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NB1230 Linear Algebra, Resit
Monday June 17 2023, 9:00-11:00



Student number :

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This exam consists of 9 main GraspLe questions plus 6 main questions on paper, worth $35+46 = 81$ points in total. Grade = $1 + \frac{\text{Point total}}{9}$. You can use the build in GraspLe calculator. Please write your answers in the answer boxes and provide explanations when requested. Raise your hand when you have a question!

1. Consider the following matrix and vector

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$$A = \begin{bmatrix} h^2 - 4 & 3 & 4 \\ 0 & h - 1 & k \\ 4 - h^2 & -3 & h - 2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} k \\ h - 1 \\ -k \end{bmatrix}$$

For each combination of values for h and k determine the number of solutions of the equation $A\mathbf{x} = \mathbf{b}$.

	No solutions	One solution	Infinitely many solutions
Answer:	$h = -2 \wedge k = -4$ $h = 2 \wedge k = \frac{4}{3}$	$h \neq -2, 1, 2$	$h = -2 \wedge k \neq -4$ $h = 1$ $h = 2 \wedge k \neq \frac{4}{3}$



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2. Consider the set S of vectors $\mathbf{x} \in \mathbb{R}^2$ for which $x_1^2 = x_2^2$.

Is S a linear subspace of \mathbb{R}^2 ?

Explain your answer: Investigate whether or not S satisfies the definition of a linear subspace.

Answer: Yes

No

Explanation:

If a subspace is linear and \vec{u} and \vec{v} are in that subspace, $\vec{u} + \vec{v}$ should be in the subspace too.

For this set, for example

$$\vec{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad 1^2 = 1^2 \quad \vec{v} = \begin{bmatrix} 2 \\ -2 \end{bmatrix} \quad 2^2 = (-2)^2$$

$$\text{however } \vec{u} + \vec{v} = \begin{bmatrix} 3 \\ -1 \end{bmatrix} \quad 3^2 \neq (-1)^2$$

$\therefore S$ is not a linear subspace.

3. Suppose that A is a 3×5 matrix whose first row consists only of zeroes. Based on this information, give the minimal and maximal possible value of the rank of A . 3

Explain your answers.

Answer: Min 0

Max 2

Explanation:

If one row is all zeros, then A can have at most two row pivots, and therefore, 2 column pivots, so maximum rank of A is 2.

It is also possible that the other rows might be all zeros too, in which case, the rank is zero (min).

4. Consider the following matrix and its echelon form. 9

$$A = \begin{bmatrix} 1 & 2 & 3 & 5 & 7 \\ -2 & -4 & -2 & -4 & -6 \\ 1 & 2 & 3 & 5 & 16 \\ -2 & -4 & 6 & 8 & 3 \end{bmatrix} \sim E = \begin{bmatrix} 1 & 2 & 3 & 5 & 7 \\ 0 & 0 & 4 & 6 & 8 \\ 0 & 0 & 0 & 0 & 9 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Which of the following sets form a basis for $\text{Col}(A)$?



$$B_1 = \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 3 \\ 6 \end{bmatrix} \right\} \quad B_2 = \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 5 \\ -6 \\ 5 \\ 2 \end{bmatrix}, \begin{bmatrix} 7 \\ -6 \\ 16 \\ 3 \end{bmatrix} \right\} \quad B_3 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 9 \\ 0 \end{bmatrix} \right\}$$

Answer:

Yes/No:

No

Yes/No:

Yes

Yes/No:

No

Explanation:

- There are 3 pivot columns in the echelon form of A , so the $\dim(\text{col}(A))$ should be equal to 3. Therefore B_1 is not a basis for $\text{col}(A)$. Rank(A)=3

- B_3 is not a proper basis because these are the columns from the echelon form and they are not in the column space of A . for example,

$$A \begin{bmatrix} 1 & 2 & 3 & 5 & 7 \\ -2 & -4 & -2 & -4 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 5 & 7 \\ -2 & -4 & -2 & -4 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Not a linear comb, so not even a part of the set of vectors.

Row reduction leads to a Contradictory row:

$$[0 \ 0 \ 0 \ 0 \ 0 \ | \ -43/7]$$

- B_2 is a proper basis because \dim of the set is 3 and the first and third vectors are in $\text{col}(A)$ - columns 1 and 5 of matrix A : which are the pivot columns in echelon form. They are a linearly independent set (not multiples of each other). ~~It forms a proper basis for a subspace spanning \mathbb{R}^3 .~~



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5. Consider the matrix $A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$, the vectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ and the linear subspace $W = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

(a) Show that A is an orthogonal matrix.

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Explanation:

Orthogonal matrix has orthonormal columns.

$$\left\| \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\| = 1 \quad \left\| \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\| = 1 \quad \left\| \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\| = 1$$

$$\mathbf{b}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \mathbf{b}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \mathbf{b}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \bullet \text{ It is a square matrix } (3 \times 3)$$

$$\text{then, } \mathbf{b}_1 \cdot \mathbf{b}_2 = 0$$

$$\mathbf{b}_2 \cdot \mathbf{b}_3 = 0$$

$$\mathbf{b}_1 \cdot \mathbf{b}_3 = 0$$

\therefore they are all orthogonal to each other.

For this matrix, $A^T = A^{-1}$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} = A^{-1} \quad \xrightarrow{\text{Gauss}} \left[\begin{array}{ccc|ccc} 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] = \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 \end{array} \right]$$

(b) Show that $A\mathbf{w} \in W$ for all $\mathbf{w} \in W$.

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Explanation:

* Since $W = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ of two linearly independent vectors, vector $\mathbf{w} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2$

$$A\mathbf{v}_1 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \mathbf{v}_2$$

$$A\mathbf{v}_2 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = (\mathbf{v}_1 + \mathbf{v}_2) \times 1 = \mathbf{v}_1 + \mathbf{v}_2$$

Since $A\mathbf{v}_1$ and $A\mathbf{v}_2$ both result in vectors in W ,

$$A(c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2) = c_1 A\mathbf{v}_1 + c_2 A\mathbf{v}_2$$

which is still some constants

times $A\mathbf{v}_1$ and $A\mathbf{v}_2$ \therefore will be in W .

~~Span of~~



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- (c) Compute the eigenvalues of A .

Answer:

1

Explanation:

Since A is an orthogonal matrix, A only has one eigenvalue: 1.

Since columns of A are linearly independent they span all of \mathbb{R}^3 . Therefore for any vector in \mathbb{R}^3 , the eigenvalue is 1 with arithmetic multiplicity of 3 and geometric multiplicity of 3.

$$\begin{bmatrix} -\lambda & 0 & 1 \\ 1 & -\lambda & 0 \\ 0 & 1 & -\lambda \end{bmatrix} \rightarrow -\lambda [\lambda^2] + 1 [1] = -\lambda^3 + 1 = 0$$

$$\lambda^3 = 1$$

$$\boxed{\lambda = 1}$$

- (d) The linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ with standard matrix A is a rotation. Determine a vector that spans the axis of rotation.

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Answer:

Explanation:

A vector that spans the axis of rotation has eigenvalue 1, because it does not change.

$$A = \begin{bmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} \text{ nul} \begin{bmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 1 & | & 0 \\ 1 & -1 & 0 & | & 0 \\ 0 & 1 & -1 & | & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} -1 & 0 & 1 & | & 0 \\ 0 & -1 & 1 & | & 0 \\ 0 & 1 & -1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 1 & | & 0 \\ 0 & 1 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \quad \begin{array}{l} -x_1 + x_3 = 0 \\ x_1 = x_3 \\ x_2 = x_3 \end{array}$$

$x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is in E_1 of



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+3

(e) Bonus: Determine the angle of rotation

Explanation:

6. Consider an *injective* linear transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^5$ and a *linearly independent* set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ in \mathbb{R}^4 . Explain why $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ in \mathbb{R}^5 is linearly independent. 5

Explanation:

Injective linear transformation is one-to-one transformation. Which means there is only one value in domain that maps onto one value in the range. For lin. independent set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$, $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ will be unique too, making $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ a linearly independent set.

$\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are not multiples of each other or a linear combination.

» $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ will have pivot in every column, so $\{T(\mathbf{v}_1), T(\mathbf{v}_2), T(\mathbf{v}_3)\}$ will have pivot in every column too.



Extra space 1

(6.)

Let

$$A = [v_1 \ v_2 \ v_3]$$

$$A\vec{x} = \vec{0}$$

$$\vec{x} = \vec{0}$$

$Nul(A) = \{\vec{0}\}$ since the vectors are linearly independent.

$T(A) = [T(v_1) \ T(v_2) \ T(v_3)]$ only has the ~~trivial~~ trivial solution as a solution to $T(A)\vec{x} = \vec{0}$. therefore, these columns are linearly independent too.

→ ~~Substitution~~ $\vec{x} = \vec{0}$



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Extra space 2

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