem is an SDP which is very difficult to solve for  $q \approx 100$  and  $p \approx 100$  for general purpose interior-point methods

# Custom Interior-Point Method

Exploiting the structure of

$$\begin{aligned} & \text{minimize} \quad (\text{tr} U + \text{tr} V)/2 \\ & \text{subject to} \quad \begin{bmatrix} U & (\mathcal{A}(x) - B)^T \\ \mathcal{A}(x) - B & V \end{bmatrix} \succeq 0 \end{aligned} \quad (3)$$

We need to solve the following linear equation system

$$\mathcal{A}_{\text{adj}}(\Delta Z) = r, \quad \begin{bmatrix} \Delta U & \mathcal{A}(\Delta x)^T \\ \mathcal{A}(\Delta x) & \Delta V \end{bmatrix} + T \begin{bmatrix} 0 & \Delta Z^T \\ \Delta Z & 0 \end{bmatrix} T = R \quad (4)$$

which can be solved by first finding  $\Delta x$

$$\tilde{\mathcal{A}}_{\text{adj}}(\mathcal{S}^{-1}(\tilde{\mathcal{A}}(\Delta x))) = \tilde{\mathcal{A}}_{\text{adj}}(\mathcal{S}^{-1}(\tilde{R}_{21})) - r \quad (5)$$

which gives  $\Delta Z$  and in turn  $\Delta U$  and  $\Delta V$