$$sim(s_q, s_t, D) = \frac{\displaystyle\sum_{f \in F} \{e^{-p_f^2/2\sigma^2} | f \subseteq s_q \land f \subseteq s_t\}}{\displaystyle\sum_{f \in F} \{e^{-p_f^2/2\sigma^2} | f \subseteq s_q \lor f \subseteq s_t\}} \cdot \frac{n_{s_q}^{frequent}}{n_{s_q}} \cdot \frac{n_{s_t}^{frequent}}{n_{s_t}} \quad (1)$$

with

 $p_f|f\subseteq s_q\wedge f\subseteq s_t$... significance of fragment f that occurs in s_q and s_t $p_f|f\subseteq s_q\vee f\subseteq s_t$... significance of fragment f that occurs in s_q or s_t σ . . . standard deviation of the gaussian distribution (0.3)

F ... set of significant features

 n_{s_q} ... number of fragments in the query structure $n_{s_q}^{frequent}$... number of query structure fragments that occur frequently enough for statistical evaluation

 n_{s_t} ... number of fragments in the neighbors $n_{s_t}^{frequent}$... number of neighbors fragments that occur frequently enough for statistical evaluation

Minimum frequencies for statistical significance are derived from the χ^2 definition (with Yates correction) under the assumption that the fragment occurs only in a single class.