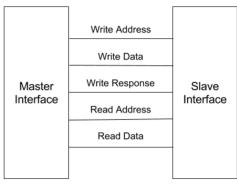
Microcontroller Interface

The microcontroller is accessible through an AXI slave interface that has 5 channels as shown in Figure 1. The microcontroller is going to give access to process, voltage and temperature measurements, through different routines.

These routines include reading the current measurement of group of sensors, enabling or disabling a continuous measuring mode where the microcontroller returns systematically the measurements of a group of sensors based on a predefined sampling interval. The interface supports commands that would return only the highest measured value within a specified group of sensors. The microcontroller interface would also allow to set a sampling interval for each one of the available measurements. The returned measurements represent values that are computed based on the average of an observation window, whose length can be defined through the interface. The interface would also provide different data formats for the different measurements. A high/low threshold can be defined for each one of the measurements, such that if it is violated the microcontroller would trigger an alarm through interrupt signals to the host processor. It supports other options as well, like sensor calibration and dynamically defining different sensor groups.



Channel connections between master and slave interfaces

Figure 1: Data and Address channels of an AXI interface.

The data and address channels both consist of 32 bits as shown on Figure 2, where the two MSBs for the data channel specifies the measurement (temperature, voltage or delay). While the bits 28th to 24th specify which command is selected, and the 16 LSTs is for the data, the remaining bits are reserved for future use.

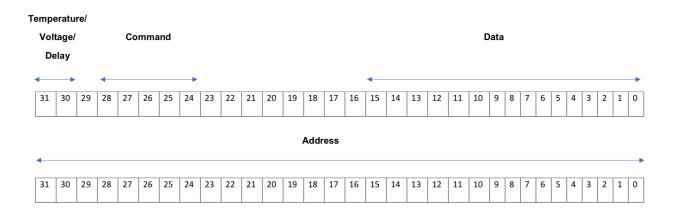


Figure 2: Data and Address bits

Temperature commands:

| Command | Description |
|--|--|
| Read Temperature | Reads the temperature of the selected sensor or group of sensors |
| Enable/Disable continuous measuring mode | When it's enabled the temperature of the selected sensor or group of sensors are captured systematically based on the sampling intervals |
| Set sample interval for the temperature | Sets a sampling interval for the temperature sensors |
| Set an averaging window/resolution for the temperature sensors | Defines the number of the previous samples to average before returning the temperature values |
| Set temperature data format | Chooses a data format (among the available ones) for the temperature readings |
| Set T_HIGH threshold [ALARM] | Sets the temperature thresholds above which the risc-v would trigger an ALARM |
| Set T_LOW threshold [ALARM] | Sets the temperature thresholds below which the risc-v would trigger an ALARM |
| Set/read temperature sensor calibration | This command may be used to calibrate the temperature sensors when a highly precise temperature reference value is available |
| Read the highest temperature value | This command returns the highest temperature value of the selected group of sensors |
| Define the sensors group | Assigns the different sensors to different groups |
| Get the available sensors ID | Get the available sensors ID |

Voltage commands:

| Command | Description |
|--|--|
| Read Voltage | Reads the voltage of the selected sensor or group of sensors |
| Enable/Disable continuous measuring mode | When it's enabled the voltage of the selected sensor or group of sensors are captured systematically based on the sampling intervals |
| Set sample interval for the voltage | Sets a sampling interval for the voltage sensors |
| Set an averaging window/resolution for the voltage sensors | Defines the number of the previous samples to average before returning the voltage values |
| Set voltage data format | Chooses a data format (among the available ones) for the voltage readings |
| Set T_HIGH threshold [ALARM] | Sets the voltage thresholds above which the risc-v would trigger an ALARM |
| Set T_LOW threshold [ALARM] | Sets the voltage thresholds below which the risc-v would trigger an ALARM |
| Set/read voltage sensor calibration | This command may be used to calibrate the voltage sensors when a highly precise voltage reference value is available |
| Read the highest voltage value | This command returns the highest voltage value of the selected group of sensors |
| Define the sensors group | Assigns the different sensors to different groups |
| Get the available sensors ID | Get the available sensors ID |

Delay commands:

| Command | Description |
|--|---|
| Read the location of the CP | Read the location of the CP |
| Enable/Disable continuous measuring mode | When it's enabled the location CP of the is captured systematically based on the sampling intervals |
| Set sampling interval for the CP | Sets a sampling interval for the CPM |
| Set an averaging window/resolution | Defines the number of the previous samples to average before returning the values |
| Set data format | Chooses a data format (among the available ones) for the readings |
| Set T_HIGH threshold [ALARM] | Sets the thresholds above which the risc-v would trigger an ALARM |
| Set T_LOW threshold [ALARM] | Sets the thresholds below which the risc-v would trigger an ALARM |
| Set/read sensor calibration | This command may be used to calibrate the sensor |
| Define the sensors group | Assigns the different sensors to different groups |
| Get the available sensors ID | Get the available sensors ID |