

PROJECT FOLDER STRUCTURE

PROJECT:	-----	Root folder
client_app:		
streamlit_app.py		
streamlit_requirements.txt		
server_app:		
app_flask:		
Dockerfile	-----	1)
.....		
app_detector:		
Dockerfile	-----	2) YOLOv5
.....		
app_grouper:		
Dockerfile	-----	3) CLIP Image encoder("ViT-B/32")
.....		DBSCAN clustering, KNN
		classifier or Cosine similarity

HOSTING - SERVER SIDE SETUP(Localhost)

SYSTEM REQUIREMENTS:

- 1) Install docker :[how to install docker](#)
- 2) GPU host machine installed with nvidia-driver > 550

- `cd server_app`

RUN FLASK APP:(1)

- `cd app_flask`
- `sudo docker build -t flask_app:v1 .`
- `sudo docker run -d --network="host" -p 127.0.0.1:7000:7000 --name flask_app_c1 flask_app:v1`

INSTALL NVIDIA CONTAINER TOOLKIT FOR GPU AVAILABILITY FOR MODELS:

Set up the package repository and GPG key:

- `distribution=$(cat /etc/os-release;echo IDVERSION_ID)`
- `curl -s -L https://nvidia.github.io/nvidia-docker/gpgkey | sudo apt-key add -`
- `curl -s -L https://nvidia.github.io/nvidia-docker/$distribution/nvidia-docker.list | sudo tee /etc/apt/sources.list.d/nvidia-docker.list`

Update the package listing and install the toolkit:

- `sudo apt-get update`
- `sudo apt-get install -y nvidia-container-toolkit`

Configure the Docker daemon to recognize the NVIDIA runtime:

- `sudo nvidia-ctk runtime configure --runtime=docker`

Restart the Docker daemon:

- `sudo systemctl restart docker`

RUN DETECTOR APP:(2)

- `cd app_detector`
- `sudo docker build -t detector_app:v1 .`
- `sudo docker run --gpus all -d --network="host" -p 127.0.0.1:7001:7001 --name detector_app_c1 detector_app:v1`

RUN GROUPER APP:(3)

- `cd app_grouper`
 - `sudo docker build -t grouper_app:v1 .`
 - `sudo docker run --gpus all -d --network="host" -p 127.0.0.1:7002:7002 --name grouper_app_c1 grouper_app:v1`
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TESTING – CLIENT SIDE SETUP

SETUP:

- `cd client_app`
- `pip install -r streamlit_requirements.txt`

RUN STREAMLIT APP:

- `streamlit run streamlit_app.py`
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TO IMPROVE

Deployments:

- 1) Models hosting in TorchServe
- 2) Use dockercompose.yml

Model Performance:

- 1) Used YOLOv5, can use YOLOv11 for better OD.
- 2) Used DBSCAN clustering algo, that too clustered object only within a single image. But,

“Thought of using **DBSCAN** for initial clustering and save centroids or features.

- For new incoming objects:
- Extract features.
- Use **KNN, cosine similarity**, or a distance-based threshold to classify the object into an existing cluster or mark it as new.
- Dynamically update the database with new objects and clusters as needed.”

- 3) Use OCR to extract the product names and other possible **text** content(keyword search) on the brand labels. **Both image and text vector** index with meta data, and also trying out Hybrid search especially on the Azure search may give better similarity search.
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