

Image Compression Using Truncated SVD

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I. INTRODUCTION

Singular Value Decomposition (SVD) is a fundamental mathematical technique used to break down a matrix into three simpler matrices. It expresses any matrix A as a product of three matrices in which two are orthogonal matrices and a diagonal matrix consisting singular values as diagonal entries.

II. SUMMARY OF STRANG'S VIDEO

A. Key points in Strang video

- Any matrix can be decomposed into three different matrices
 - Orthogonal matrix of left singular vectors
 - Diagonal matrix
 - Orthogonal matrix of right singular vectors
- Suppose A be a matrix of order $m \times n$, then A can be written as

$$A = U\Sigma V^T \quad (0.1)$$

where U and V are orthogonal matrices and Σ is a diagonal matrix.

- This decomposition of a matrix is called Singular Value Decomposition.
- Consider a square symmetric matrix B , then B can be written as

$$B = Q\lambda Q^T \quad (0.2)$$

where Q is a matrix containing eigen vectors of B and λ is a diagonal matrix containing eigen values as diagonal entries.

- This is called Eigenvalue Decomposition. This is the basis for the proof of SVD.

B. Proof of SVD

Consider a orthogonal matrix V in row space and a orthogonal matrix U consisting of unit vectors in column space

$$V = (v_1, v_2, \dots, v_n) \quad (0.3)$$

$$U = (u_1, u_2, \dots, u_m) \quad (0.4)$$

Consider a matrix A such that, u_i can be written in terms of v_i

$$\sigma_i u_i = A v_i \quad (0.5)$$

$$U\Sigma = A V \quad (0.6)$$

$$A = U\Sigma V^{-1} \quad (0.7)$$

Since $U^T U = I$ and $V^T V = I$

$$A = U\Sigma V^T \quad (0.8)$$

C. Calculating U and V

Consider

$$\mathbf{A}^T \mathbf{A} = \mathbf{V} \Sigma^T \mathbf{U}^T \mathbf{U} \Sigma \mathbf{V}^T \quad (0.9)$$

$$\mathbf{A}^T \mathbf{A} = \mathbf{V} \Sigma^T \Sigma \mathbf{V}^T \quad (0.10)$$

From this we can say that \mathbf{V} is a matrix of eigen vectors of matrix $\mathbf{A}^T \mathbf{A}$, and similarly \mathbf{U} is a matrix of eigen vectors of matrix $\mathbf{A} \mathbf{A}^T$ and the diagonal matrix is given by,

$$\Sigma = \begin{pmatrix} \sigma_1 & 0 & 0 & 0 \\ 0 & \sigma_2 & 0 & 0 \\ 0 & 0 & \sigma_3 & 0 \\ 0 & 0 & 0 & \sigma_4 \end{pmatrix} \quad (0.11)$$

For a 4x4 matrix, where

$$\sigma_i = \sqrt{\lambda_i} \quad (0.12)$$

where λ_i are the eigen values of matrix $\mathbf{A}^T \mathbf{A}$.

III. EXPLANATION OF THE ALGORITHM

The given c code compresses an image using the SVD technique. It uses the Power Iteration method to find the largest singular values and their corresponding singular vectors.

- The input image is read using the STB image library and converted into a matrix A , where each element represents a pixel intensity (0-255).
- A symmetric matrix $\mathbf{A}^T \mathbf{A}$ is calculated and used for finding right singular vectors of A .
- A random vector v is created as the starting point for the iteration.
- Some random vector v is assumed and it is repeatedly multiplied with $\mathbf{A}^T \mathbf{A}$ and normalized by the algorithm:

$$v = \frac{\mathbf{A}^T(\mathbf{A}v)}{\|\mathbf{A}^T(\mathbf{A}v)\|} \quad (0.13)$$

After several repetitions by approximation, v becomes the right singular vector corresponding to the largest singular value.

- Once v is found, the left singular vector is calculated as:

$$u = \frac{\mathbf{A}v}{\|\mathbf{A}v\|} \quad (0.14)$$

- The singular value is given by:

$$\sigma = \|\mathbf{A}v\| \quad (0.15)$$

- Using the values of u , v , and σ , a rank-1 matrix is formed:

$$A_1 = \sigma uv^T \quad (0.16)$$

- Subtracting this rank-1 approximation from the original matrix to remove its effect:

$$A = A - A_1 \quad (0.17)$$

This step allows finding the next largest singular value and vector.

- The above steps are repeated k times to form a rank- k approximation:

$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^T \quad (0.18)$$

- The reconstructed matrix A_k is converted back to pixel form and saved as a new compressed image.