## PDC Home Assignment - 4

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1: Fault Molerant Message Passing in Distributed System

Fault-tolerant message passing ensures that communication between processes continues correctly despite failures. Sechniques include message acknowledgment, retransmission, checksums for data integrity, and using persistent gueues. Redundant paths and consensus protocols also help maintain communication integrity.

2: Chandy-Lamport Snapshot (P2 Initiates)

P2 records its local state.

P2 sends a marker on all outgoing channels. Upon receiving the first marker, P1/P3/P4 record their local state and the state of the channel as empty.

If a marker is received later, the process stops recording that

channel.

Complete global state is compiled.

3: Yotal Storage = (10s /
0.2s) \* 5MB = 50 \* 5MB = 250MB

4: Recovery Sime = Sime after fault + next reset interval = 2s + 0.5s = 2.5s

5: Dijkstra's Self-Stabilizing Algorithm

Each process maintains a state and periodically updates it based on its neighbors. Regardless of the initial state, it converges to a legitimate configuration in finite steps, thus recovering from transient faults without external intervention.

6: Ricart-Agarwala (3 Nodes)

Pland P2 request access (send REQUES Actimestamp, id)).

P3 receives both, replies to the lower timestamp.
Plenters critical section.

P2 waits for REPLY from P1. Plexits, sends REPLY to

P2 enters critical section 7: Fault Molerant Message Handling Use acknowledgment and timeout. If no ACK from P2, P1 retries or uses backup nodes. Persistent logging or consensus algorithms (e.g., Paxos) ensure eventual consistency or alternate resolution. 8: Global State Consistency MI -> M2 (happened-before). P3 records before M2 => It misses M2. Hence, it's not a consistent global state. 9: Bully Algorithm Execution (P2 Initiates) P2 sends ELECTION to P3 and P4. P3 and P4 respond OK. P3 starts its own election. P4 responds OK to P3. Pf starts its own election, wins (highest ID), sends COORDINATOR. Conflict Resolution: Higher ID wins. Lower ID processes stop upon receiving

OKICOORDINAMOR. 10: Ring Election (P3 Initiates) P3 sends (30) to P4 -> P5 -> P6 (fails) -> P1 -> P2 -> back to P3. P3 elects highest ID (P5: 50), sends ELECMED(50) Multiple initiators: Messages circulate; only highest ID remains. II: Ricart-Agarwala (P2 then P3) P2 sends REQUEST to P1, P3, P4. All reply. P2 enters CS P3 sends REQUEST (timestamp > P2). Others reply; P2 delays REPLY. P2 exits CS, replies to P3. P3 enters CS Q12: Chandy-Lamport with Lost Marker P1, P2, P3 record local states. P3 gets P1 marker but not P2. P4 doesn't get any. Resulting snapshot is incomplete, as P4's state isn't recorded. Q3: Marker Sending Rules for Pi Upon recording local state, send marker on all outgoing channels. Upon receiving marker for first

time:
Record local state.
Send marker on outgoing channels.
Record local state. Send marker on outgoing channels. Record messages received on channel until
marker arrives.
Correctness: Ensures consistent global
state
Complexity: O(n) time and messages where n = number of processes.
n = number of processes.