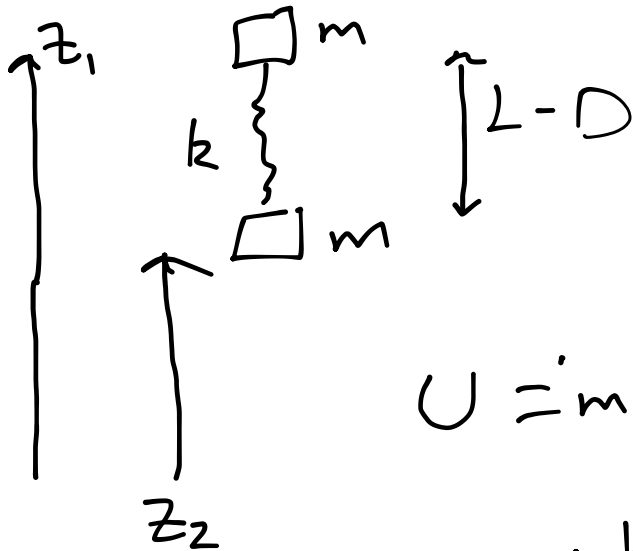


4. 4



$$U = mgz_1 + mgz_2 + \frac{k}{2} (z_1 - z_2 - L)^2$$

$$m\ddot{z}_1 = - \frac{\partial U}{\partial z_1} = -mg - k(z_1 - z_2 - L)$$

$$m\ddot{z}_2 = - \frac{\partial U}{\partial z_2} = -mg - k(z_2 - z_1 + L)$$

$$\ddot{z}_1 = -\left(mg - \frac{k}{m}L\right) + \frac{k}{m}(z_1 - z_2)$$

$$\ddot{z}_2 = -\left(mg + \frac{k}{m}L\right) + \frac{k}{m}(z_2 - z_1)$$

Define c.o.m  $Z_c = \frac{m_1 z_1 + m_2 z_2}{m_1 + m_2}$

$$= \frac{z_1}{2} + \frac{z_2}{2}$$

and relative  $z_r = z_1 - z_2$

Then  $\ddot{Z}_c = -g$

c.f. problem  
3.8

$$\ddot{z}_r = -\frac{2k}{m}(z_r - L)$$

$$Z_c = Z_c^0 - g \frac{t^2}{2} \quad (\dot{Z}_c^0 = 0)$$

$$z_r = L + A \cos \omega t + B \sin \omega t$$

$$\omega = \sqrt{\frac{2k}{m}}$$

$$\text{at } t=0 \quad z_r = L-D \quad \dot{z}_r = 0$$

$$\Rightarrow A = -D, \quad B = 0$$

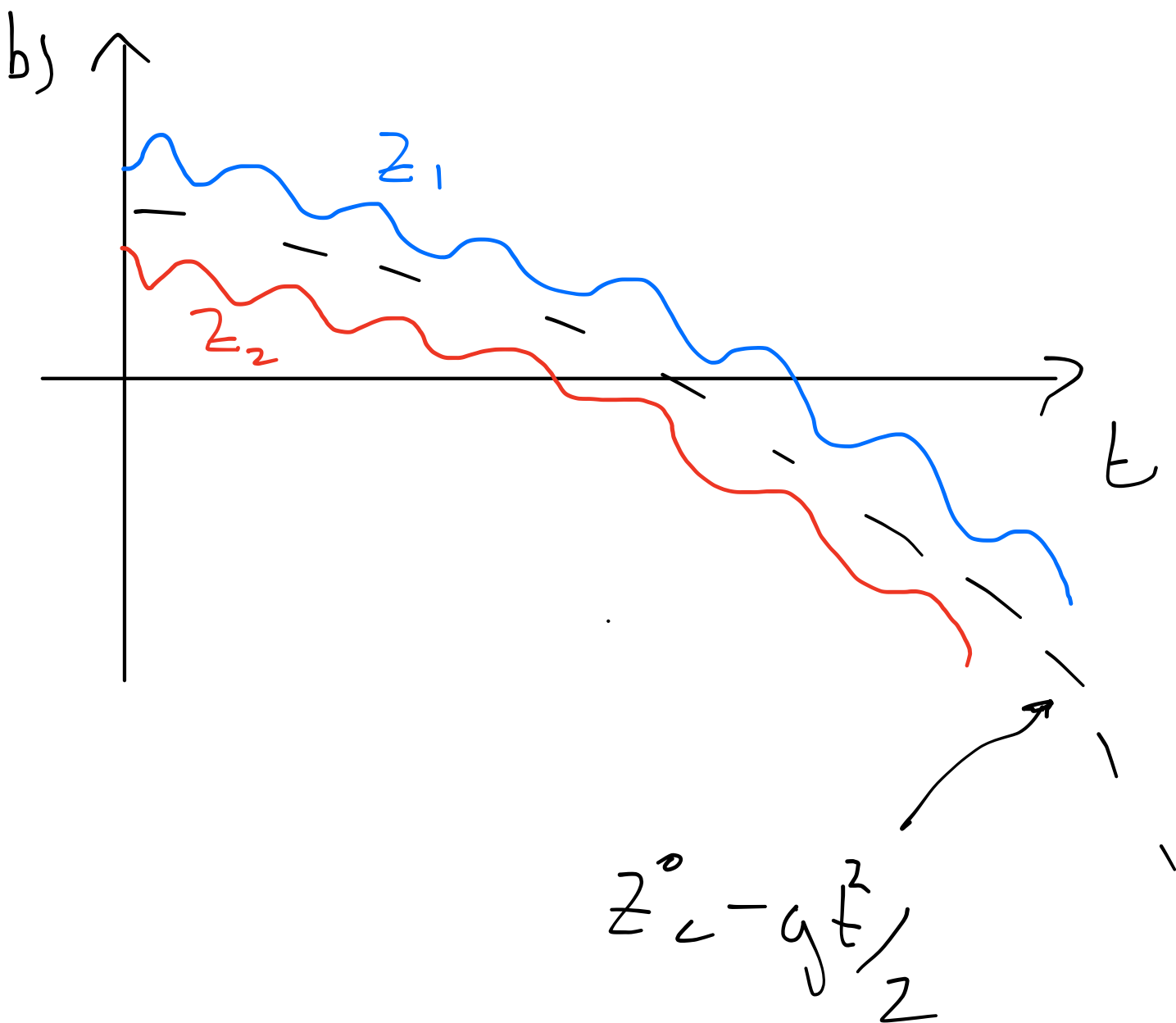
$$z_r = L - D \cos \omega t$$

$\Rightarrow$

$$z_1 = z_c + \frac{z_r}{2}$$

$$z_1 = z_c^0 - \frac{g t^2}{2} + \frac{L}{2} - \frac{D}{2} \cos \omega t$$

$$z_2 = z_c^0 - \frac{g t^2}{2} - \frac{L}{2} + \frac{D}{2} \cos \omega t$$



c)

$$\dot{z}_1 = -gt + \frac{D\omega}{2} \sin \omega t$$

for  $t$  small

$$z_1 \approx -\left(g + \frac{D\omega^2}{2}\right)t$$

if  $\frac{D\omega^2}{2} > g$  it goes up  
at  $t=0$

lower mass can also go up!

d) mass 1.

$$v_1 = -gt + \omega \frac{D}{2} \sin \omega t$$

we want peak of third upward  
movement at  $\omega t = 2\pi + \frac{\pi}{2}$   
 $= 9\pi/2$

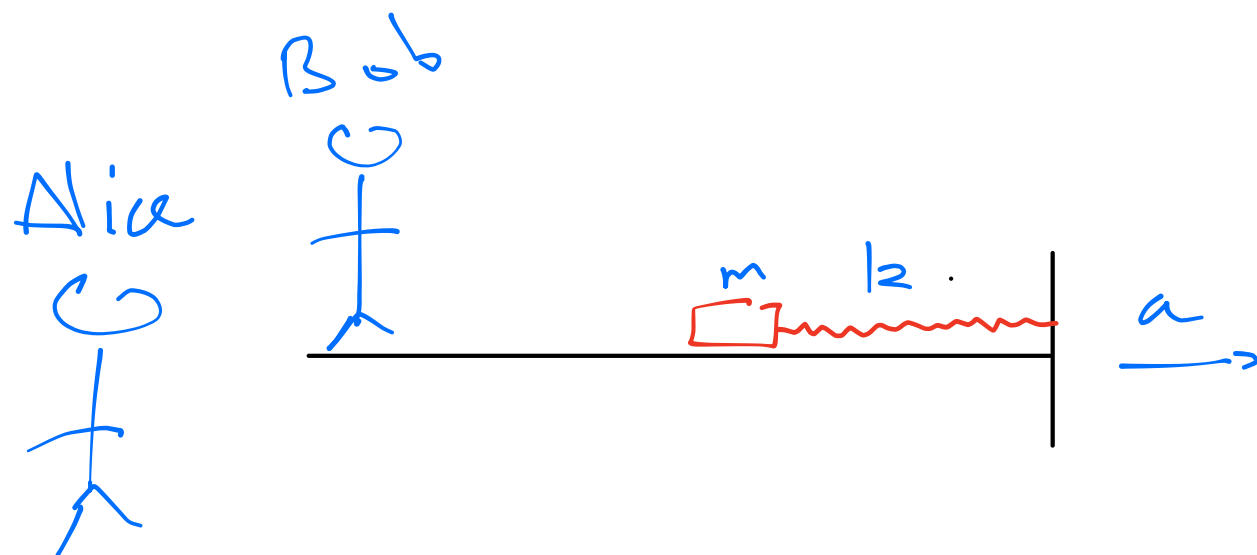
at this time

$$V_1 = - \frac{g}{\omega} \frac{9\pi}{2} + \omega \frac{D}{2}$$

we want  $V_1 = 0$

$$\Rightarrow D > \frac{9g\pi}{\omega^2}$$

4.5



$$m \frac{d^2 x_{PB}}{dt^2} = -k x_{PB} - \underbrace{ma}_{\text{fictitious force}}$$

or

$$\frac{d^2}{dt^2} \left( x_{PB} + \frac{ma}{k} \right) = -\frac{k}{m} \left( x_{PB} + \frac{ma}{k} \right)$$

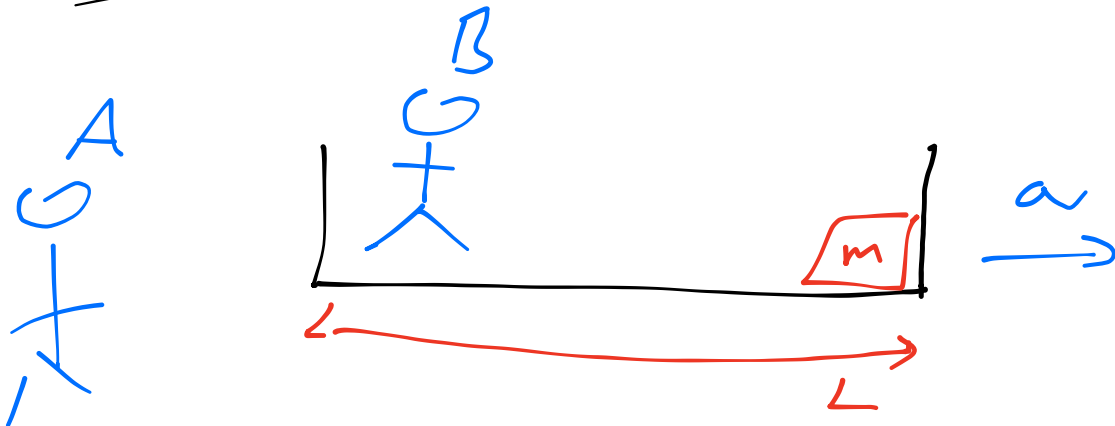
↑ has zero time derivative

$$x_{PB} + \frac{ma}{k} = A \cos(\omega t + \phi) \quad \omega^2 = \frac{k}{m}$$

$$x_{PB} = A \cos(\omega t + \phi) - \frac{ma}{k}$$

$$x_{PA} = x_{PB} + a \frac{t^2}{2}.$$

4-6



For Bob a fictitious force

$$F = -ma$$

What happens?

$$\text{for } 0 < t < \sqrt{\frac{2L}{a}}$$

mass slides back:

$$x_B = L - a \frac{t^2}{2}$$



$$at \frac{t}{T} = \sqrt{\frac{2L}{a}} \quad \text{Elastic collision}$$

from Bob's perspective  
particle then moves forward with velocity

at

for Alice it moves forward with  
velocity  $2aT$   $\perp$

$$T < t < 3T$$

$$x_B(t) = aT(t-T) - a \frac{(t-T)^2}{2}$$

(suvat)  $\nearrow$

$$at \quad t=T \quad x_B = 0$$

$$= 2T \quad x_B = L \leftarrow \text{max}$$

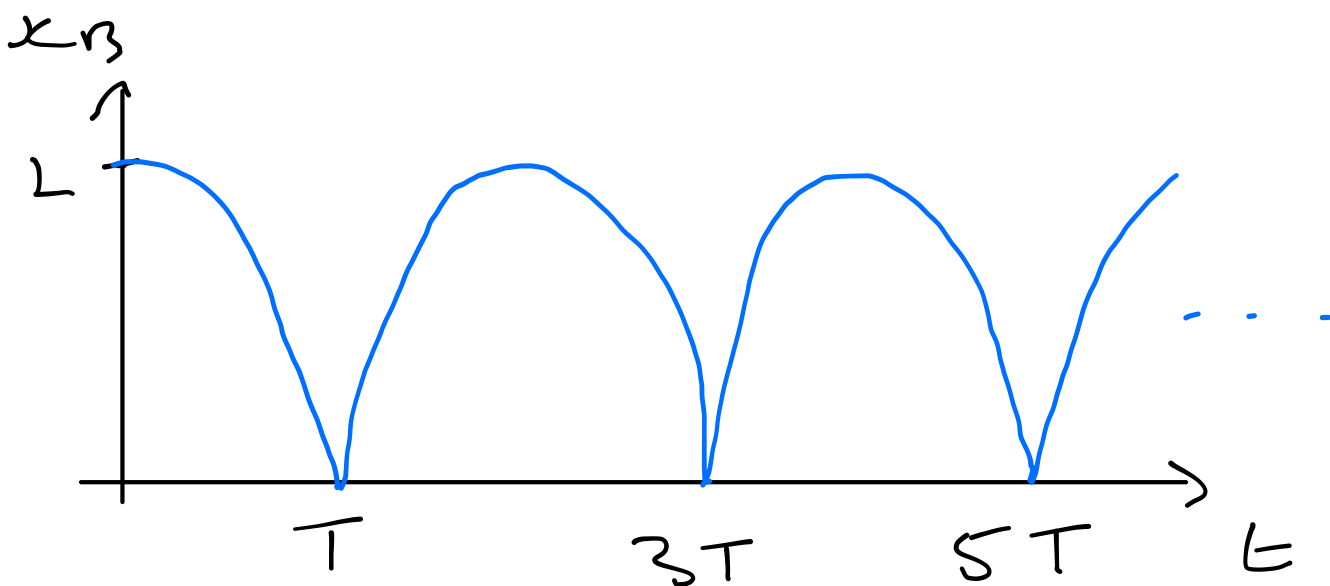
$$t = 3T \quad x_B = 0$$

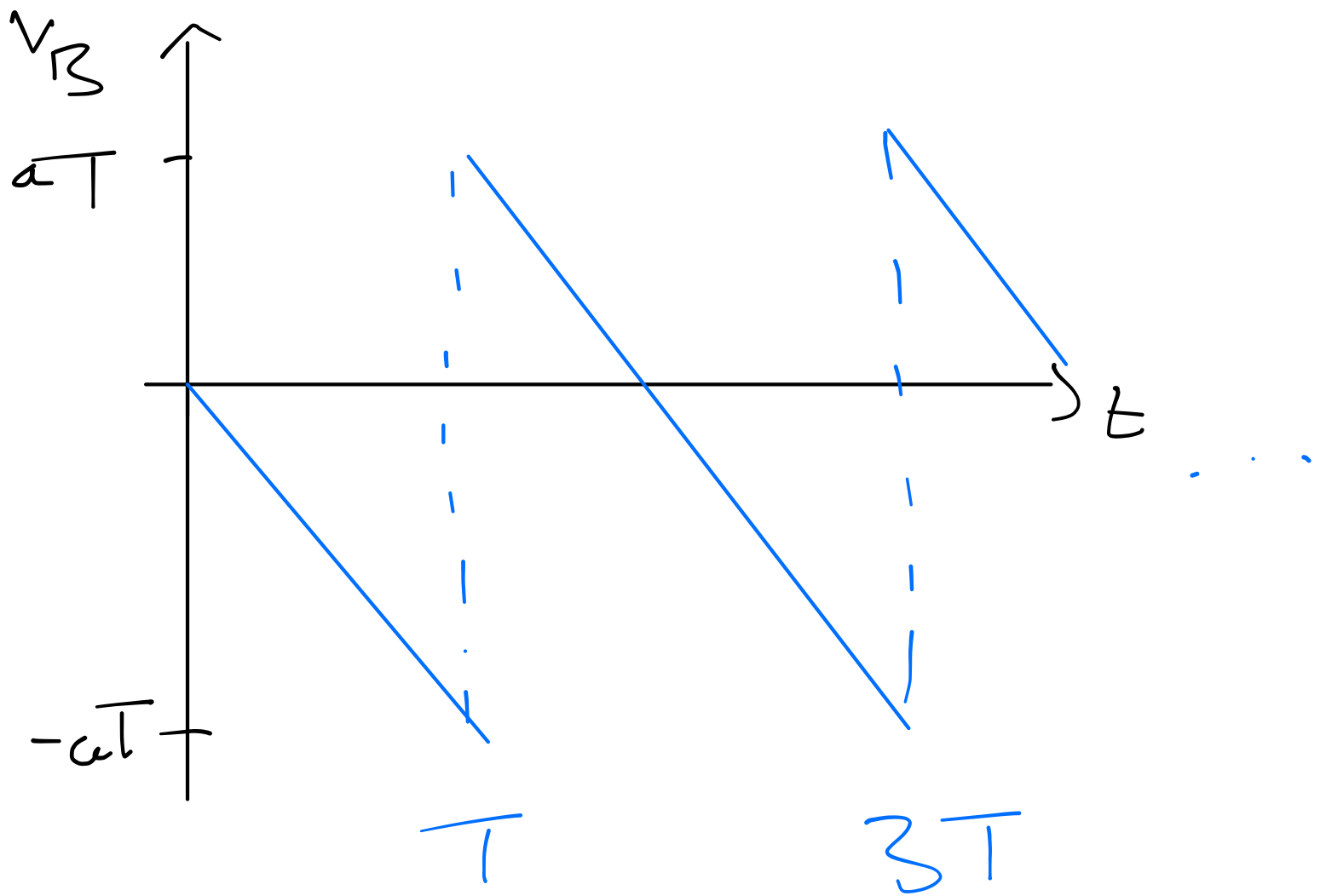
$$\left[ \text{at } t = 3T \quad v_B = \dot{x}_B = -aT \right.$$

↳ elastic collision

$$\text{so } x_B = aT(t - 3T) - \frac{a(t - 3T)^2}{2} \quad \left. \right]$$

The pattern continues...





Now Alice

$$x_A = x_B + \frac{at^2}{2}$$

but Alice never seen

forces, except at collisions

$\Rightarrow \mathcal{L}_A$  is linear

can we see this?

for  $2n+1 < \frac{t}{T} < 2n+3$

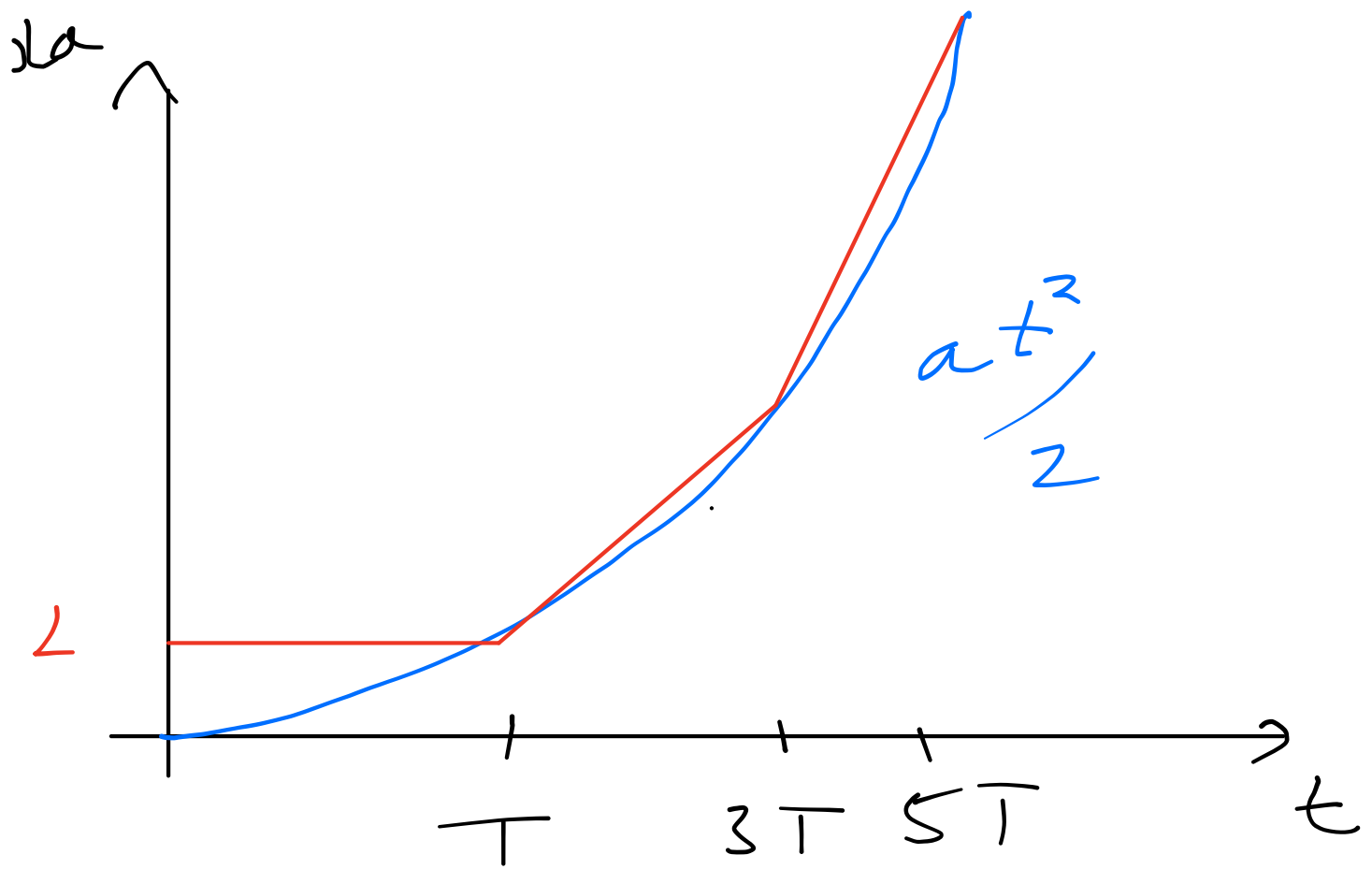
$$\mathcal{L}_B = aT (t - (2n+1)T)$$

$$- \frac{a}{2} (t - (2n+1)T)^2$$

$$\Rightarrow \mathcal{L}_A = \frac{aT}{2} \left[ -(3 + 4n(2+n))T + 4(1+n)t \right]$$

linear





4-7 No solu<sup>n</sup> given