STAT1012 Statistics for Life Sciences

Quick Revision Notes

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(Reference: lecture and tutorial notes)

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# I) Descriptive Statistics

Data type: Qualitative (special: Categorical), Quantitative (Discrete, Continuous)

Population: the whole set of entities of interest

Sample: a subset of the population

## Central tendency

Sample mean:

Sequential update property:

Mode: the value which has the greatest number of occurrence (may not be unique)

Median: the “middle” value, or the average of the two values closest to “middle” after sorting

Percentile: the p-th percentile () is a value such that p% of the data are less than or equal to . In particular, upper quantile = , median = , lower quantile =

Denote the sorted data by where . This is equivalent to saying that is the smallest, is the second smallest etc.

Median: if n is odd or if n is even

Percentile: where if is not an integer

Otherwise,

## Dispersion

Symmetric: the left hand side of the distribution mirrors the right hand side

Unimodal: the mode is unique

Skewness: measure of asymmetry

Left-skewed (negatively skewed): mean < median, have a few extreme small values

Right-skewed (positively skewed): mean > median, have a few extreme large values

Symmetric mean = median (converse not true)

Symmetric + unimodal mean = median = mode (converse not true)



Range: maximum – minimum ()

Interquartile range:

Sample variance: or

Sample standard deviation:

## Graphical methods

Bar graph: use for categorical data, show the number of observations in each category

Histogram: use for quantitative data, showing the number of observations in each range

Stem-and-leaf plot: ordered the data into a tree-like structure

Boxplot: show 5 numbers (min, Q1, median, Q3, max), help locate outliers (As a rule of thumb, some people define outliers as values > Q3 + 1.5\*IQR or < Q1 – 1.5\*IQR)

# II) Probability

## Notations

Sample space: the set of all possible outcomes, often denoted as

Outcome: a possible type of occurrence

Event: any set of outcomes of interest, can be denoted as

Probability (of an event): denoted by , always lies between 0 and 1 (both inclusive)

Union: either A or B occurs, or they both occurs, denoted by (logically equivalent to OR)

Intersection: both A and B occur, denoted by (logically equivalent to AND)

Complement: A does not occur, denoted by (logically equivalent to NOT)

Commutativity:

Associativity:

Distributive laws:

DeMorgan’s laws:

## Probability theory

Mutually exclusive: A and B are mutually exclusive if (cannot co-occur)

Independence: iff A and B are independent. Their complements (A and BC; AC and B; AC and BC) will be pairwise independent as well

Addition law:

Multiplication law: if are mutually independent, then

## Conditional probability

Conditional probability: , if , then A and B are independent

Relative risk:

Total probability rule:

Exhaustive: if are exhaustive, then (at least one of them must occur)

Generalized total probability rule: let be mutually exclusive and exhaustive events. For any event B, we have



Bayes' theorem: conditional probability + generalized total probability rule. let be mutually exclusive and exhaustive events. For any event B,

# III) Discrete Probability Distributions

Random variables: numeric quantities that take different values with specified probabilities

Discrete random variable: a R.V. that takes value from a discrete set of numbers

Continuous random variable: a R.V. that takes value over an interval of numbers

## Discrete random variables

Probability mass function: a pmf assigns a probability to each possible value x of the discrete random variable X, denoted by

(total probability rule)

Cumulative distribution function: a cdf gives the probability that X is less than or equal to the value x, denoted by

Expected value: (the idea is “probability weighted average”)

Variance: , alternatively

Translation/rescale: ,

Linearity of expectation:

## Binomial distribution

Factorial: , note that

Permutation (order is important):

Combination (order is not important): , also denoted as

Binomial distribution: probability distribution on the number of successes in independent experiments, each experiment has a probability of success , then

Pmf: for

Mean:

Variance:

Skewness: right-skewed if p<0.5, symmetric if p=0.5, left-skewed if p>0.5

## Poisson distribution

Poisson distribution: probability distribution on the number of occurrence (usually of a rare event) over a period of time or space with rate , then

Pmf: for

Mean:

Variance:

Skewness: right-skewed

Poisson limit theorem (poisson approximation to binomial): if where and , then where

## Hypergeometric distribution (not required)

Hypergeometric distribution: probability distribution on the number of success in trials without replacement, from a finite population of size that contains trials classified as success, then

Pmf: for

Mean:

Variance:

## Geometric distribution (not required)

Geometric distribution: probability distribution on the number of trials when the first success occurs, each trial has a probability of success , then

Pmf: for

Mean:

Variance:

Memoryless: . Geometric distribution is the only discrete distribution with this property

## Negative binomial distribution (not required)

Negative binomial distribution: probability distribution on the number of times when the success occurs, each trial has a probability of success , then

Pmf: for

Mean:

Variance:

# IV) Continuous Probability Distributions

## Continuous random variables

Probability density function: a pdf specifies the probability of the random variable falling within a particular range of values, denoted by

, which is the area under the curve from a to b

for all

(total probability rule)

Cumulative distribution function: a cdf gives the probability that X is less than or equal to the value x, denoted by

(by the fundamental theorem of calculus)

Expected value:

Variance:

(Note: Calculus is NOT required in our course)

## Uniform distribution

Uniform distribution: if follows uniform distribution on the interval , then it has the same probability density at any point in the interval and we denote it by

Pdf: for , otherwise 0

Cdf: for

Mean:

Variance:

## Normal distribution

Normal distribution: if follows normal distribution with mean and variance , then , often used to represent continuous random variable with unknown distributions

Pdf: for

Shape: bell-shape, symmetric about the mean, unimodal

Standard normal distribution:

Cdf of standard normal: denoted as

by symmetric property

Percentile of standard normal:

Standardization: if , then

De Moivre–Laplace theorem (normal approximation to binomial): if , where . The 0.5s are continuity correction

Normal approximation to poisson: if where

## Some remarks (not required)

Statistical parameter: a numerical characteristic of a statistical population or a statistical model. We are given these numbers (e.g. ) in previous chapters but in reality we do not know these numbers. These lead to the next part of our course: Statistical Inference

Why approximation: one major reason is that calculating binomial probability involves combination and large factorials are hard/costly to compute in previous centuries

Variance of sum:

Tower rule of expectation:

Law of total variance (EVE):

Sum of poisson: if independently, then

Sum of normal: if independently, then

# V) Point Estimation

Statistical inference: process of drawing conclusions from data that are subject to random variations

Estimation: estimate the values of specific population parameters based on the observed data

Hypothesis testing: test on whether the value of a population parameter is equal to some specific value based on the observed data

## Sampling

Sample: the data obtained after the experiments are performed, usually denoted by

Random sample: the data before the experiments are performed, usually denoted by

Non-probability sample: some elements of the population have no chance of being selected

Probability sample: all elements in the population has known nonzero chance to be selected

Simple random sample: all elements in the population has the same probability to be selected

Systematic sample: elements are selected at regular intervals through certain order

Stratified sample: all elements are classified into different stratums and each stratum is sampled as an independent sub-population

Cluster sample: all elements are divided into different clusters and a simple random sample of clusters is selected

Coverage error: exists if some groups are excluded from the frame and have no chance of being selected

Non-response error: people who do not respond may be different from those who do respond

Measurement error: due to weaknesses in question design, respondent error, and interviewer’s impact on the respondent

Sampling error: Chance (luck of the draw) variation from sample to sample

## Point estimation

Point estimator: a rule for calculating a single value to “best guess” an unknown population parameter of interest based on the observed data

(Note: estimator is random, estimate is fixed, estimand is the unknown parameter)

Unbiasedness:

Minimum variance:

Independent and identically distributed (i.i.d.): an assumption where the random variables are sampled such that they are independent and follows the same distribution

Central limit theorem (CLT, Lindeberg–Lévy): Let be i.i.d. random variables with mean and finite variance , then as n tends to infinity (>30 in practice),

## Mean

Estimand:

Sample mean (estimator):

Expectation: (unbiased)

Variance: (by i.i.d.)

Distribution: . If , then this follows from the fact that sum of independent normal is normal (remarks in section IV). If follows some other distribution, then this follows from the CLT when n is large (usually ≥30)

## Variance

Estimand:

Sample variance (estimator):

Expectation: (unbiased)

Variance: (not required)

Distribution: (not required)

# VI) Interval Estimation

## Confidence interval

Confidence interval: an interval associated with a confidence level that may contain the true value of an unknown population parameter

Meaning of confidence level: in the long run, of all the confidence intervals that can be constructed will contain the unknown true parameter (NOT the probability that an interval will contain the parameter)

Form of confidence interval: , where is the point estimate, is the critical value from some distribution under the confidence level , is the standard error of the point estimate

## Mean

Confidence interval ( is known):

Margin of error: (that means width is , help determine sample size)

## Variance

Confidence interval ( is unknown):

Confidence interval ( is known):