```
In [95]:
import t
```

```
import torch
import torch.nn as nn
import torch.optim as optim
from torch.optim import lr scheduler
from torch.autograd import Variable
import torchvision
from torchvision import datasets, models, transforms
from torch.utils.data import Dataset, DataLoader, ConcatDataset
from skimage import io, transform, data
from torchvision import transforms, utils
import numpy as np
import math
import glob
import matplotlib.pyplot as plt
import time
import os
import copy
import sklearn.svm
import cv2
from matplotlib import pyplot as plt
import numpy as np
from os.path import exists
import pandas as pd
import PIL
import random
from google.colab import drive
from sklearn.metrics.cluster import completeness score
from sklearn.cluster import KMeans
from tqdm import tqdm, tqdm notebook
from functools import partial
from torchsummary import summary
from torchvision.datasets import ImageFolder
from torch.utils.data.sampler import SubsetRandomSampler
\# cuda \ output = ! ldconfig \ -p | grep \ cudart.so | sed \ -e \ 's/.* \. \ ([0-9]*\) \. \ ([0-9]*\) \$/cu\1\2/'
#accelerator = cuda output[0] if exists('/dev/nvidia0') else 'cpu'
#print("Accelerator type = ",accelerator)
#print("Pytorch verision: ", torch. version )
```

In [9]:

```
!pip install tifffile
```

Requirement already satisfied: tifffile in /usr/local/lib/python3.7/dist-packages (2021.4 .8)

Requirement already satisfied: numpy>=1.15.1 in /usr/local/lib/python3.7/dist-packages (f rom tifffile) (1.19.5)

Import Drive

```
In [2]:
```

```
# This will prompt for authorization.
drive.mount('/content/drive')
```

Mounted at /content/drive

Sentinel-2 Land-Cover Subet Dataset with 5 Categories, having 100 images each

```
In [206]:
```

```
import tifffile
```

```
from PIL import Image
from torchvision.transforms import ToTensor

files_0 = os.listdir(aerial_path+'/0/')
files_1 = os.listdir(aerial_path+'/1/')
files_2 = os.listdir(aerial_path+'/2/')
files_3 = os.listdir(aerial_path+'/3/')
files_4 = os.listdir(aerial_path+'/4/')

img_rgb_0 = Image.open(aerial_path+'/4/')

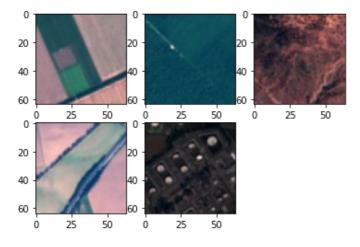
img_rgb_1 = Image.open(aerial_path + '/0/' + files[5])
img_rgb_2 = Image.open(aerial_path + '/1/' + files[45])
img_rgb_3 = Image.open(aerial_path + '/2/' + files[30])
img_rgb_4 = Image.open(aerial_path + '/4/' + files[70])
```

In [207]:

```
plt.subplot(231)
plt.imshow(img_rgb_0)
plt.subplot(232)
plt.imshow(img_rgb_1)
plt.subplot(233)
plt.imshow(img_rgb_2)
plt.subplot(234)
plt.imshow(img_rgb_3)
plt.imshow(img_rgb_3)
plt.subplot(235)
plt.imshow(img_rgb_4)
```

Out[207]:

<matplotlib.image.AxesImage at 0x7f14106a1a50>



Path to Aerial Dataset

(A combination of samples from Small Village and Industrial Datasets from Sensefly)

```
In [129]:
aerial path = '/content/drive/MyDrive/sentinel-2 rgb'
```

Aerial Dataset Class

```
In [4]:
```

```
def get_sat_data(folder_path,transforms=None):
    if transforms:
        dataset_full = ImageFolder(folder_path,preprocessor)
    else:
        dataset_full = ImageFolder(folder_path,preprocessor)
```

In [128]:

In [86]:

```
, , ,
def find classes (dir):
   classes = [d for d in os.listdir(dir) if os.path.isdir(os.path.join(dir, d))]
   classes.sort()
   class to idx = {classes[i]: i for i in range(len(classes))}
   return classes, class to idx
IMG_EXTENSIONS = [
    '.jpg', '.JPG',
                   '.jpeg', '.JPEG',
    '.png', '.PNG', '.ppm', '.PPM', '.bmp', '.BMP', '.tif'
def is image file(filename):
   return any (filename.endswith (extension) for extension in IMG EXTENSIONS)
def make dataset(dir, class to idx):
   images = []
   dir = os.path.expanduser(dir)
   for target in sorted(os.listdir(dir)):
       d = os.path.join(dir, target)
        if not os.path.isdir(d):
            continue
        for root, _, fnames in sorted(os.walk(d)):
            for fname in sorted(fnames):
                if is_image_file(fname):
                    path = os.path.join(root, fname)
                    item = (path, class_to_idx[target])
                    images.append(item)
   return images
class ImageFolder(torch.utils.data.Dataset):
 def __init__(self, root, transform=None, target_transform=None):
      classes, class_to_idx = find_classes(root)
      imgs = make dataset(root, class to idx)
      if len(imgs) == 0:
          raise (RuntimeError ("Found 0 images in subfolders of: " + root + "\n"
                              "Supported image extensions are: " + ", ".join(IMG EXTENSIO
NS)))
      self.root = root
     self.imgs = imgs
      self.classes = classes
      self.class to idx = class to idx
      self.transform = transform
      self.target transform = target transform
```

```
def __getitem__(self, index):

    path, target = self.imgs[index]
    #print(ok)

#img = self.loader(path)
    img_13 = tifffile.imread(path)
    img_bgr = img_13[:,:,1:4]
    img = img_bgr[::-1]
    img = cv2.normalize(img, None, 0, 255, cv2.NORM_MINMAX, dtype=cv2.CV_8U)
    if self.transform is not None:
        img = self.transform(img)
    if self.target_transform is not None:
        target = self.target_transform(target)
    return img, target

def __len__(self):
    return len(self.imgs)

'''
```

Dataset and Dataloader initialization

```
In [133]:
```

```
#Pre processing the data
normalize = transforms.Normalize(mean = [0.485, 0.456, 0.406],
                                std = [0.229, 0.224, 0.225])
resize = transforms.Resize((224,224))
preprocessor = transforms.Compose([ resize, transforms.ToTensor(), normalize
aerial dataset full = get sat data(aerial path,preprocessor)
# Creating data indices for training and validation splits:
dataset size = len(aerial dataset full)
indices = list(range(dataset size))
validation split = 0.2
split = int(np.floor(validation split * dataset size))
shuffle dataset = True
random seed= 101
if shuffle dataset :
   np.random.seed(random seed)
    np.random.shuffle(indices)
train indices, val indices = indices[split:], indices[:split]
# Creating PT data samplers and loaders:
train sampler = SubsetRandomSampler(train indices)
valid sampler = SubsetRandomSampler(val indices)
aerial train loader = torch.utils.data.DataLoader(aerial dataset full, batch size=16,
                                           sampler=train sampler)
aerial validation loader = torch.utils.data.DataLoader(aerial dataset full, batch size=16
                                                sampler=valid sampler)
```

In [134]:

```
[[-0.5651, -0.5651, -0.5651, ..., -0.1800, -0.1975, -0.1975],
        [-0.5651, -0.5651, -0.5651,
                                    ..., -0.1800, -0.1975, -0.1975],
        [-0.5651, -0.5651, -0.5651,
                                    ..., -0.1975, -0.2150, -0.2150],
        [-1.3004, -1.3004, -1.3004,
                                    ..., 0.1702, 0.1877, 0.1877],
        [-1.2829, -1.2829, -1.2829,
                                     ..., 0.1877, 0.2052, 0.2052],
        [-1.2829, -1.2829, -1.2829,
                                     ..., 0.1877, 0.2052, 0.2052]],
        [[-0.6541, -0.6541, -0.6541,
                                     ..., -0.2707, -0.2881, -0.2881],
        [-0.6541, -0.6541, -0.6541,
                                     \dots, -0.2707, -0.2881, -0.2881],
        [-0.6541, -0.6541, -0.6541,
                                     \dots, -0.2881, -0.3055, -0.3055],
        [-0.9330, -0.9330, -0.9330,
                                    ..., 0.0779, 0.0953, 0.0953],
         [-0.9330, -0.9330, -0.9330,
                                    ...,
                                          0.0953, 0.1128, 0.1128],
         [-0.9330, -0.9330, -0.9330,
                                          0.0953, 0.1128, 0.1128]]]), 0)
In [131]:
num classes = 5
```

Training and Validation/Test loop

```
In [150]:
```

```
def training and validation loop(epochs,xp lr scheduler,model,optmizer,aerial train loade
r, aerial validation loader, best acc, best model wts, saved model name):
 train loss = []
 test loss = []
 accuracy = []
 for e in range(epochs):
        step lr scheduler.step()
        #put model in training mode
        model.train()
        avg loss = 0
        for i, (x,y) in enumerate(aerial train loader):
              optimizer.zero grad()
              if gpu flag:
                    img var = Variable(x).cuda()
                    label actual = Variable(y).cuda()
              else:
                    img var = Variable(x)
                    label actual = Variable(y)
              label predicted = model.forward(img var)
              loss = criterion(label predicted, label actual)
              loss.backward()
              if(i%10 == 0):
                   print(i, loss.item())
              avg loss+=loss.item()
              optimizer.step()
        print("Done Training")
        train loss.append(avg loss*1.0/(i+1))
        #set model in evaluation mode
        model.eval()
        avg loss = 0
        correct pred = 0
        total pred = 0
        for i, (x test, y test) in enumerate(aerial validation loader):
```

```
if gpu_flag:
                img_test_var = Variable(x_test).cuda()
                label test var = Variable(y test).cuda()
            else:
                img_test_var = Variable(x test)
                label test var = Variable(y_test)
            label predicted test = model.forward(img test var)
            loss = criterion(label predicted test, label_test_var)
            avg loss+=loss.item()
            vals, label predicted = torch.max(label predicted test, 1)
            correct pred += (label predicted.cpu().data.numpy() == label test var.cpu().da
ta.numpy()).sum()
            total pred += len(label predicted test.cpu())
        test loss.append(avg loss*1.0/i)
        accuracy.append(correct pred*100.0/total pred)
       print("Epoch: ", e, "Train Loss: ", train loss[-1], "Test Loss: ", test loss[-1]
, "Accuracy: ", accuracy[-1])
        #replace model saved
       if accuracy[-1]>best acc:
           best acc = accuracy[-1]
           best model wts = copy.deepcopy(model.state dict())
            model.load state dict(best model wts)
            torch.save(model,f'/content/drive/My Drive/sentinel-2/{saved model name}.pt'
            print("Saved model with accuracy: ", best acc)
 return train loss, test loss, accuracy
```

VGG-16 Model Initialization

```
In [151]:
```

```
# Initialize the model
model = models.vgg16(pretrained=True)

# Change the device to GPU
device = torch.device('cuda:0' if torch.cuda.is_available() else "cpu")
```

In [152]:

```
# Freeze training for all layers
for param in model.features.parameters():
   param.require grad = False
num features = model.classifier[6].in features
# Remove last layer
features = list(model.classifier.children())[:-1]
# Add our layer with 10 outputs
features.extend([nn.Linear(num features, num classes)])
# Replace the model classifier
model.classifier = nn.Sequential(*features)
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), lr=0.001, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer, step size=7, gamma=0.1)
#preprocessor = transforms.Compose([resize,transforms.ToTensor(),normalize])
```

```
In [153]:
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
    criterion = criterion.cuda()
print (model)
True
VGG (
  (features): Sequential(
    (0): Conv2d(3, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (3): ReLU(inplace=True)
    (4): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (5): Conv2d(64, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (6): ReLU(inplace=True)
    (7): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU(inplace=True)
    (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (10): Conv2d(128, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU(inplace=True)
    (12): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (13): ReLU(inplace=True)
    (14): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (15): ReLU(inplace=True)
    (16): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU(inplace=True)
    (19): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (20): ReLU(inplace=True)
    (21): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (22): ReLU(inplace=True)
    (23): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (24): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (25): ReLU(inplace=True)
    (26): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (27): ReLU(inplace=True)
    (28): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace=True)
    (30): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
  (avgpool): AdaptiveAvgPool2d(output size=(7, 7))
  (classifier): Sequential(
    (0): Linear(in_features=25088, out features=4096, bias=True)
    (1): ReLU(inplace=True)
    (2): Dropout(p=0.5, inplace=False)
    (3): Linear(in features=4096, out features=4096, bias=True)
    (4): ReLU(inplace=True)
    (5): Dropout(p=0.5, inplace=False)
    (6): Linear(in features=4096, out features=5, bias=True)
In [142]:
```

VGG16 Model Training and Validation

```
In [154]:
```

tqdm = partial(tqdm, position=0, leave=True)

```
epochs=10
best_model_wts = copy.deepcopy(model.state_dict())
best_acc = 0.0
train_loss_vgg,test_loss_vgg,accuracy_vgg = training_and_validation_loop(epochs,step_lr_s
```

```
cheduler, model, optimizer, aerial train loader, aerial validation loader, best acc, best model
_wts,'vgg16')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
cted call of `lr_scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step(
)`. Failure to do this will result in PyTorch skipping the first value of the learning r
ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus
t-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
0 1.5527842044830322
10 1.1667479276657104
20 0.4904910922050476
Done Training
Epoch: 0 Train Loss: 0.7880626530028306 Test Loss: 0.48988191597163677 Accuracy: 86.1
3861386138613
Saved model with accuracy: 86.13861386138613
0 0.49932748079299927
10 0.5737537741661072
20 0.31253236532211304
Done Training
Epoch: 1 Train Loss: 0.4315136923956183 Test Loss: 0.19656771731873354 Accuracy:
2970297029702
Saved model with accuracy: 97.0297029702
0 0.2683732509613037
10 0.030051369220018387
20 0.023899676278233528
Done Training
Epoch: 2 Train Loss: 0.16336509306879285 Test Loss: 0.20336214414176843 Accuracy: 94.
05940594059406
0 0.4393337070941925
10 0.021655520424246788
20 0.07452696561813354
Done Training
Epoch: 3 Train Loss: 0.17263744227910557 Test Loss: 0.3493415353198846 Accuracy: 93.0
6930693069307
0 0.06903021782636642
10 0.024842623621225357
20 0.19570061564445496
Done Training
Epoch: 4 Train Loss: 0.06718521419231994 Test Loss: 0.1708200064022094 Accuracy: 98.0
1980198019803
Saved model with accuracy: 98.01980198019803
0 0.015900788828730583
10 0.01582414284348488
20 0.16407975554466248
Done Training
Epoch: 5 Train Loss: 0.032973583098142766 Test Loss: 0.2692276057059644 Accuracy: 96.
03960396039604
0 0.0057505345903337
10 0.00110455765388906
20 0.0022066733799874783
Done Training
Epoch: 6 Train Loss: 0.016668705225478895 Test Loss: 0.36249972550043214 Accuracy: 96
.03960396039604
0 0.0008651029784232378
10 0.003201031591743231
20 0.0007410083780996501
Done Training
Epoch: 7 Train Loss: 0.006345281222400865 Test Loss: 0.23956618032146557 Accuracy: 96
.03960396039604
0 0.005501323379576206
10 0.004438275471329689
20 0.001072247396223247
Done Training
Epoch: 8 Train Loss: 0.0022743612241286496 Test Loss: 0.23154676596944532 Accuracy: 9
6.03960396039604
0 0.0022516895551234484
10 0.0040488713420927525
20 0.00182342529296875
Done Training
```

0 mm: - T.--. 0 0004000100E700C1417 mask T.--. 0 000000C007704000C A------

Danah.

Resnet-50 Model Training and Validation

```
In [158]:
```

```
gpu flag = torch.cuda.is available()
#preloading Resnet18
model = models.resnet50(pretrained = True)
#append a new last layer
model.fc = nn.Linear(2048, num classes)
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), lr=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer, 5, .3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
ResNet (
  (conv1): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil mode=False)
  (layer1): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(64, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fal
se)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
    (1): Bottleneck(
      (conv1): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fal
se)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (hn1) · RatchNorm2d(64 ens=1e-05 momentum=0 1 affine=True track running stats=Tr
```

```
(DIII). Date-inversible (OI) epo te oo, mementeum o.i, alline ilae, claes_lainiling_ocaco il
ue)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fal
se)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    )
  (layer2): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
    (1): Bottleneck(
      (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    (3): Bottleneck(
      (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    )
  )
  (layer3): Sequential(
```

(A) · Bottleneck (

```
(0). DOCCTORCOR(
      (conv1): Conv2d(512, 256, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(512, 1024, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
    )
    (1): Bottleneck(
      (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    (3): Bottleneck(
      (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    (4): Bottleneck(
      (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
    (5): Bottleneck(
      (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
```

(hn1) · RatchNorm2d(256 ens=1e-05 momentum=0 1 affine=True track running state=T

```
(DIII). Date-inversed (200) ope is se, memeneum s.i, alline ilue, claes_laming_scate i
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
  (layer4): Sequential (
    (0): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(1024, 2048, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track_running_stats=
True)
    )
    (1): Bottleneck(
      (conv1): Conv2d(2048, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(2048, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=F
alse)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
  )
  (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
  (fc): Linear(in features=2048, out features=5, bias=True)
In [159]:
epochs=10
best model wts = copy.deepcopy(model.state dict())
best acc = 0.0
train_loss_resnet,test_loss_resnet,accuracy_resnet = training_and_validation_loop(epochs,
step lr scheduler, model, optimizer, aerial train loader, aerial validation loader, best acc, b
est model wts, 'resnet50')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
```

cted call of 'lr scheduler sten()' hefore 'ontimizer sten()' In PuTorch 1 1 A and later

you should call them in the opposite order: `optimizer.step()` before `lr_scheduler.step()`. Failure to do this will result in PyTorch skipping the first value of the learning r ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus t-learning-rate "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning) 0 1.6110183000564575 10 0.5589222311973572 20 1.349152684211731 Done Training Epoch: 0 Train Loss: 0.9287485717437588 Test Loss: 0.9159820924202601 Accuracy: 72.27 722772277228 Saved model with accuracy: 72.2772277228 0 1.3665858507156372 10 0.2676994204521179 20 0.4635784924030304 Done Training Epoch: 1 Train Loss: 0.5461058244109154 Test Loss: 1.049634374678135 Accuracy: 75.247 52475247524 Saved model with accuracy: 75.2475247524 0 0.3235670328140259 10 0.03906668722629547 20 0.2946530282497406 Done Training Epoch: 2 Train Loss: 0.42483941780833095 Test Loss: 0.8813686346014341 Accuracy: 80.1 980198019802 Saved model with accuracy: 80.1980198019802 0 1.0905179977416992 10 0.3394052982330322 20 0.44129037857055664 Done Training Epoch: 3 Train Loss: 0.34826357662677765 Test Loss: 0.3741537357370059 Accuracy: 84.1 5841584158416 Saved model with accuracy: 84.15841584158416 0 0.23335310816764832 10 0.015993745997548103 20 0.22321070730686188 Done Training Epoch: 4 Train Loss: 0.165728610008955 Test Loss: 0.25290432991459966 Accuracy: 96.03 960396039604 Saved model with accuracy: 96.03960396039604 0 0.015189481899142265 10 0.09379495680332184 20 0.030404366552829742 Done Training Epoch: 5 Train Loss: 0.09600810106628789 Test Loss: 0.3074860156048089 Accuracy: 95.0 4950495049505 0 0.03764432296156883 10 0.1498563587665558 20 0.007877579890191555 Done Training Epoch: 6 Train Loss: 0.07369136228226125 Test Loss: 0.41468999123511213 Accuracy: 95. 04950495049505 0 0.057389602065086365 10 0.021660560742020607 20 0.06330671161413193 Done Training Epoch: 7 Train Loss: 0.08703623591170001 Test Loss: 0.47049053634206456 Accuracy: 95. 04950495049505 0 0.006919586565345526 10 0.033407341688871384 20 0.01770119182765484 Done Training Epoch: 8 Train Loss: 0.03781272534979507 Test Loss: 0.3121490275952965 Accuracy: 95.0 4950495049505 0 0.012149544432759285 10 0.03099174238741398 20 0.007940023206174374 Done Training Epoch: 9 Train Loss: 0.024119627487380058 Test Loss: 0.30220169263581437 Accuracy: 96 .03960396039604

Densenet (121) Model Training and Validation

```
In [161]:
gpu flag = torch.cuda.is available()
#preloading Resnet18
model = models.densenet121(pretrained = True)
#append a new last layer
model.fc = nn.Linear(1024, num classes)
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), lr=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer, 5, .3)
gpu_flag = torch.cuda.is_available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
DenseNet (
  (features): Sequential(
    (conv0): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
    (norm0): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
    (relu0): ReLU(inplace=True)
    (pool0): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil mode=False)
    (denseblock1): _DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stat
s=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(64, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(96, eps=1e-05, momentum=0.1, affine=True, track running stat
s=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(96, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
```

(denselayer4): DenseLayer(

```
(norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(160, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
    (transition1): Transition(
      (norm): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(256, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock2): _DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(160, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
```

```
False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer9): _DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
```

```
(conv1): Conv2d(416, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(480, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      )
    )
    (transition2): Transition(
      (norm): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock3): _DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer4): DenseLayer(
```

```
(norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(416, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(480, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(512, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(544, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(544, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
```

```
(relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(576, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(576, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(608, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(608, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer13): DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer15): _DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer16): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer17): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1, affine=True, track running sta
```

```
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer18): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer19): _DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer20): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer21): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer22): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer23): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
```

```
(conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer24): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
    (transition3): Transition(
      (norm): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats
=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(1024, 512, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (pool): AvgPool2d(kernel_size=2, stride=2, padding=0)
    )
    (denseblock4): DenseBlock(
      (denselayer1): _DenseLayer(
        (norm1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(544, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(544, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(576, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(576, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer4): _DenseLayer(
        (norm1): BatchNorm2d(608, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(608, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
```

```
(norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
```

```
(denselayer12): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer13): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
t.s=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1, affine=True, track running sta
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer15): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
      (denselayer16): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running sta
ts=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=
False)
    (norm5): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
  )
  (classifier): Linear(in features=1024, out features=1000, bias=True)
  (fc): Linear(in features=1024, out features=5, bias=True)
In [162]:
epochs=10
best model wts = copy.deepcopy(model.state dict())
best acc = 0.0
train loss densenet, test loss densenet, accuracy densenet = training and validation loop(e
pochs, step lr scheduler, model, optimizer, aerial train loader, aerial validation loader, best
_acc, best_model_wts, 'densenet121')
```

/usr/local/lib/python3.7/dist-packages/torch/optim/lr_scheduler.py:134: UserWarning: Dete cted call of `lr_scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later, you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step()`. Failure to do this will result in PyTorch skipping the first value of the learning r ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus t-learning-rate "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning) 0 9.705202102661133 10 1.8997547626495361 20 0.2708981931209564 Done Training Epoch: 0 Train Loss: 2.325413996210465 Test Loss: 4.114207178354263 Accuracy: 53.4653 4653465346 Saved model with accuracy: 53.4653465346 0 0.655325710773468 10 1.1922310590744019 20 0.2323516458272934 Done Training Epoch: 1 Train Loss: 0.8417523835714047 Test Loss: 1.111289491256078 Accuracy: 68.316 83168316832 Saved model with accuracy: 68.3168316832 0 0.8691451549530029 10 0.8151715993881226 20 1.1121634244918823 Done Training Epoch: 2 Train Loss: 0.8161684715977082 Test Loss: 0.7000947905083498 Accuracy: 88.11 881188118812 Saved model with accuracy: 88.1188118812 0 0.10334624350070953 10 0.4691743850708008 20 0.027096794918179512 Done Training Epoch: 3 Train Loss: 0.8315990215453964 Test Loss: 0.7349641422430674 Accuracy: 77.22 772277227723 0 0.021810298785567284 10 0.11064959317445755 20 0.9100956320762634 Done Training Epoch: 4 Train Loss: 0.5999822888093499 Test Loss: 0.4965669612089793 Accuracy: 93.06 930693069307 Saved model with accuracy: 93.06930693069307 0 0.20059028267860413 10 0.15047284960746765 20 0.5790111422538757 Done Training Epoch: 5 Train Loss: 0.22976944065437868 Test Loss: 0.2640717608543734 Accuracy: 90.0 990099009901 0 0.007777201011776924 10 0.787854790687561 20 0.142087921500206 Done Training Epoch: 6 Train Loss: 0.16637964783093104 Test Loss: 0.25434550767143566 Accuracy: 91. 08910891089108 0 0.17004606127738953 10 0.21045733988285065 20 0.1657445728778839 Done Training Epoch: 7 Train Loss: 0.1393758445046842 Test Loss: 0.3628948579231898 Accuracy: 95.04 950495049505 Saved model with accuracy: 95.04950495049505 0 0.004513930529356003 10 0.16530217230319977 20 0.031200917437672615 Done Training Epoch: 8 Train Loss: 0.13758672763092014 Test Loss: 0.20719012493888536 Accuracy: 94. 05940594059406

Done Training

Epoch: 9 Train Loss: 0.04339828609059063 Test Loss: 0.27611384928847355 Accuracy: 95.

0 0.06431688368320465 10 0.02816973254084587 20 0.005277049727737904

ShuffleNet Model Training and Validation

```
In [175]:
gpu flag = torch.cuda.is available()
#preloading Resnet18
model = models.shufflenet_v2_x1_0(pretrained = True)
#append a new last layer
model.fc = nn.Linear(1024, num classes)
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), lr=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer,5,.3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
ShuffleNetV2(
  (conv1): Sequential(
    (0): Conv2d(3, 24, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
    (1): BatchNorm2d(24, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (2): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil mode=False)
  (stage2): Sequential(
    (0): InvertedResidual(
      (branch1): Sequential (
        (0): Conv2d(24, 24, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=24,
        (1): BatchNorm2d(24, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (2): Conv2d(24, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (3): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (4): ReLU(inplace=True)
      (branch2): Sequential(
        (0): Conv2d(24, 58, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (2): ReLU(inplace=True)
        (3): Conv2d(58, 58, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=58,
bias=False)
        (4): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (5): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (7): ReLU(inplace=True)
    (1): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (2): ReLU(inplace=True)
```

```
(3): CONVZA(SO, SO, KETNEL SIZE=(S, S), SUTTAGE=(I, I), padaing=(I, I), groups=SO,
bias=False)
        (4): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (5): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (7): ReLU(inplace=True)
      )
    (2): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (2): ReLU(inplace=True)
        (3): Conv2d(58, 58, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=58,
bias=False)
        (4): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (5): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (7): ReLU(inplace=True)
      )
    )
    (3): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (2): ReLU(inplace=True)
        (3): Conv2d(58, 58, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=58,
bias=False)
        (4): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (5): Conv2d(58, 58, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(58, eps=1e-05, momentum=0.1, affine=True, track running stats=Tr
ue)
        (7): ReLU(inplace=True)
    )
  (stage3): Sequential(
    (0): InvertedResidual(
      (branch1): Sequential(
        (0): Conv2d(116, 116, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=1
16, bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (3): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (4): ReLU(inplace=True)
      )
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    )
```

```
(I): Inverteakesiauai(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    )
    (2): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential (
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    (3): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    (4): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    (5): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
```

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```
(1): Batchnorm2d(110, eps=1e-00, momentum=0.1, alline=frue, track running stats=f
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    (6): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
    (7): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(116, 116, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(116, 116, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
16, bias=False)
        (4): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(116, 116, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(116, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    )
  (stage4): Sequential(
    (0): InvertedResidual(
      (branch1): Sequential(
        (0): Conv2d(232, 232, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1), groups=2
32, bias=False)
        (1): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (3): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (4): ReLU(inplace=True)
      (branch2): Sequential(
        (0): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(232, 232, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=2
32, bias=False)
        (4): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(232, 232, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track_running_stats=T
rue)
        /7) - Datii/imalaaa_m.....
```

```
(/): KeLU(Inplace=True)
      )
    )
    (1): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track_running_stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(232, 232, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=2
32, bias=False)
        (4): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(232, 232, kernel_size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    )
    (2): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(232, 232, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=2
32, bias=False)
        (4): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
        (5): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
    )
    (3): InvertedResidual(
      (branch1): Sequential()
      (branch2): Sequential(
        (0): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (2): ReLU(inplace=True)
        (3): Conv2d(232, 232, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=2
32, bias=False)
        (4): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (5): Conv2d(232, 232, kernel size=(1, 1), stride=(1, 1), bias=False)
        (6): BatchNorm2d(232, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
        (7): ReLU(inplace=True)
      )
   )
 )
  (conv5): Sequential(
    (0): Conv2d(464, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
    (1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True
)
    (2): ReLU(inplace=True)
  (fc): Linear(in features=1024, out features=5, bias=True)
)
In [176]:
epochs=10
```

train_loss_shufflenet,test_loss_shufflenet,accuracy_shufflenet = training_and_validation_ loop(epochs,step lr scheduler,model,optimizer,aerial train loader,aerial validation loade

best_model_wts = copy.deepcopy(model.state dict())

r, best acc, best model wts, 'shufflenet')

best acc = 0.0

/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete cted call of `lr scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later, you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step()`. Failure to do this will result in PyTorch skipping the first value of the learning r ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus t-learning-rate "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning) 0 1.6033337116241455 10 1.6107604503631592 20 1.5923737287521362 Done Training Epoch: 0 Train Loss: 1.6067176919717054 Test Loss: 1.8734468420346577 Accuracy: 13.86 1386138613861 Saved model with accuracy: 13.86138613861 0 1.5837866067886353 10 1.582115650177002

20 1.582777976989746 Done Training Epoch: 1 Train Loss: 1.596213868031135 Test Loss: 1.861076295375824 Accuracy: 13.8613 86138613861 0 1.6032180786132812 10 1.5895551443099976 20 1.6050935983657837 Done Training Epoch: 2 Train Loss: 1.583980408998636 Test Loss: 1.8472758332888286 Accuracy: 31.683 168316831683 Saved model with accuracy: 31.68316831683 0 1.5536614656448364 10 1.56793212890625 20 1.5777385234832764 Done Training Epoch: 3 Train Loss: 1.570602563711313 Test Loss: 1.8322415947914124 Accuracy: 34.653 46534653465 Saved model with accuracy: 34.6534653465 0 1.564038634300232 10 1.5339574813842773 20 1.5721039772033691 Done Training Epoch: 4 Train Loss: 1.5625664316690886 Test Loss: 1.8287366429964702 Accuracy: 35.64 356435643565 Saved model with accuracy: 35.64356435643565 0 1.5709927082061768 10 1.5568150281906128 20 1.5404891967773438 Done Training Epoch: 5 Train Loss: 1.5554108161192675 Test Loss: 1.8219211896260579 Accuracy: 41.58 Saved model with accuracy: 41.584158415841586 0 1.5704905986785889 10 1.5494848489761353 20 1.5431454181671143 Done Training Epoch: 6 Train Loss: 1.5522752037415137 Test Loss: 1.8143902222315471 Accuracy: 45.54 455445544554 Saved model with accuracy: 45.54455445544554 0 1.5349936485290527 10 1.541061520576477 20 1.5467309951782227 Done Training Epoch: 7 Train Loss: 1.544596763757559 Test Loss: 1.8095630009969075 Accuracy: 44.554 455445544555 0 1.5348665714263916 10 1.5333999395370483 20 1.5395089387893677 Done Training Epoch: 8 Train Loss: 1.5413180818924537 Test Loss: 1.794878363609314 Accuracy: 47.524

752475247524

0 1.547098159790039 10 1.5344599485397339 20 1 5345213413238525

Saved model with accuracy: 47.524752475247524

```
Done Training
Epoch: 9 Train Loss: 1.5399072903853197 Test Loss: 1.795938531557719 Accuracy: 48.5148514851
Saved model with accuracy: 48.5148514851
```

SqueezeNet Model Training and Validation

```
In [179]:
gpu_flag = torch.cuda.is available()
#preloading Resnet18
model = models.squeezenet1 1(pretrained = True)
#append a new last layer
#model.fc = nn.Linear(1024, num classes)
# Freeze training for all layers
for param in model.features.parameters():
    param.require grad = False
# num_features = model.classifier[6].in features
model.classifier[1] = nn.Conv2d(512, num classes, kernel size=(1,1), stride=(1,1))
model.num classes = num classes
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), 1r=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer,5,.3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
SqueezeNet (
  (features): Sequential(
    (0): Conv2d(3, 64, kernel size=(3, 3), stride=(2, 2))
    (1): ReLU(inplace=True)
    (2): MaxPool2d(kernel size=3, stride=2, padding=0, dilation=1, ceil mode=True)
    (3): Fire(
      (squeeze): Conv2d(64, 16, kernel size=(1, 1), stride=(1, 1))
      (squeeze activation): ReLU(inplace=True)
      (expand1x1): Conv2d(16, 64, kernel_size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(16, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    (4): Fire(
      (squeeze): Conv2d(128, 16, kernel size=(1, 1), stride=(1, 1))
      (squeeze_activation): ReLU(inplace=True)
      (expand1x1): Conv2d(16, 64, kernel size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(16, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    (5): MaxPool2d(kernel size=3, stride=2, padding=0, dilation=1, ceil mode=True)
    (6): Fire(
      (squeeze): Conv2d(128, 32, kernel_size=(1, 1), stride=(1, 1))
      (squeeze_activation): ReLU(inplace=True)
      (expand1x1): Conv2d(32, 128, kernel size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(32, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
```

```
(7): Fire(
      (squeeze): Conv2d(256, 32, kernel size=(1, 1), stride=(1, 1))
      (squeeze_activation): ReLU(inplace=True)
      (expand1x1): Conv2d(32, 128, kernel size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(32, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    (8): MaxPool2d(kernel size=3, stride=2, padding=0, dilation=1, ceil mode=True)
    (9): Fire(
      (squeeze): Conv2d(256, 48, kernel size=(1, 1), stride=(1, 1))
      (squeeze activation): ReLU(inplace=True)
      (expand1x1): Conv2d(48, 192, kernel_size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(48, 192, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    (10): Fire(
      (squeeze): Conv2d(384, 48, kernel size=(1, 1), stride=(1, 1))
      (squeeze activation): ReLU(inplace=True)
      (expand1x1): Conv2d(48, 192, kernel_size=(1, 1), stride=(1, 1))
      (expand1x1_activation): ReLU(inplace=True)
      (expand3x3): Conv2d(48, 192, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    (11): Fire(
      (squeeze): Conv2d(384, 64, kernel size=(1, 1), stride=(1, 1))
      (squeeze_activation): ReLU(inplace=True)
      (expand1x1): Conv2d(64, 256, kernel_size=(1, 1), stride=(1, 1))
      (expand1x1_activation): ReLU(inplace=True)
      (expand3x3): Conv2d(64, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3 activation): ReLU(inplace=True)
    )
    (12): Fire(
      (squeeze): Conv2d(512, 64, kernel size=(1, 1), stride=(1, 1))
      (squeeze activation): ReLU(inplace=True)
      (expand1x1): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1))
      (expand1x1 activation): ReLU(inplace=True)
      (expand3x3): Conv2d(64, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
      (expand3x3_activation): ReLU(inplace=True)
   )
  )
  (classifier): Sequential(
    (0): Dropout(p=0.5, inplace=False)
    (1): Conv2d(512, 5, kernel size=(1, 1), stride=(1, 1))
    (2): ReLU(inplace=True)
    (3): AdaptiveAvgPool2d(output size=(1, 1))
In [180]:
epochs=10
best model wts = copy.deepcopy(model.state dict())
best acc = 0.0
train loss squeezenet, test loss squeezenet, accuracy squeezenet = training and validation
loop(epochs, step lr scheduler, model, optimizer, aerial train loader, aerial validation loade
r, best acc, best model wts, 'squeezenet')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
cted call of `lr_scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step(
)`. Failure to do this will result in PyTorch skipping the first value of the learning r
ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus
t-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
0 1.7215379476547241
10 1.6010282039642334
```

)

20 1.4354884624481201

Done Training

```
Epoch: 0 Train Loss: 1.4422244085715368 Test Loss: 1.635127862294515 Accuracy: 35.643
56435643565
Saved model with accuracy: 35.6435643565
0 1.3008087873458862
10 1.2585126161575317
20 0.783483624458313
Done Training
Epoch: 1 Train Loss: 1.208700737127891 Test Loss: 1.1290804743766785 Accuracy: 53.465
34653465346
Saved model with accuracy: 53.4653465346
0 1.0218905210494995
10 1.1352678537368774
20 1.1979849338531494
Done Training
Epoch: 2 Train Loss: 1.0654778755628145 Test Loss: 1.1282269656658173 Accuracy: 63.36
6336633663366
Saved model with accuracy: 63.366336633663366
0 0.9712321162223816
10 1.3727526664733887
20 1.3082871437072754
Done Training
Epoch: 3 Train Loss: 1.1262206114255464 Test Loss: 0.9444511830806732 Accuracy: 73.26
732673267327
Saved model with accuracy: 73.26732673267327
0 1.116815209388733
10 0.6448909044265747
20 0.477353572845459
Done Training
Epoch: 4 Train Loss: 0.812299424639115 Test Loss: 0.7945498277743658 Accuracy: 77.227
72277227723
Saved model with accuracy: 77.2277227723
0 0.9044416546821594
10 0.43160927295684814
20 0.6947808861732483
Done Training
Epoch: 5 Train Loss: 0.6539827894705993 Test Loss: 0.7696951727072397 Accuracy: 78.21
782178217822
Saved model with accuracy: 78.2178217822
0 0.3752029538154602
10 0.5891660451889038
20 0.291564404964447
Done Training
Epoch: 6 Train Loss: 0.5745096917335804 Test Loss: 0.45032640794912976 Accuracy: 86.1
3861386138613
Saved model with accuracy: 86.13861386138613
0 0.5270010232925415
10 0.46165716648101807
20 0.6236396431922913
Done Training
Epoch: 7 Train Loss: 0.522449747301065 Test Loss: 0.5495490295191606 Accuracy: 79.207
92079207921
0 0.3170940577983856
10 0.47029057145118713
20 0.3927542567253113
Done Training
Epoch: 8 Train Loss: 0.45165283060990846 Test Loss: 0.4318101741373539 Accuracy: 87.1
2871287128714
Saved model with accuracy: 87.1287128714
0 0.2743155360221863
10 0.22817355394363403
20 0.473066121339798
Done Training
Epoch: 9 Train Loss: 0.3533420834976893 Test Loss: 0.45879171291987103 Accuracy:
```

Mobilenet-V3 Model Training and Validation

In [183]:

```
#preloading Resnet18
model = models.mobilenet v3 large(pretrained = True)
#append a new last layer
# Freeze training for all layers
for param in model.features.parameters():
    param.require grad = False
model.classifier[3] = nn.Linear(1280, num classes)
# num features = model.classifier[6].in features
\# model.classifier[1] = nn.Conv2d(512, num classes, kernel size=(1,1), stride=(1,1))
#model.num classes = num classes
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), 1r=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer,5,.3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
MobileNetV3(
  (features): Sequential(
    (0): ConvBNActivation(
      (0): Conv2d(3, 16, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
      (1): BatchNorm2d(16, eps=0.001, momentum=0.01, affine=True, track running stats=Tru
e)
      (2): Hardswish()
    (1): InvertedResidual(
      (block): Sequential (
        (0): ConvBNActivation(
          (0): Conv2d(16, 16, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=1
6, bias=False)
          (1): BatchNorm2d(16, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        (1): ConvBNActivation(
          (0): Conv2d(16, 16, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(16, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (2): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(16, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(64, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        (1): ConvBNActivation(
          (0): Conv2d(64, 64, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups=6
4, bias=False)
          (1): BatchNorm2d(64, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        (2): ConvBNActivation(
```

```
(0): Conv2d(64, 24, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(24, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (3): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(24, 72, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(72, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        (1): ConvBNActivation(
          (0): Conv2d(72, 72, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups=7
2. bias=False)
          (1): BatchNorm2d(72, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        )
        (2): ConvBNActivation(
          (0): Conv2d(72, 24, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(24, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (4): InvertedResidual(
      (block): Sequential (
        (0): ConvBNActivation(
          (0): Conv2d(24, 72, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(72, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        (1): ConvBNActivation(
          (0): Conv2d(72, 72, kernel_size=(5, 5), stride=(2, 2), padding=(2, 2), groups=7
2, bias=False)
          (1): BatchNorm2d(72, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): ReLU(inplace=True)
        )
        (2): SqueezeExcitation(
          (fc1): Conv2d(72, 24, kernel_size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(24, 72, kernel_size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(72, 40, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(40, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (5): InvertedResidual(
      (block): Sequential (
        (0): ConvBNActivation(
          (0): Conv2d(40, 120, kernel_size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(120, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): ReLU(inplace=True)
        (1): ConvBNActivation(
          (0): Conv2d(120, 120, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), groups
=120, bias=False)
          (1): BatchNorm2d(120, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): ReLU(inplace=True)
```

```
)
        (2): SqueezeExcitation(
          (fc1): Conv2d(120, 32, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(32, 120, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(120, 40, kernel_size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(40, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    )
    (6): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(40, 120, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(120, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): ReLU(inplace=True)
        )
        (1): ConvBNActivation(
          (0): Conv2d(120, 120, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), groups
=120, bias=False)
          (1): BatchNorm2d(120, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): ReLU(inplace=True)
        (2): SqueezeExcitation(
          (fc1): Conv2d(120, 32, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(32, 120, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(120, 40, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(40, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (7): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(40, 240, kernel\_size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(240, eps=0.001, momentum=0.01, affine=True, track_running_stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(240, 240, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups
=240, bias=False)
          (1): BatchNorm2d(240, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        )
        (2): ConvBNActivation(
          (0): Conv2d(240, 80, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(80, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (8): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(80, 200, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(200, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
```

```
)
        (1): ConvBNActivation(
          (0): Conv2d(200, 200, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=200, bias=False)
          (1): BatchNorm2d(200, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): ConvBNActivation(
          (0): Conv2d(200, 80, kernel_size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(80, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (9): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(80, 184, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(184, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(184, 184, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=184, bias=False)
          (1): BatchNorm2d(184, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): ConvBNActivation(
          (0): Conv2d(184, 80, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(80, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
        )
      )
    (10): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(80, 184, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(184, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        )
        (1): ConvBNActivation(
          (0): Conv2d(184, 184, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=184, bias=False)
          (1): BatchNorm2d(184, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): ConvBNActivation(
          (0): Conv2d(184, 80, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(80, eps=0.001, momentum=0.01, affine=True, track running stats
=True)
          (2): Identity()
    (11): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(80, 480, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(480, eps=0.001, momentum=0.01, affine=True, track_running_stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(480, 480, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
```

```
=480, bias=False)
          (1): BatchNorm2d(480, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): SqueezeExcitation(
          (fc1): Conv2d(480, 120, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(120, 480, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(480, 112, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(112, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Identity()
        )
      )
    (12): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(112, 672, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(672, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(672, 672, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=672, bias=False)
          (1): BatchNorm2d(672, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): SqueezeExcitation(
          (fc1): Conv2d(672, 168, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(168, 672, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(672, 112, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(112, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Identity()
        )
      )
    )
    (13): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(112, 672, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(672, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(672, 672, kernel size=(5, 5), stride=(2, 2), padding=(2, 2), groups
=672, bias=False)
          (1): BatchNorm2d(672, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): SqueezeExcitation(
          (fc1): Conv2d(672, 168, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(168, 672, kernel_size=(1, 1), stride=(1, 1))
        )
        (3): ConvBNActivation(
          (0): Conv2d(672, 160, kernel_size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(160, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Identity()
        )
```

```
)
    )
    (14): InvertedResidual(
      (block): Sequential (
        (0): ConvBNActivation(
          (0): Conv2d(160, 960, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(960, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (1): ConvBNActivation(
          (0): Conv2d(960, 960, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), groups
=960, bias=False)
          (1): BatchNorm2d(960, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        (2): SqueezeExcitation(
          (fc1): Conv2d(960, 240, kernel size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(240, 960, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(960, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(160, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Identity()
        )
      )
    (15): InvertedResidual(
      (block): Sequential(
        (0): ConvBNActivation(
          (0): Conv2d(160, 960, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(960, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        )
        (1): ConvBNActivation(
          (0): Conv2d(960, 960, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), groups
=960, bias=False)
          (1): BatchNorm2d(960, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Hardswish()
        )
        (2): SqueezeExcitation(
          (fc1): Conv2d(960, 240, kernel_size=(1, 1), stride=(1, 1))
          (relu): ReLU(inplace=True)
          (fc2): Conv2d(240, 960, kernel size=(1, 1), stride=(1, 1))
        (3): ConvBNActivation(
          (0): Conv2d(960, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
          (1): BatchNorm2d(160, eps=0.001, momentum=0.01, affine=True, track running stat
s=True)
          (2): Identity()
        )
      )
    (16): ConvBNActivation(
      (0): Conv2d(160, 960, kernel size=(1, 1), stride=(1, 1), bias=False)
      (1): BatchNorm2d(960, eps=0.001, momentum=0.01, affine=True, track running stats=Tr
ue)
      (2): Hardswish()
  (avgpool): AdaptiveAvgPool2d(output size=1)
  (classifier): Sequential(
    (0): Linear(in_features=960, out_features=1280, bias=True)
    (1): Hardswish()
    (2): Dropout (p=0.2, inplace=True)
    (3): Linear(in features=1280, out features=5, bias=True)
 )
```

```
In [184]:
epochs=10
best model wts = copy.deepcopy(model.state dict())
best acc = 0.0
train loss mobilenetv3, test loss mobilenetv3, accuracy mobilenetv3 = training and validati
on loop(epochs, step lr scheduler, model, optimizer, aerial train loader, aerial validation lo
ader,best acc,best model wts,'mobilenetv3')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr_scheduler.py:134: UserWarning: Dete
cted call of `lr scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step(
)`. Failure to do this will result in PyTorch skipping the first value of the learning r
ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus
t-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
0 1.6962727308273315
10 0.9379370808601379
20 0.5122504830360413
Done Training
Epoch: 0 Train Loss: 0.9164435823376362 Test Loss: 1.0266722242037456 Accuracy: 66.33
663366336634
Saved model with accuracy: 66.33663366336634
0 0.36596229672431946
10 0.2600838541984558
20 0.3212284445762634
Done Training
Epoch: 1 Train Loss: 0.22065730765461922 Test Loss: 0.6730715930461884 Accuracy: 77.2
2772277227723
Saved model with accuracy: 77.2277227723
0 0.10982154309749603
10 0.09889861196279526
20 0.004817329812794924
Done Training
Epoch: 2 Train Loss: 0.10280085442802654 Test Loss: 0.4956468492746353 Accuracy: 79.2
0792079207921
Saved model with accuracy: 79.2079207921
0 0.023399077355861664
10 0.042387496680021286
20 0.17555740475654602
Done Training
Epoch: 3 Train Loss: 0.09921029331878974 Test Loss: 0.45173787077267963 Accuracy: 86.
13861386138613
Saved model with accuracy: 86.13861386138613
0 0.004938613623380661
10 0.060320060700178146
20 0.05156673863530159
Done Training
Epoch: 4 Train Loss: 0.0688504070813696 Test Loss: 0.3266122452914715 Accuracy: 90.09
90099009901
Saved model with accuracy: 90.0990099009901
0 0.04229728505015373
10 0.24877209961414337
20 0.010873413644731045
Done Training
Epoch: 5 Train Loss: 0.06131853037871993 Test Loss: 0.25344367573658627 Accuracy: 95.
04950495049505
Saved model with accuracy: 95.04950495049505
0 0.017235731706023216
10 0.005363339092582464
20 0.0073574078269302845
Done Training
Epoch: 6 Train Loss: 0.06692946499858338 Test Loss: 0.3183552209908764 Accuracy: 96.0
3960396039604
Saved model with accuracy: 96.03960396039604
0 0.01606336049735546
10 0.02280532568693161
20 0.12902143597602844
```

7 m---- 0 0/020/50010/0000/5 m--- 0 1700/5/00050/2/10 7-----

)

Done Training

Decade .

Resnext50 Model Training and Validation

```
In [188]:
gpu flag = torch.cuda.is available()
#preloading Resnet18
model = models.resnext50 32x4d(pretrained = True)
#append a new last layer
# Freeze training for all layers
#for param in model.features.parameters():
  param.require grad = False
model.fc = nn.Linear(2048, num classes)
# num features = model.classifier[6].in features
\# model.classifier[1] = nn.Conv2d(512, num classes, kernel size=(1,1), stride=(1,1))
#model.num classes = num classes
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), lr=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer, 5, .3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
ResNet (
  (conv1): Conv2d(3, 64, kernel_size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil mode=False)
  (layer1): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(64, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=T
rue)
      (conv3): Conv2d(128, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (1) · Conv2d(64 256 kernel size=(1 1) stride=(1 1) hias=False)
```

```
(U). CONVERTOR, 200, ROTHOL DIEC (1, 1,, DOLLAG (1, 1,, DIAD LALDO)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
    (1): Bottleneck(
      (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(128, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    )
  )
  (layer2): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(256, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
    (1): Bottleneck(
      (conv1): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    )
    (2): Bottleneck(
      (conv1): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3) · Conv2d(256 512 kernel size=(1 1) stride=(1 1) hias=False)
```

```
(CONVO). CONVER(200, SIE, RETHOT_SIEC (I, I), SCHICK (I, I), SIEC LATEC.)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    (3): Bottleneck(
      (conv1): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(256, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (relu): ReLU(inplace=True)
    )
  )
  (layer3): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(512, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(512, 1024, kernel_size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track_running_stats=
True)
    (1): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
    (2): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
    (3): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3) · Conv2d(512 1024 kernel size=(1 1) stride=(1 1) hias=False)
```

```
(CONVO). CONVERTOR, TOE1, ACTUAL_CIEC (I, I), CONTACT (I, I), STAD TATOC,
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    (4): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
    (5): Bottleneck(
      (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), groups
=32, bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=T
rue)
      (conv3): Conv2d(512, 1024, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
  )
  (layer4): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(1024, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv2): Conv2d(1024, 1024, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), grou
ps=32, bias=False)
      (bn2): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv3): Conv2d(1024, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(1024, 2048, kernel size=(1, 1), stride=(2, 2), bias=False)
        (1): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
    (1): Bottleneck(
      (conv1): Conv2d(2048, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv2): Conv2d(1024, 1024, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), grou
ps=32, bias=False)
      (bn2): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv3): Conv2d(1024, 2048, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
    )
    (2): Bottleneck(
      (conv1): Conv2d(2048, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv2): Conv2d(1024, 1024, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), grou
ps=32, bias=False)
      (bn2): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (conv3) · Conv2d(1024 2048 kernel size=(1 1) stride=(1 1) bias=False)
```

```
(CONVO). CONVER(1021, 2010, ACTION_DIEC (1, 1), CONTROL (1, 1), DEAD TRADE(
      (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=
True)
      (relu): ReLU(inplace=True)
   )
  )
  (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
  (fc): Linear(in features=2048, out features=5, bias=True)
In [189]:
epochs=10
best model wts = copy.deepcopy(model.state dict())
best acc = 0.0
train loss resnext50, test loss resnext50, accuracy resnext50 = training and validation loo
p(epochs, step lr scheduler, model, optimizer, aerial train loader, aerial validation loader, b
est acc,best model wts,'resnext50')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
cted call of `lr_scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step(
)`. Failure to do this will result in PyTorch skipping the first value of the learning r
ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus
t-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
0 1.6011916399002075
10 1.0162638425827026
20 0.2314624786376953
Done Training
Epoch: 0 Train Loss: 0.9264364407326167 Test Loss: 0.3514340395728747 Accuracy: 92.07
920792079207
Saved model with accuracy: 92.07920792079207
0 0.1070927232503891
10 0.19874049723148346
20 0.017556529492139816
Epoch: 1 Train Loss: 0.2772250609436574 Test Loss: 1.289975549094379 Accuracy: 89.108
91089108911
0 0.28347036242485046
10 0.08403738588094711
20 0.9381603598594666
Done Training
Epoch: 2 Train Loss: 0.5000027325004339 Test Loss: 0.5131245429317156 Accuracy: 88.11
881188118812
0 0.7235650420188904
10 0.15493351221084595
20 0.6514920592308044
Done Training
Epoch: 3 Train Loss: 0.5695049930363894 Test Loss: 0.6332099844391147 Accuracy: 83.16
831683168317
0 0.04096861183643341
10 0.1745675653219223
20 1.43146812915802
Done Training
Epoch: 4 Train Loss: 0.267289810670683 Test Loss: 0.10521493883182605 Accuracy: 96.03
960396039604
Saved model with accuracy: 96.03960396039604
0 0.07244125008583069
10 0.1705205738544464
20 0.02601541578769684
Done Training
Epoch: 5 Train Loss: 0.128083876781882 Test Loss: 0.1065621489348511 Accuracy: 97.029
70297029702
Saved model with accuracy: 97.02970297029702
0 0.009709823876619339
10 0.11867626011371613
20 0.04265532270073891
Done Training
Epoch: 6 Train Loss: 0.08838373793360706 Test Loss: 0.11272055958397686 Accuracy: 95.
04950495049505
0 0.0171968974173069
```

```
10 0.015890110284090042
20 0.09912033379077911
Done Training
Epoch: 7 Train Loss: 0.1321186474703539 Test Loss: 0.09160041188200314 Accuracy: 97.0
2970297029702
0 0.16895270347595215
10 0.0885232612490654
20 0.02021438628435135
Done Training
Epoch: 8 Train Loss: 0.0989963800753825 Test Loss: 0.10930849860111873 Accuracy: 98.0
1980198019803
Saved model with accuracy: 98.01980198019803
0 0.06568863242864609
10 0.019072074443101883
20 0.0017813225276768208
Done Training
Epoch: 9 Train Loss: 0.06514420984491992 Test Loss: 0.07508201338350773 Accuracy: 96.
03960396039604
In [218]:
#Pre processing the data
normalize = transforms.Normalize(mean = [0.485, 0.456, 0.406],
                               std = [0.229, 0.224, 0.225])
resize = transforms.Resize((299,299))
preprocessor = transforms.Compose([ resize, transforms.ToTensor(), normalize
aerial dataset full = get sat data(aerial path,preprocessor)
# Creating data indices for training and validation splits:
dataset size = len(aerial dataset full)
indices = list(range(dataset size))
validation split = 0.2
split = int(np.floor(validation split * dataset size))
shuffle dataset = True
random seed= 101
if shuffle dataset :
   np.random.seed(random seed)
   np.random.shuffle(indices)
train_indices, val_indices = indices[split:], indices[:split]
# Creating PT data samplers and loaders:
train sampler = SubsetRandomSampler(train indices)
valid sampler = SubsetRandomSampler(val indices)
aerial train loader = torch.utils.data.DataLoader(aerial dataset full, batch size=16,
                                          sampler=train sampler)
aerial validation loader = torch.utils.data.DataLoader(aerial dataset full, batch size=16
                                                sampler=valid sampler)
gpu flag = torch.cuda.is available()
#preloading Resnet18
```

model = models.inception v3(pretrained = True)

num features = model.classifier[6].in features

#for param in model.features.parameters():

model.fc = nn.Linear(2048, num classes)

#append a new last layer

Freeze training for all layers

param.require grad = False

```
#model.classifier[1] = nn.Conv2d(512, num_classes, kernel_size=(1,1), stride=(1,1))
#model.num_classes = num_classes
model.aux logits=False
# define loss function
criterion = nn.CrossEntropyLoss()
# setup SGD
optimizer = torch.optim.SGD(model.parameters(), 1r=0.004, momentum=0.9)
step lr scheduler = lr scheduler.StepLR(optimizer, 5, .3)
gpu flag = torch.cuda.is available()
print(gpu flag)
if gpu flag:
    model = model.cuda()
print (model)
True
Inception3(
  (Conv2d 1a 3x3): BasicConv2d(
    (conv): Conv2d(3, 32, kernel size=(3, 3), stride=(2, 2), bias=False)
    (bn): BatchNorm2d(32, eps=0.001, momentum=0.1, affine=True, track running stats=True)
  (Conv2d_2a_3x3): BasicConv2d(
    (conv): Conv2d(32, 32, kernel size=(3, 3), stride=(1, 1), bias=False)
    (bn): BatchNorm2d(32, eps=0.001, momentum=0.1, affine=True, track running stats=True)
  (Conv2d 2b 3x3): BasicConv2d(
    (conv): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=True)
  (maxpool1): MaxPool2d(kernel size=3, stride=2, padding=0, dilation=1, ceil mode=False)
  (Conv2d 3b 1x1): BasicConv2d(
    (conv): Conv2d(64, 80, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn): BatchNorm2d(80, eps=0.001, momentum=0.1, affine=True, track running stats=True)
  (Conv2d 4a 3x3): BasicConv2d(
    (conv): Conv2d(80, 192, kernel_size=(3, 3), stride=(1, 1), bias=False)
    (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=True
)
  (maxpool2): MaxPool2d(kernel size=3, stride=2, padding=0, dilation=1, ceil mode=False)
  (Mixed 5b): InceptionA(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(192, 64, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 1): BasicConv2d(
      (conv): Conv2d(192, 48, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(48, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 2): BasicConv2d(
      (conv): Conv2d(48, 64, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), bias=Fals
e)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl_1): BasicConv2d(
      (conv): Conv2d(192, 64, kernel\_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(64, 96, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
```

```
(branch3x3dbl 3): BasicConv2d(
      (conv): Conv2d(96, 96, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch pool): BasicConv2d(
      (conv): Conv2d(192, 32, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(32, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
  )
  (Mixed 5c): InceptionA(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 1): BasicConv2d(
      (conv): Conv2d(256, 48, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(48, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 2): BasicConv2d(
      (conv): Conv2d(48, 64, kernel size=(5, 5), stride=(1, 1), padding=(2, 2), bias=Fals
e)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 1): BasicConv2d(
      (conv): Conv2d(256, 64, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(64, 96, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 3): BasicConv2d(
      (conv): Conv2d(96, 96, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch_pool): BasicConv2d(
      (conv): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
  )
  (Mixed 5d): InceptionA(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(288, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 1): BasicConv2d(
      (conv): Conv2d(288, 48, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(48, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch5x5 2): BasicConv2d(
      (conv): Conv2d(48, 64, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2), bias=Fals
e)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 1): BasicConv2d(
      (conv): Conv2d(288, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
```

```
e)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(64, 96, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 3): BasicConv2d(
      (conv): Conv2d(96, 96, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch pool): BasicConv2d(
      (conv): Conv2d(288, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
  )
  (Mixed 6a): InceptionB(
    (branch3x3): BasicConv2d(
      (conv): Conv2d(288, 384, kernel size=(3, 3), stride=(2, 2), bias=False)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 1): BasicConv2d(
      (conv): Conv2d(288, 64, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(64, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(64, 96, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fals
e)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
    (branch3x3dbl 3): BasicConv2d(
      (conv): Conv2d(96, 96, kernel size=(3, 3), stride=(2, 2), bias=False)
      (bn): BatchNorm2d(96, eps=0.001, momentum=0.1, affine=True, track running stats=Tru
e)
  (Mixed 6b): InceptionC(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 1): BasicConv2d(
      (conv): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 2): BasicConv2d(
      (conv): Conv2d(128, 128, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 3): BasicConv2d(
      (conv): Conv2d(128, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 1): BasicConv2d(
      (conv): Conv2d(768, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 2): BasicConv2d(
```

```
(conv): Conv2d(128, 128, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 3): BasicConv2d(
      (conv): Conv2d(128, 128, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 4): BasicConv2d(
      (conv): Conv2d(128, 128, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 5): BasicConv2d(
      (conv): Conv2d(128, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch pool): BasicConv2d(
      (conv): Conv2d(768, 192, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
  (Mixed 6c): InceptionC(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 1): BasicConv2d(
      (conv): Conv2d(768, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 2): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7_3): BasicConv2d(
      (conv): Conv2d(160, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 1): BasicConv2d(
      (conv): Conv2d(768, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
11e)
    (branch7x7dbl 2): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 3): BasicConv2d(
      (conv): Conv2d(160, 160, kernel_size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 4): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
```

```
(bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 5): BasicConv2d(
      (conv): Conv2d(160, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch_pool): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
  )
  (Mixed 6d): InceptionC(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 1): BasicConv2d(
      (conv): Conv2d(768, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 2): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 3): BasicConv2d(
      (conv): Conv2d(160, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
11e)
    (branch7x7dbl 1): BasicConv2d(
      (conv): Conv2d(768, 160, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 2): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 3): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 4): BasicConv2d(
      (conv): Conv2d(160, 160, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(160, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 5): BasicConv2d(
      (conv): Conv2d(160, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch pool): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
```

```
)
  (Mixed 6e): InceptionC(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 2): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7 3): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 2): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 3): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 4): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7dbl 5): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch pool): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
  )
  (AuxLogits): InceptionAux(
    (conv0): BasicConv2d(
      (conv): Conv2d(768, 128, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(128, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (conv1): BasicConv2d(
      (conv): Conv2d(128, 768, kernel_size=(5, 5), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(768, eps=0.001, momentum=0.1, affine=True, track_running_stats=Tr
ue)
    (fc): Linear(in features=768, out features=1000, bias=True)
  )
```

```
(Mixed 7a): InceptionD(
    (branch3x3 1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3_2): BasicConv2d(
      (conv): Conv2d(192, 320, kernel size=(3, 3), stride=(2, 2), bias=False)
      (bn): BatchNorm2d(320, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7x3 1): BasicConv2d(
      (conv): Conv2d(768, 192, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7x3 2): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(1, 7), stride=(1, 1), padding=(0, 3), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch7x7x3 3): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(7, 1), stride=(1, 1), padding=(3, 0), bias=Fa
lse)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track_running_stats=Tr
ue)
    (branch7x7x3 4): BasicConv2d(
      (conv): Conv2d(192, 192, kernel size=(3, 3), stride=(2, 2), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
  )
  (Mixed 7b): InceptionE(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(1280, 320, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(320, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3 1): BasicConv2d(
      (conv): Conv2d(1280, 384, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3_2a): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(1, 3), stride=(1, 1), padding=(0, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3 2b): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(3, 1), stride=(1, 1), padding=(1, 0), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
110)
    (branch3x3dbl 1): BasicConv2d(
      (conv): Conv2d(1280, 448, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(448, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(448, 384, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 3a): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(1, 3), stride=(1, 1), padding=(0, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
```

```
ue)
    (branch3x3dbl 3b): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(3, 1), stride=(1, 1), padding=(1, 0), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch_pool): BasicConv2d(
      (conv): Conv2d(1280, 192, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    )
  )
  (Mixed 7c): InceptionE(
    (branch1x1): BasicConv2d(
      (conv): Conv2d(2048, 320, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(320, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
11e)
    (branch3x3 1): BasicConv2d(
      (conv): Conv2d(2048, 384, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3_2a): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(1, 3), stride=(1, 1), padding=(0, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3 2b): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(3, 1), stride=(1, 1), padding=(1, 0), bias=Fa
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 1): BasicConv2d(
      (conv): Conv2d(2048, 448, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(448, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 2): BasicConv2d(
      (conv): Conv2d(448, 384, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 3a): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(1, 3), stride=(1, 1), padding=(0, 1), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch3x3dbl 3b): BasicConv2d(
      (conv): Conv2d(384, 384, kernel size=(3, 1), stride=(1, 1), padding=(1, 0), bias=Fa
lse)
      (bn): BatchNorm2d(384, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    (branch pool): BasicConv2d(
      (conv): Conv2d(2048, 192, kernel_size=(1, 1), stride=(1, 1), bias=False)
      (bn): BatchNorm2d(192, eps=0.001, momentum=0.1, affine=True, track running stats=Tr
ue)
    )
  (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
  (dropout): Dropout(p=0.5, inplace=False)
  (fc): Linear(in features=2048, out features=5, bias=True)
```

In [219]:

```
epochs=10
best model wts = copy.deepcopy(model.state dict())
best_acc = 0.0
train loss inceptionv3, test loss inceptionv3, accuracy inceptionv3= training and validatio
n loop(epochs, step lr scheduler, model, optimizer, aerial train loader, aerial validation loa
der, best acc, best model wts, 'inceptionv3')
/usr/local/lib/python3.7/dist-packages/torch/optim/lr scheduler.py:134: UserWarning: Dete
cted call of `lr_scheduler.step()` before `optimizer.step()`. In PyTorch 1.1.0 and later,
you should call them in the opposite order: `optimizer.step()` before `lr scheduler.step(
)`. Failure to do this will result in PyTorch skipping the first value of the learning r
ate schedule. See more details at https://pytorch.org/docs/stable/optim.html#how-to-adjus
t-learning-rate
  "https://pytorch.org/docs/stable/optim.html#how-to-adjust-learning-rate", UserWarning)
0 1.694513201713562
10 1.0917048454284668
20 0.49491679668426514
Done Training
Epoch: 0 Train Loss: 1.0073338030622556 Test Loss: 0.3565973962346713 Accuracy: 91.08
910891089108
Saved model with accuracy: 91.08910891089108
0 0.520588755607605
10 0.2112034410238266
20 0.060612358152866364
Done Training
Epoch: 1 Train Loss: 0.3076208070493661 Test Loss: 0.54404117166996 Accuracy: 85.1485
1485148515
0 0.41368117928504944
10 0.42476990818977356
20 0.5938020944595337
Done Training
Epoch: 2 Train Loss: 0.4169445474847005 Test Loss: 0.5692161619663239 Accuracy: 84.15
841584158416
0 0.5391332507133484
10 0.10983309149742126
20 0.6402960419654846
Done Training
Epoch: 3 Train Loss: 0.34146898268507075 Test Loss: 0.29244164874156314 Accuracy: 94.
05940594059406
Saved model with accuracy: 94.05940594059406
0 0.020844949409365654
10 0.24728870391845703
20 0.08756891638040543
Done Training
Epoch: 4 Train Loss: 0.21987662808253214 Test Loss: 0.13971334944168726 Accuracy: 98.
01980198019803
Saved model with accuracy: 98.0198019803
0 0.09229560941457748
10 0.1156827062368393
20 0.07667431980371475
Done Training
Epoch: 5 Train Loss: 0.1309989677527203 Test Loss: 0.08099470722178619 Accuracy: 97.0
2970297029702
0 0.019800426438450813
10 0.00872484128922224
20 0.0453021377325058
Done Training
Epoch: 6 Train Loss: 0.1386321228212462 Test Loss: 0.09129184950143099 Accuracy: 97.0
2970297029702
0 0.044308796525001526
10 0.05256880074739456
20 0.018832072615623474
Done Training
Epoch: 7 Train Loss: 0.0753283197633349 Test Loss: 0.09106522053480148 Accuracy: 98.0
1980198019803
0 0.020167671144008636
10 0.12418577075004578
20 0.03628227487206459
Done Training
Epoch: 8 Train Loss: 0.08867174145192482 Test Loss: 0.07429948410329719 Accuracy: 98.
```

01000100010002

```
0 0.008196840062737465

10 0.2795017659664154

20 0.09500784426927567

Done Training

Epoch: 9 Train Loss: 0.09433283988171472 Test Loss: 0.0757292954561611 Accuracy: 99.0

0990099009901

Saved model with accuracy: 99.00990099009
```

Accuracy Plot vs Epochs for All Models

```
In [220]:
```

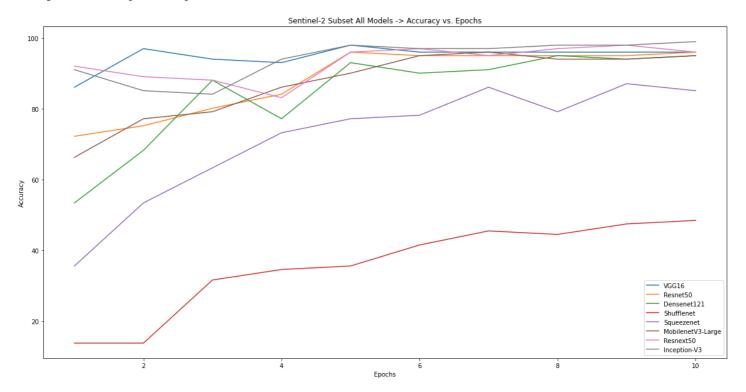
```
list_epochs = [i+1 for i in range(10)]
plt.figure(figsize = (20,10))

plt.plot(list_epochs,accuracy_vgg,label='VGG16')
plt.plot(list_epochs,accuracy_resnet,label='Resnet50')
plt.plot(list_epochs,accuracy_densenet,label='Densenet121')
plt.plot(list_epochs,accuracy_shufflenet,label='Shufflenet')
plt.plot(list_epochs,accuracy_squeezenet,label='Squeezenet')
plt.plot(list_epochs,accuracy_mobilenetv3,label='Mobilenetv3-Large')
plt.plot(list_epochs,accuracy_resnext50,label='Resnext50')
plt.plot(list_epochs,accuracy_inceptionv3,label='Inception-V3')

plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.title('Sentinel-2 Subset All Models -> Accuracy vs. Epochs')
plt.legend()
```

Out[220]:

<matplotlib.legend.Legend at 0x7f141185fd90>



Training Loss Plot vs Epochs for All Models

```
In [221]:
```

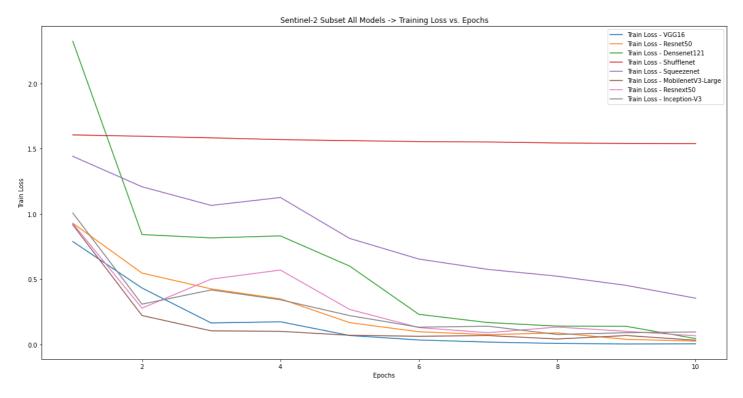
```
plt.figure(figsize = (20,10))
```

```
plt.plot(list_epochs, train_loss_vgg, label='Train Loss - VGG16')
plt.plot(list_epochs, train_loss_resnet, label='Train Loss - Resnet50')
plt.plot(list_epochs, train_loss_densenet, label='Train Loss - Densenet121')
plt.plot(list_epochs, train_loss_shufflenet, label='Train Loss - Shufflenet')
plt.plot(list_epochs, train_loss_squeezenet, label='Train Loss - Squeezenet')
plt.plot(list_epochs, train_loss_mobilenetv3, label='Train Loss - Mobilenetv3-Large')
plt.plot(list_epochs, train_loss_resnext50, label='Train Loss - Resnext50')
plt.plot(list_epochs, train_loss_inceptionv3, label='Train Loss - Inception-V3')

plt.xlabel('Epochs')
plt.ylabel('Train Loss')
plt.title('Sentinel-2 Subset All Models -> Training Loss vs. Epochs')
plt.legend()
```

Out[221]:

<matplotlib.legend.Legend at 0x7f108dfbba50>



Test Loss Plot vs Epochs for All Models

```
In [222]:
```

```
plt.figure(figsize = (20,10))

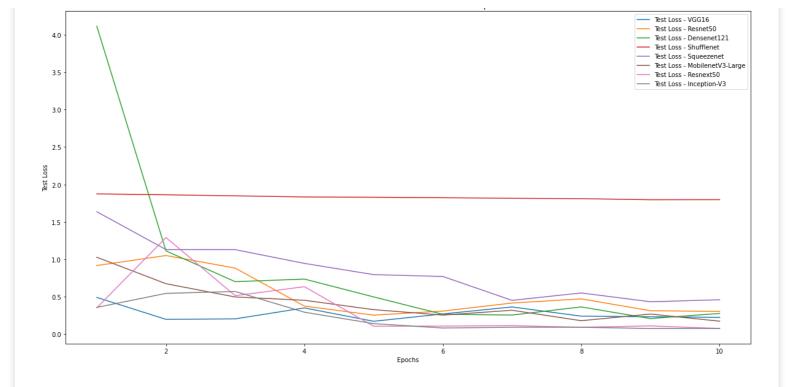
plt.plot(list_epochs,test_loss_vgg,label='Test Loss - VGG16')
plt.plot(list_epochs,test_loss_resnet,label='Test Loss - Resnet50')
plt.plot(list_epochs,test_loss_densenet,label='Test Loss - Densenet121')
plt.plot(list_epochs,test_loss_shufflenet,label='Test Loss - Shufflenet')
plt.plot(list_epochs,test_loss_squeezenet,label='Test Loss - Squeezenet')
plt.plot(list_epochs,test_loss_mobilenetv3,label='Test Loss - Mobilenetv3-Large')
plt.plot(list_epochs,test_loss_resnext50,label='Test Loss - Resnext50')
plt.plot(list_epochs,test_loss_inceptionv3,label='Test Loss - Inception-V3')

plt.xlabel('Epochs')
plt.ylabel('Test Loss')
plt.title('Sentinel-2 Subset All Models -> Test Loss vs. Epochs')

plt.legend()
```

Out[222]:

<matplotlib.legend.Legend at 0x7f108df3a810>



Reference

https://pytorch.org/vision/stable/models.html

In []: