CS 510: NUMERICAL ANALYSIS, Fall 2019, 3 Credits

Instructor: Bahman Kalantari (kalantar@cs.rutgers.edu)

Lecture: Thursday 12:00-2:50 PM, TIL-226, LIV (Livingston).

Office Hours: Wed 1:00-2:00 PM, Hill Center 444 (also by appointment).

Prerequisites: Multivariate Calculus, Linear Algebra, Ability to program in a high level language, e.g., Matlab,

Python, C, C++

Grading: Midterm 20%; Final 30%; Programming (Group) Project 50%

Teaching Assistant: Chun Leung Lau; larryl@cs.rutgers.edu; Office: Hill Center 427; Office hours: Tuesday

12:00-1:00PM

Objectives: Introduction to derivation, analysis, algorithms, and their computer implementation and application in order to solve fundamental numerical problems.

Course Outline:

- Floating point numbers and roundoff error
- Solution of nonlinear algebraic equations

bisection method, regula falsi, fixed point iteration, secant method, Newton's method

convergence rates (linear, quadratic)

systems of nonlinear equations - Newton's method

• Introduction to dynamical systems, fixed point iterations

basics of complex numbers, the geometric modulus principle, the fundamental theorem of algebra

Newton's method, Halley's method, the Basic Family of iteration functions

Taylor's theorem and generalized Taylor's theorem

basins of attraction, Voronoi diagrams of roots of polynomials

bounds on modulus of zeros of polynomials

Fatou and Julia sets, the Mandelbrot set

fractals, polynomiography

• Solution of linear algebraic systems

Gaussian elimination/ LU decomposition

special cases: symmetric, banded, sparse matrices

error analysis, norms, condition number

iterative methods (Jacobi, Gauss-Seidel, SOR, a geometric method, convergence rates)

overdetermined systems, least squares solutions

• Other numerical linear algebra topics + applications

QR decomposition

Singular value decomposition (SVD)

Web search, PageRank via power method, PageRank via a convex hull algorithm

some application of eigenvalue problems in optimization

• Interpolation, approximation of functions

the interpolating polynomial (its construction and error term)

piecewise polynomial interpolation, splines

Tchebycheff interpolation, minimax approximation

least squares approximation, orthogonal polynomials

• Numerical differentiation and integration

quadrature formulas, error terms

adaptive quadrature, Gaussian quadrature

numerical differentiation, error terms

• Numerical solution of ordinary differential equations

basic methods (Taylor methods, Runge-Kutta methods, multistep methods)

stability, consistency, convergence

higher order equations, systems

Some Reference:

- M. T. Heath, Scientific Computing, An Introductory Survey, 2nd edition, McGraw-Hill, 2002.
- G. Dahlquist & A. Bjorck, Numerical Methods, Prientice-Hall, 1974; SIAM, 2008.
- G. H. Golub & C. F. Van Loan, Matrix Computations, 3rd edition, Johns Hopkins University Press, 1996.

Kendall Atkinson, An Introduction to Numerical Analysis, John Wiley & Sons, Inc., Second Edition, 1989.

Bahman Kalantari, Polynomial Root-Finding and Polynomiography, World Scientific, 2008.

Matlab tutorial + links to other references + some articles