



Assignment 1

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Course Title: Digital Signal Processing

Course Code: EEE321

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$$\therefore a = 2$$

$$b = 10$$

$$19) H(z) = \frac{az}{z-b}$$

$$H(z) = \frac{2z}{z-10}$$

Given,

$$x(n) = u(n)$$

$$X(z) = Z[u(n)] = \frac{z}{z-1}$$

We know,

$$Y(z) = H(z) \cdot X(z)$$

$$= \frac{2z}{z-10} \times \frac{z}{z-1}$$

$$= \frac{2z^2}{(z-10)(z-1)}$$

\therefore The system response in z-domain,

$$Y(z) = \frac{2z^2}{(z-10)(z-1)}$$

$$b) y(n) = Z^{-1} [Y(z)]$$

$$= Z^{-1} \left[\frac{2z^2}{(z-10)(z-1)} \right]$$

$$= Z^{-1} \left[2 + \frac{80}{3(z-10)} - \frac{14}{3(z-1)} \right]$$

$$= 2\delta(n) + \frac{80}{3} (10)^{n-1} u(n-1)$$

$$- \frac{14}{3} (1)^{n-1} u(n-1) \quad (\text{Ans.})$$

∴ The system response in time domain,

$$y(n) = 2\delta(n) + \frac{80}{3} (10)^{n-1} u(n-1)$$

$$- \frac{14}{3} (1)^{n-1} u(n-1) \quad (\text{Ans.})$$

$$\begin{array}{r} 2 \\ \times \\ z^2 - 11z - 10 \overline{) 2z^2} \\ \underline{- 2z^2 - 22z - 20} \\ 22z + 20 \end{array}$$

$$= 2 + \frac{22z + 20}{z^2 - 11z - 10}$$

$$= 2 + \frac{22z + 20}{(z-10)(z-1)}$$

By Partial Fraction:

$$\frac{22z + 20}{(z-10)(z-1)} = \frac{A}{(z-10)} + \frac{B}{(z-1)}$$

$$22z + 20 = A(z-1) + B(z-10)$$

$$\text{Let } z=1$$

$$42 = -9B$$

$$B = -\frac{14}{3}$$

$$\text{Let } z=10$$

$$240 = 9A$$

$$A = \frac{80}{3}$$

$$2 + \frac{80}{3(z-10)} - \frac{14}{3(z-1)}$$

$$c) x(n) = 2^n u(n-1)$$

$$X(z) = Z[2^n u(n-1)]$$

$$= \frac{2}{z-2}$$

$$Y(z) = H(z) \cdot X(z)$$

$$= \frac{2z}{z-10} \times \frac{2}{z-2}$$

$$= \frac{4z}{(z-10)(z-2)}$$

The output of response, in z domain,

$$Y(z) = \frac{4z}{(z-10)(z-2)}$$

In Time domain,

$$y(n) = Z^{-1} \left[\frac{4z}{(z-10)(z-2)} \right]$$

$$= Z^{-1} \left[\frac{5}{z-10} - \frac{1}{z-2} \right]$$

$$= 5 \cdot (10)^{n-1} u(n-1) - (2)^{n-1} u(n-1)$$

$$(1-n)2^n - (1-n)u(n) = (n)2^n$$

$$(1-n)2^n - (1-n)u(n) = (n)2^n$$

$$Z[u(n)] = \frac{z}{z-1}$$

$$Z[u(n-1)] = z^{-1} \frac{z}{z-1} \quad [\text{Sample Shifting property}]$$

$$\frac{(1-z)z}{(1-z)z-1} = \frac{z}{z-1}$$

$$Z[2^n u(n-1)] = \frac{z}{(1-z) \frac{z}{2} - 1} \quad [\text{Frequency Shifting property}]$$

$$= \frac{2z}{z-2}$$

$$1 < |z| < 10$$

$$\frac{4z}{(z-10)(z-2)} = \frac{A}{z-10} + \frac{B}{z-2}$$

$$4z = A(z-2) + B(z-10)$$

$$\text{Let } z=2$$

$$8 = -8B$$

$$B = -1$$

$$\text{Let } z=10$$

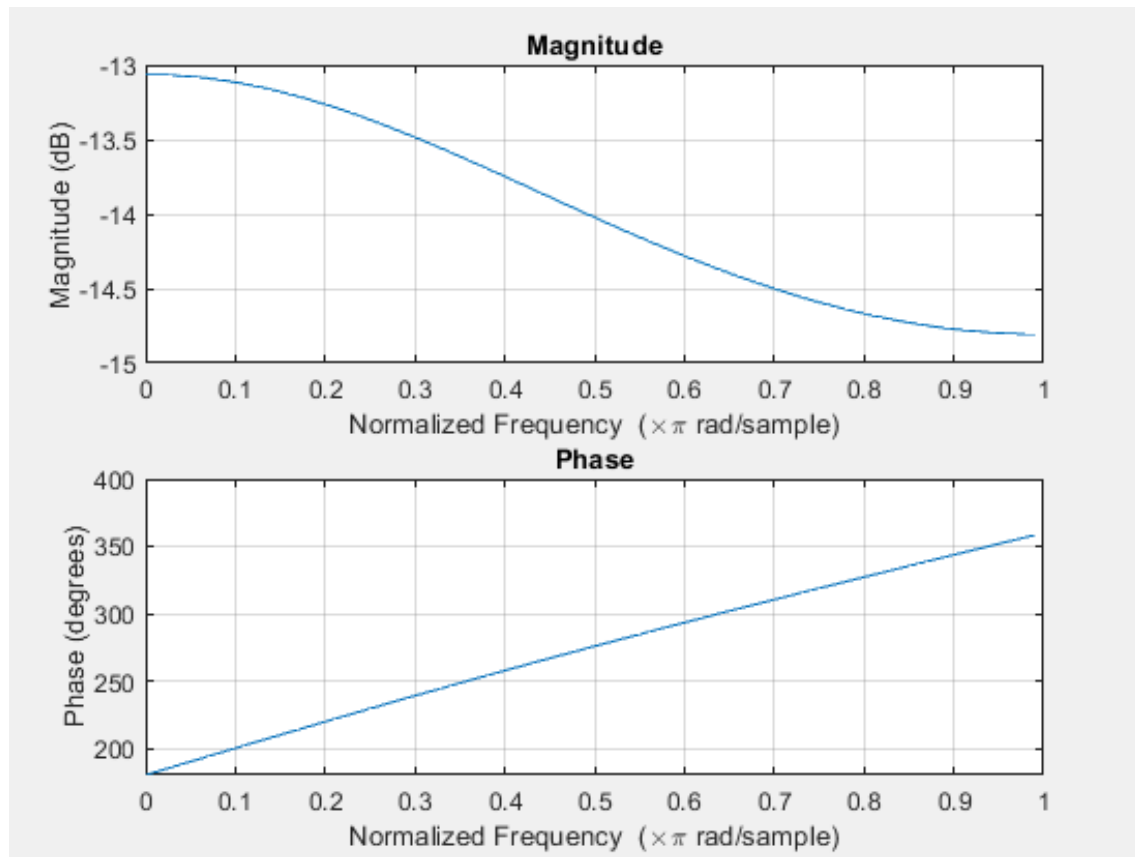
$$40 = 8A$$

$$A = 5$$

$$= \frac{5}{z-10} - \frac{1}{z-2}$$

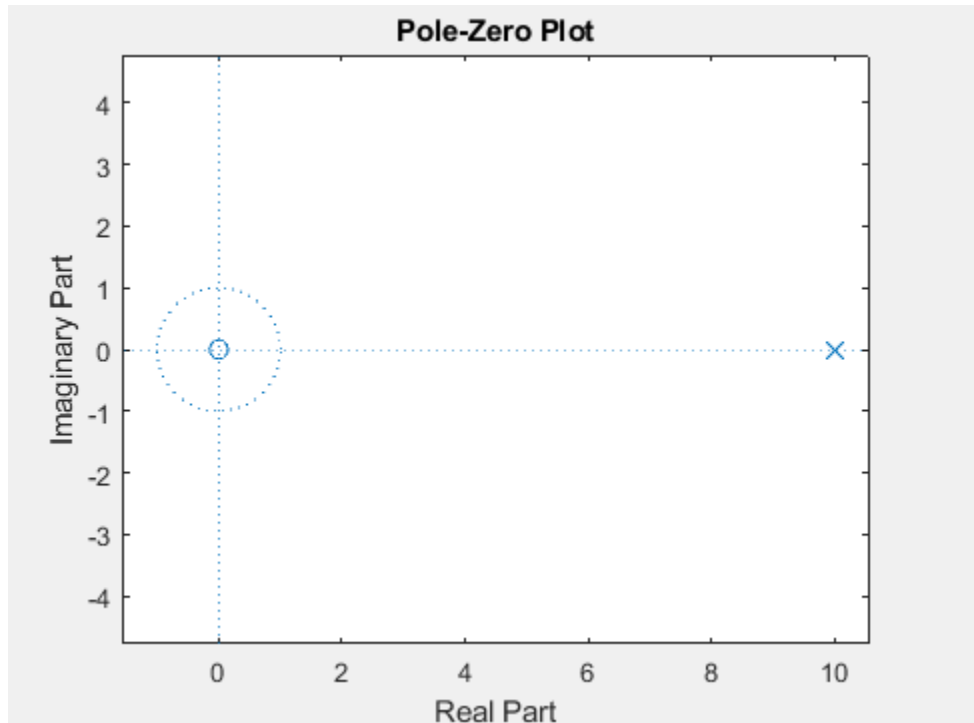
d) Plot the frequency response of the LTI system using MATLAB simulation.

```
%frequency plot of the LTI system  
%  $H(z) = 2z/(z-10)$   
a=[1, -10];  
b=[2, 0];  
freqz(b,a,100);
```



e) Plot the pole-zero plot on a complex z-plane for the system using MATLAB. Comment on the stability of the system?

```
%Pole-zero plot  
%  $H(z) = 2z/(z-10)$   
a=[1,-10];  
b=[2,0];  
zplane(b,a)
```



Since the pole of the z-transfer function is outside of the unit circle on the z-plane pole-zero plot, the system is unstable.

$$2. a) x(n) = 5u(n-1) - 2\delta(n-1)$$

$$X(z) = Z[5u(n-1) - 2\delta(n-1)]$$

$$= Z[5u(n-1)] - Z[2\delta(n-1)]$$

$$= \frac{5}{z-1} - \frac{2}{z}$$

$$= \frac{5z - 2(z-1)}{z(z-1)}$$

$$= \frac{5z - 2z + 2}{z(z-1)}$$

$$= \frac{3z + 2}{z(z-1)}$$

$$(ROC_1) z \neq 0 \quad (ROC_2) : z > 1$$

$$ROC = (ROC_1) \cap (ROC_2)$$

$$ROC = z > 1$$

$$(1-n)u^n \delta = (n)X \quad (1)$$

$$Z[u(n)] = \frac{z}{z-1}$$

$$Z[u(n-1)] = z^{-1} \frac{z}{z-1}$$

$$\frac{s}{s-s} \times \frac{s}{01-s} = \frac{1}{z-1}$$

$$Z[\delta(n)] = 1$$

$$Z[\delta(n-1)] = z^{-1} = \frac{1}{z}$$

$$\frac{s}{(s-s)(01-s)} = (s)Y$$

$$\left[\frac{s}{(s-s)(01-s)} \right]^{-1} \delta = (n)Y$$

$$\left[\frac{1}{s-s} - \frac{s}{01-s} \right]^{-1} \delta =$$

$$(1-n)u^n \delta = (1-n)u^n \delta$$

$$b) Z \{ n[5u(n-1) - 2\delta(n-1)] \} \{ [0 - n]25 - (1-n)00 \} n \{ Z \}$$

$$-Z \cdot \frac{d}{dz} \left(\frac{3z+2}{z^2-z} \right)$$

$$-Z \cdot \frac{z^2-z \frac{d}{dz}(3z+2) - (3z+2) \frac{d}{dz}(z^2-z)}{(z^2-z)^2}$$

$$-Z \cdot \frac{(z^2-z) \cdot 3 - (3z+2)(2z-1)}{(z^2-z)^2}$$

$$-Z \cdot \frac{3(z^2-z) - (6z^2-3z+4z-2)}{(z^2-z)^2}$$

$$-Z \cdot \frac{-3z^2-4z+2}{z^2(z-1)^2}$$

$$= \frac{3z^2+4z-2}{z(z-1)^2}$$

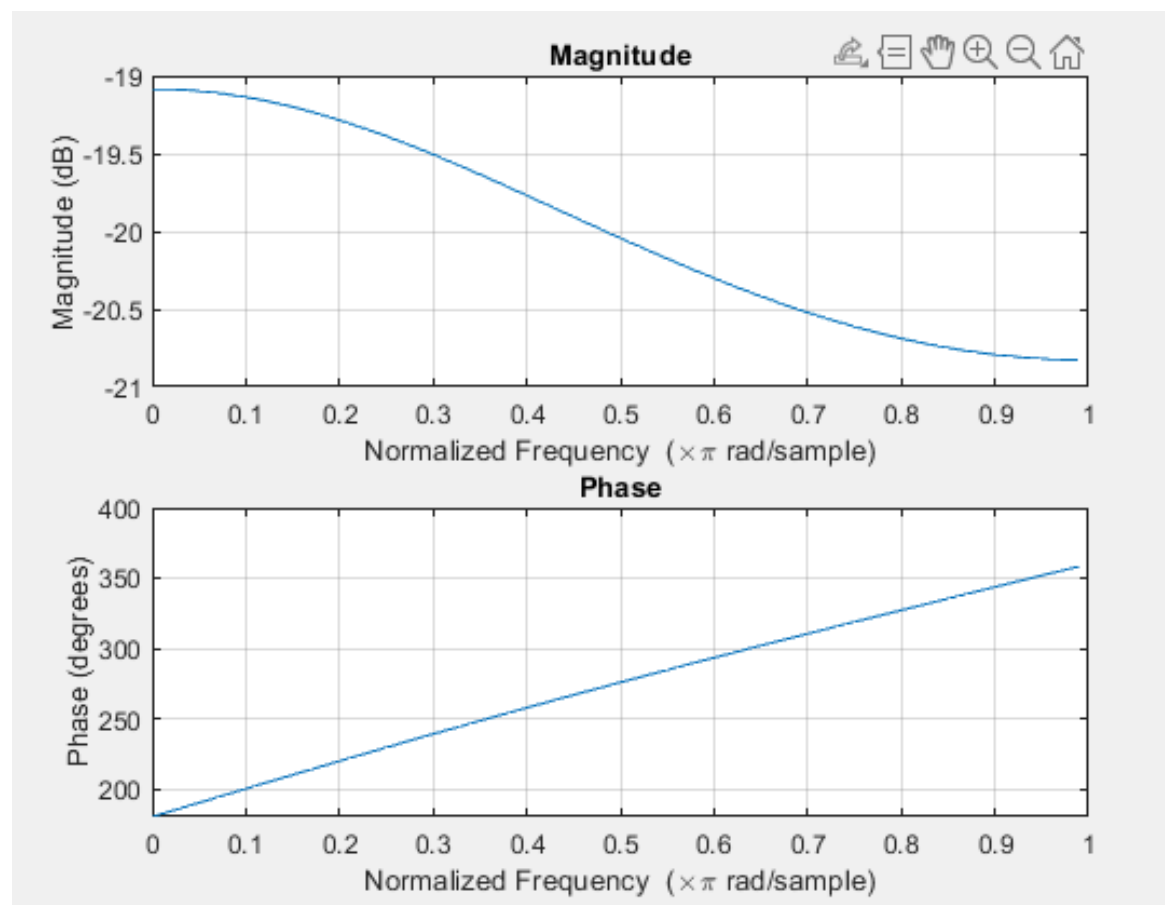
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$$(ROC_1) z \neq 0 \quad (ROC_2) z > 1$$

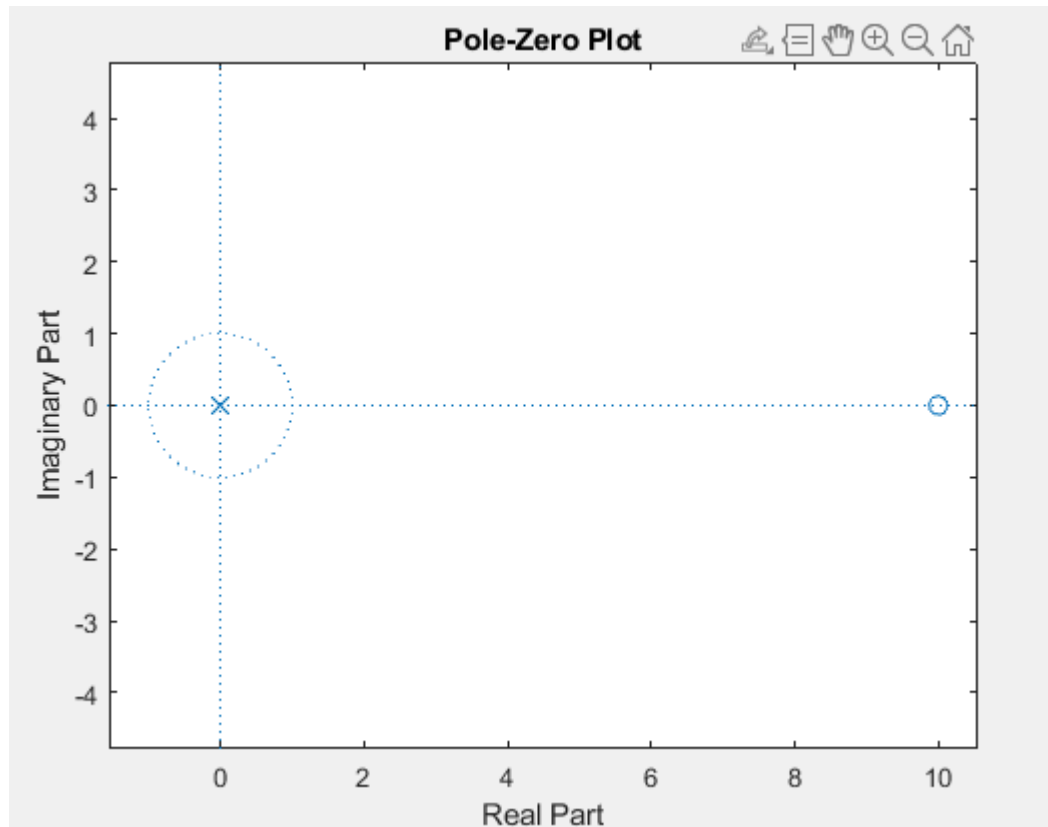
$$ROC = (ROC_1) \cap (ROC_2)$$

$$\boxed{ROC = z > 1}$$


```
%frequency plot of the LTI system  
%  $H(z) = z/(z-10)$   
a=[1,-10];  
b=[1, 0];  
freqz(b,a,100);
```



```
%Pole-zero plot  
%  $H(z) = z/(z-10)$   
b=[1,-10];  
a=[1,0];  
zplane(b,a)
```



Since the pole of the z-transfer function is outside of the unit circle on the z-plane pole-zero plot, the system is unstable.

c) $H(z) = \frac{z}{z-10}$

$$H(z) = \frac{1}{1-10z^{-1}}$$

Here;

$$b_0 = 1, b_1 = 0$$

$$a_0 = 1, a_1 = -10$$

\therefore The difference equation is,

$$y(n) - 10y(n-1) = x(n) \quad (\text{Ans:})$$

d) The impulse response $h(n)$ of the system is given.

$$h(n) = 10^n u(n)$$

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```
function [x,n] = stepseq(n0, n1, n2)
    n = n1:n2
    x = (n>=n0)
    stem(n,x)
```

end

```
%h(n) = 10^nu(n)
n = 0:10;
x = (10.^n).*stepseq(0,0,10);
stem(n,x)|
```

