

Analytical Formulation for Gravitational Wave Event Rates

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1 Overview

This document presents the analytical framework for calculating gravitational-wave (GW) event rates from compact-binary coalescences (CBCs), encompassing binary black holes (BBH), binary neutron stars (BNS), and neutron star–black hole binaries (NSBH). The formulation combines cosmic merger-rate densities with detector sensitivity and selection effects to predict annual detection rates. Practical implementations using the `1er` package are referenced throughout.

2 Introduction

The annual rate of detectable (unlensed) GW events, $\Delta N_{\text{U}}^{\text{obs}}/\Delta t$, represents the expected number of observed CBC mergers per year for a given detector network. It is obtained by combining the total intrinsic merger rate in the detector frame, $\Delta N_{\text{U}}/\Delta t$, with the population-averaged probability of detection $P(\text{obs})$:

$$\frac{\Delta N_{\text{U}}^{\text{obs}}}{\Delta t} = \frac{\Delta N_{\text{U}}}{\Delta t} \times P(\text{obs}). \quad (1)$$

3 Parameter-Marginalized Event Rate

Let the full parameter vector be $\vec{\theta} = \{\vec{\theta}_{\text{int}}, \vec{\theta}_{\text{ext}}\}$, where intrinsic parameters describe the source-frame properties of the binary, and extrinsic parameters describe its configuration relative to the detector network. Explicitly,

$$\vec{\theta} = \{z_s, m_1, m_2, a_1, a_2, \theta_1, \theta_2, \phi_{12}, \phi_{JL}, \iota, \phi, \psi, \text{RA}, \text{Dec}, t_c\}. \quad (2)$$

Given a joint prior $P(\vec{\theta})$ and conditional detection probability $P(\text{obs} \mid \vec{\theta})$, the population-averaged detection probability is

$$P(\text{obs}) = \int P(\text{obs} \mid \vec{\theta}) P(\vec{\theta}) d\vec{\theta}. \quad (3)$$

The detectable event rate therefore becomes

$$\frac{\Delta N_{\text{U}}^{\text{obs}}}{\Delta t} = \frac{\Delta N_{\text{U}}}{\Delta t} \int P(\text{obs} \mid \vec{\theta}) P(\vec{\theta}) d\vec{\theta}. \quad (4)$$

4 Redshift Distribution and Intrinsic Merger Rates

The `1er` framework parameterizes source distance using redshift z_s and assumes z_s is statistically independent of other source parameters. The redshift probability density is proportional to the detector-frame merger-rate density and the comoving volume element:

$$\begin{aligned} P(z_s) &\propto \frac{d^2 N}{dt dV_c} \frac{dV_c}{dz_s} \\ &\propto \frac{d^2 N}{d\tau dV_c} \frac{d\tau dV_c}{dt dz_s} \\ &\propto \frac{R_{\text{U}}(z_s) dV_c}{1 + z_s dz_s}. \end{aligned} \quad (5)$$

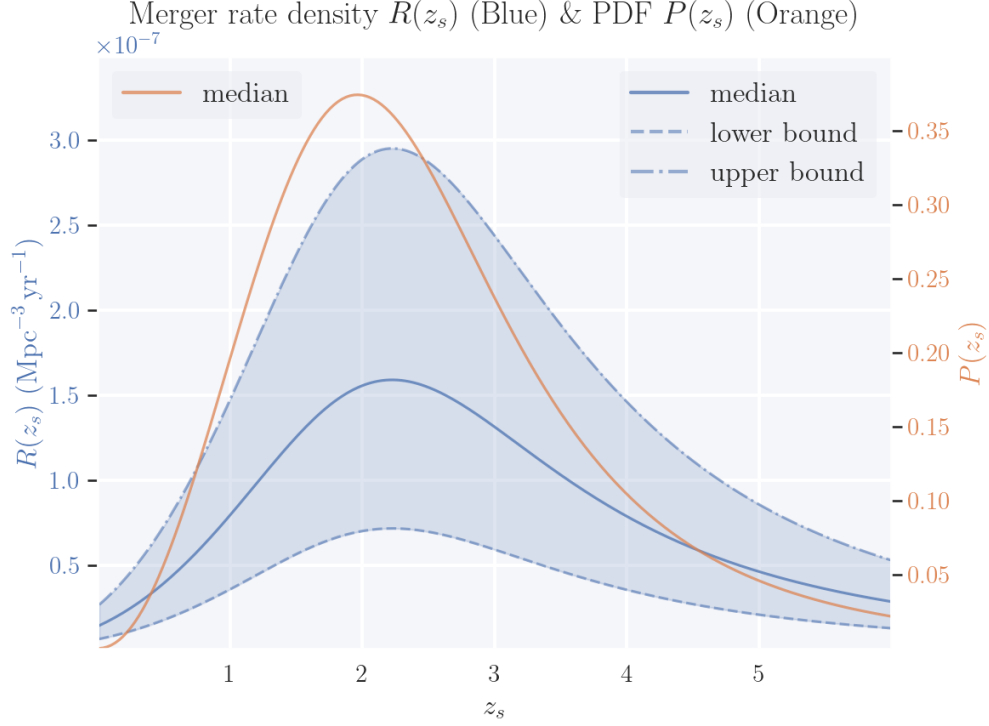


Figure 1: Redshift evolution of the merger-rate density $R(z_s)$ (left axis) and normalized redshift probability density $P(z_s)$ (right axis) for BBH mergers. The model follows a Madau–Dickinson–like prescription including metallicity and time-delay effects.

Here $R_U(z_s)$ is the source-frame merger-rate density per comoving volume, and the factor $(1 + z_s)^{-1}$ accounts for cosmological time dilation.

Normalizing the distribution introduces \mathcal{N}_U , the total intrinsic merger rate per detector-frame year:

$$P(z_s) = \frac{1}{\mathcal{N}_U} \frac{R_U(z_s)}{1 + z_s} \frac{dV_c}{dz_s}, \quad (6)$$

with

$$\mathcal{N}_U = \int_{z_{\min}}^{z_{\max}} \frac{R_U(z_s)}{1 + z_s} \frac{dV_c}{dz_s} dz_s. \quad (7)$$

The observed event rate can therefore be written compactly as

$$\frac{\Delta N_U^{\text{obs}}}{\Delta t} = \mathcal{N}_U \left\langle P(\text{obs} \mid \vec{\theta}) \right\rangle_{\vec{\theta} \sim P(\vec{\theta})}. \quad (8)$$

5 Detection Criterion and SNR Modeling

The conditional detection probability is defined through an SNR threshold ρ_{th} :

$$P(\text{obs} \mid \vec{\theta}) \equiv P_{\text{det}}(\vec{\theta}, \rho_{\text{th}}) = \Theta \left[\rho_{\text{obs}}(\vec{\theta}) - \rho_{\text{th}} \right], \quad (9)$$

where Θ is the Heaviside step function.

In practice, the observed SNR ρ_{obs} is treated as a stochastic variable derived from the optimal SNR ρ_{opt} . The `1er` and `gwsnr` packages adopt a non-central chi-squared model by default, following modern population-analysis practice.

Remark. The detection-probability formalism is generic and applies to any signal characterized by an SNR-like detection statistic, including electromagnetic transients.

6 Simulation Results

All results shown below are generated using the default configuration of the `1er` package.

6.1 Simulation Settings

A flat Λ CDM cosmology is assumed with $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$, $\Omega_m = 0.3$, and $\Omega_\Lambda = 0.7$.

Waveforms are generated using the IMRPhenomXPHM approximant with a sampling frequency of 2048 Hz. The detection threshold is $\rho_{\text{th}} = 10$, and a 100% duty cycle is assumed.

6.2 GW Source Parameter Priors

Table 1: Prior distributions for GW source parameters.

Parameter	Unit	Prior	Range	Description
z_s	–	Derived	$[0, 10]$	Source redshift
$m_{1,2}$	M_\odot	PowerLaw+Peak / Bimodal	see text	Component masses
$a_{1,2}$	–	Uniform	$[0, 0.99]$	Spin magnitudes
$\theta_{1,2}$	rad	Sine	$[0, \pi]$	Spin tilt angles
RA	rad	Uniform	$[0, 2\pi]$	Right ascension
Dec	rad	Cosine	$[-\pi/2, \pi/2]$	Declination
ι	rad	Sine	$[0, \pi]$	Inclination
ψ	rad	Uniform	$[0, \pi]$	Polarization angle

6.3 Detectable vs Intrinsic Populations

6.4 Rate Estimates

Detector Network	BBH yr^{-1}	BNS yr^{-1}	BBH:BNS
L1–H1–V1 (O4)	292.7	7.4	39.5
CE–ET (3G)	8.87×10^4	1.49×10^5	0.6

Note. O4 rates assume design sensitivity and a 100% duty cycle and should be regarded as optimistic upper limits.

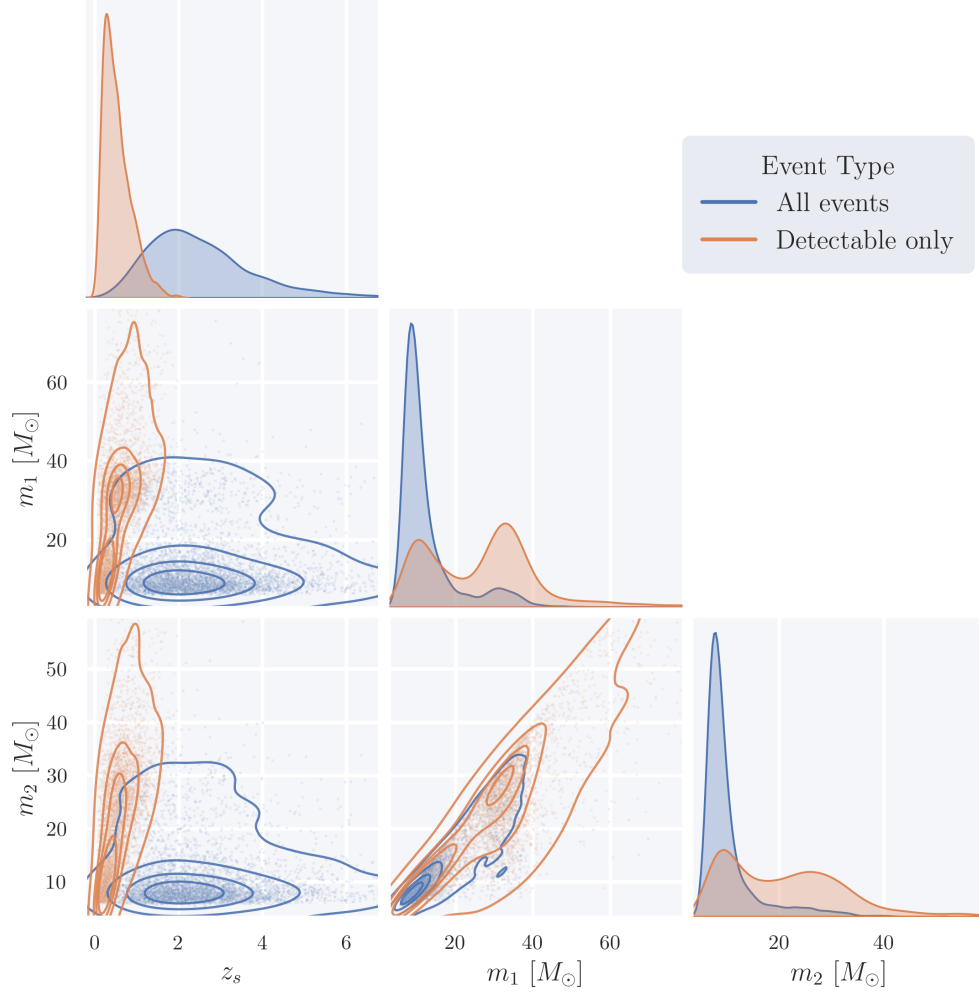


Figure 2: Corner plot comparing intrinsic (blue) and detectable (orange) BBH populations for the LIGO–Virgo–KAGRA O4 network. Detectable events are biased toward lower redshift and higher masses.