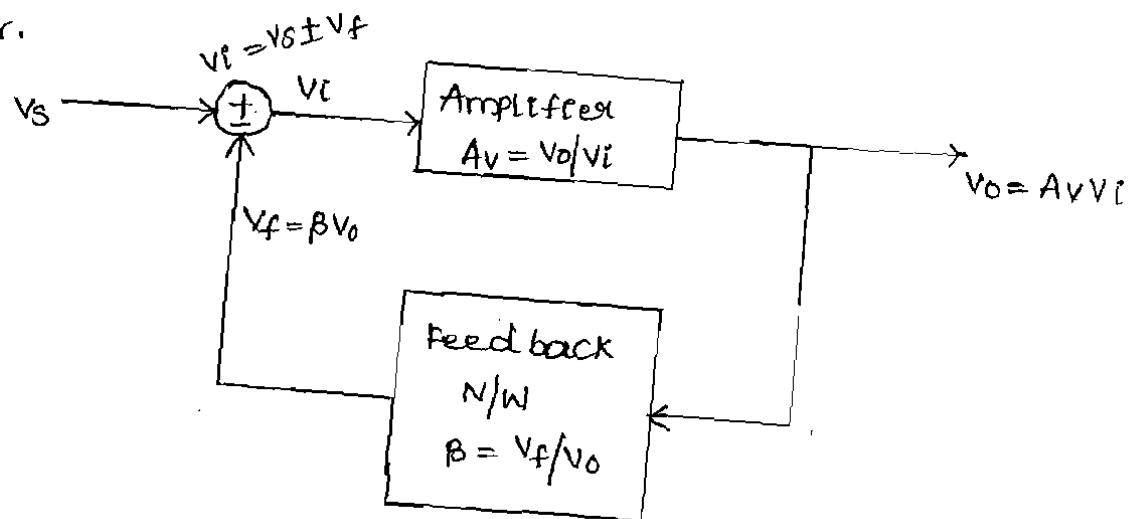


## UNIT - III

# FEED BACK AMPLIFIERS

### Introduction:-

A feedback amplifier is a circuit in which the output signal is sampled and fed back to the input. The block diagram of a feedback amplifier is shown in fig 1. It consists of a basic amplifier (or having a voltage gain ' $A_v$ ' and a feedback network. The gain of the gain of the feedback network is ' $B$ ' which is also known as feedback factor.



Amplifier:- An electronic circuit which increases the strength (voltage, power, current) of the gain input signal.

feedback:- A portion of sampled output signal is provided as an input as feedback.

The network which is used for feedback is known as feedback network.

## Types of feedback!-

1. Positive feedback.
2. Negative feedback

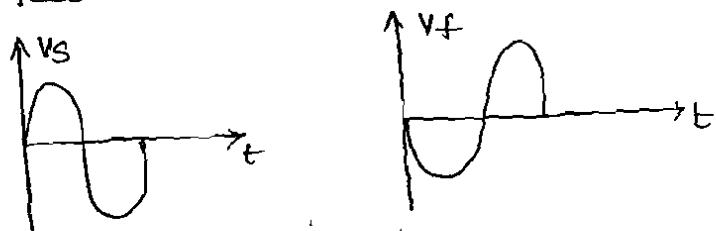
### 1. Positive feedback!-

If the feedback signal is in phase with the source signal then the feedback is known as positive feedback.  
i.e.,  $V_f = V_s + V_f$



### 2. Negative feedback!-

If the feedback signal is out of phase with the source signal then the feedback (signal) is negative feedback i.e.  $V_f = V_s - V_f$



## Gain of feedback Amplifier!-

The gain of feedback amplifier is given as

$$A_{vf} = \frac{V_o}{V_s}$$

The input voltage to the amplifier with feedback is given as

$$V_i = V_s \pm V_f$$

$$V_s = V_i \mp V_f$$

$$\Rightarrow V_s = V_i \mp \beta V_o$$

$$\Rightarrow V_s = V_i \mp \beta A V_i$$

$$\Rightarrow V_s = V_i [1 \mp \beta A]$$

$$\frac{V_S}{V_I} = 1 + \beta A_V$$

From ① we have

$$\begin{aligned} A_{Vf} &= \frac{V_O}{V_S} = \frac{V_O}{V_I} \times \frac{V_I}{V_S} \\ &= A_V \cdot \frac{V_I}{V_S} \end{aligned}$$

From ②

$$\Rightarrow A_{Vf} = \frac{A_V}{1 + \beta A_V}$$

For +ve feedback,  $A_{Vf} = \frac{A_V}{1 - \beta A_V}$

For -ve feedback,  $A_{Vf} = \frac{A_V}{1 + \beta A_V}$

Note:-

1. Negative feedback is used for amplifiers
2. Positive feedback is used for oscillators.

### CHARACTERISTICS OF NEGATIVE FEEDBACK

(OR)

### ADVANTAGE OF NEGATIVE FEEDBACK OVER POSITIVE FEEDBACK

1. Increase stability

The expression for voltage gain with feedback is given as

$$A_{Vf} = \frac{A_V}{1 + \beta A_V}$$

as  $\beta A_V \gg 1$

$$\Rightarrow A_{Vf} = \frac{A_V}{\beta A_V} \Rightarrow A_{Vf} = \frac{1}{\beta}$$

## 2. Desensitivity of Transfer gain

The fractional change of transfer gain with divided by fractional change of transfer gain without feedback is known as sensitivity of transfer gain

$$S = \frac{\left| \frac{dA_{Vf}}{A_{Vf}} \right|}{\left| \frac{dAv}{Av} \right|}$$

We know that  $A_{Vf} = \frac{Av}{1 + \beta Av}$

Differentiate w.r.t  $Av$ .

$$\Rightarrow \frac{d}{dAv}(A_{Vf}) = \frac{(1 + \beta Av)(1) - Av(\beta Av)}{(1 + \beta Av)^2} = \frac{1 + \beta Av - \beta Av}{(1 + \beta Av)^2}$$

$$\Rightarrow \frac{dA_{Vf}}{dAv} = \frac{1}{(1 + \beta Av)^2} \Rightarrow dA_{Vf} = \frac{dAv}{(1 + \beta Av)^2}$$

Dividing L.H.S & R.H.S by  $A_{Vf}$

$$\begin{aligned} \Rightarrow \frac{dA_{Vf}}{A_{Vf}} &= \frac{dAv}{Av(1 + \beta Av)^2} \\ &= \frac{dAv}{\left(\frac{Av}{1 + \beta Av}\right)(1 + \beta Av)^2} = \frac{dAv}{Av} \cdot \frac{1}{(1 + \beta Av)} \end{aligned}$$

$$\Rightarrow \frac{dA_{Vf}}{dAv} = \frac{dAv}{Av} \cdot \frac{1}{1 + \beta Av}$$

$$\Rightarrow S = \left| \frac{\frac{dA_{vf}}{A_{vf}}}{\frac{dA_v}{A_v}} \right| = \frac{1}{1 + BA_v}$$

Desensitivity is reciprocal of sensitivity

$$\Rightarrow D = \frac{1}{S} = 1 + BA_v$$

$$\therefore D = 1 + BA_v$$

### 3. Reduction in frequency distortion:-

We know that

$$A_{vf} = A_v \cdot \frac{1}{1 + BA_v} \Rightarrow A_{vf} = \frac{1}{\beta}$$

If the feedback network is made up of resistors but not with reactive elements like capacitor, Inductor  $A_{vf}$  is independent of frequency. So distortions due to frequency is reduced.

### 4. Reduction in noise:-

Let ' $N_f$ ' be the noise with feedback & ' $N$ ' be the noise without feedback then,

$$\therefore N_f = N \cdot \frac{1}{1 + BA_v}$$

$$\left( \because A_{vf} < A_v \text{ & } N_f < N_v \right)$$

### 5. Reduction in distortion

If ' $D_f$ ' is the distortion with feedback & ' $D$ ' is the distortion without feedback then,

$$D_f = D \cdot \frac{1}{1 + BA_v}$$

## 6. Increase in bandwidth :-

If  $B \cdot W_f$  is the band width with feedback and  $B \cdot W$  is the bandwidth without feedback then,

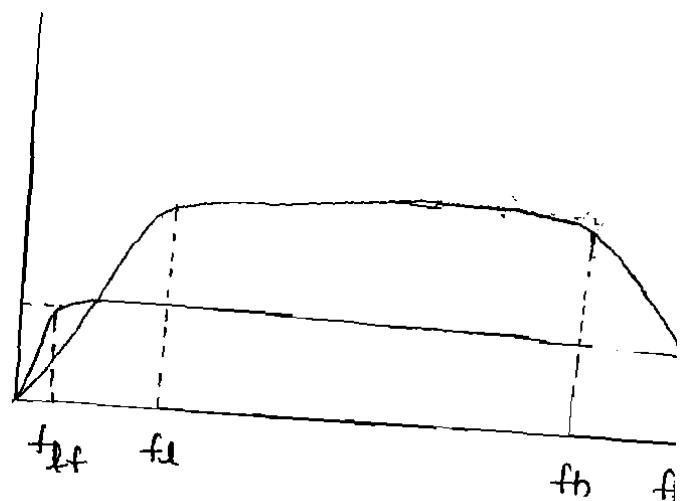
$$B \cdot W_f = B \cdot W (1 + B A_v)$$

$$\text{i.e } B \cdot W_f > B \cdot W$$

$$B \cdot W = f_h - f_l$$

$$B \cdot W_f = f_{hf} - f_{lf}$$

$$\therefore B \cdot W_f = f_{hf} - f_{lf}$$



## FEED BACK TOPOLOGIES:-

In feedback amplifiers, the output signal sampled may be either voltage (or) current and the sampled signal can be mixed either in series or in shunt with the input based on the type of sampled signal (can be mixed either) at the output side and the type of mixing at the input side the amplifiers are divided into four types. They are:

1. Voltage series feedback amplifier
2. Voltage shunt feedback amplifier.
3. Current series feedback amplifier
4. Current shunt feedback amplifier.

### Note:-

1. If the sampled output signal is Voltage irrespective of type of input mixing the output impedance decreases.
2. If the sampled output signal is current irrespective of type of i/p mixing the o/p impedance increases.

3. If the type of mixing in input is in series irrespective of the type of sampled output the input impedance increases.
4. If the type of mixing the input is in shunt then irrespective of type of sampled output the input impedance decreases.

### Voltage-series feedback Amplifier:-

If voltage is sampled and the mixing is in series then the type of feedback is known as voltage series. Since the voltage is sampled, the output parameter monitored i.e. voltage and since mixing at the input is series, the parameter that is affected is the input voltage.  $A_v$  is stabilised.

The feedback factor  $B$  is the ratio of output signal to the input signal of the feedback network which is equal to

$$B = \frac{V_f}{V_o}$$

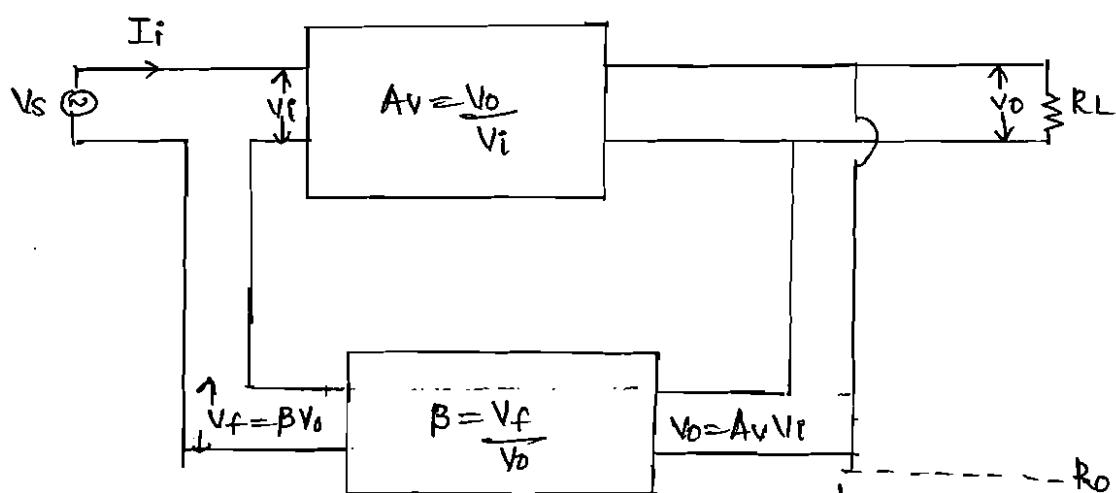
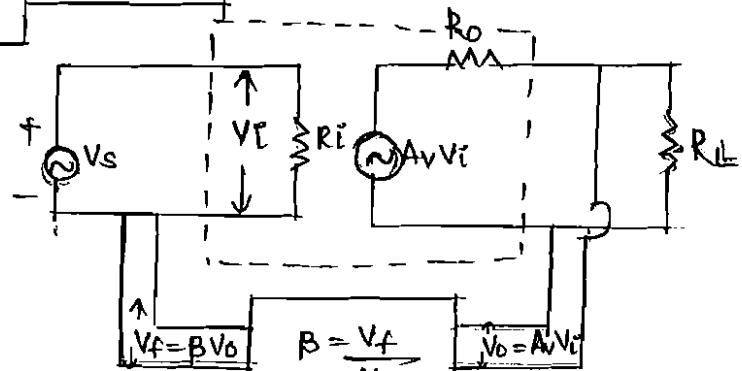


fig (a)



## Gain with feedback ( $A_{vf}$ ) :-

From the circuit we have,

$$V_F = V_S - V_f$$

$$V_S = V_i + V_f = V_i + \beta V_o = V_i + \beta (A_v \cdot V_i) = V_i (1 + \beta A_v)$$

$$\Rightarrow \frac{V_S}{V_i} = (1 + \beta A_v) \rightarrow \frac{V_F}{V_S} = \frac{1}{1 + \beta A_v}$$

$$A_{vf} = \frac{V_o}{V_S} = \frac{V_o}{V_i} \times \frac{V_i}{V_S} = A_v \frac{1}{1 + \beta A_v}$$

$$\therefore \boxed{A_{vf} = \frac{A_v}{1 + \beta A_v}}$$

## Input impedance with feedback ( $R_{if}$ ) :-

We have,

$$V_i = V_S - V_f \Rightarrow V_S = V_i + V_f \text{ & } R_{if} = \frac{V_S}{I_i} \quad R_i = \frac{V_i}{I_i}$$

$$R_{if} = \frac{V_S}{I_i} = \frac{V_i + V_f}{I_i} = \frac{V_i + \beta V_o}{I_i} = \frac{V_i + \beta (A_v V_i)}{I_i}$$

$$\Rightarrow R_{if} = \frac{V_i}{I_i} (1 + \beta A_v)$$

$$\Rightarrow \boxed{R_{if} = R_i (1 + \beta A_v)}$$
 [  $R_{if} \uparrow$   $\because$   $V_f$  is series ]

## Output impedance with feedback ( $R_{of}$ ) :-

Output impedance is obtained by making source to 'zero'. i.e  $V_S = 0$ .

$$\text{As, } V_F = V_S - V_f \Rightarrow V_f = V_S$$

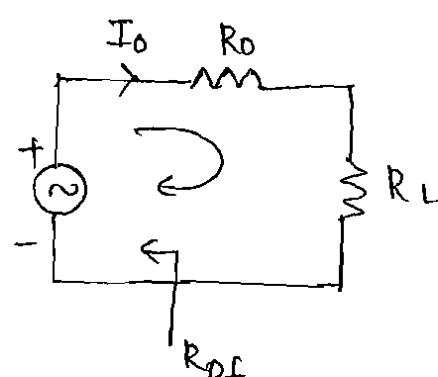
$$\Rightarrow V_F = -V_f \quad [\because V_S = 0]$$

Consider the o/p ckt  $\rightarrow$

From the ckt,

$$V_o = I_o R_o + A_v V_i$$

$$\Rightarrow V_o = I_o R_o + A_v (-V_f) = I_o R_o - A_v (\beta V_o) \Rightarrow I_o R_o = V_o + A_v (\beta V_o)$$



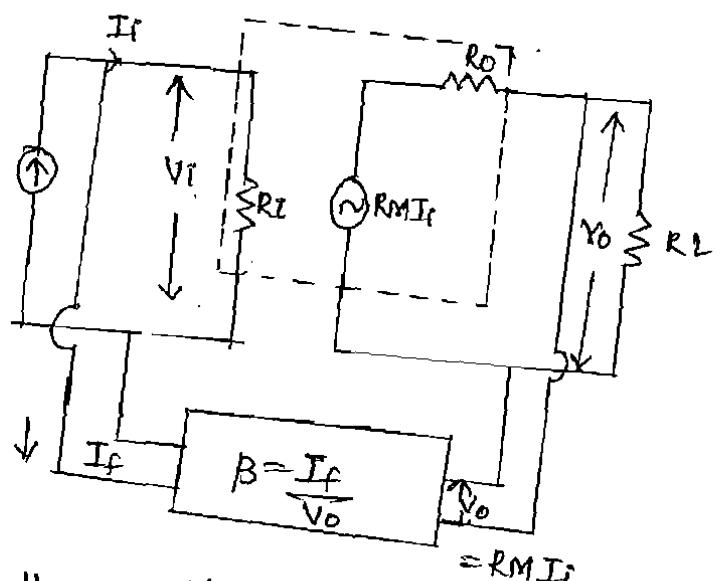
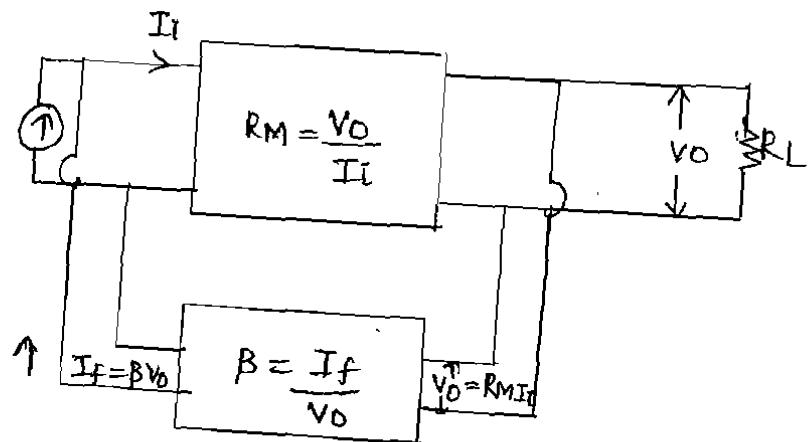
$$V_o(HBAv) = I_o R_o$$

$$\Rightarrow \frac{V_o}{I_o} = \frac{R_o}{1+BAv}$$

$$\Rightarrow R_{of} = \frac{R_o}{1+BAv}$$

### Voltage shunt feedback Amplifier:-

If voltage is sampled and the mixing is shunt  $I_s$  then the type of feedback is known as voltage shunt since the mixing at the input is shunt then the parameter that is affected is the input current. The parameter is that is stabilized in voltage shunt feedback is  $\frac{V_o}{I_i}$  which is known as transresistance denoted by ' $R_m$ '.



→ The feedback factor ' $B$ ' is the ratio of feedback current to the output voltage, that is

$$B = \frac{I_f}{V_o}$$

→ In this amplifier, with feedback the o/p resistance & t/p resistance decrease.

Transresistance without feedback  $R_M = \frac{V_o}{I_i}$

Transresistance with feedback  $R_{Mf} = \frac{V_o}{I_s}$

$\therefore$  From the circuit

$$\text{We have } I_i = I_s - I_f$$

$$\Rightarrow I_s = I_i + I_f$$

$$\Rightarrow I_s = I_i + \beta V_o = I_i + \beta (R_M I_i) = I_i (1 + \beta R_M)$$

$$\Rightarrow \frac{I_i}{I_s} = \frac{1}{1 + \beta R_M}$$

$$\therefore R_{Mf} = \frac{V_o}{I_s} = \frac{V_o}{I_i} \times \frac{I_i}{I_s} = R_M \cdot \frac{1}{1 + \beta R_M}$$

$$\boxed{R_{Mf} = \frac{R_M}{1 + \beta R_M}}$$

Input impedance:-

Input impedance without feedback e.g.  $R_i = \frac{V_i}{I_i}$

Input impedance with feedback e.g.  $R_{if} = \frac{V_i}{I_s}$

From the ckt we have,

$$I_i = I_s - I_f$$

$$\Rightarrow I_s = I_i + I_f = I_i + \beta V_o = I_i + \beta R_M I_i = I_i (1 + \beta R_M)$$

$$\Rightarrow R_{if} = \frac{V_i}{I_s} \Rightarrow \frac{I_s}{I_i} = 1 + \beta R_M \Rightarrow \frac{I_i}{I_s} = \frac{1}{1 + \beta R_M}$$

$$\text{As, } R_{if} = \frac{V_i}{I_s} = \frac{V_i}{I_i} \times \frac{I_i}{I_s} = R_i \cdot \frac{1}{1 + \beta R_M}$$

$$\therefore \boxed{R_{if} = \frac{R_i}{1 + \beta R_M}}$$

## Output impedance:-

To get o/p impedance make source to zero i.e.  $I_s = 0$

$$As, I_f = I_s - I_o \Rightarrow I_o = -I_f$$

considering the o/p ckt,  $\rightarrow$

Applying KVL,

$$V_o = R_o I_o + R_m I_f$$

$$= I_o R_o - R_m I_f$$

$$V_o = -I_o R_o - R_m B V_o$$

$$\Rightarrow V_o + R_m B V_o = I_o R_o \Rightarrow V_o (1 + R_m B) = I_o R_o \Rightarrow V_o = \frac{I_o R_o}{1 + R_m B}$$

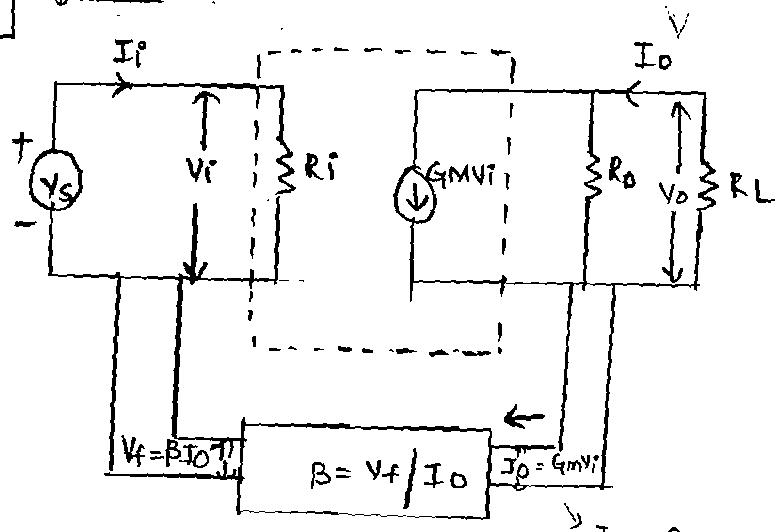
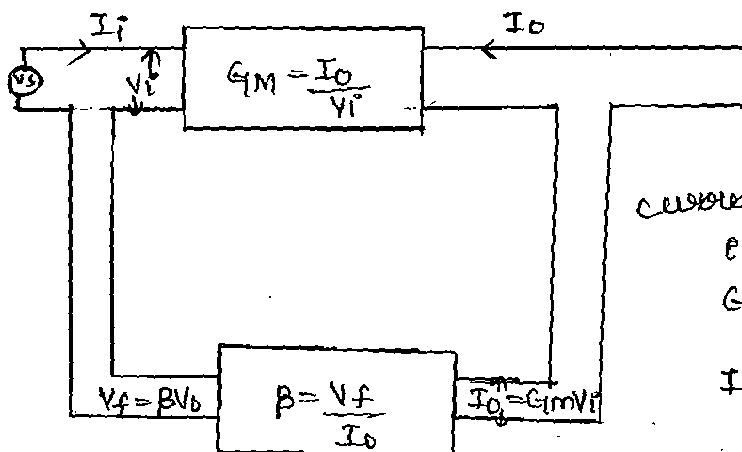
$$\Rightarrow \frac{V_o}{I_o} = \frac{R_o}{1 + R_m B}$$

$$\Rightarrow R_{of} = \frac{R_o}{1 + R_m B}$$

## Current series feed back amplifier:-

If current is sampled by the midring as FB series with the o/p then the type of FB feedback is known as current series. Since the current gain without feedback is  $G_m$  & gain with feedback is  $G_m(1 + B)$ . If feedback factor  $B = \frac{V_f}{V_i}$

In ckt, both o/p & r/p resistance increase



Transconductance without feedback  $G_M = \frac{I_o}{V_i}$

Transconductance with feedback  $G_{Mf} = \frac{I_o}{V_s}$

From the circuit

$$V_i = V_s - V_f$$

$$V_s = V_i + V_f = V_i + \beta I_o = V_i + \beta (G_M V_i) = V_i (1 + \beta G_M)$$

$$\Rightarrow \frac{V_s}{V_i} = 1 + \beta G_M \Rightarrow \frac{V_i}{V_s} = \frac{1}{1 + \beta G_M}$$

$$\therefore G_{Mf} = \frac{I_o}{V_s} = \frac{I_o}{V_i} \cdot \frac{V_i}{V_s} = G_M \cdot \frac{1}{1 + \beta G_M}$$

$$\therefore \boxed{G_{Mf} = \frac{G_M}{1 + \beta G_M}}$$

Input impedance :-

Input impedance without feedback  $R_P = \frac{V_i}{I_i}$

Input impedance with feedback  $R_{Pf} = \frac{V_s}{I_i}$

from the circuit

$$V_i = V_s - V_f$$

$$\Rightarrow V_s = V_i + V_f = V_i + \beta I_o = V_i + \beta (G_M V_i) = V_i (1 + \beta G_M)$$

$$\Rightarrow \frac{V_s}{V_i} = 1 + \beta G_M \Rightarrow \frac{V_i}{V_s} = \frac{1}{1 + \beta G_M}$$

$$\therefore R_{Pi} = \frac{V_i}{I_i} = \frac{V_i}{V_s} \cdot \frac{V_s}{I_i} = \frac{1}{1 + \beta G_M} \cdot R_{Pf}$$

$$\Rightarrow R_P = \frac{R_{Pf}}{1 + \beta G_M}$$

$$\Rightarrow \boxed{R_{Pf} = R_P (1 + \beta G_M)}$$

## Output impedance :-

To get the o/p impedance make source to zero i.e  $V_s = 0$

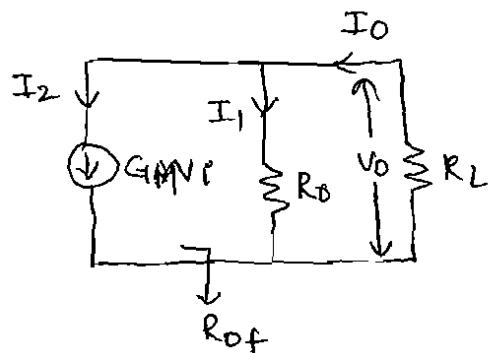
$$\Rightarrow V_P = V_s - V_f = -V_f$$

consider the o/p CKT,

Applying KCL,

$$I_O = I_1 + I_2$$

$$= \frac{V_O}{R_O} + G_M V_C = \frac{V_O}{R_O} - G_M V_f$$



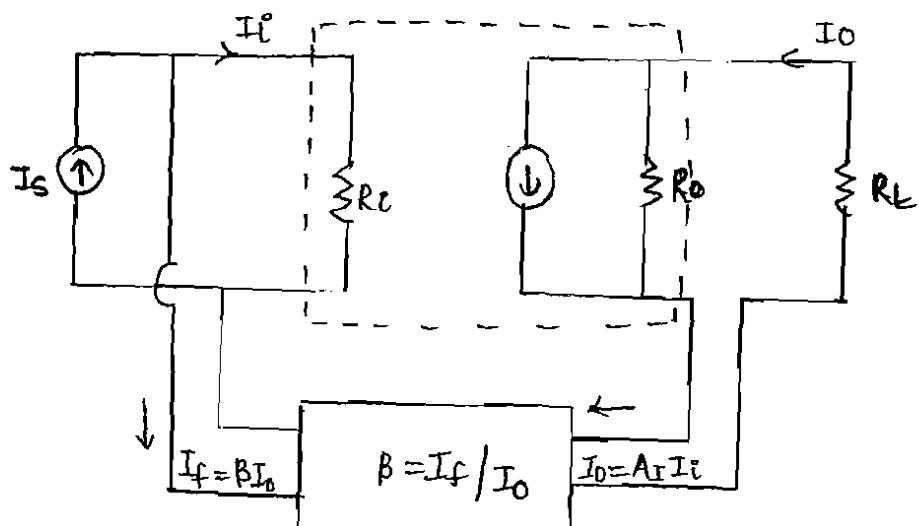
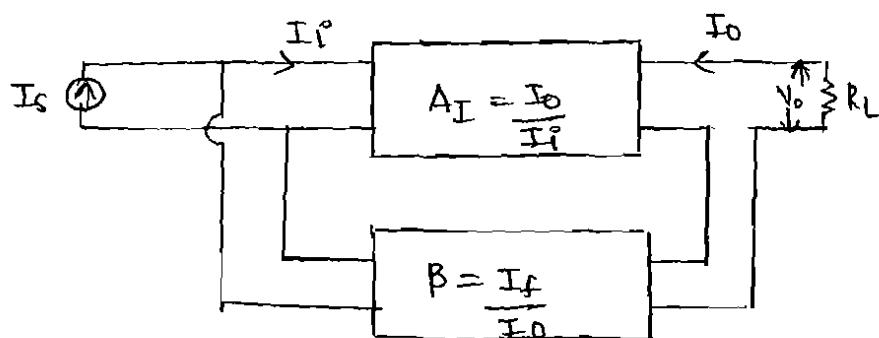
$$I_O = \frac{V_O}{R_O} - G_M \beta I_O$$

$$\Rightarrow I_O (1 + G_M \beta) = \frac{V_O}{R_O}$$

$$\Rightarrow \frac{V_O}{I_O} = R_O (1 + \beta G_M)$$

$$\Rightarrow R_{of} = R_O (1 + \beta G_M)$$

## current shunt feedback Amplifier -



### Current gain:-

current gain without feedback  $A_I = \frac{I_o}{I_i}$

current gain with feedback  $A_{If} = \frac{I_o}{I_s}$

From the CKE,

$$I_f = I_s - I_i$$

$$\Rightarrow I_s = I_i + I_f = I_i + \beta I_o = I_i + \beta(A_I I_f)$$

$$\Rightarrow I_s = I_i(1 + \beta A_I) \Rightarrow \frac{I_f}{I_s} = \frac{1}{1 + \beta A_I}$$

$$\Rightarrow A_{If} = \frac{I_o}{I_s} = \frac{I_o}{I_i} \cdot \frac{I_f}{I_s} = A_I \cdot \frac{1}{1 + \beta A_I}$$

$$\boxed{A_{If} = \frac{A_I}{1 + \beta A_I}}$$

### Input impedance:-

Input impedance without feedback  $R_P = \frac{V_i}{I_i}$

Input impedance with feedback  $R_{Pf} = \frac{V_i}{I_s}$

We have,

$$I_f = I_s - I_i$$

$$\Rightarrow I_s = I_i + I_f = I_i + \beta(A_I I_f) = I_i(1 + \beta A_I)$$

$$\Rightarrow \frac{I_s}{I_i} = 1 + \beta A_I \Rightarrow \frac{I_f}{I_s} = \frac{1}{1 + \beta A_I}$$

$$\therefore R_{Pf} = \frac{V_i}{I_s} = \frac{V_i}{I_i} \cdot \frac{I_i}{I_s} = \frac{R_P}{1 + \beta A_I}$$

$$\therefore R_{Pf} = \frac{R_P}{1 + \beta A_I}$$

### Output impedance:-

To get o/p impedance,

$$I_s = 0 \text{ As, } I_i = I_s - I_f = -I_f$$

considering B/P CKT:

Apply KCL,

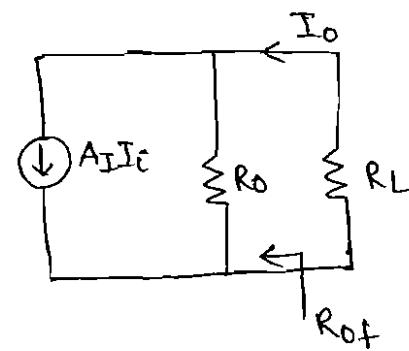
$$I_O = \frac{V_O}{R_O} + A_I I_F$$

$$= \frac{V_O}{R_O} + A_I (-I_F)$$

$$I_O = \frac{V_O}{R_O} - A_I \beta I_O \Rightarrow I_O + A_I \beta I_O = \frac{V_O}{R_O}$$

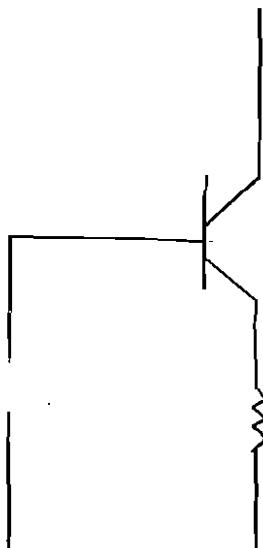
$$\Rightarrow I_O (1 + A_I \beta) = \frac{V_O}{R_O} \Rightarrow \frac{V_O}{I_O} = R_O (1 + \beta A_I)$$

$$\Rightarrow [R_{OF} = R_O (1 + \beta A_I)]$$



Practical CKT for voltage series feedback Amplifier

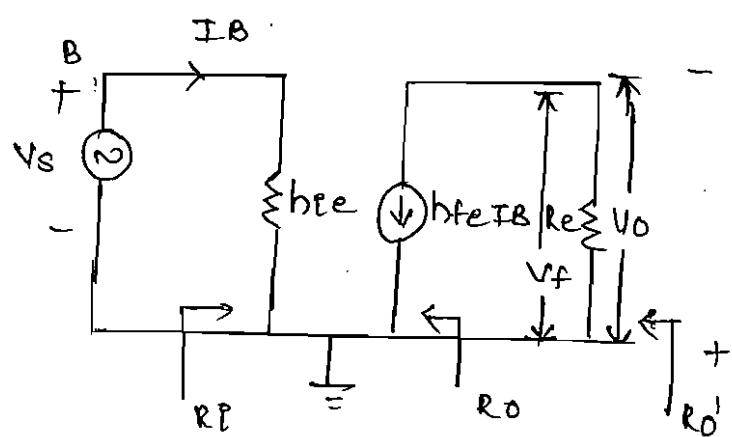
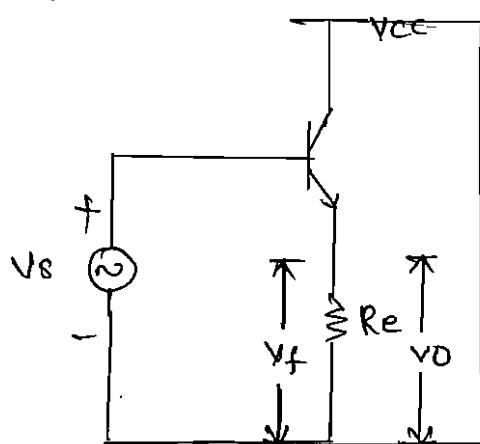
Emitter follower (cc Amplifier)





## Practical Ckt for Voltage series feedback amplifier

Emitter followed B/CCE Amplifier



As, the signal sampled at  $Re$  is voltage and the voltage drop across  $Re$  is provided as feedback and it gets subtracted with the source voltage  $V_s$ .

∴ Emitter follower acts as voltage series feedback amplifier.

$$\text{As, } V_o = V_f$$

$$\text{feedback factor, } \beta = \frac{V_f}{V_o} = \frac{V_o}{V_o} = 1$$

$$\Rightarrow \boxed{\beta = 1}$$

Voltage gain ( $A_V$ ) :-

$$A_V = \frac{V_o}{V_s} = \frac{I_c R_e}{I_B h_{FE}} = \frac{h_{FE} I_B R_e}{I_B h_{FE}} = \frac{h_{FE} R_e}{h_{FE}}$$

$$A_V = \frac{h_{FE} R_e}{h_{FE}}$$

INPUT impedance  $R_{in}$

$$R_{in} = h_{FE}$$

OUTPUT impedance  $R_{out}$ :

To get o/p impedance make source to zero

$$R_{in} = V_s = 0$$

If  $V_B = 0 \Rightarrow I_B = 0$

$$\Rightarrow R_O = \frac{V_O}{I_C} = \frac{V_O}{h_{FE} I_B} = \frac{V_O}{0} = \infty.$$

$R_O$ :

$$R_O = \infty$$

$$R_d = R_O // R_e = \frac{R_O R_e}{R_O + R_e} = R_e \quad \left[ \begin{array}{l} \because R_O = \infty \\ \therefore R_O \gg R_e \end{array} \right]$$

\* Voltage gain with feedback ( $A_{VF}$ ):-

$$A_{VF} = \frac{A_v}{1 + B A_v} = \frac{A_v}{1 + A_v} \quad \left[ \because B = 1 \right]$$

$$A_{VF} = \frac{h_{FE} R_e}{\frac{h_{FE}}{1 + \frac{h_{FE} R_e}{h_{CE}}}} = \frac{h_{FE} R_e}{h_{CE} + h_{FE} R_e}$$

$$\Rightarrow A_{VF} = \frac{h_{FE} R_e}{h_{CE} + h_{FE} R_e}$$

\* Input impedance with feedback ( $R_{IF}$ ):-

$$R_{IF} = R_C (1 + B A_v) = R_P (1 + A_v) = h_{CE} \left( 1 + \frac{h_{FE} R_e}{h_{CE}} \right)$$

$$R_{IF} = h_{CE} + h_{FE} R_e$$

\* Output impedance with feedback ( $R_{OF}$  &  $R_{OF}'$ ):-

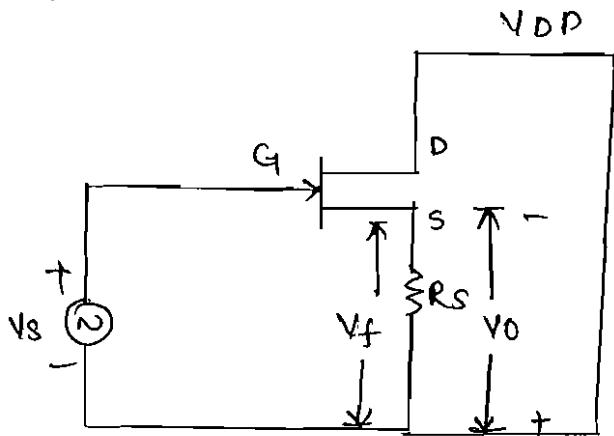
$$R_{OF} = \frac{R_O}{1 + B A_v} = \frac{R_O}{1 + A_v} = \frac{\infty}{1 + A_v} = \infty.$$

$$R_{OF} = \infty$$

$$R_{\text{of}}' = \frac{R_o'}{1 + \beta A_v} = \frac{R_e}{1 + \beta A_v} = \frac{R_e}{1 + h_{fe} R_e} = \frac{h_{fe} R_e}{h_{fe} + R_e}$$

$$R_{\text{of}}' = \frac{h_{fe} R_e}{h_{fe} + R_e}$$

\* Source Amplifier

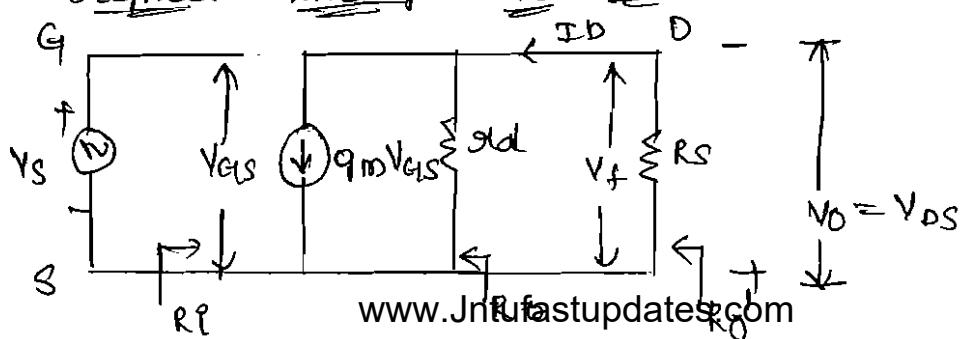


As, the output voltage and feedback voltage are calculated across  $R_s$   
 signal  $\therefore V_f = V_0$  and the feedback signal  
 gets subtracted with the source signal.  
 $\therefore$  source follower acts as voltage source  
 feedback amplifier

$$\text{Amplification factor } \beta = \frac{V_f}{V_0} = \frac{V_0}{V_0} = 1$$

$$\therefore \boxed{\beta = 1}$$

small signal analysis for FET :-



Voltage gain  $A_v = \frac{V_{DS}}{V_{GS}}$

$$A_v = \frac{V_D}{V_S} = \frac{V_{DS}}{V_{GS}}$$

considering the o/p cat  $q_m V_{GS}$

$$V_{DS} = I_d \times R_D$$

$$\therefore A_v = \frac{I_d R_D}{V_{GS}}$$

$$\Rightarrow A_v = \frac{q_m V_{GS} R_D}{V_{GS}}$$

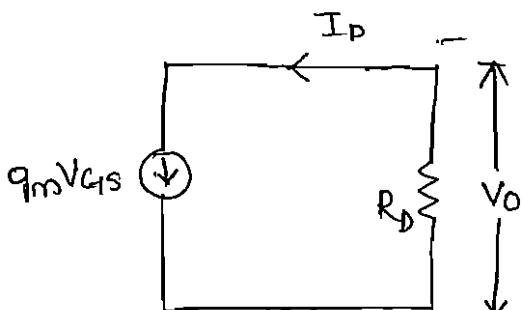
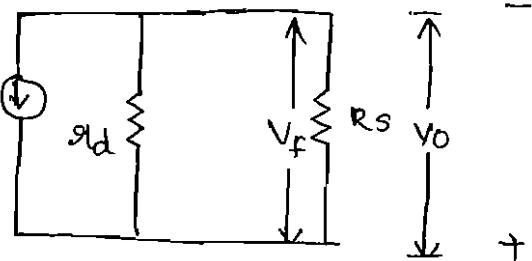
$$\Rightarrow A_v = q_m R_D$$

Substitute value of  $R_D$

$$A_v = \frac{q_m s_d R_S}{s_d + R_S}$$

$$R_D = \frac{s_d R_S}{s_d + R_S}$$

$$A_v = \frac{s_d R_S}{R_S + s_d}, \text{ where, } s_d = q_m s_d$$



\* Input impedance ( $R_I$ ) :-

As the input current of fet is 0 so the input impedance  $R_I = \infty$ .

\* Output impedance ( $R_O$ ) :-

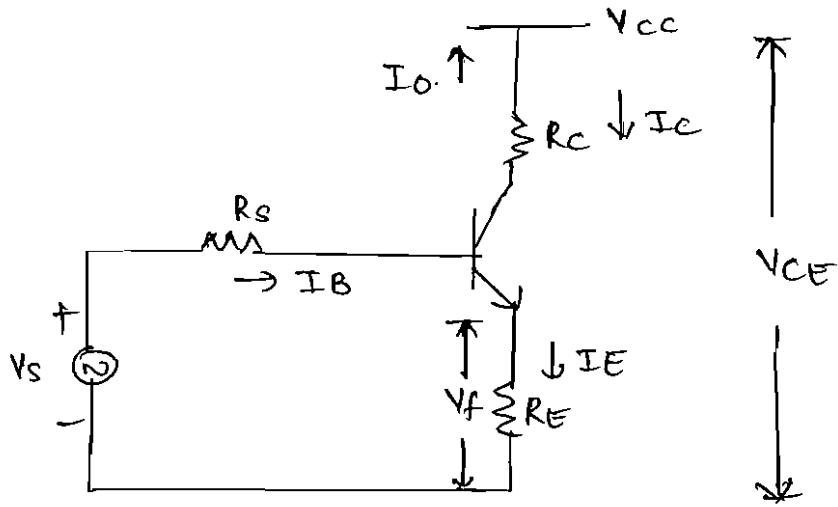
$$R_O = s_d$$

$$R_O' = R_O // R_S = \frac{R_O R_S}{R_O + R_S} = \frac{s_d R_S}{s_d + R_S}$$

$$\boxed{R_{\text{of}}' = \frac{\alpha R_s}{\alpha + 1 + \beta}}$$

current - series feedback amplifier

CE - Amplifier with unbypassed emitter resistor



the feedback voltage is provided across  $R_E$

$$V_f = I_E R_E = (I_B + I_C) R_E$$

$$\Rightarrow I_E = I_B + I_C$$

$$I_C \gg I_B \quad \therefore V_E = I_C$$

$$\therefore \boxed{V_f = I_C R_E}$$

$$\Rightarrow V_f = -I_O R_E$$

As, the feedback voltage is related to o/p current the output signal sampled. As current across the drop across ' $R_E$ ' gets subtracted with source voltage  $V_s$ . Hence, the mixing is en series. Hence common emitter amplifier with unbypassed emitter resistor acts as current series feed back amplifier

Voltage gain with feedback ( $A_{vf}$ )

$$A_{vf} = \frac{A_v}{1 + \beta A_v} = \frac{\mu R_s}{R_s + R_d}$$

$$\frac{1 + \mu R_s}{R_s + R_d}$$

$$A_{vf} = \frac{\mu R_s}{R_s + R_d + \mu R_s}$$

$$\Rightarrow A_{vf} = \frac{\mu R_s}{R_d + R_s [1 + \mu]}$$

\* Input impedance with feedback ( $R_{if}$ ) :-

$$R_{if} = R_i \cdot (1 + \beta A_v)$$

$$= \infty (1 + \beta A_v) = \infty$$

$$\Rightarrow R_{if} = \infty$$

\* Output impedance with feedback ( $R_{of}$ ) :-

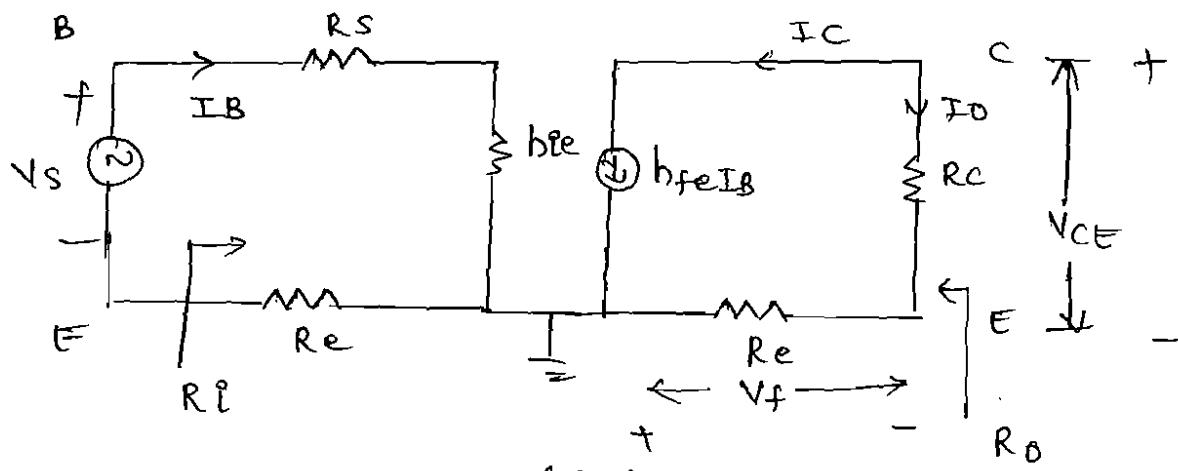
$$R_{of} = \frac{R_o}{1 + \beta A_v} = \frac{\mu d}{1 + \frac{\mu R_s}{\mu d + R_s}}$$

$$R_{of} = \frac{\mu d (\mu d + R_s)}{\mu d + R_s [1 + \mu]}$$

$$R_{of}' = \frac{R_o'}{1 + \beta A_v} = \frac{\mu d R_s}{\mu d + R_s}$$

$$\frac{1 + \frac{\mu R_s}{\mu d + R_s}}{\mu d + R_s}$$

## Practical circuit :-



\* Trans conductance ( $G_m$ ) :-

$$G_m = \frac{I_o}{V_s} = -\frac{I_c}{V_s} = -\frac{h_{fe} I_b}{I_b [R_b + h_{ie} + R_e]}$$

$$\Rightarrow G_m = \frac{-h_{fe}}{R_b + h_{ie} + R_e}$$

\* Input impedance ( $R_i$ ) :-

$$R_i = \frac{V_s}{I_b} = \frac{I_b [R_b + h_{ie} + R_e]}{I_b} = R_b + h_{ie} + R_e$$

$$\frac{B}{V_o} = \frac{V_f}{I_o} = \frac{-I_o R_e}{I_o} = -R_e$$

$$\Rightarrow \boxed{B = -R_e}$$

$$\Rightarrow \boxed{R_i = R_b + h_{ie} + R_e}$$

\* Output impedance ( $R_o$ ) :-

To get  $R_o$ , make source to zero i.e.  $V_s = 0$ .

$$I_f = V_s = 0 \Rightarrow I_b = 0 \Rightarrow h_{fe} I_b = 0 \Rightarrow I_c = 0$$

As the o/p current is zero, output impedance is infinity.

$$\therefore \boxed{R_o = \infty}$$

\* Trans conductance with feedback

$$G_{Mf} = \frac{G_m}{1 + \beta G_m}$$

$$= \frac{-h_{fe}}{R_s + h_{fe} + R_e}$$

If  $R_e \ll h_{fe}$

$$\approx \frac{-h_{fe}}{R_s + h_{fe}}$$

$$G_{Mf} = \frac{-h_{fe}}{R_s + R_e \{ h_{fe} + h_{fe} \}}$$

\* Input impedance ( $R_{if}$ )

$$R_{if} = R_e (1 + \beta G_M)$$

$$= (R_s + h_{fe} + R_e) \left[ 1 + \frac{(1 + \beta R_e)(-h_{fe})}{R_s + h_{fe} + R_e} \right]$$

$$= R_s + h_{fe} + R_e + R_e + R_e h_{fe}$$

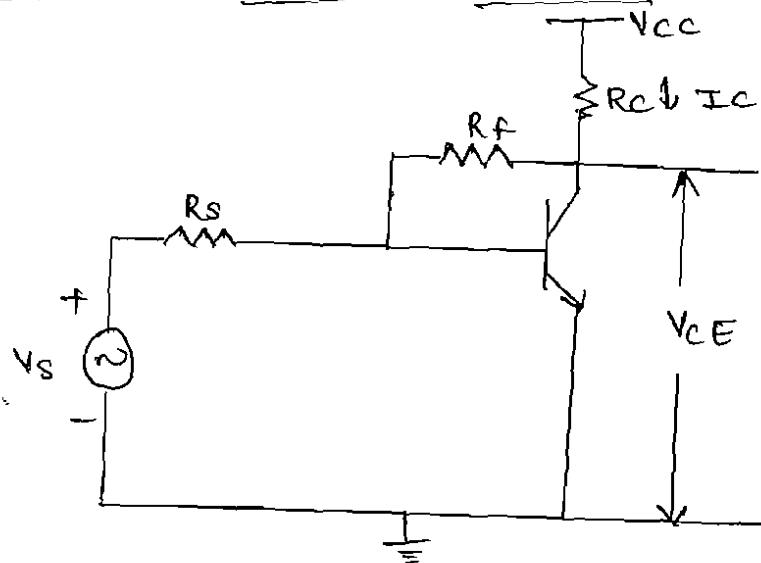
$R_{if} = R_s + h_{fe} + R_e [1 + h_{fe}]$

Output impedance with feedback ( $R_{of}$ )

$$R_{of} = R_o (1 + \beta G_M)$$

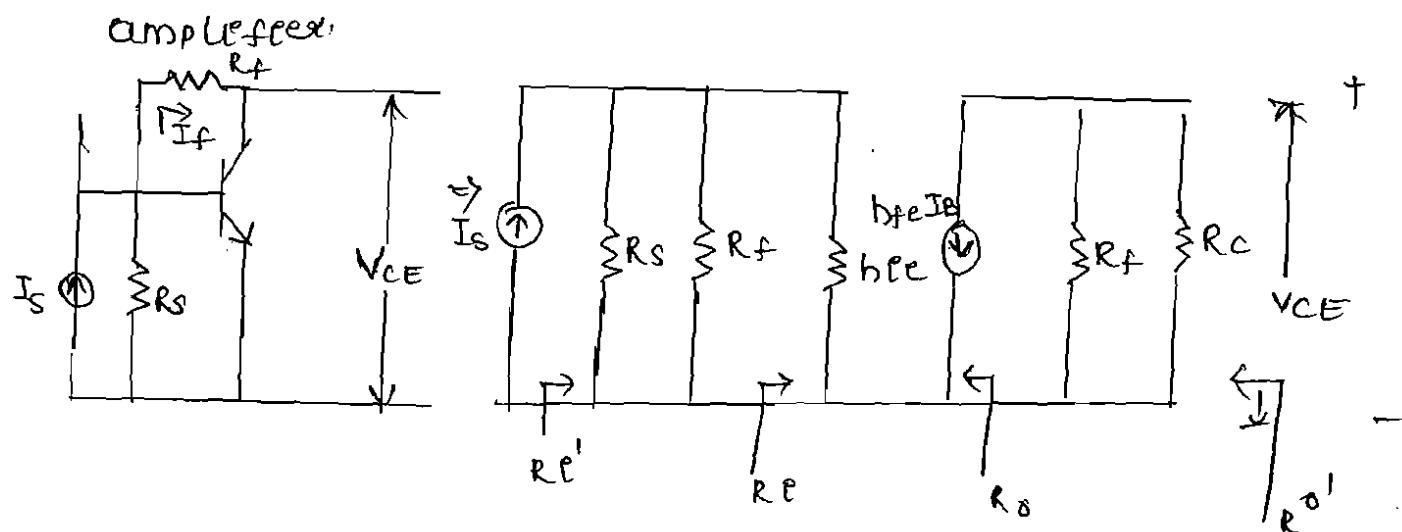
$$\Rightarrow R_{of} = \infty$$

## Voltage short feedback Amplifier.



As  $I_f = 0$  when  $V_{CE} = 0$  and the max. current at the input is  $I_C = I_S - I_f$

1. The CRT acts as voltage short feedback amplifier:



Without feedback:-

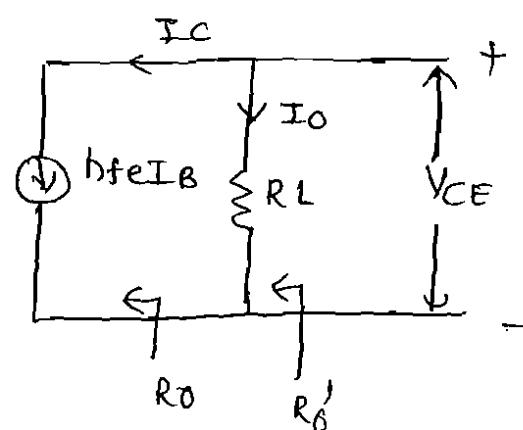
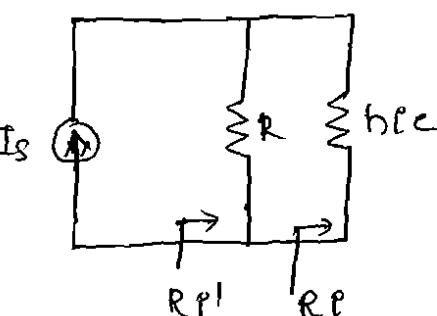
INPUT impedance:-

$$R_p = \frac{V_o}{I_p}$$

$$R_p = h_{fe}/g$$

$$R = \frac{R_s R_f}{R_s + R_f}$$

$$R_p = R_s R_f / (R_s + R_f)$$



$$R_{\text{f}}' = R \parallel R_{\text{f}}^{\text{c}}$$

$$= R \parallel h_{\text{fe}}$$

$$R_{\text{f}}' = \frac{R h_{\text{fe}}}{R + h_{\text{fe}}}$$

where  $R = \frac{R_{\text{f}} R_{\text{f}}^{\text{c}}}{R_{\text{f}} + R_{\text{f}}^{\text{c}}}$

\* Transistor resistance ( $R_M$ ) :-

$$R_M = \frac{V_O}{I_E} = \frac{V_{CE}}{I_S} = \frac{I_{O\text{RL}}}{I_B} = \frac{-h_{\text{fe}} I_{O\text{RL}}}{I_B}$$

$$\therefore R_M = -h_{\text{fe}} R_L$$

$$\left. \begin{aligned} &\because I_O = -I_C \\ &\text{& } I_C = -h_{\text{fe}} I_B \end{aligned} \right]$$

\* Output impedance ( $R_o$  &  $R_o'$ )

To get o/p impedance make source zero

i.e.  $I_B = 0 \Rightarrow I_R = 0 \Rightarrow h_{\text{fe}} I_B = 0 \Rightarrow I_C = 0$ .

$$\therefore R_o = \infty$$

$$R_o' = R_o \parallel R_L = R_L \quad [ \because R_o \gg R_L ]$$

where,  $R_L = \frac{R_f R_c}{R_f + R_c}$

\* Transistor resistance with feedback :-

$$R_{Mf} = \frac{R_M}{1 + B R_M}$$

where,  $I_f = \frac{V_{ED} - V_{CE}}{R_f} = \frac{-V_{CE}}{R_f}$

$$B = \frac{I_f}{V_O} = \frac{-V_{CE}}{R_f \times V_O} = -\frac{1}{R_f}$$

$$R_{Mf} = \frac{-h_{feRL}}{1 - \frac{1}{R_f} [-h_{feRL}]} = \frac{-h_{feRL} R_f}{R_f + h_{feRL}}$$

$$\Rightarrow \boxed{R_{Mf} = \frac{-h_{feRL} R_f}{R_f + h_{feRL}}}$$

\* Input impedance ( $R_{ref}$ ) with feedback

$$R_{ref} = \frac{R_p}{1 + \beta R_M} = \frac{h_{ee}}{1 + \frac{1}{R_f} (h_{feLL})} = \frac{h_{ee} R_f}{R_f + h_{feLL}}$$

$$R_{ref}' = \frac{R_p'}{1 + \beta R_M} = \frac{\frac{R_p h_{ee}}{R + h_{ee}}}{1 + \frac{h_{feRL}}{R_f}}$$

$$= \frac{R_p h_{ee}}{R + h_{ee}} \frac{1}{\frac{R_f + h_{feRL}}{R_f}}$$

$$\Rightarrow R_{ref}' = \frac{R_p R_f h_{ee}}{(R + h_{ee})(R_f + h_{feRL})}$$

\* Output impedance with feedback

$$R_{of} = \frac{R_o}{1 + \beta R_M} = \infty$$

$$R_{of}' = \frac{R_o'}{1 + \beta R_M} = \frac{\frac{R_L}{1 + h_{feRL}}}{R_f} = \frac{R_L R_f}{R_f + h_{feRL}}$$

$$\Rightarrow \boxed{R_{of}' = \frac{R_f R_L}{R_f + h_{feRL}}}$$



## FEED BACK AMPLIFIERS

- i. If an input of 0.028V peak to peak given to an open loop amplifier it gives fundamental frequency output of 36V peak to peak, but it is associated with 7% distortion.
- ii. If the distortion is to be reduced to 1%, how much feed back is to be introduced and what will be required input voltage?
- iii. If 1.2% of output is feed back and the input is maintained at the same level, what is the output voltage?

Sol

Given;  $V_i = 0.028V$

$V_o = 36V$

Voltage gain of amplifier is  $A_v = \frac{V_o}{V_i}$

$$\begin{aligned} &= \frac{36}{0.028} \\ &= 1285.7. \end{aligned}$$

i. Distortion without feed back = 7%

Distortion with feedback  $\frac{1.2\%}{1285.7} = 0.001$

$A_v = 1285.7.$

$$A_v = \frac{V_o}{V_{in}}$$

$$V_{in} = \frac{V_o}{A_v}$$

$$V_{in} = \frac{36}{183.67}$$

$$\boxed{V_{in} = 0.19 V.}$$

coherece  $A_{vf} = \frac{Av}{1+\beta Av}$

$$= \frac{1285.7}{1+\beta[1285.7]} \Rightarrow \frac{1285.7}{(1+0.04)(1285.7)} \Rightarrow 183.67.$$

To find  $\beta$  ;

$$D_f = \frac{D}{1+\beta Av} \Leftrightarrow$$

$$\beta = \left[ \frac{D}{D_f} - 1 \right] \cdot \frac{1}{Av}$$

$$= \left[ \frac{0.07}{0.01} - 1 \right] \cdot \frac{1}{1285.7}$$

$$\boxed{\beta = 0.004.}$$

(ii) Given;  $\beta = 12\gamma \Rightarrow 0.012$

O/P voltage  $V_o = A_{vf} \cdot V_{in}$

$$A_{vf} = \frac{Av}{1+\beta Av} \Rightarrow \frac{1285.7}{1+0.012[1285.7]} \Rightarrow 78.26.$$

$$V_o = 78.26 \cdot 0.028$$

$$\boxed{V_o = 2.19 V}$$

- d. A common source FET amplifier has a load resistance of  $500\text{k}\Omega$ . The ac drain resistance of the device is  $100\text{k}\Omega$  and the transconductance is  $0.8 \text{ mA/V}^2$ . Calculate the voltage gain of the amplifier

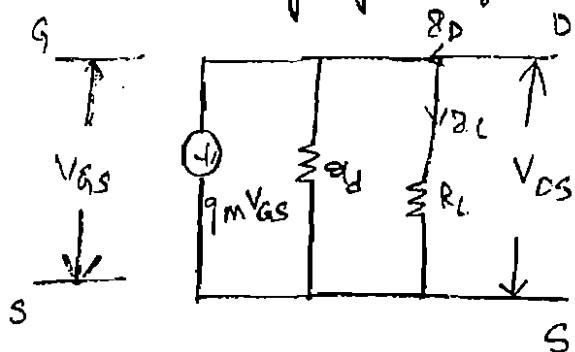
Q1

Given ;

$$R_L = 500\text{k}\Omega$$

$$R_D = 100\text{k}\Omega$$

$$g_m = 0.8 \text{ mA/V}$$



$$AV = \frac{V_o}{V_i}$$

$$= \frac{V_{DS}}{V_{GS}} \Rightarrow \frac{R_D \cdot R_D}{V_{GS}} \quad \left\{ \because R_D = g_m / g_m \right\}$$

$$AV = -\frac{Z_L \cdot R_D}{V_{GS}}$$

$$= -\frac{R_D \cdot R_D}{V_{GS}}$$

$$= -\frac{g_m V_{GS} R_D}{V_{GS}} \quad \left\{ \because R_D = g_m V_{GS} \right\}.$$

$$AV = -g_m \cdot R_D$$

$$= -0.8 \times 10^{-3} [500\text{k} / 100\text{k}]$$

$$= -0.8 \times 10^{-3} \left[ \frac{100\text{k} \times 500\text{k}}{100\text{k} + 500\text{k}} \right] \Rightarrow -66.6 \text{ V.}$$

3. An amplifier has an open loop voltage gain of 1000 delivers 10 watts output with 10% second harmonic distortion when the input is 10mV. If 40dB of negative feedback is applied, what is the value of distortion? How much input voltage should be applied to get 10 watts of output power?

Sol

Given;

$$\text{gain } [A_v] : 1000.$$

$$\text{Distortion without feed back } [D] = 10\% = 0.1.$$

$$\text{Input Voltage} = 10 \text{ mV.}$$

$$\beta = 40 \text{ dB.}$$

$$\text{i. input signal voltage } V_s' = V_s [1 + \beta_A]$$

$$= V_s [1 + 100]$$

$$\therefore \text{Here } \beta \text{ is given in dB so; } \Rightarrow 10 \text{ m} [1 + 100]$$

$$\text{Antilog} \left( \frac{40}{20} \right) \Rightarrow 1.01 \text{ V.}$$

$$\Rightarrow 100.$$

ii. Value of Second harmonic distortion;

$$D_f = \frac{D}{1 + \beta_A}$$

$$= \frac{10\%}{1 + 100} \Rightarrow 0.99 \times 10^{-3}.$$

4. An amplifier with negative feedback gives an output of 12.5 V with an input of 1.5 V. When feedback is removed, it requires 0.25 V input for the same output. Find

i. Value of voltage gain without feedback

ii. Value of  $B$ , if the input and output are in phase and  $\beta$  is ideal.

50

Given ;

$$V_{of} = 12.5$$

$$V_{in} = 1.5 \text{ V}$$

$$\therefore A_{vf} = \frac{V_{of}}{V_{in}} = \frac{12.5}{1.5} \\ = 8.33$$

$$\text{i. } A_v = \frac{V_o}{V_{in}} = \frac{12.5}{0.25} \\ = 50$$

$$\text{ii. } A_{vf} = \frac{A}{1 + A_v B}$$

$$8.33 = \frac{50}{1 + 50 B}$$

$$\therefore 1 + 50 B = \frac{50}{8.33}$$

$$50 B = \frac{50}{8.33} - 1 \Rightarrow B = \frac{5.002}{50}$$

$$0.1 < B$$

5. An amplifier has a mid band gain of 125 and bandwidth of 250 kHz. If 4% negative feedback is introduced and the new bandwidth and gain.

Sol

Given ;

$$A_v = 125 ;$$

$$B.W = 250 \text{ kHz} ;$$

$$\beta = 4\% \Rightarrow 0.04 .$$

$$\begin{aligned} A_{vf} &= \frac{A_v}{1 + \beta A_v} \\ &= \frac{125}{1 + (0.04)(125)} \end{aligned}$$

$$= 0.83 .$$

$$\begin{aligned} B.W_f &= B.W * [1 + \beta A_v] \\ &= 250 \text{ kHz} * [1 + 0.04 * 125] \\ &= 1.5 \text{ MHz} . \end{aligned}$$

6. The open loop voltage gain of the amplifier is 50. Its input impedance is  $1k\Omega$ . What will be the input impedance where a negative feedback of 40% is applied to the amplifier?

Sol:- Given;

$$A_v = 50,$$

$$R_i = 1\text{ k}\Omega$$

$$\beta = 10\% \Rightarrow 0.1.$$

$$\begin{aligned}D &= 1 + \beta A_v \\&= 1 + (0.1 * 50) \\&= 6.\end{aligned}$$

$$\begin{aligned}R_{if} &= R_i * D \\&= 1\text{ k} * 6. \\&= 6\text{ k}.\end{aligned}$$

7. The open loop gain of an amplifier is 50dB. A negative feedback factor is 0.004 is applied to it. If the open loop gain is thereby reduced by 10%. find the change in overall gain.

Sol Gain of amplifier is given as  $50\text{dB} = 20 \log \frac{V_o}{V_i}$

$$\begin{aligned}AV_i &= \text{antilog} \left( \frac{50}{20} \right) \\&= 316.22 \\&\quad \beta = 0.004.\end{aligned}$$

when it is reduced by 10% of  $AV_i$ .

$$= AV_i \times \frac{10}{100}.$$

$$= 316.22 \times \frac{1}{10}$$

$$= 31.622.$$

$$AV_2 = AV_1 - 10\% \text{ of } AV_1$$

$$= 316.22 - 31.622$$

$$= 284.5$$

$$Af_1 = \frac{AV_1}{1 + \beta AV_1} = \frac{316.22}{1 + (0.004 * 316.22)}$$

$$= 139.61.$$

$$Af_2 = \frac{AV_2}{1 + \beta AV_2} = \frac{284.5}{1 + (0.004 * 284.5)}$$

$$= 133.08$$

$$\% \text{ change in over all gain} = \frac{Af_1 - Af_2}{Af_1} \times 100$$

$$= \frac{139.61 - 133.08}{139.61} \times 100$$

$$= 4.08\%.$$

8. A single stage CE amplifier has a voltage gain of 600 without feedback. When feedback is employed, its gain is reduced to 50. Calculate the percentage of output which is fed back to the input.

Sol  $AV = 600$

$$AV_f = 50;$$

$$\beta = ?$$

$$AV_f = \frac{Av}{1+\beta Av}$$

$$50 = \frac{600}{1+\beta 600}$$

$$1+\beta(600) = \frac{600}{50}$$

$$\beta = \frac{11}{600}$$

$$\% \beta = \frac{11}{600} \times 100$$

$$\boxed{\beta = 1.83 \%}$$

$\therefore$  The % of the o/p which is fed back to i/p is 1.83 %.

9. Calculate the voltage gain, input impedance and output impedance of a voltage series feed back amplifiers having an open loop gain  $A=300$ ;  $R_i=1.5\text{k}\Omega$ ;  $R_o=50\text{k}\Omega$ ;  $\beta=-\frac{1}{20}$ ?

Q1 Given  $Av = 300$ ;

$$R_i = 1.5\text{k}\Omega$$

$$R_o = 50\text{k}\Omega$$

$$\beta = -\frac{1}{20}$$

$$\begin{aligned} \text{Input Impedance } R_{if} &= R_i[1+\beta Av] \\ &= 1.5\text{k} \left[ 1 + \left(-\frac{1}{20}\right) 300 \right] \\ &= 24\text{k} \end{aligned}$$

$$\text{Output impedance : } R_{of} = \frac{R_o}{1+\beta A_v}$$

$$= \frac{50 \text{ K}}{1 + (\gamma_{20})(300)}$$

$$= 8.125 \text{ K.}$$

$$\text{Voltage gain : } A_f = \frac{A_v}{1 + \beta A_v}$$

$$= \frac{300}{1 + (\gamma_{20})(300)}$$

$$= 18.75.$$

10. For voltage series feed back amplifier with parameters of the internal amplifier as  $A_v = -200$ ;  $R_{in} = 5\text{K}$ ;  $R_o = 20\text{K}$ ; Bandwidth =  $50\text{kHz}$  and having feedback factor  $\beta = -0.02$ . calculate

- i. Voltage gain  $A_{vf}$
- ii. Input impedance  $R_{inf}$
- iii. Output impedance  $R_{of}$  and
- iv. Bandwidth

Sol Given;  $A_v = -200$ ;  
 $R_{in} = 5\text{K}$ ;  
 $R_o = 20\text{K}$ ;  
 $B.W = 50\text{kHz}$ ;  
 $\beta = -0.02$ .

i) voltage gain  $A_{vf} = \frac{Av}{1+\beta Av}$

$$= \frac{-200}{1+(-0.02)(-200)}$$

$$= -40.$$

ii) input impedance  $R_{if} = R_i[1+\beta Av]$

$$= 5K [1+(-0.02)(-200)]$$

$$= 25K.$$

iii) output impedance  $R_{of} = \frac{R_o}{1+\beta Av}$

$$= \frac{20K}{1+(-0.02)(-200)}$$

$$= 4K.$$

iv) Bandwidth of  $= Av * B.W.$

$$= (-200)(50K)$$

$$= -10M.$$

Q11) An amplifier circuit has a gain of 60dB and an output impedance  $Z_o = 10K\Omega$ ; it is required to modify its output impedance to  $1K\Omega$  by applying -ve feed back. Calculate the value of the feed back factor. Also find the percentage change in overall gain, for 10% change in the gain of the internal amplifier.

Sol: Given;

Gain of the amplifier is  $60\text{dB} = 20 \log Av$ .

$$Av = \frac{V_o}{V_s}$$

we know that ;

$\approx 1000$ .

$$R_{of} = \frac{R_o}{1 + \beta Av}$$

Given ;

Output impedance  $R_o = 10\text{K}$  ;

$$R_{of} = 500\Omega$$

$$\beta = ?$$

$$R_{of} = \frac{R_o}{1 + \beta Av}$$

$$500 = \frac{10\text{K}}{1 + \beta \cdot 1000}$$

$$1000\beta + 1 = \frac{10\text{K}}{500}$$

$$1000\beta = 20 - 1$$

$$\beta = \frac{19}{1000} \Rightarrow 0.019.$$

(ii) % change in overall gain =  $\frac{10}{1 + \beta Av} \Rightarrow \frac{10}{1 + 0.019 \cdot 1000}$   
 $\approx 0.5\%$ .

## 4 - Oscillators

Oscillator :-

An oscillator is an electronic ckt which produces Ac o/p voltage without any Ac input, to produce an Ac voltage it is energized with DC power supply.

It is an electronic ckt which converts DC voltage to AC voltage. Then it is also called DC to AC converter. An amplifier with +ve feed back is called an oscillator.

Principle of Oscillations :-

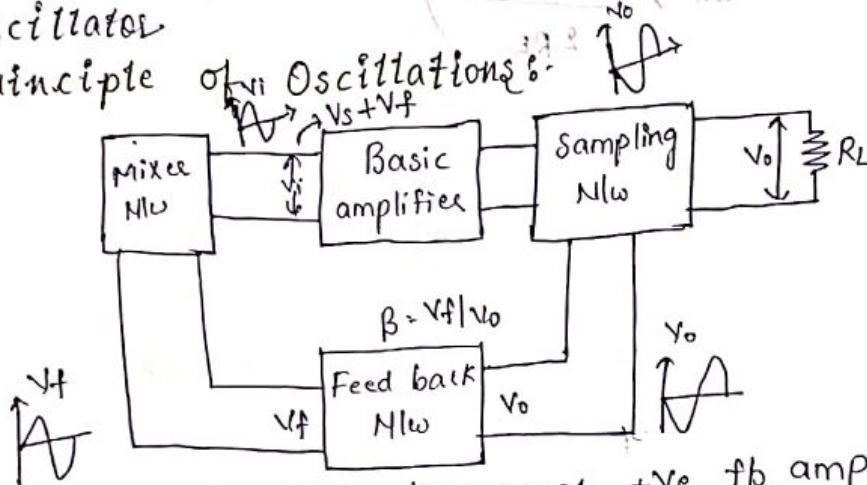
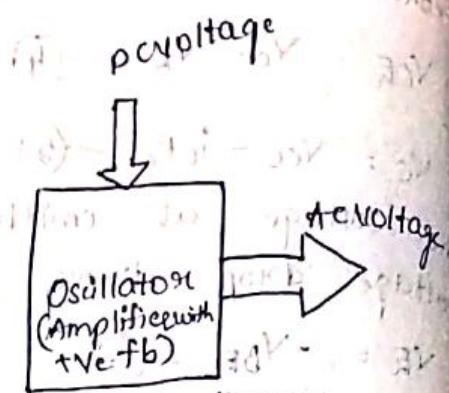


fig: Block diagram of +ve fb amplifier

The above figure shows an amplifier with +ve feed back. When dc power supply is switched on, noisy current is developed in the amplifier circuit and it is considered as the input of amplifier. Now the amplifier amplifies this noise input with 180° phase shift. The sampling Nlw is used to take the part of the output voltage and it is fed back to the input of amplifier through a feed back Nlw.

The feed back Nlw is so designed to provide another 180° phase shift so that the total phase shift around the closed loop is 360°.

Now the feed back signal is inphase with the input signal and it is added to the i/p of amplifier.



Simple block diagram representation of oscillator

i.e.,  $V_o = V_s + V_f$ . It is further amplified by the basic amplifiers. This process will be continues until sustained oscillations are generated.

Expression for gain with +ve fb :-  
The gain of an amplifier without fb is given by

$$A = \frac{V_o}{V_i} = \frac{V_o}{V_s} \rightarrow ①$$

By providing +ve fb,  $V_i \rightarrow V_s + V_f$

$$A = \frac{V_o}{V_s + V_f}$$

$$AV_s + AV_f = V_o$$

$$AV_s + A\beta V_o = V_o$$

$$AV_s = V_o - A\beta V_o = V_o(1 - A\beta)$$

$$AV_s = \frac{V_o}{V_s} = \frac{A}{1 - A\beta} \rightarrow ②$$

If the product of  $A\beta = 1$

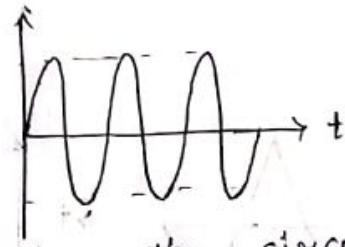
$$AV_s = \frac{A}{1 - 1} = \infty$$

This indicates that the circuit produces an output without external input just by feeding its own input

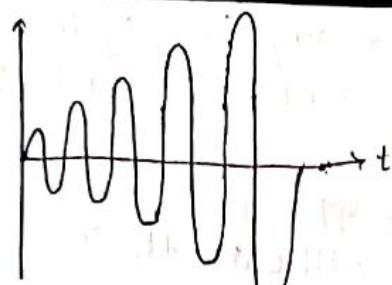
Barkhausen Criterion :-  
The Barkhausen criterion states that an amplifier with +ve feed back by satisfying the total phase shift around the closed loop is  $360^\circ$  and the product of  $A \& \beta = 1$ , then the circuit works as an oscillator.

In general, an amplifier with +ve feedback, the total phase shift around the closed loop is  $360^\circ$ .

1. If  $A\beta = 1$ , then the circuit generates sustained oscillations (or) undamped oscillations. and it is shown in fig(a).

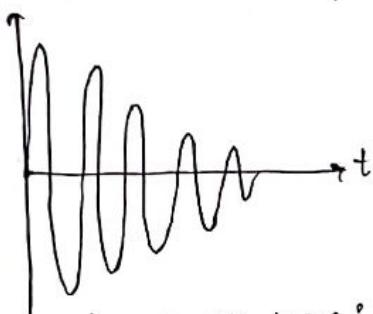


2) If  $A\beta \neq 1$ , then the circuit generates continuously increasing types of oscillations and it is shown in fig.



over damped Oscillations

3) If  $A\beta < 1$ , then the circuit generates continuously decreasing type of oscillations (or) undamped oscillations. It is as shown in fig.



under damped Oscillations

#### Classification of Oscillators:

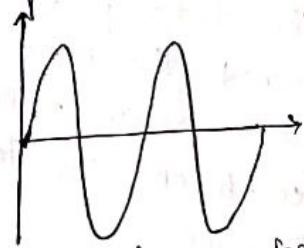
Oscillators are classified based on four criteria.

I According to waveforms generated

1. Sinusoidal Oscillators

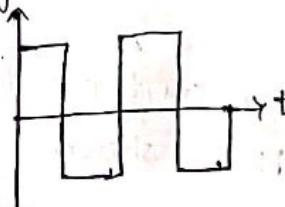
2. Non Sinusoidal Oscillators.

→ The sinusoidal oscillator generates sinusoidal voltages (or) currents as shown in fig (a).

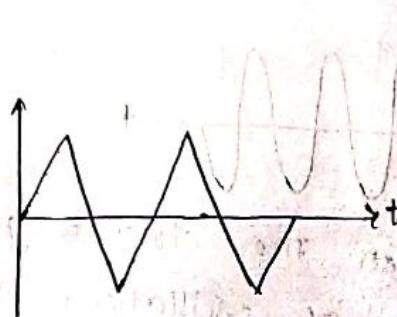


Sinusoidal waveform

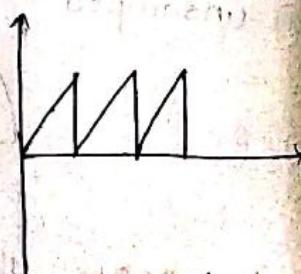
→ Non sinusoidal oscillators generate non-sinusoidal wave forms which are vary one or more times in a given cycle of time as shown in figures



Square waveform



triangular wave form



sawtooth waveform

## II. According to Fundamental Mechanisms used:

- Negative Resistance Oscillators
- Positive feedback Oscillators

## III. According to Frequency Range:

- Audio frequency Oscillators - upto 20kHz
- Radio frequency Oscillators - 20kHz - 30MHz
- Very high frequency Oscillators : 30MHz - 300MHz
- Ultra high frequency Oscillators : 300MHz - 3GHz
- Micro wave oscillators : > 3GHz

## IV. According to Circuit Components: Sinusoidal oscillators are further classified into 2 types.

### 1. LC oscillators

- Hartley oscillator
- Colpitts oscillator

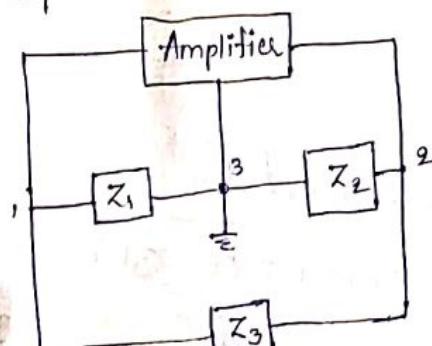
### 2. RC oscillators

- RC Phase shift oscillator

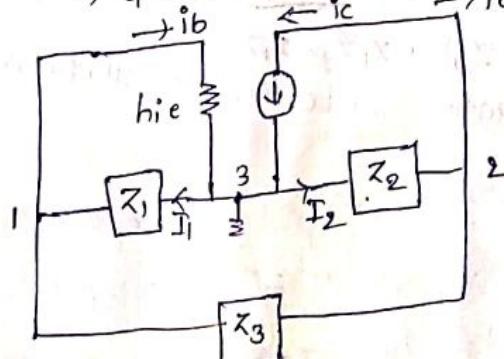
- Wein bridge oscillator

General

Expression for LC oscillator :



a) General form of the oscillator



b) Equivalent ckt

fig(a) shows general form of LC oscillator. It consists of an amplifier with feedback  $N_{LW}$ . As shown in fig(a), the feedback  $N_{LW}$  is formed by 3 reactive elements  $Z_1, Z_2$  &  $Z_3$ . The reactive elements  $Z_1$  &  $Z_2$  acts as voltage dividers  $N_{LW}$  i.e., the voltage across  $Z_1$  is feedback voltage & the voltage across  $Z_2$  is o/p voltage. To determine condition to generate sustained oscillations fig(a) is replaced by fig(b).

As shown in fig(b)  $h_{ie}$  &  $Z_1$  are in parallel & their equivalent resistance is given by  $Z' = \frac{Z_1 h_{ie}}{Z_1 + h_{ie}}$ . The load impedance in b/w terminals 2 & 3 is the equivalent impedance of  $Z_2$  in parallel with the series combination of  $Z'$  &  $Z_3$ .

$$Z_L = Z_2 \parallel (Z' + Z_3)$$

$$Z_L = \frac{Z_2(Z' + Z_3)}{Z_2 + Z' + Z_3} = \frac{Z_2 Z' + Z_2 Z_3}{Z_2 + \frac{Z_1 h_{ie}}{Z_1 + h_{ie}} + Z_3}$$

$$Z_L = \frac{Z_2 \left( \frac{Z_1 h_{ie}}{Z_1 + h_{ie}} \right) + Z_2 Z_3}{Z_2 + \left( \frac{Z_1 h_{ie}}{Z_1 + h_{ie}} \right) + Z_3}$$

$$= \frac{Z_1 Z_2 h_{ie} + Z_2 Z_3 Z_1 + Z_2 Z_3 h_{ie}}{Z_1 Z_2 + Z_2 h_{ie} + Z_1 h_{ie} + Z_1 Z_3 + Z_3 h_{ie}}$$

$$Z_L = \frac{Z_2 [Z_1 h_{ie} + Z_3 Z_1 + Z_3 h_{ie}]}{h_{ie} (Z_1 + Z_2 + Z_3) + Z_1 Z_2 + Z_1 Z_3} \quad \text{--- (2)}$$

The condition to generate sustained oscillations is  $A \beta = 1$   $\rightarrow$  (3)

$$\text{wkt} \quad A = \frac{V_o}{V_i} \quad \text{--- (4)}$$

$$\text{where } V_o = ILZ_L$$

$$= -i_C Z_L$$

$$V_o = -h_{fe} i_B Z_L \quad \text{--- (5)}$$

$$V_i = h_{fe} i_B \quad (6)$$

$$A = \frac{-h_{fe} Z_L}{h_{ie} \beta}$$

$$\boxed{A = \frac{-h_{fe} Z_L}{h_{ie}}} \quad (7)$$

$$B = V_f / V_o \quad (8)$$

$$V_f = -I_1 Z \quad (9)$$

The o/p voltage  $V_o$  in b/w terminals 2 & 3 in terms of current  $I_1$  is given by

$$V_o = -I_1 (Z_1 + Z_3) \quad (10)$$

$$B = \frac{e^{\frac{-I_1 Z}{h_{ie}}}}{+I_1 (Z_1 + Z_3)}$$

$$\begin{aligned} B : \frac{\frac{z_1 h_{ie}}{z_1 + h_{ie}}}{\frac{z_1 h_{ie}}{z_1 + h_{ie}} + z_3} &= \frac{z_1 h_{ie}}{z_1 h_{ie} + z_1 z_3 + z_3 h_{ie}} \\ &= \frac{z_1 h_{ie}}{z_1 z_3 + h_{ie}(z_1 + z_3)} \end{aligned}$$

$$B = \frac{z_1 h_{ie}}{z_1 z_3 + h_{ie}(z_1 + z_3)} \quad (11)$$

Now A & B are sub. in eq (3)

$$\frac{-h_{fe} Z_L}{h_{ie}} \cdot \frac{z_1 h_{ie}}{z_1 z_3 + h_{ie}(z_1 + z_3)} = 1$$

$$\frac{-h_{fe} Z_L z_1}{z_1 z_3 + h_{ie}(z_1 + z_3)} = 1$$

$$\frac{-h_{fe} z_1 z_2 [z_1 h_{ie} + z_1 z_3 + z_3 h_{ie}]}{h_{ie}(z_1 + z_2 + z_3) + z_1 z_2 + z_1 z_3} = 1$$

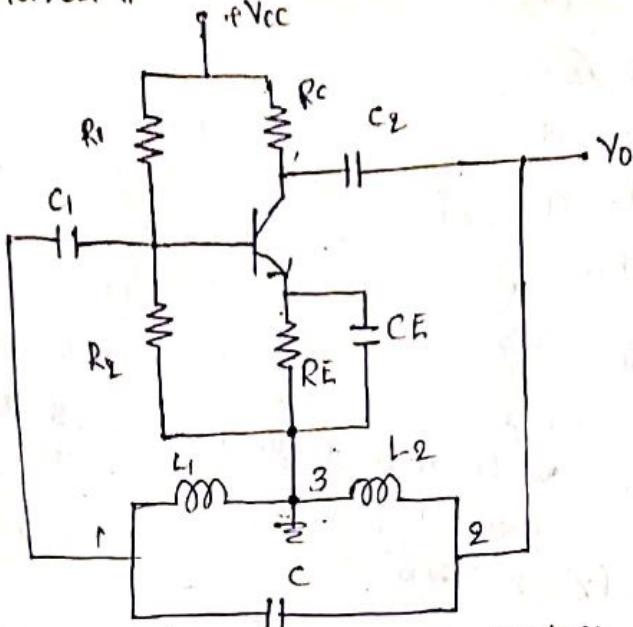
$$\frac{-h_{fe} z_1 z_2}{z_1 z_3 + h_{ie}(z_1 + z_3)} = 1$$

$$\Rightarrow -h_{fe} z_1 z_2 = h_{ie}(z_1 + z_2 + z_3) + z_1 z_2 + z_1 z_3$$

$$\Rightarrow h_{ie}(z_1 + z_2 + z_3) + z_1(z_2 + z_3) + h_{fe} z_1 z_2 = 0 \quad (12)$$

The above eq. is general expression of LC oscillator. By using this we can determine the frequency of LC oscillator.

## Hartley Oscillator



ckt diagram of Hartley Oscillator

The above fig shows The circuit diagram of Hartley oscillator. It consists of an amplifier with feedback network. The feedback network is formed by two inductors and one capacitor i.e., The reactive elements  $Z_1$  and  $Z_2$  are inductors and  $Z_3$  is capacitor.

### Operation :-

when power supply +V<sub>CC</sub> is switched on, noisy currents developed within the amplifier circuit and it will be considered as input for same amplifier. Then amplifier amplifies noise inputs and this amplified noise output back to the feedback network.

Due to this, oscillatory currents developed across  $L_1$  &  $L_2$ . The terminal 3 is grounded and it is at zero potential if terminal 1 is at +ve potential with respect to terminal 3 at any instant and terminal 2 is at -ve potential with respect to terminal 3 at the same instant. Thus, the phase shift around the closed loop is  $180^\circ$  between terminal 1 and terminal 2 is  $180^\circ$  and another  $180^\circ$  phase shift is provided by amplifier. The total phase shift around the closed loop is  $360^\circ$ . i.e., one of the condition is satisfied, and other condition  $A\beta = 1$  is also satisfied by designing the Feedback Network. Then the ckt works as an Oscillator.

Frequency of Oscillation:  
NKT, the general expression of LC oscillator is given by

$$hie(z_1 + z_2 + z_3) + z_1 z_2 (1 + hfe) + z_1 z_3 = 0 \quad \text{---(1)}$$

The reactance of inductor L<sub>1</sub>,

$$z_1 = j\omega L_1 + j\omega M = j\omega (L_1 + M) \quad \text{---(2)}$$

The reactance of L<sub>2</sub>

$$z_2 = j\omega L_2 + j\omega M = j\omega (L_2 + M) \quad \text{---(3)}$$

The reactance of C

$$z_3 = \frac{1}{j\omega C} \quad \text{---(4)}$$

Substitute eq (2), (3), (4) in (1)

$$hie(j\omega L_1 + j\omega (L_2 + M) + \frac{1}{j\omega C}) + j\omega (L_1 + M)(j\omega (L_2 + M))$$

$$hie[j\omega(L_1 + M) + j\omega(L_2 + M) + \frac{1}{j\omega C}] + j\omega^2(L_1 + M)(L_2 + M)(1 + hfe) +$$

$$hie j\omega \left[ L_1 + L_2 + 2M + \frac{1}{j^2 \omega^2 C} \right] + j\omega^2(L_1 + M)(L_2 + M)(1 + hfe) + \frac{L_1 + M}{j\omega C} = 0.$$

$$\Rightarrow hie j\omega \left[ L_1 + L_2 + 2M - \frac{1}{\omega^2 C} \right] - \omega^2(L_1 + M)(L_2 + M)(1 + hfe) + \frac{L_1 + M}{\omega^2 C} = 0.$$

To determine the frequency of oscillation, equate to zero.

Imaginary part of above eq.

$$hie j\omega \left[ L_1 + L_2 + 2M - \frac{1}{\omega^2 C} \right] = 0$$

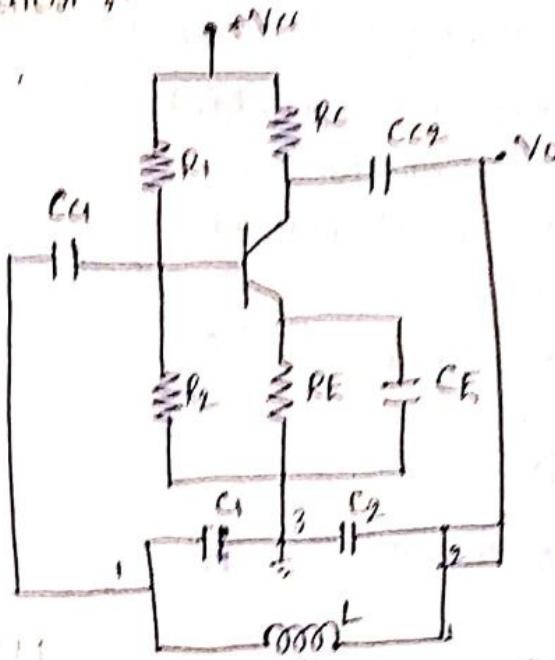
$$\therefore L_1 + L_2 + 2M = \frac{1}{\omega^2 C}$$

$$\omega^2 = \frac{1}{(L_1 + L_2 + 2M)C}$$

$$\omega = \frac{1}{\sqrt{(L_1 + L_2 + 2M)C}}$$

$$f = \frac{1}{2\pi\sqrt{(L_1 + L_2 + 2M)C}} \quad \text{---(5)}$$

## Colpitts Oscillator :-



Ckt diagram of colpitts oscillator

→ Same theory as per Hartley oscillator.

Frequency of oscillation :-

The General expression of LC oscillator is given

$$\text{by } hie(z_1 + z_2 + z_3) + z_1 z_2 (1 + hfe) + z_1 z_3 = 0 \quad \text{--- (1)}$$

From the ckt diagram,

The reactance of capacitor  $C_1, C_2$  is given by

$$z_1 = \frac{1}{j\omega C_1} \quad \text{--- (2)}$$

$$z_2 = \frac{1}{j\omega C_2} \quad \text{--- (3)}$$

$$z_3 = j\omega L \quad \text{--- (4)}$$

Substitute eq 2,3,4 in eq (1)

$$hie \left[ \frac{1}{j\omega C_1} + \frac{1}{j\omega C_2} + j\omega L \right] + \frac{1}{j\omega C_1} \cdot \frac{1}{j\omega C_2} (1 + hfe) + \frac{1}{j\omega C_1} = 0$$

$$\Rightarrow \frac{hie}{j\omega} \left[ \frac{1}{C_1} + \frac{1}{C_2} + (j\omega)^2 L \right] - \frac{1}{\omega^2 C_1 C_2} (1 + hfe) + \frac{h}{C_1} = 0$$

$$\Rightarrow -hie \frac{1}{\omega} \left[ \frac{1}{C_1} + \frac{1}{C_2} - \omega^2 L \right] - \frac{1}{\omega^2 C_1 C_2} (1 + hfe) + \frac{h}{C_1} = 0$$

To determine the frequency of oscillation, the imaginary part of above eq. is equating to zero.

$$\Rightarrow \frac{1}{LC} \left[ \frac{1}{C_1} + \frac{1}{C_2} - \omega^2 \right] = 0$$

$$\frac{1}{C_1} + \frac{1}{C_2} = \omega^2 L$$

$$\omega^2 = \frac{1}{L} \left[ \frac{1}{C_1} + \frac{1}{C_2} \right]$$

$$\omega = \sqrt{\frac{1}{L} \left[ \frac{1}{C_1} + \frac{1}{C_2} \right]}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{1}{L} \left( \frac{C_1 + C_2}{C_1 C_2} \right)}$$

$$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{C_1 + C_2}{L C_{eq}}} = \frac{1}{2\pi} \sqrt{\frac{1}{L C_{eq}}} \quad \text{--- (5)}$$

1. In a Hartley Oscillator, if  $L_1 = 0.2 \text{ mH}$ ,  $L_2 = 0.3 \text{ mH}$ ,  $C = 0.003 \mu\text{F}$ , calculate the freq. of its oscillation.

Given,  $L_1 = 0.2 \text{ mH}$ ,  $L_2 = 0.3 \text{ mH}$ ,  $C = 0.003 \mu\text{F}$

$$\text{wkt } f = \frac{1}{2\pi \sqrt{(L_1 + L_2) C}} \quad (\because M=0)$$

$$f = \frac{1}{2\pi \sqrt{(0.2 + 0.3) \times 10^{-3} \times 0.003 \times 10^{-6}}} \\ = \frac{1}{2\pi \times 1.224 \times 10^{-6}}$$

$f = 0.130 \text{ MHz.} \Rightarrow 130 \text{ kHz.}$   
2. In the Hartley Oscillator;  $L_2 = 0.4 \text{ mH}$  &  $C = 0.004 \mu\text{F}$ , if the freq. of oscillation is  $120 \text{ kHz.}$  Find the value of  $L_1.$  (Neglect  $M$ )

$$\text{wkt } f = \frac{1}{2\pi \sqrt{(L_1 + L_2) C}}$$

$$120 \times 10^3 = \frac{1}{2\pi \sqrt{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}}$$

$$240\pi \times 10^3 = \frac{1}{\sqrt{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}}$$

$$\Rightarrow 5.68 \times 10^{11} = \frac{1}{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}$$

$$\Rightarrow 22.12 \Rightarrow \frac{1}{(L_1 + 0.01 \times 10^{-3})}$$

$$\Rightarrow 22.12 L_1 + 0.0088 = 1$$

$$22.12 L_1 = 0.0088$$

$$L_1 = 4.01 \times 10^{-5} \text{ H}$$

Q3) In a transistORIZED Hartley oscillator, the inductances are  $2\text{mH}$ ,  $20\text{mH}$ , while the freq. is to be changed from  $950\text{ KHz}$  to  $2050\text{ KHz}$ , calculate the range over which the capacitance is to be varied.

Given,  $L_1 = 2\text{mH}$ ,  $L_2 = 20\text{mH}$

$$\omega_1 = 950\text{ KHz}, C_1 = ?$$

$$\omega_2 = 2050\text{ KHz}, C_2 = ?$$

$$\text{WKT } \omega = \frac{1}{2\pi \sqrt{(L_1 + L_2)C}}$$

$$\Rightarrow \sqrt{(L_1 + L_2)C_1} = \frac{1}{2\pi\omega_1}$$

$$\sqrt{(2 \times 10^{-3} + 20 \times 10^{-3})}, \sqrt{C_1} = \frac{1}{2\pi (950 \times 10^3)}$$

$$0.0449 \sqrt{C_1} = 1.67 \times 10^{-7}$$

$$\sqrt{C_1} = 3.719 \times 10^{-6}$$

$$C_1 = 13.83 \text{ pF}$$

$$\Rightarrow \sqrt{(L_1 + L_2)C_2} = \frac{1}{2\pi\omega_2} = \frac{1}{2\pi \times 2050 \times 10^3}$$

$$0.0449 \sqrt{C_2} = 7.76 \times 10^{-8}$$

$$\sqrt{C_2} = 1.728 \times 10^{-6}$$

$$C_2 = 2.98 \text{ pF}$$

The range of capacitance is from  $2.98 \text{ pF}$  to  $13.83 \text{ pF}$ .

Q)  $L_1 = 38\text{mH}$ ,  $L_2 = 12\text{mH}$ ,  $C = 500\text{pF}$ . Find the freq of oscillation and feed back factor  $\beta$ .

$$\text{WKT} \quad f = \frac{1}{2\pi\sqrt{(L_1 + L_2)C}}$$

$$= \frac{1}{2\pi\sqrt{(38+12)\times 10^{-6} \times 500 \times 10^{-12}}} = 0.10 \times 10^6$$

$$= \frac{1}{2\pi\sqrt{2.5 \times 10^{-14}}} = \frac{1}{2\pi \times 1.58 \times 10^{-7}} = 1 \times 10^6$$

$$f = 1\text{MHz.}$$

$$\beta = \frac{L_1}{L_2} = \frac{38}{12} = 3.16$$

5) A Colpitts oscillator is designed with  $C_1 = 100\text{pF}$ ,  $C_2 = 750\text{pF}$ . The inductance is variable, determine the range of inductance values, if the freq. of oscillator is to vary b/w 950 KHz, and 2050 KHz.

$$\text{WKT} \quad f = \frac{1}{2\pi\sqrt{L_{eq}}}$$

$$C_{eq} = 98.6\text{ pF}$$

$$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$$

$$= \frac{(100 \times 750) \times 10^{-12}}{(100 + 750) 10^{-12}}$$

$$127.90 = \frac{1}{\sqrt{L_2}}$$

$$\sqrt{L_2} = 7.81\text{KHz}$$

$$950 \times 10^3 = \frac{1}{2\pi\sqrt{L_1} (9.82 \times 10^{-6})}$$

$$\Rightarrow 59.21 = \frac{1}{\sqrt{L_1}}$$

$$\sqrt{L_1} = 0.016$$

$$L_1 = 2.85 \times 10^{-4}$$

$$L_1 = 0.285\text{mH}$$

$$\Rightarrow 2050 \times 10^3 = \frac{1}{\sqrt{L_2} (6.23 \times 10^{-5})}$$

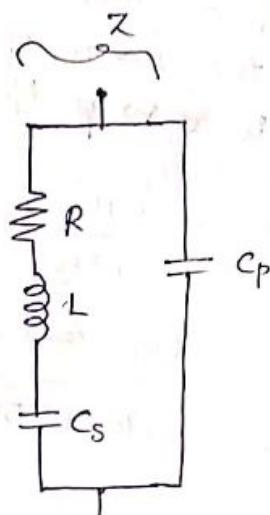
$$\Rightarrow \sqrt{L_2} = 7.82 \times 10^{-3}$$

$$L_2 = 61.3\text{mH}$$

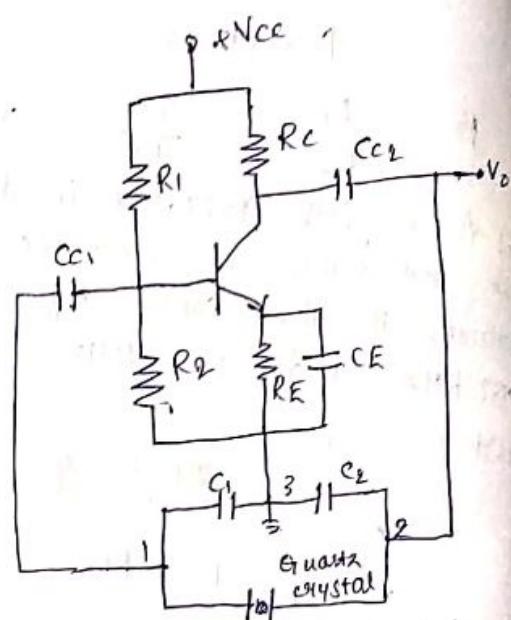
The inductance value changes from  $0.28\text{mH}$  to  $0.061\text{mH}$ .

Why LC oscillators are not used at low frequencies.  
 For LC oscillators, the frequency of oscillation is given by  $f = \frac{1}{2\pi\sqrt{LC}}$ . It clearly shows that the frequency of oscillation is inversely proportional to inductance and capacitance i.e.,  $f \propto \frac{1}{\sqrt{LC}}$ . If we design LC oscillators at low frequencies, it requires large values of inductors and capacitors which occupies large space size and high cost. This is the reason the LC oscillators are not used at low frequencies.

### Crystal Oscillator:



(b) Equivalent ckt of crystal



(a) ckt diagram of crystal oscillator

Fig (a) shows the circuit diagram of crystal oscillator. It is similar to the Colpitts oscillator except in feedback network inductor is replaced by quartz crystal. This oscillator works on the principle of piezo electric effect which states that when mechanical force is applied at one phase of crystal and it develops ac voltage at opposite phase of the crystal and in reverse when ac voltage is applied at one phase of the crystal and it develops mechanical vibrations at opposite phase of the crystal. To determine the frequency of oscillation, quartz crystal is replaced by its equivalent circuit as shown in fig (b).

When crystal is not vibrating just it is represented by capacitor symbol ( $C_p$ ) and when it is vibrating it is represented by series RLC circuit i.e. the internal losses are represented by resistor symbol, the magnetic field around the crystal is represented by inductor and the ac voltage which is developed by crystal is represented with the capacitor ( $C_s$ ).

Frequency of oscillation :-

As shown in fig (b), the equivalent impedance  $Z'$  is given by (neglecting internal losses)

$$Z' = \left( j\omega L + \frac{1}{j\omega C_s} \right) \parallel \frac{1}{j\omega C_p}$$

$$\cdot \frac{\left( j\omega L + \frac{1}{j\omega C_s} \right)}{j\omega C_p} \cdot \frac{1}{j\omega C_p}$$

$$\frac{j\omega L + \frac{1}{j\omega C_s} + \frac{1}{j\omega C_p}}{j\omega C_p}$$

$$= \frac{j \left( \omega L - \frac{1}{\omega C_s} \right) \frac{1}{j\omega C_p}}{j\omega C_p \left( \omega L - \frac{1}{\omega C_s} - \frac{1}{\omega C_p} \right)}$$

$$= \frac{\omega \left( \omega L - \frac{1}{\omega C_s} \right) \frac{1}{j\omega C_p}}{\omega \left( \omega L - \frac{1}{\omega C_s} - \frac{1}{\omega C_p} \right)}$$

$$Z = \frac{\omega \left( \omega L - \frac{1}{\omega C_s} \right) \frac{1}{j\omega C_p}}{\omega \left( \omega L - \frac{1}{\omega C_s} - \frac{1}{\omega C_p} \right)}$$

$$\therefore \left( \omega^2 - \frac{1}{L C_s} \right) \frac{1}{j\omega C_p}$$

$$\left[ \frac{1}{\omega^2 - \left( \frac{1}{L C_s} + \frac{1}{C_p} \right)} \right]$$

$$Z = \frac{\left( \omega^2 - \omega_s^2 \right) \frac{1}{j\omega C_p}}{\omega^2 - \omega_s^2}$$

From the above equation,  $\omega_s^2 = \frac{1}{L C_s}$

$$\Rightarrow \omega_s = \frac{1}{\sqrt{L C_s}}$$

$$f_s = \frac{1}{2\pi\sqrt{L C_s}}$$

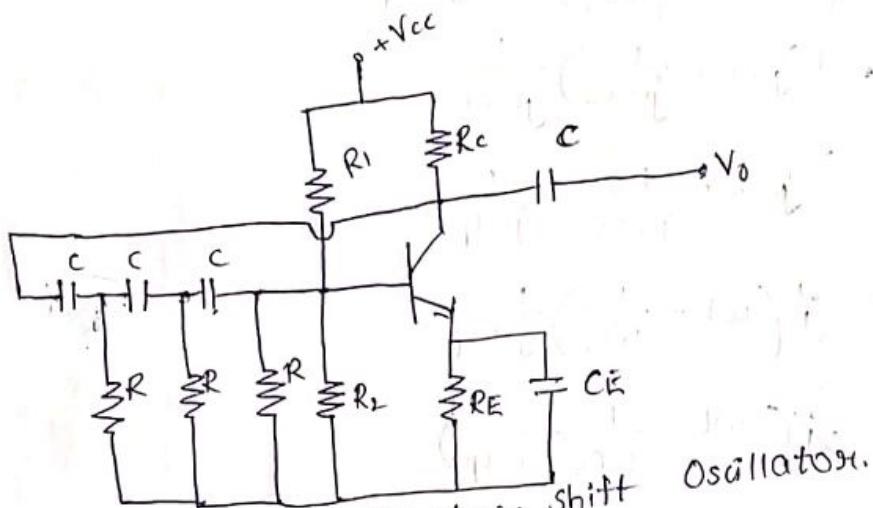
$$\text{where } \omega_p = \left( \frac{1}{C_S} + \frac{1}{C_P} \right) \cdot \frac{1}{L} \Rightarrow \frac{1}{L C_{eq}}$$

$$\omega_p = \sqrt{\left( \frac{1}{C_S} + \frac{1}{C_P} \right) \frac{1}{L}}$$

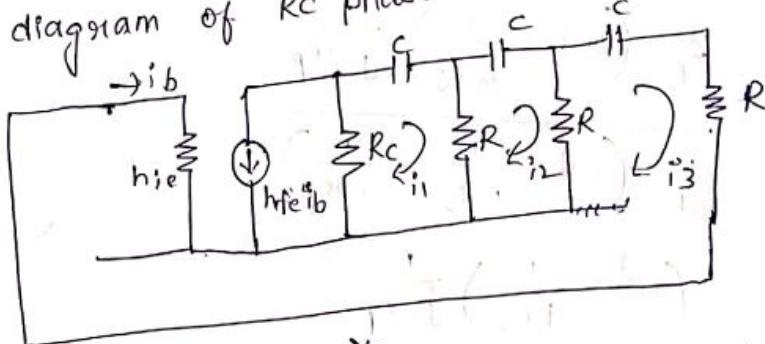
$$\omega_p = \sqrt{\frac{C_P + C_S}{C_S C_P L}} = \frac{1}{\sqrt{L C_{eq}}}$$

$$f_p = \frac{1}{2\pi\sqrt{L C_{eq}}}$$

RC - Phase shift Oscillator



a) ckt diagram of RC phase shift oscillator.



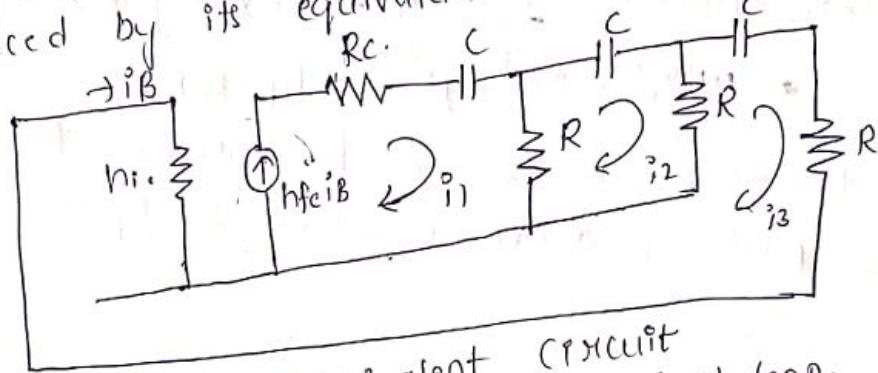
b) equivalent circuit

Fig(a) shows the circuit diagram of RC phase shift oscillator. It consists of a CE amplifier and feed back network which is formed by 3 RC networks. When a power supply  $+V_{cc}$  is switched ON, noisy current is developed within the amplifier circuit and it will be considered as input for the amplifier circuit. Thus, an amplifier amplifies it with  $180^\circ$  phase shift and this amplified noise output back to the input of the amplifier through a feedback network.

In a feedback network, each RC network provides 60° phase shift i.e., the phase shift provided by RC ladder network is 180°. Thus, the total phase shift around the closed loop is 360° and by designing feedback network if  $A\beta = 1$  then above circuit works as an oscillator.

Frequency of Oscillation :-

To determine the frequency of oscillation, fig (a) is replaced by its equivalent circuit as shown in fig (b).



o Simplified equivalent circuit

From fig(c), apply KVL to the first loop:  $(i_B = i_3)$

$$\Rightarrow h_f e i_B R_c + i_1 R_c - i_{1j} j x_c + R(i_1 - i_2) = 0 \quad \text{---(1)}$$

$$\Rightarrow i_1(R_c - j x_c + R) + i_2(-R) + i_3 h_f e R_c = 0$$

Apply KVL to the second loop.

$$\Rightarrow R(i_2 - i_1) - i_{2j} j x_c + R(i_2 - i_3) = 0$$

$$\Rightarrow -Ri_1 + i_2(R - j x_c + R) - Ri_3 = 0 \quad \text{---(2)}$$

Apply KVL to the third loop.

$$R(i_3 - i_2) - i_{3j} j x_c + R_i_3 R = 0$$

$$\Rightarrow -Ri_2 + i_3(R + R - j x_c) = 0 \quad \text{---(3)}$$

From 1, 2, 3:

$$A = \begin{bmatrix} (R_c + R) - j x_c & -R & h_f e R_c \\ -R & 2R - j x_c & -R \\ 0 & -R & 2R - j x_c \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix} = 0$$

$$\begin{bmatrix} R_c + R - j x_c & -R & h_f e R_c \\ -R & 2R - j x_c & -R \\ 0 & -R & 2R - j x_c \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix} = 0$$

$$\Rightarrow (R_c + R - jx_c) \left[ (2R - jx_c)^2 - R^2 \right] + R \left[ -R(2R - jx_c) \right] + h_{fe} R_c R^2 = 0$$

$$\Rightarrow (R_c + R - jx_c) \left[ 4R^2 - j4Rx_c - x_c^2 - R^2 \right] - 2R^3 + jR^2 x_c + h_{fe} R_c R^2 = 0$$

$$\Rightarrow (R_c + R - jx_c) (3R^2 - x_c^2 - j4Rx_c) - 2R^3 + jR^2 x_c + h_{fe} R_c R^2 = 0$$

$$\Rightarrow 3R^2 R_c - R_c x_c^2 - j4Rx_c R_c + 3R^3 - Rx_c^2 - j4Rx_c - j3R^2 x_c + jx_c^3 - 2R^3 + jR^2 x_c + h_{fe} R_c R^2 = 0$$

$\Rightarrow R^3$  To determine frequency of oscillation, the imaginary part of above equation is equal to zero.

$$\Rightarrow -4Rx_c R_c - 4R^2 x_c - 3R^2 x_c + x_c^3 + 2R^2 x_c = 0$$

$$\Rightarrow -6R^2 x_c + x_c^3 - 4Rx_c R_c = 0$$

$$\Rightarrow x_c (x_c^2 - 6R^2 - 4Rx_c) = 0$$

$$\Rightarrow x_c^2 = 6R^2 + 4Rx_c$$

$$x_c^2 = \sqrt{R(R^2 + 4Rc)}$$

$$x_c = \sqrt{R^2 \left( 6 + \frac{4Rc}{R} \right)}$$

$$\frac{1}{\omega_c} = \sqrt{R^2 \left( 6 + \frac{4Rc}{R} \right)}$$

$$\omega_c = \frac{1}{\sqrt{Rc \sqrt{6 + \frac{4Rc}{R}}}}$$

$$f = \frac{1}{2\pi R C \sqrt{6 + \frac{4Rc}{R}}}$$

$$\frac{Rc}{R} = k$$

$$f = \frac{1}{2\pi R C \sqrt{6 + 4k}}$$

$$s = \frac{1}{2\pi f C}$$

# Wein bridge Oscillator

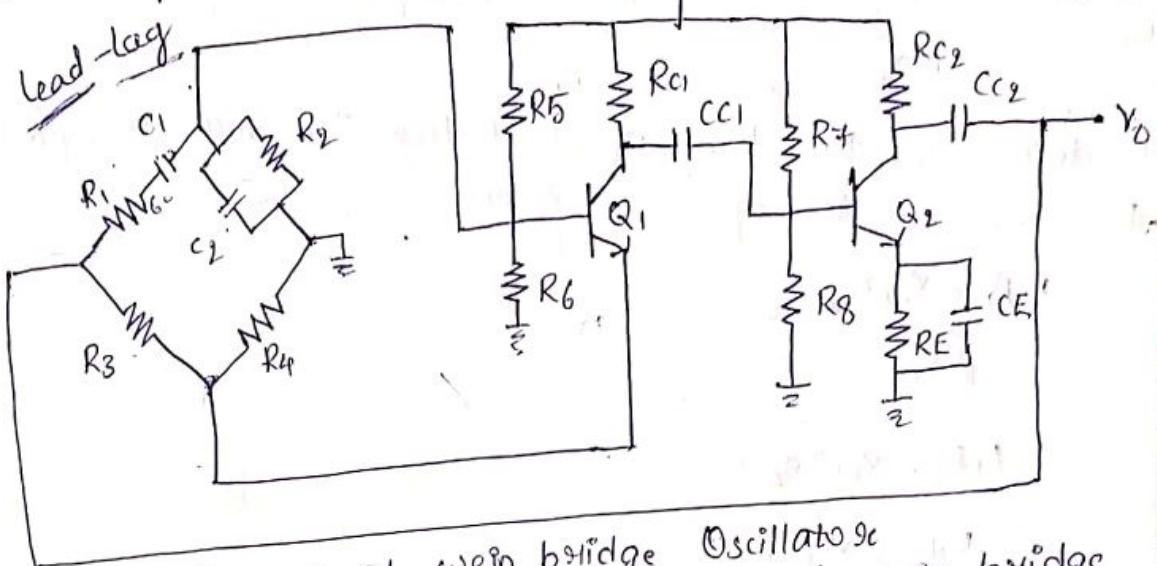


Fig: ckt diagram of wein bridge Oscillator  
 The above fig. shows the ckt diagram of wein bridge oscillator, it consists of two amplifier sections in CE mode and balanced bridge network each CE mode provides  $180^\circ$  phase shift and the total phase shift by the two amplifier sections is  $360^\circ$  and hence no need to introduce any additional phase shift by the balanced bridge Nlw which is formed by balanced bridge Nlw. The lead-lag Nlw which is formed by  $R_1-C_1$  &  $R_2-C_2$  provides the +ve feedback to the PIP of 1st stage of amplifiers and the voltage divider Nlw which is formed by  $R_3$  &  $R_4$  provides -ve fb to the emitter of 2nd stage of transistors. This balanced bridge Nlw provides stability of oscillations in both amplitude & frequency. To determine freq. of oscillation we consider the condition for balancing the bridge.

$$\text{i.e., } \frac{R_3}{R_4} = \frac{R_1 + \frac{1}{j\omega C_1}}{R_2 || \left( \frac{1}{j\omega C_2} \right)} \Rightarrow \frac{R_3}{R_4} = \frac{R_1 - jX_{C_1}}{R_2 || (-jX_{C_2})}$$

$$\Rightarrow \frac{\frac{R_1 - jX_{C_1}}{R_2 (-jX_{C_2})}}{R_2 - jX_{C_2}} = \frac{(R_1 - jX_{C_1})(R_2 - jX_{C_2})}{-jR_2 X_{C_2}}$$

$$\Rightarrow \frac{R_1 R_2 - jR_1 X_{C_2} - jR_2 X_{C_1} - X_{C_1} X_{C_2}}{-jR_2 X_{C_2}}$$

$$\Rightarrow \frac{R_1 R_2 - X_{C_1} X_{C_2}}{-jR_2 X_{C_2}} : \frac{-j(R_1 X_{C_2} + R_2 X_{C_1})}{jR_2 X_{C_2}}$$

$$\frac{R_3}{R_4} \Rightarrow \frac{j(R_1 R_2 - X_{C1} X_{C2})}{R_2 X_{C2}} + \frac{R_1 X_{C2} + R_2 X_{C1}}{R_2 X_{C2}}$$

To determine the freq. of oscillation, the imaginary part of above eq. is equal to zero.

$$\frac{R_1 R_2 - X_{C1} X_{C2}}{R_2 X_{C2}} = 0$$

$$\Rightarrow R_1 R_2 - X_{C1} X_{C2} = 0$$

$$R_1 R_2 = X_{C1} X_{C2}$$

$$R_1 R_2 = \frac{1}{\omega C_1} \cdot \frac{1}{\omega C_2}$$

$$\omega^2 = \frac{1}{R_1 R_2 C_1 C_2}$$

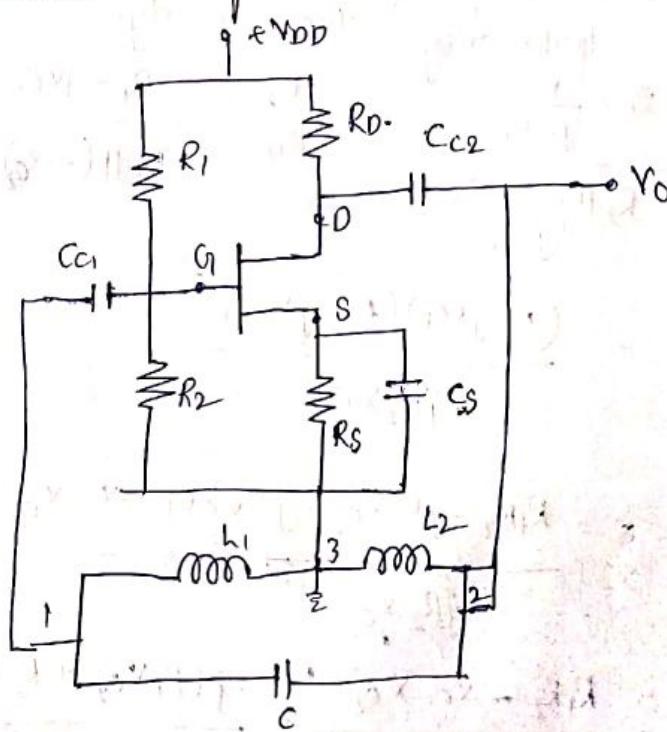
$$\omega = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

$$f = \frac{1}{2\pi \sqrt{R_1 R_2 C_1 C_2}}$$

$$\text{if } R_1 = R_2 = R \quad \& \quad C_1 = C_2 = C$$

$$f = \frac{1}{2\pi R C}$$

Hartley oscillator using JFET :-



$$G.E - h_{ie} (Z_1 + Z_2 + Z_3) + (1 + h_{fe}) Z_1 Z_2 + Z_1 Z_3 = 0$$

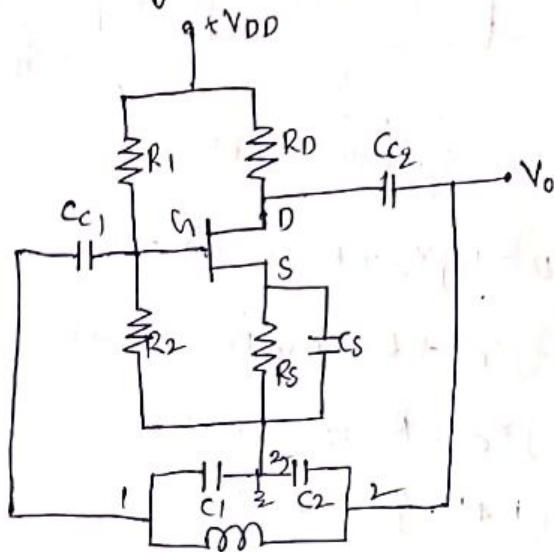
$$\Rightarrow Z_1 = j\omega h_{ie} + j\omega M = j\omega (L_1 + M)$$

$$Z_2 = j\omega h_2 + j\omega M = j\omega (L_2 + M)$$

$$Z_3 = \frac{1}{j\omega C}$$

$$f = \frac{1}{2\pi \sqrt{(L_1 + L_2 + 2M)C}}$$

Colpitts Oscillator using JFET :-



$$G.E - h_{ie} (Z_1 + Z_2 + Z_3) + (1 + h_{fe}) Z_1 Z_2 + Z_1 Z_3 = 0$$

$$Z_1 = \frac{1}{j\omega C_1} \quad \text{---(1)}$$

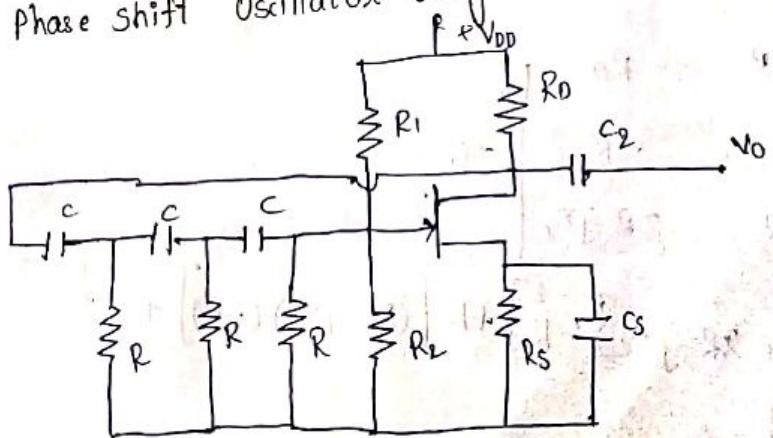
$$Z_2 = \frac{1}{j\omega C_2}$$

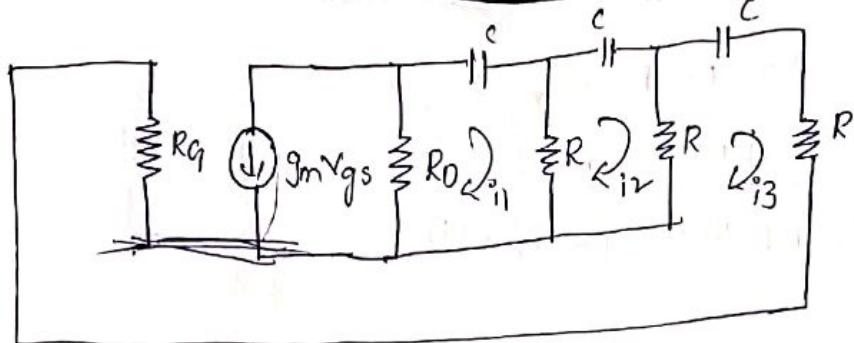
$$Z_3 = j\omega L$$

$$f = \frac{1}{2\pi \sqrt{L C_{eq}}}$$

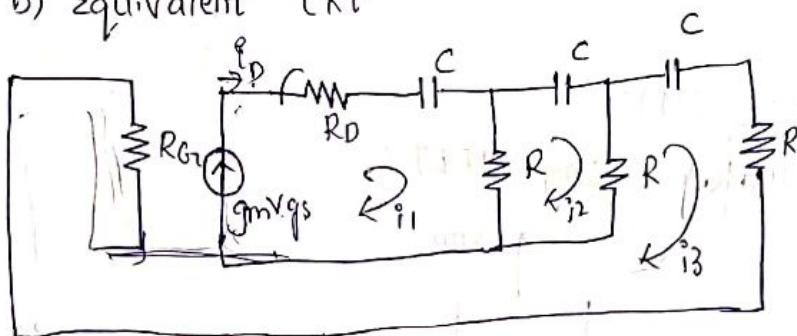
$$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$$

RC Phase shift Oscillator using JFET :-





b) Equivalent ckt



c) Simplified equivalent ckt

$$gm = \frac{i_D}{V_{GS}}$$

$$\rightarrow gmV_{GS}R_D + i_1R_D - i_1jX_C + R(i_1 - i_2) = 0$$

$$\Rightarrow i_1(R_D + R - jX_C) + Ri_2 + i_B R_D = 0 \quad \text{---(1)}$$

$$\rightarrow R(i_2 - i_1) - i_2jX_C + R(i_2 - i_3) = 0$$

$$\Rightarrow -i_1R + i_2(R + R - jX_C) + Ri_3 = 0$$

$$-Ri_1 + i_2(2R - jX_C) - i_3R = 0 \quad \text{---(2)}$$

$$\rightarrow R(i_3 - i_2) - j i_3 X_C + i_3 R = 0$$

$$\Rightarrow -Ri_2 + i_3(R - jX_C) = 0 \quad \text{---(3)}$$

$$\begin{bmatrix} R_D + R - jX_C & -R & R_D \\ -R & 2R - jX_C & -R \\ 0 & -R & 2R - jX_C \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{vmatrix} R_D + R - jX_C & -R & R_D \\ -R & 2R - jX_C & -R \\ 0 & -R & 2R - jX_C \end{vmatrix} = 0$$

$$\Rightarrow (R_D + R - jX_C) [(2R - jX_C)^2 - R^2] + R [(2R - jX_C)(-R)] + R_D [R^2] = 0$$

$$\Rightarrow (R_D + R - jX_C) [4R^2 - 4RjX_C - X_C^2] R + R [-2R^2 + jX_C R] + R_0 R > 0$$

$$\Rightarrow (R_D + R - jX_C) (3R^2 - 4RjX_C - X_C^2) + 2R^3 + jX_C R^2 + R_0 R^2 > 0$$

$$\Rightarrow 3R^2 R_D - 4R_0 R jX_C - R_0 X_C^2 + 3R^3 - 4R^2 jX_C + RX_C^2 - 3R^2 jX_C > 0$$

$$4R X_C^2 + jX_C^3 + 2R^3 + jX_C R^2 + R_0 R^2 = 0$$

To determine the frequency of oscillation, the imaginary part of above eq. is zero.

$$jX_C^3 + jX_C R^2 = 3R^2 jX_C - 4R_0 R jX_C = 0$$

$$X_C^2 + R^2 - 3R^2 - 4R^2 - 4R_0 R = 0$$

$$X_C^2 - 8R^2 - 4R_0 R = 0$$

$$X_C^2 = 6R^2 + 4R_0 R$$

$$X_C^2 = R(6R + 4R_0)$$

$$X_C = \sqrt{R^2 \left( 6 + \frac{4R_0}{R} \right)}$$

$$\frac{1}{\omega_C} = \sqrt{R^2 \left( 6 + \frac{4R_0}{R} \right)}$$

$$\omega = \frac{1}{RC \sqrt{\left( 6 + \frac{4R_0}{R} \right)}}$$

$$f = \frac{1}{2\pi RC \sqrt{\left( 6 + \frac{4R_0}{R} \right)}}$$

$$K = \frac{R_0}{R}$$

$$f = \frac{1}{2\pi RC \sqrt{6 + 4K}}$$

Frequency and amplitude stability of oscillator :-  
In the Weinbridge oscillator, if the RC NLs consists of resistors of  $200\text{ k}\Omega$  and the capacitors of  $300\text{ pF}$ , find its frequency of oscillation.

$$f = \frac{1}{2\pi \sqrt{R_1 C_1 R_2 C_2}}$$

$$R_1 = R_2 = 200\text{ k}\Omega, C_1 = C_2 = 300\text{ pF}$$

$$f = \frac{1}{2\pi RC} = \frac{1}{2\pi \times 200 \times 10^3 \times 300 \times 10^{-12}} \\ = \frac{10^5}{12\pi}$$

$$f = 2.652 \text{ kHz}$$

Frequency and amplitude stability of oscillator :-

Frequency stability of an oscillator is a measure of the frequency stability of an oscillator. The frequency stability of an oscillator is its ability to maintain the required frequency over a long time interval. The main drawback in transistors oscillators is that the frequency of oscillation is not stable during a long time operation. The following are the factors which contribute to the change in frequency.

- i) Due to change in temperature the value of the frequency determining components such as resistor, inductor and capacitor changes.
- ii) Due to variations in the power supply, change in climatic conditions and due to aging of components the transistor parameters changes.
- iii) The effective resistance of the tank circuit is changed when the load is connected.
- iv) Due to variations in biasing conditions and loading temp.

In the absence of automatic control, the effect of temp. on the LC circuit can be reduced by selecting the inductance 'L' with +ve temperature coefficient and capacitance 'C' with -ve temperature coefficient. As Piezo-electric crystals have high 'Q' values of the order of  $10^5$ , they can be used as parallel resonant circuits in oscillators to get very high frequency stability.

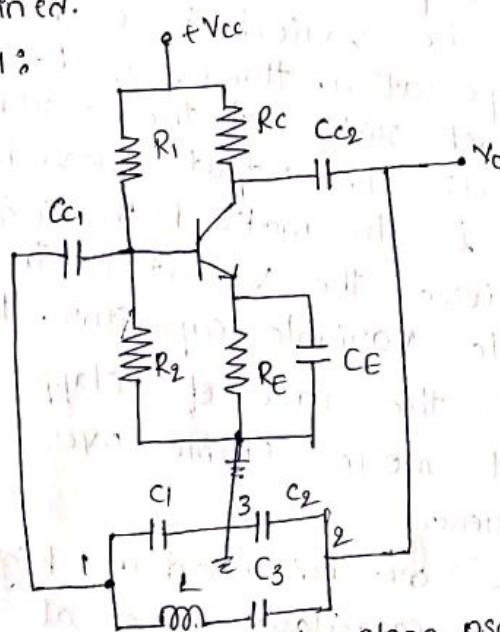
## Amplitude stability of an Oscillators.

All oscillators need +ve feedback for their operation. If the +ve resistance of the LC tank ckt is cancelled by introducing the right amount of -ve resistance across the tank ckt, then the steady oscillation can be maintained.

There are several devices such as Thermistor, UJT and tunnel diode exhibits a region of -ve resistance in V-I characteristics. Such devices operated in negative resistance region are placed across LC ckt section.

as the frequency determining In the case of RC oscillators, the amplitude against the variations due to aging of the transistors and other components can be stabilized by replacing the resistor in bridge by resistors which are temperature dependent resistors. Thus, the stability in amplitude of the RC oscillators can be easily maintained.

## Clapp Oscillator:



a) ckt diagram of clapp oscillator

- Clapp oscillator is an advanced version of Colpitts oscillator in which an additional capacitor  $C_3$  is added into the tank circuit to be in series with the inductor as shown in figure.

Apart from the presence of extra capacitor, all other components and their connections remain similar to that in the case of Colpitts oscillator.

Hence, the working of this circuit is almost similar to that of the colpitts oscillator. However, the frequency of oscillation in the case of clapp oscillator is given by

$$f = \frac{1}{2\pi \sqrt{L\left(\frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3}\right)}}$$

Usually, the value of  $C_3$  is chosen that to be much smaller than the other two capacitors. This is because at higher frequencies, smaller the  $C_3$ , larger will be the inductor, which simplifies the implementation as well as reduces the effect of leakage inductance.

However, is to be noted that when  $C_3$  is chosen to be smaller with comparison in  $C_1$  &  $C_2$ , the net capacitance will be more dependent on it. Thus,

$$f = \frac{1}{2\pi \sqrt{LC_3}}$$

In the case of colpitts oscillator, the capacitor  $C_1$  (or)  $C_2$  need to be varied in order to vary its frequency of operation. However, during this process even the feedback ratio of the oscillator changes which intusin effects its output waveform. One solution to this problem is to make both  $C_1$  &  $C_2$  to be fixed, while achieve the variation in frequency using a separate variable capacitor. This is what the  $C_3$  does in the case of clapp oscillator, which intusin makes it more stable over colpitts in terms of frequency.

Why RC oscillators are not used at high frequency? The 'c' in RC is capacitance and at high frequency the capacitor reactance will decreases than at low frequencies. As capacitor performance goes down, the circuit performance also goes down. Thus, RC oscillators performance is poor at high frequencies and not provides stable oscillations. This is the reason RC oscillators are not used at high frequencies.