## **ECE 3731: Introduction to Microprocessors**

# Lab 6: Timer Subsystem -Flag Polling and Interrupts



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#### Honor Code:

I have neither given nor received unauthorized assistance on this graded report.

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## Contents

Objective	.3
Equipment Used	
Flowchart	
Procedure	
Code	
Conclusion	

### **Objective**

- Generate a tone (any frequency) on the speaker.
- Maintain a 4-bit counter on the Port B LED's
- Use an output compare channel in interrupt mode to update the value of the counter
- Update counter every second.

## **Equipment Used**

- Codewarrior
- HCS12 Microprocessor
- Notepad++ to import code with format
- <a href="https://www.lucidchart.com/">https://www.lucidchart.com/</a> to easily make flowcharts.

#### **Flowchart**

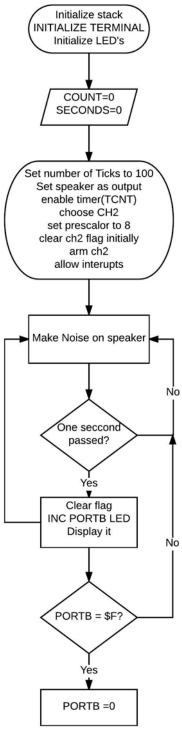


Figure 1: Flow

#### **Procedure**

The main loop makes a sound on the speaker of any frequency and if one second passes the interrupt service takes place. The interrupt service increments the value of PORTB LED and displays it. If the value reaches \$F\$ it rolls over to 0. As Mentioned in the flowchart the speaker must set as output and the timer must be enabled with a pre-scale value of 8 and appropriate flags must be cleared. Stetting the prescaler to 8 allows for 10ms per tick and total of 100 ticks allows for 1 second calculation.

#### Code

```
Insert your code here
        lds
              #ROMStart ; load stack pointer
SET UP THE (interrupt) SERVICE & INITIALIZE
              TermInit ; Initialize Serial
        JSR
        JSR
              led_enable
             COUNT
      CLR
        CLR
              SECONDS
        CLR
              MINUTES
        CLR
              HOURS
        MOVB
              #100,NUMTICKS
                              ; number of ticks (int
              DDRT, %00100000 ; PT5 (spkr) is output
        bset
              TSCR1,TEN
                           ; enable TCNT
        bset
              TIOS, IOS2
                             ; choose OC2 for timer
        bset
              #$03,TSCR2
        movb
        movb
              #C2F,TFLG1
                             ; clear C2F flag initially
        bset
              TIE, C2I
                           ; arm OC2
        cli
                           ; allow interupts
 main program loop follows
   BRCLR TFLG2, #%10000000, LOOP
   LDAA PTT
   EORA #%00100000
   STAA PTT
          #%10000000, TFLG2
   MOVB
   bra L
OC2ISR
        MOVB
               #C2F,TFLG1
        LDD
               TC2 ; schedule next interrupt
        ADDD
               #30000
                       ; 30000 cycles = 10ms
               TC2
        STD
                          . . . . .
               COUNT
        LDAB
               COUNT
        CMPB
               NUMTICKS ; has count reached
        BNE
               DONE
                     ; not one second vet so return
        CLR
               COUNT
        JSR
               ONE.SECOND
DONE
        RTI
               END OF SERVICE ROUTINE
 subroutines follow this
 ONE.SECOND:
 what to do ev
ONE . SECOND
        bclr PORTB, %11110000
              SECONDS
              SECONDS
        LDAA
        CMPA
              #60
        BEQ
              ONE.MINUTE
        BRA
              UpdateDone
UpdateDone
            ; return from subrouitne
        RTS
```

### Conclusion

We learned how devices (that are not connected to the internet) keep track of time using the frequency of the processor. And how to effectively uses that frequency to do events at specific time stamps.