## **Tennis Ball**

This tutorial proposes options to find a tennis ball in a picture.

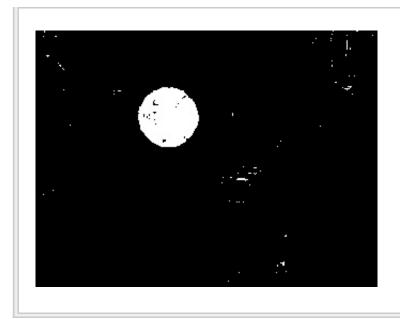
```
(.ns divine-briars
    (:require
       [opencv3.utils :as u]
       [opencv3.colors.rgb :as color]
       [opencv3.core :refer :all]))
nil
```

First, let's load the image that will be the base for our image finding exercice.



## **Using Hough Circles**

```
(def hsv (-> img clone (cvt-color! COLOR_RGB2HSV)))
(def thresh-image (new-mat))
(in-range hsv (new-scalar 50 100 0) (new-scalar 95 255
255) thresh-image)
; the ball is here
(u/mat-view thresh-image)
```



```
(let[ circles (new-mat) output (clone img) minRadius 25
maxRadius 40 ]

(hough-circles thresh-image circles CV_HOUGH_GRADIENT 1
minRadius 120 15 minRadius maxRadius)

(dotimes [i (.cols circles)]
   (let [ circle (.get circles 0 i) x (nth circle 0) y
   (nth circle 1) r (nth circle 2) p (new-point x y)]
      (opencv3.core/circle output p (int r) color/plum 2)))

; the ball is detected
(u/mat-view output))
```



## **Method2: Using Find Contours**

```
thresh-image
contours
(new-mat) ; mask
RETR_LIST
CHAIN_APPROX_SIMPLE)

(dotimes [ci (.size contours)]
(if (> (contour-area (.get contours ci)) 100 )
    (draw-contours output contours ci color/plum 2)))
(u/mat-view output)]
```

