Hemant Kumar

PhD Student | UMD College Park, USA | Email | Google Scholar | Phone No. | Linkedin | Github

Research Summary

My research focuses on integrating control theory with learning-based methods to develop robots that can perceive, adapt, and act intelligently in unstructured environments. I aim to build control-theoretically grounded learning systems that leverage foundation models and vision-language-action representations to enable safe, generalizable, and reliable robot behavior in real world, human-centric settings.

Education

University of Maryland, College Park

Ph.D. in Robotics

Thesis Direction: Autonomous Disassembly of EVs (Electric Vehicles).

Imitation Learning · Reinforcement Learning · Control Theory · VLA's · Truth-worthy Robotics · Computer-Vision

Sept 2022 - Present

Advisor: Nikhil Chopra

Sept 2015 - May 2020

Advisor: Chetan S. Mistry

Indian Institute of Technology (IIT), Kharagpur

Bachelors of Technology (Honors) - Aerospace Engineering Master of Technology - Aerospace Engineering

Patents

- Hemant Kumar (Lead Inventor), Kaustubh Joshi, Nikhil Chopra, RACE: Real-Time Adaptive Camera Intrinsic Estimation (US-Patent under-review).
- Piyush Goenka, **Hemant Kumar**, Kaustubh Joshi, Alexander Beyer, Tianchen Liu, Nikhil Chopra, *UniScrew: Electronically Actuated Universal Electric Screwdriver Adapter for Any Robot Arm* (US-Patent under-review).

Publications

- Hemant Kumar*, Kaustubh Joshi*, Nikhil Chopra, *Generalized Real-Time Camera Calibration*, The IEEE/CVF Conference on Computer Vision and Pattern Recognition CVPR-2026 (under-review).
- Hemant Kumar, Kaustubh Joshi, Nikhil Chopra, *RACE: Real-Time Adaptive Camera-Intrinsic Estimation via Control Theory*, The International Conference on Learning Representations (ICLR-2026) (under-review).
- Hemant Kumar, Piyush Goenka, Nikhil Chopra, *DAWN-Visuomotor Diffusion policy for Imitation Learning for Contact Rich Manipulation Task*, International Conference of Robotic and Automation-2026 (under-review).
- Hemant Kumar*, Kaustubh Joshi*, Nikhil Chopra, *From Offline to Online: Adaptive Camera Calibration in Real Time.*, International Conference of Robotic and Automation, ICRA-2026 (under-review).
- Piyush Goenka, **Hemant Kumar**, Nikhil Chopra, *Toward Generalizable Robotic Disassembly: A Visuo-Tactile Pipeline for Screw Unfastening*, Robotics and Computer-Integrated Manufacturing (under-review).
- Benchmarking Vision-Language Models for Disassembly Tasks Building a dataset of multi-object assembly/disassembly sequences with question—answer supervision to train and evaluate vision-language model reasoning, correctness, and tool selection (in-progress).
- Adaptive Control Wrapper for Foundation Robotics Models Developing a control-theoretic wrapper over foundation models, single-policy networks, and VLA models to enable real-time adaptation under uncertainty in contact-rich manipulation tasks (in-progress).
- **Hemant Kumar**, Chetan S. Mistry, *Tip Clearance Mechanism in Mixed Flow Compressor*, Propulsion and Power Research 2023. *[Link]*.
- Hemant Kumar, Chetan S. Mistry, *Implementation of Similarity Principle and Scaling Laws for Low-to-High Speed Mixed Flow Compressor*, American Society of Mechanical Engineers Turbo Expo Boston 2023 [Link].
- Hemant Kumar, Chetan S. Mistry, *Numerical investigations on aerodynamic design criteria for low speed mixed flow compressor*, American Society of Mechanical Engineers (ASME) GTIndia 2021. [Link]
- Hemant Kumar, Chetan S. Mistry, Numerical Performance and Flow Field study of Centrifugal Compressor with Supercritical Carbon dioxide, American Society of Mechanical Engineers (ASME) GTIndia 2019. [Link].

Experience

• Research Intern | Destro-AI | Remote

Spring 2026 (upcoming)

- Developing a foundation Vision-Language-Action model for robotic grasping, picking, and manipulation in warehouse environments using customer driven data to enhance generalization and task understanding.
- Research Associate | Turbomachines Research Lab | *IIT Kharagpur*

Aug 2020 - May 2022

Supervisor: Prof. Chetan S. Mistry

- Investigated scaling laws and similarity principles to predict high-speed compressor performance from low-speed test data, establishing generalized scaling correlations for mixed-flow compressors.
- Analyzed **condensation and two-phase nucleation phenomena** in supercritical CO₂ compressors, identifying their impact on stability and off-design performance.
- Designed compressor stages with **variable tip clearances** using in-house code and CFD (ANSYS) to study tip-leakage vortex behavior and 3D flow-field characteristics at high rotor speeds.
- Published two peer-reviewed papers based on the above studies in international journal and conference.
- Research Intern | Turbomachines Research Lab | IIT Kharagpur

May 2019 - July 2019

Supervisor: Prof. Chetan S. Mistry

- Designed a **subsonic mixed-flow compressor** for a new low-speed turbomachinery facility at IIT Kharagpur; performed theoretical and thermal design calculations for a 3000 Pa pressure rise and 3000 rpm operation.
- Conducted CFD analysis and performance optimization in **ANSYS**; established the facility's proof-of-concept and co-authored a publication based on the results.
- Research Intern | Turbomachines Research Lab | IIT Kharagpur

May 2018 - July 2018

Supervisor: Prof. Chetan S. Mistry

- Designed and developed a supercritical CO₂ centrifugal compressor through theoretical modeling and in-house simulation code; performed CFD analysis in ANSYS to study flow-field and performance.
- Validated results with experimental data from **Sandia National Laboratories** and co-authored a publication.
- Research Intern | DRDO | Chandigarh, India

May 2017 - July 2017

Supervisor: Scientist 'E' Munesh Kumar Patle

- Conducted theoretical design and numerical analysis of a Pulse Detonation Engine (PDE) using ANSYS.
- Modeled 3D PDE geometry via custom code and analyzed detonation wave propagation, temperature distribution, and performance for various fuel–air mixtures.

Other Projects

- Advanced Machine Learning: Theory and Applications, University of Maryland (Feb–Jun 2023) Developed deep neural and reinforcement learning algorithms for autonomous course navigation.
- **Equilibrium Programming**, University of Maryland (Feb–Jun 2023) Implemented a bi-level optimization framework using game-theoretic principles for energy market.
- AIAA Design Competition 2019 Ranked among the Top 8 globally for hybrid-electric UAV engine design, organized by the American Institute of Aeronautics and Astronautics.
- Aerodynamics of Golf Ball, IIT Kharagpur (Jul–Nov 2017) Designed and tested a new dimple geometry using an indigenous force balance setup; validated with CFD and wind tunnel data.
- **Jetpack Design and Analysis**, IIT Kharagpur (Jul–Dec 2018) Proposed a theoretical model for dual low-bypass turbofan propulsion and control via thrust vectoring optimization.
- Cardiovascular Biofluid Dynamics, IIT Kharagpur (Jul 2019–Apr 2020) Simulated carotid artery flow in COMSOL to analyze hemodynamic patterns and flow separation effects.

Academic Service

Reviewer: RA-L (Robotics Automation and Letters), ICRA'25, ASME.

Technologies

 $\textbf{Languages:} \ \ \textbf{Python, MATLAB, Familiar with C \& C++}.$

Technologies: Git, Docker, LATEX, MAVLink, Arduino.

Robot Platforms: Universal Robots (UR5e and UR3e), Franka Emika (FR3), Neuromeka IndyRP2.

Robot Software & Simulation: ROS, ROS-2, Gazebo, NVIDIA Issac Sim.

Vision/AR/VR Systems: Intel Realsense, Quest 3, Real-time object detection & Navigation system integration.

Teaching

• Graduate Teaching Assistant, ENES221: Dynamics, UMD, College Park.	Spring 2025
• Graduate Teaching Assistant, ENES102: Mechanics-I, UMD, College Park.	Fall 2023
• Graduate Teaching Assistant, ENES102: Mechanics-I, UMD, College Park.	Spring 2023
• Graduate Teaching Assistant, ENES102: Mechanics-I, UMD, College Park.	Fall 2022
• Graduate Teaching Assistant, AE39003: Structure Lab-II, Indian Institute of Technology, Kharagpu	ır. Fall 2020

Positions of Responsibility

• Captain, IIT Kharagpur Men's Basketball Team - Silver Medal, 54 th Inter IIT Sports Meet.	2019–20
• Captain, Inter Hall Basketball Team - Silver Medal, General Championship, IIT Kharagpur.	2018–19
• Captain, Inter Hall Basketball Team - Gold Medal, General Championship, IIT Kharagpur.	<i>2017–18</i>
• Group Leader, National Service Scheme (NSS) - led in community service initiatives.	2016–17

Awards and Achievements

• Institute-Level Achievements

- Dean's Fellowship from University of Maryland (2023).
- Conferred the prestigious **Institute Blue Award** for outstanding contribution to Basketball, IIT Kharagpur.
- Recipient of the **AICTE Postgraduate Scholarship**, Government of India, for academic excellence.

• Inter IIT Sports Meets

- Captain, IIT Kharagpur Men's Basketball Team, Silver Medal, 54th Inter IIT Sports Meet, IIT KGP ('19–'20).
- Participant, Basketball, 53rd Inter IIT Sports Meet, IIT Guwahati (2018–19).
- Gold Medalist, Basketball, 52nd Inter IIT Sports Meet, IIT Madras (2017–18).

• Outstation Tournaments

- Silver Medalist, Basketball, Udghosh 2018, India's largest sports festival, IIT Kanpur.
- Represented IIT Kharagpur in the **Inter College Basketball League**, organized by the Basketball Federation of India, Kolkata (2018), finishing in **4th place**.
- Participated in the West Bengal Senior State Basketball Championship, Kolkata (2017).
- Participated in **Spardha 2017**, IIT (BHU) Varanasi.

• Inter-Hall Tournaments

- Captain, Nehru Hall Basketball Team, Silver Medal, General Championship, , IIT Kharagpur (2018–19).
- Gold Medalist, Inter Hall Basketball Tournament, General Championship, IIT Kharagpur (2017–18).
- Represented Nehru Hall Basketball Team (2017, 2020).
- Represented Nehru Hall Athletics Team (Hammer Throw, Shot-Put), General Championship (2017).

Other Activities

- Participated in a week-long **NSS Camp** on first-aid awareness and rural development.
- Awarded **Young Blood**, Nehru Hall of Residence (2017–18).
- Gold Medalist (2013) and Silver Medalist (2012), Regional High School Basketball Championships.