

Calibration results

Camera-system parameters:

cam0 (/cam0/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.23464297 -0.69308071 0.00140951 0.00102531] +- [0.00498915 0.01836351 0.0004132 0.00040355]

projection: [653.42208189 646.93887941 260.19675418 259.46533261] +- [1.28055194 1.21496087 0.68881036

0.69641006]

reprojection error: [0.000001, 0.000000] +- [0.583495, 0.437800]

Target configuration

Type: aprilgrid

Tags:

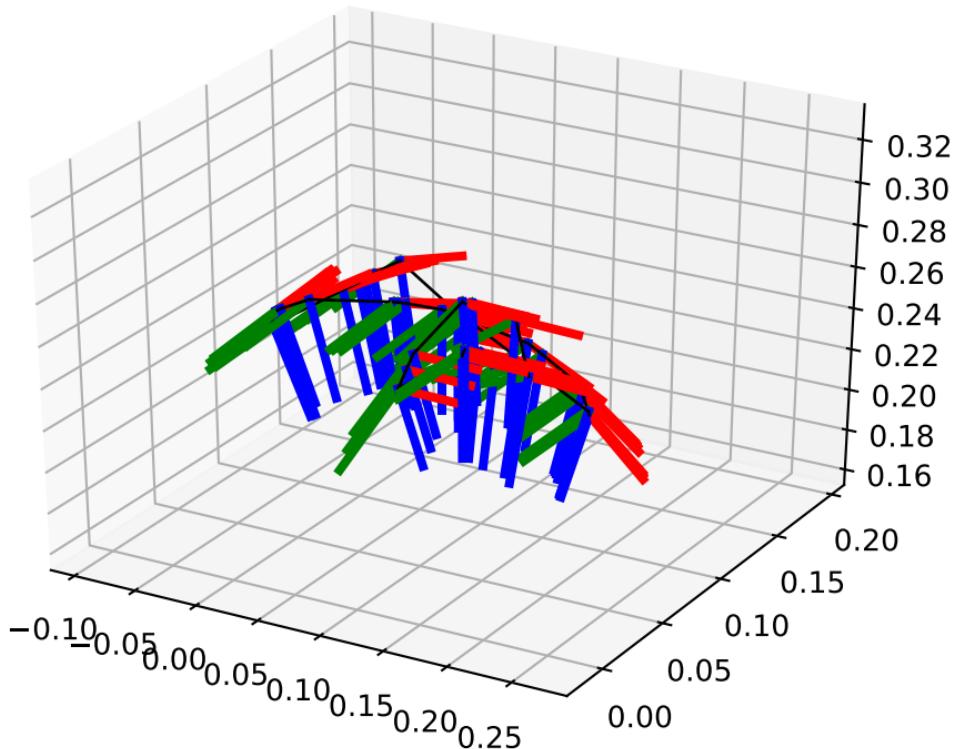
Rows: 6

Cols: 6

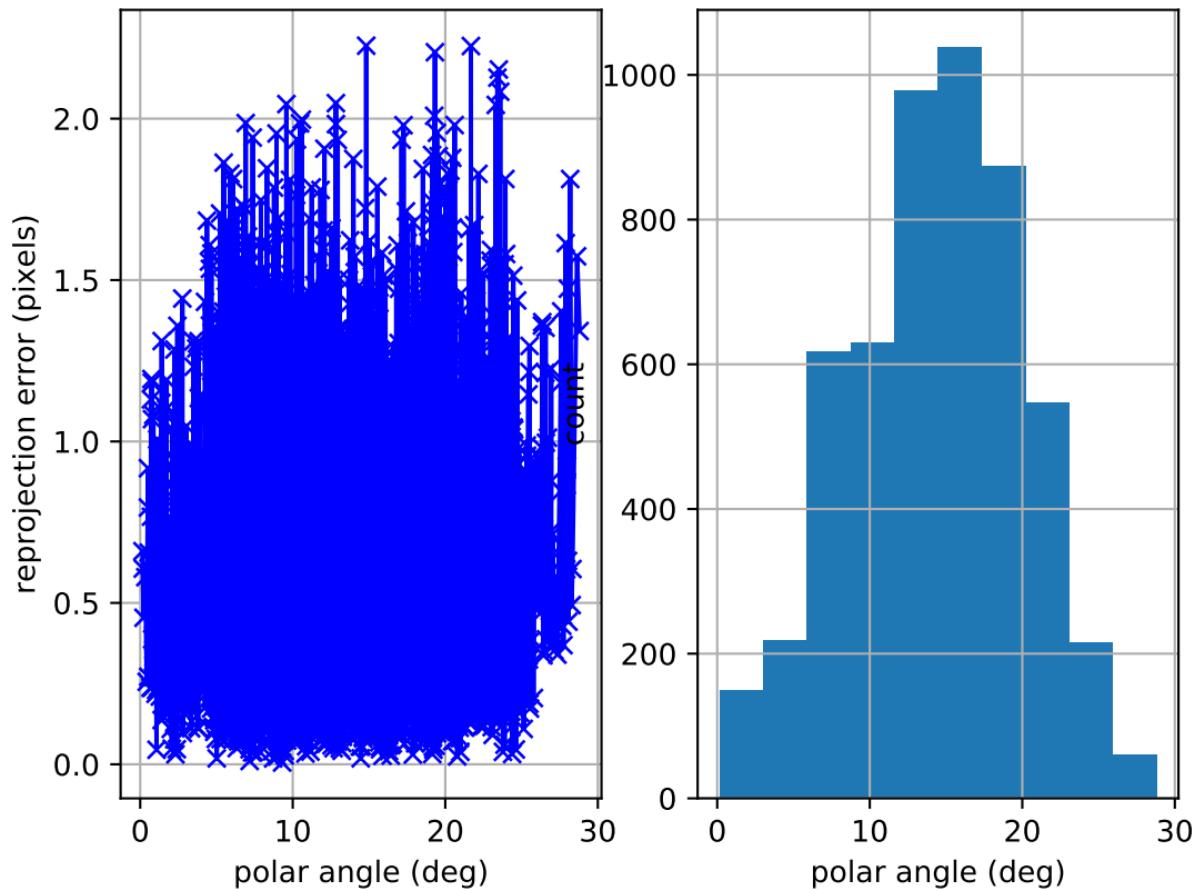
Size: 0.025 [m]

Spacing 0.0075 [m]

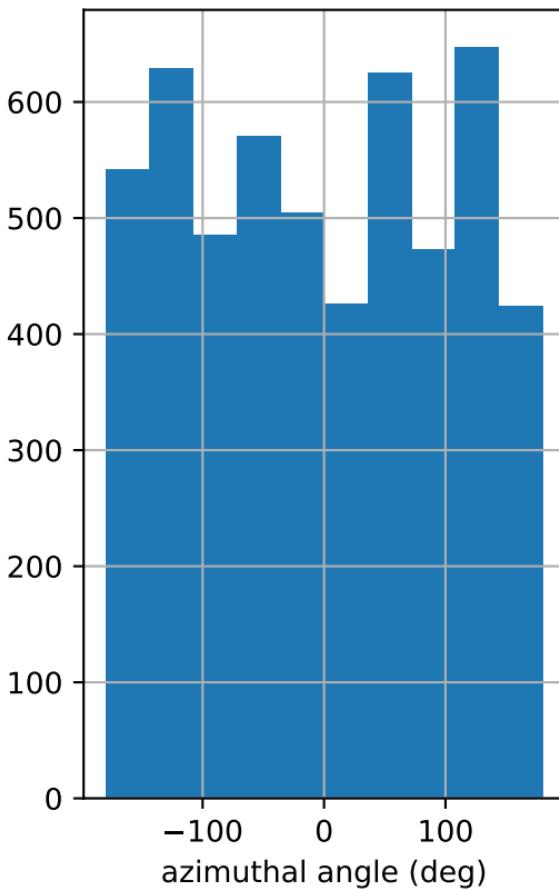
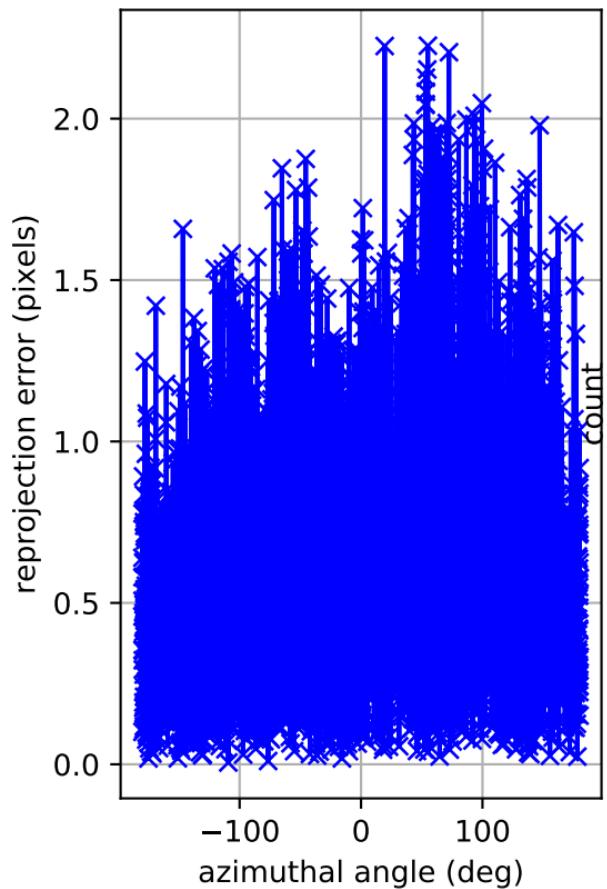
cam0: estimated poses



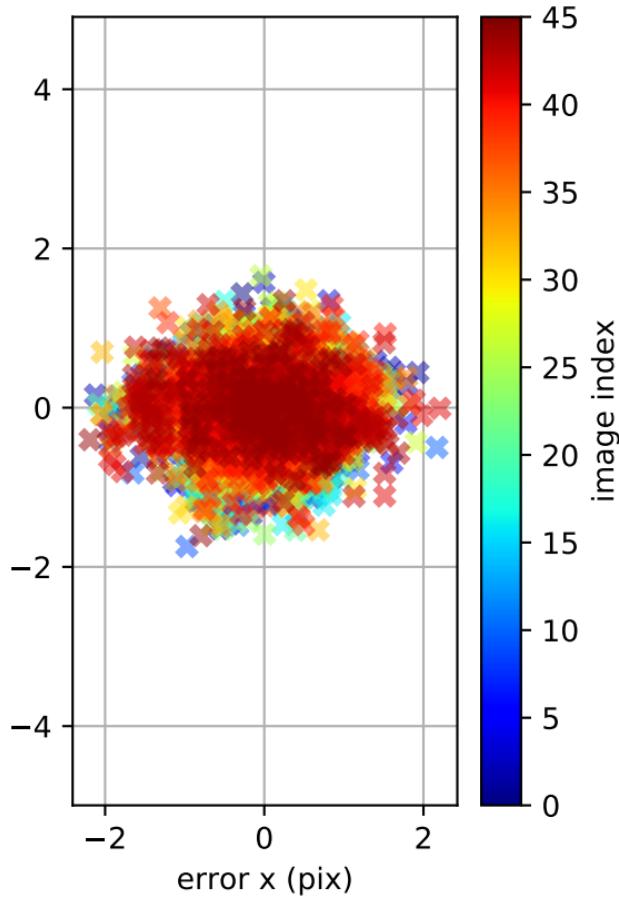
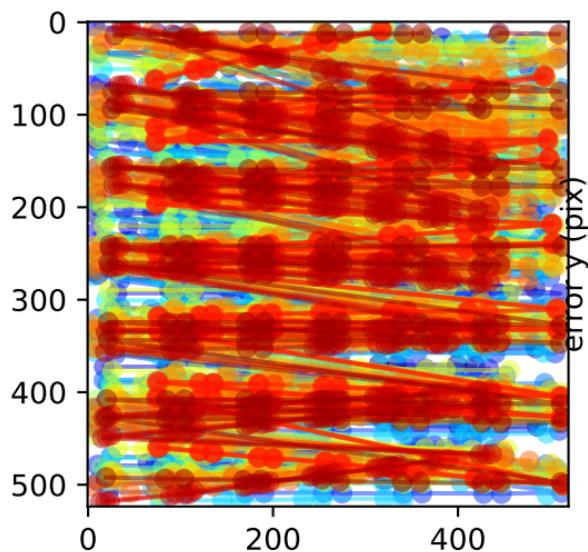
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

