

Destr : Object Detection with Split Transformer

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Motivation 1:

The content of object queries is inferred for every image from scratch => slows training convergence.

How to improve initialization of the object representation in the decoder?

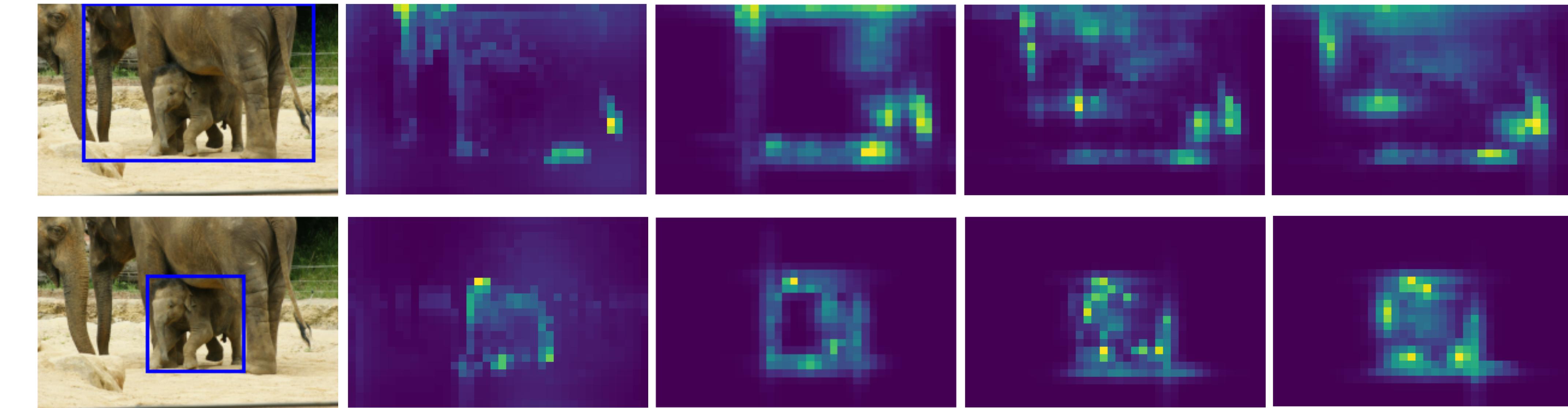
Contribution 1:
Mini-detector is used to initialize the objects' classification, regression and positional embeddings.

Motivation 2:

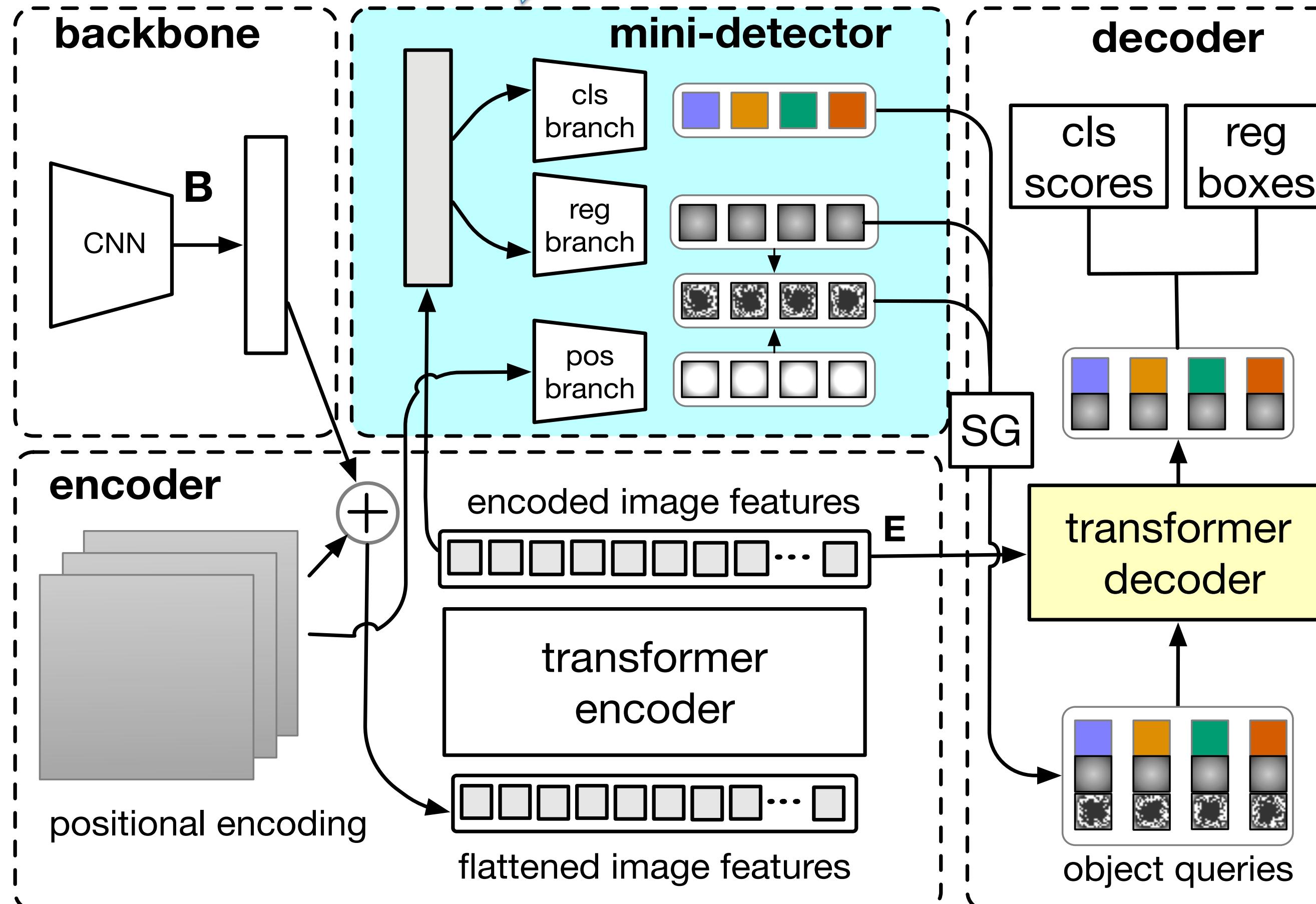
A single cross-attention is typically used for both classification and bounding-box regression.

These two tasks are different, and hence a single cross-attention may not be optimal for both.

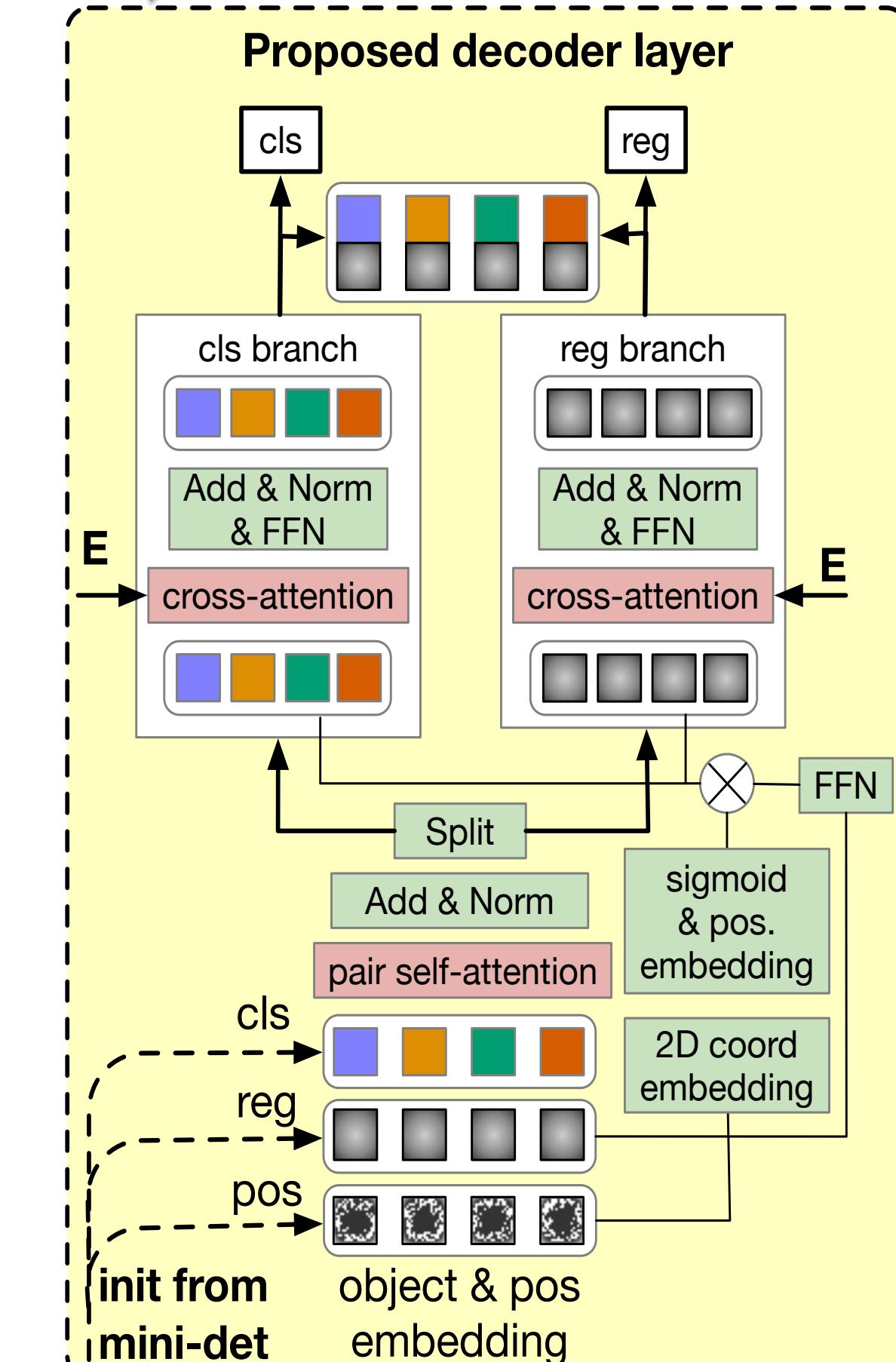
Contribution 2:
Split the cross attention into two independent branches – one for classification and the other for box regression



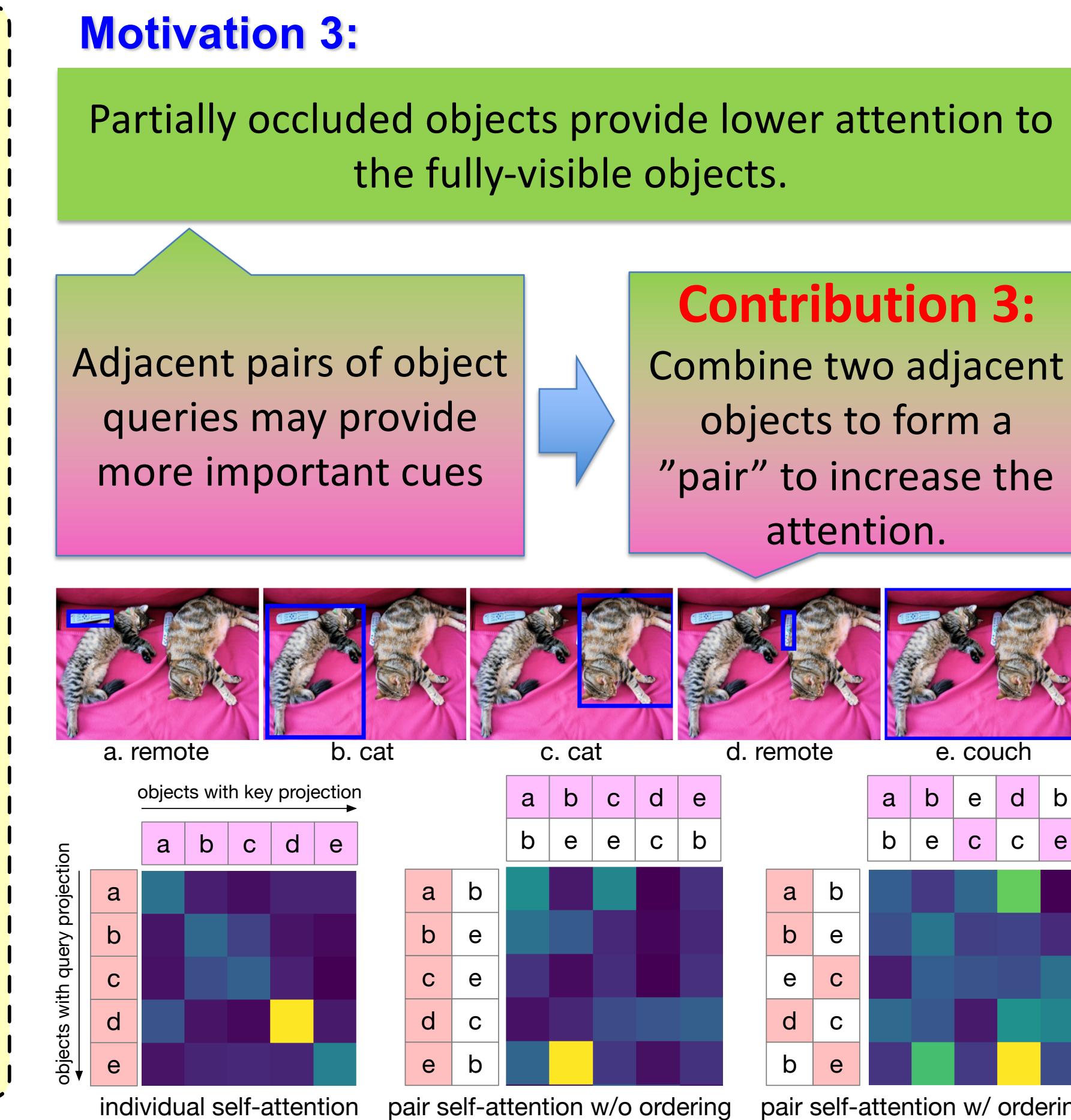
Cross-attention maps estimated by: (a) DETER; (b) C-DETR; (c) DESTR's classification branch and (d) regression branch;



An overview of DESTR



Decoder layer in DESTR



Pair self-attention

Model	#epochs	GFLOPs	#params (M)	AP
DETR-R50 [2]	500	86	41	42.0
Deform-DETR-R50-SS [30]	50	78	34	39.4
UP-DETR-R50 [4]	150	86	41	40.5
UP-DETR-R50 [4]	300	86	41	42.8
C-DETR-R50 [19]	50	90	44	40.9
Anchor DETR-R50 [25]	50	–	–	42.1
DESTR-R50	50	104	69	43.6
DETR-DC5-R50 [2]	500	187	41	43.3
Deform-DETR-DC5-R50-SS [30]	50	128	34	41.5
C-DETR-DC5-R50 [19]	50	195	44	43.8
Anchor DETR-DC5-R50 [25]	50	151	–	44.2
DESTR-DC5-R50	50	232	69	45.3
DETR-R101 [2]	500	152	60	43.5
C-DETR-R101 [19]	50	156	63	42.8
Anchor DETR-R101 [25]	50	–	–	43.5
DESTR-R101	50	171	88	44.6
DETR-DC5-R101 [2]	500	253	60	44.9
C-DETR-DC5-R101 [19]	50	262	63	45.0
Anchor DETR-DC5-R101 [25]	50	–	–	45.1
DESTR-DC5-R101	50	299	88	46.4

Comparison with other DETR variants on COCO-val

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