计算机辅助手术讲座(11) Image Guided Surgery (11)

灰度的数学形态学(3)

Mathematical morphology in gray scale (3)

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#### **Conditional Dilation**

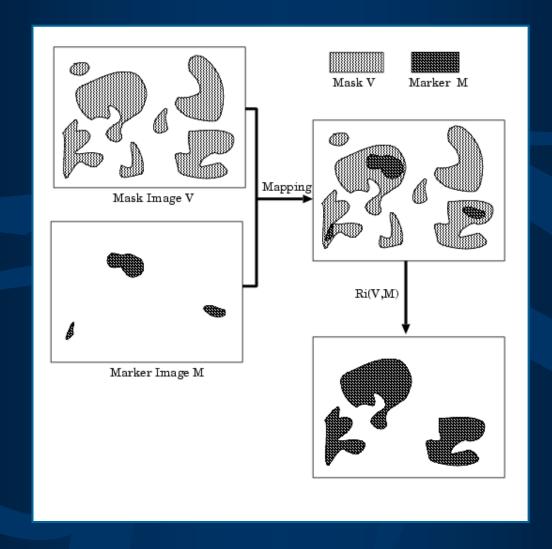
- Conditional Dilation: a special recursive dilation operation. It is also known as *Geodesic Dilation* or *Morphological Reconstruction* used for restoring destroyed objective regions.
  - Arr Let M and V ( $M \subseteq V$ ) be two binary images defined as "marker" and "mask", respectively.
  - $\bullet$  Conditional dilation  $R_i(M, V)$  is defined as:

$$R_{i}(M,V) = (M \oplus K) \cap V,$$

$$until \ R_{i}(M,V) = R_{i-1}(M,V)$$

 $\clubsuit$  Marker M is only allowed to grow in the region restricted by mask V.

### How it works



### Morphological Reconstruction

#### Algorithm for binary reconstruction:

- 1.  $M = V \circ K$ , where K is any SE.
- 2. T = M,
- 3.  $M = M \oplus K_i$ , where i=4 or i=8,
- 4.  $M = M \cap V$ , [Take only those pixels from M that are also in V.]
- 5. if  $M \neq T$  then go to 2,
- 6. else stop;



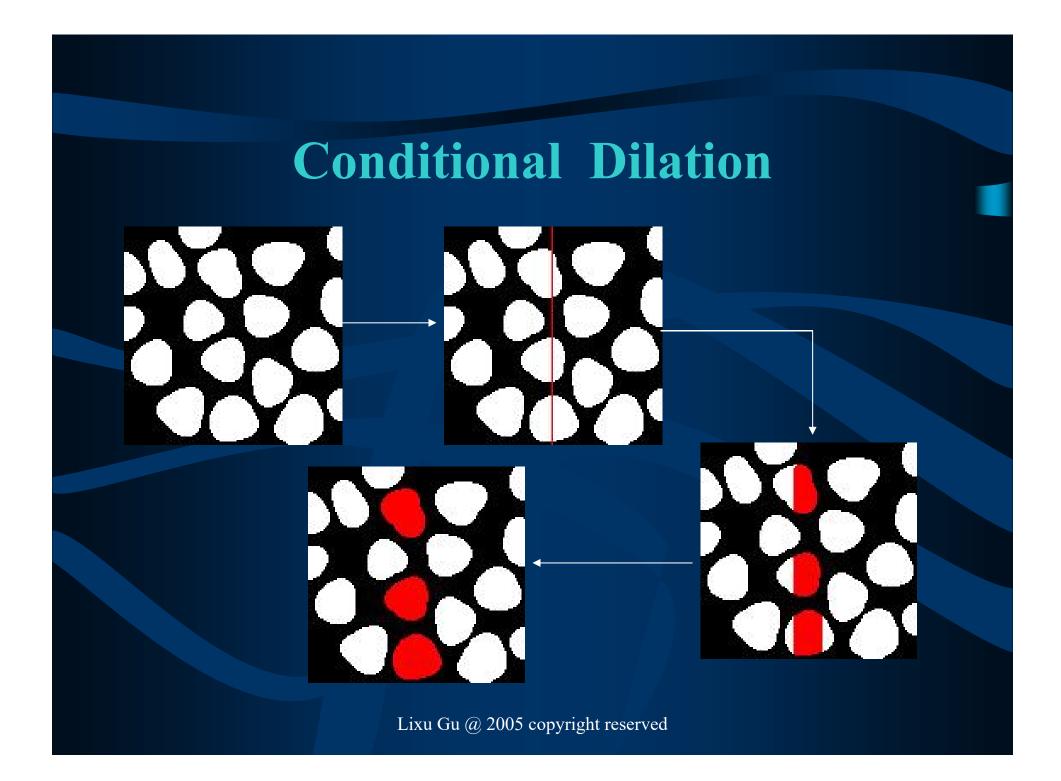
Original (V)



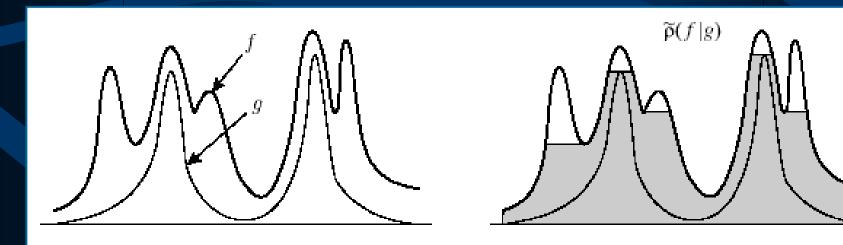
Opened (M)

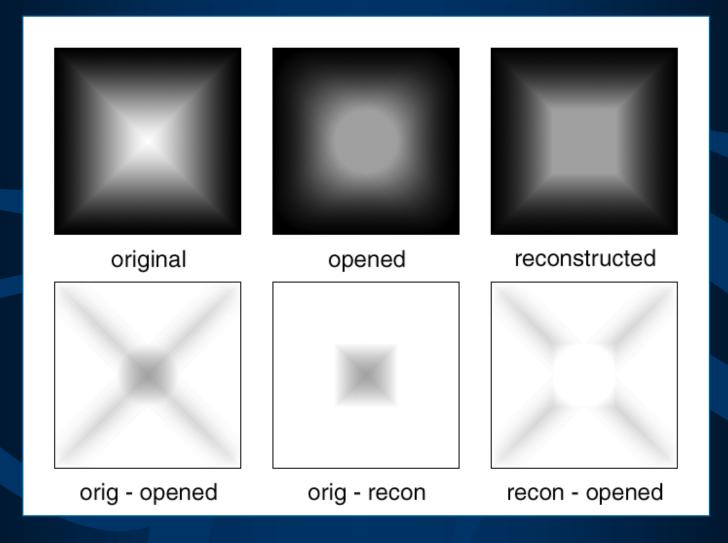


Reconstructed (T)

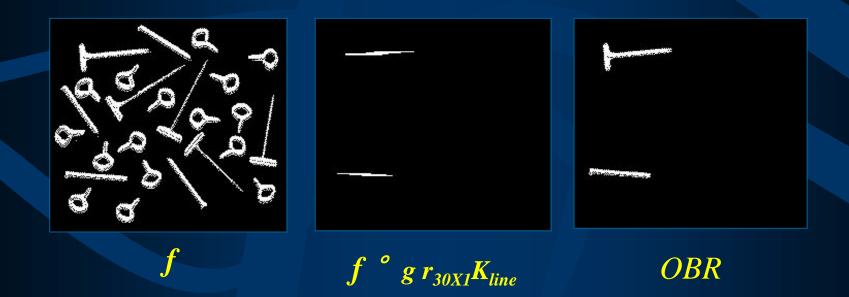


- Grayscale Reconstruction:
  - ❖ Step1: perform grayscale dilation on marker *g*.
  - ❖ Step2: check every gray value in dilated result is not exceed the restriction of mask *f*.
  - Step3: repeat step1 and 2, until g getting stable.

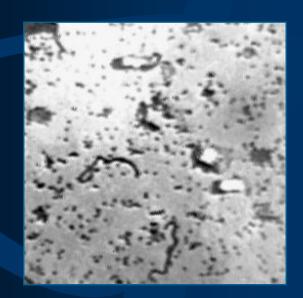




- Grayscale Opening by Reconstruction (OBR):
  - 1. Smooth image or detect seeds by grayscale opening operation
  - 2. Recover the objective regions by grayscale reconstruction



- Grayscale Closing by Reconstruction(CBR):
  - 1. Smooth image by grayscale closing operation
  - 2. Recover the objective regions by grayscale reconstruction







Source





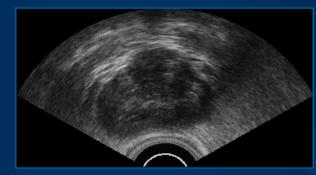


OBR



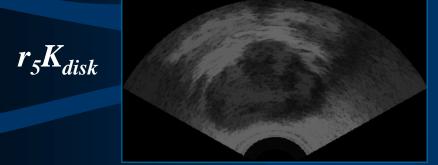
 $r_{20}K_{disk}$ 

CBR

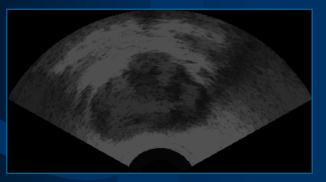


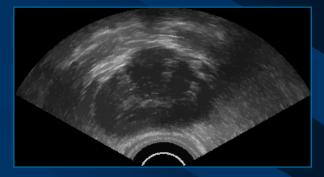
OBR

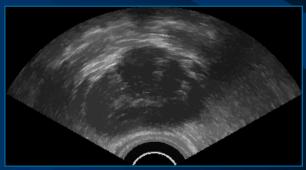
CBR

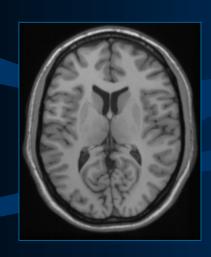


 $r_{10}K_{disk}$ 

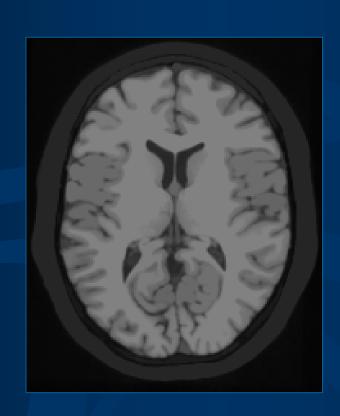




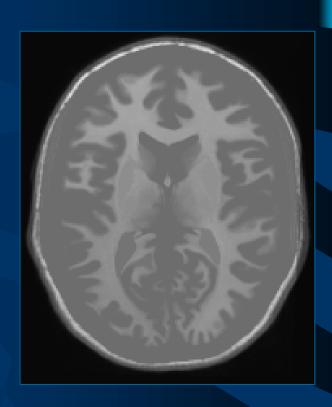




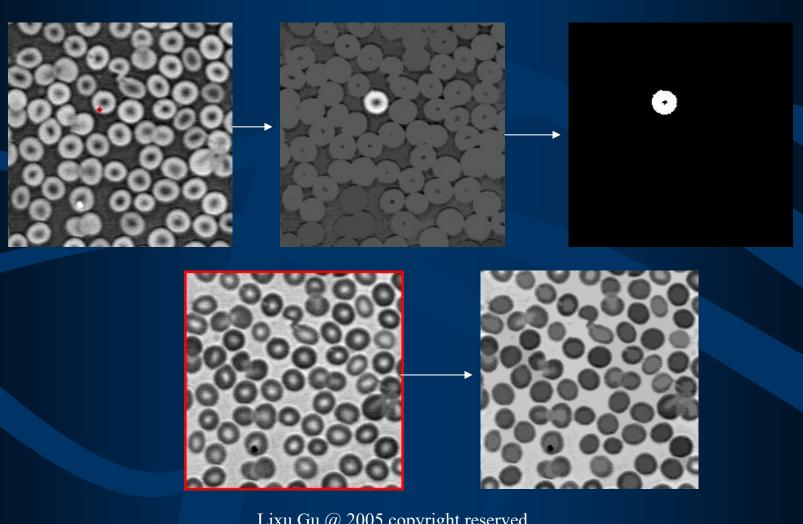
Source



 $OBR \ by \ r_{10}K_{disk}$ 



CBR by  $r_{10}K_{disk}$ 

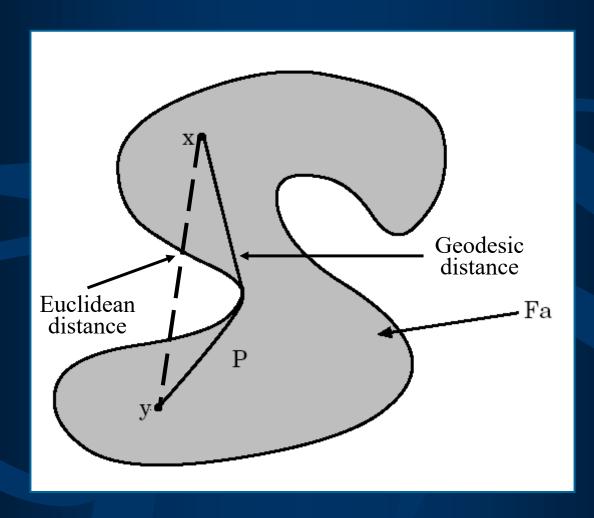


#### Geodesic Distance

• Geodesic Distance: Let  $F_a$  be a connected region. The geodesic distance  $d_{Fa}(x,y)$  between two pixels x and y in  $F_a$  is the infimum of the length of the paths P which join x and y and are totally included in  $F_a$ :

 $d_{F_a}(x, y) = \wedge \{l(P)\}$ where, "\wedge" stands for the infimum and l(P)is the length of the path P.

#### Geodesic Distance vs. Euclidean Distance

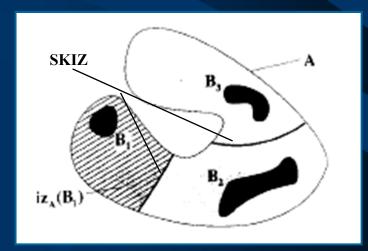


#### Geodesic Influence Zone

• Geodesic Influence Zone (IZ): Suppose a region A contains a set B made of several connected components  $B_1, B_2, ..., B_k$ . IZ is denoted by  $iz_A(B_i)$  and defined as:

$$iz_A(B_i) = \{ p \in A, \forall j \in [1, k] / \{i\}, d_A(p, B_i) < d_A(p, B_j) \}$$

 $iz_A(B_i)$  is the locus of the points of A whose geodesic distance to  $B_i$  is smaller than the distances to any other components of B.



#### SKIZ

Skeleton by Influence Zone (SKIZ): the points of A which do not belong to any IZ, constitute the SKIZ of B inside A, denoted as SKIZ<sub>A</sub>(B):

$$SKIZ_A(B) = A / IZ_A(B)$$

$$with IZ_A(B) = \bigcup_{i \in [1.k]} iz_A(B_i)$$

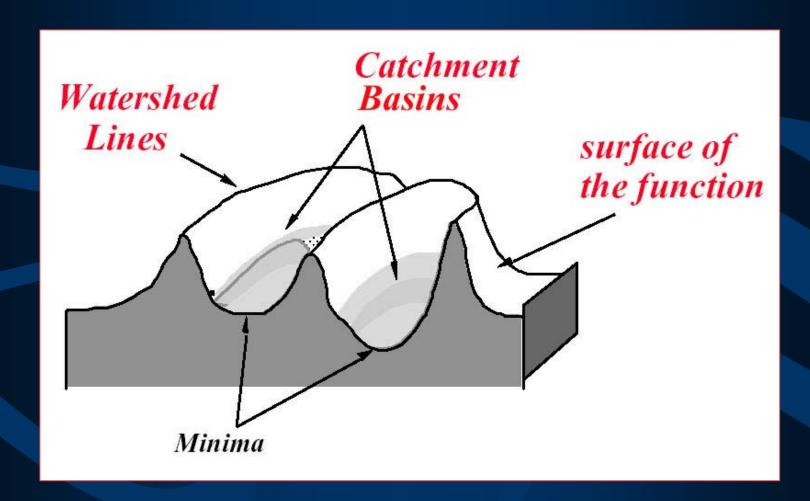
\* "A/B" means all members in A except those in B (B $\subset$ A)

### Watershed

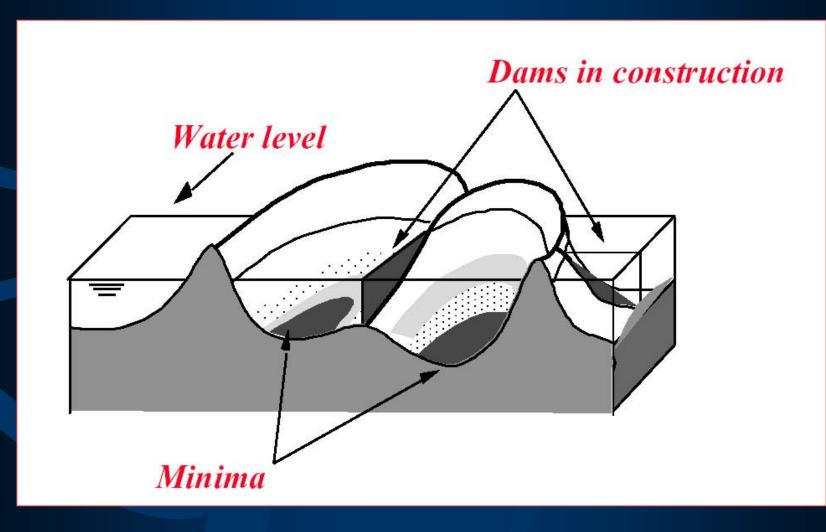


The Great Divide

#### Watershed - Catchment Basin



### Watershed - Dam

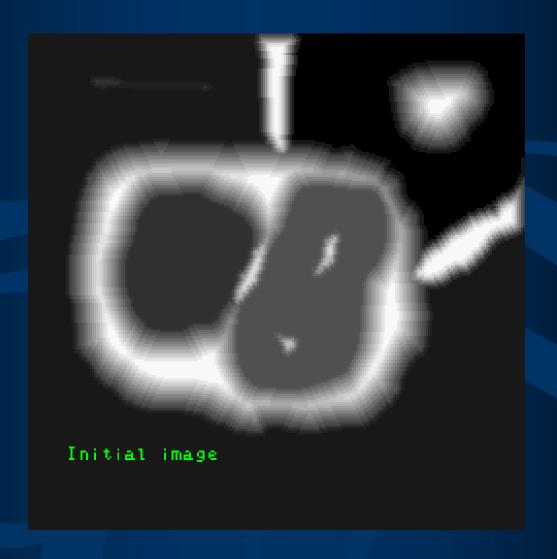


### Watershed

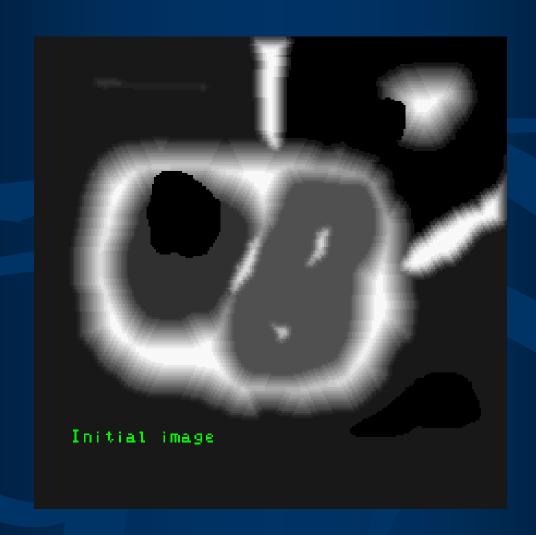
#### How it works:

- 1. Sort all the pixels in an image by their intensities
- 2. Find the minimum intensity pixel as the start point (it's gray level as the initial threshold level)
- 3. Increase threshold level by 1:
  - 1) If find another local minimum point, add it to minimum list, and calculate the SKIZ with other existing minimum points
  - 2) Otherwise, calculate SKIZ within existing minimum list.
- 4. Repeat 3, until all the pixels are sorted to basins or threshold exceed maximum intensity.

### Watershed Demo



### Marked Watershed - Demo



### Watershed - Example





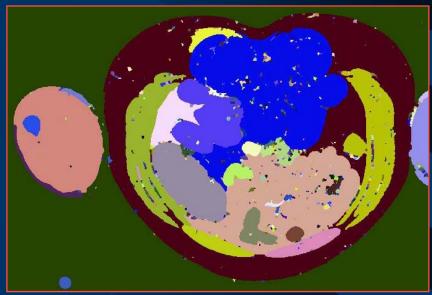
Source Image

Watershed

Over-segmented

### Watershed - Example



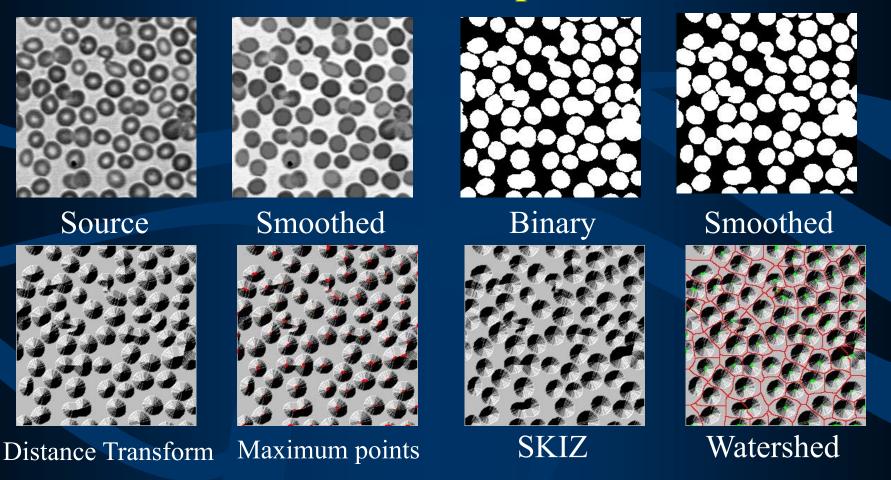


Merged by increase flood level

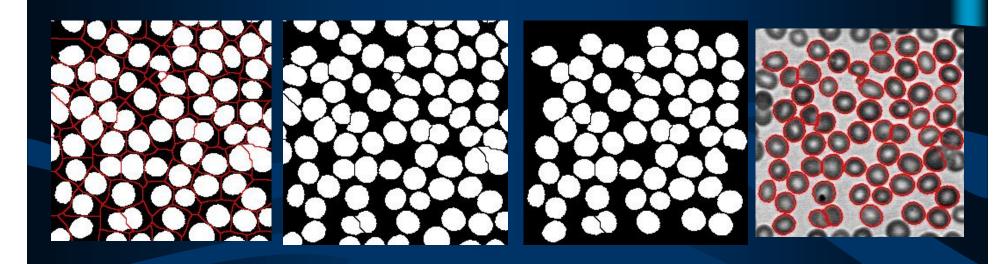
Final Result

### **Application**

Extract blood cells and separate them:



### Application



The cell binary image overlay with watershed lines

Cells separated by watershed lines

The Cells that touch the frames are removed

Final

### Exercise

$$f = \begin{bmatrix} * & 0 & 2 & 2 & 2 & 1 \\ * & 1 & 2 & 6 & 2 & 1 \\ * & 0 & 6 & 7 & 2 & 1 \\ * & 1 & 1 & 6 & 1 & * \\ * & 1 & 0 & 2 & 2 & 1 \\ * & * & * & * & * & * \end{bmatrix}$$

$$g = \begin{bmatrix} 0 & 3 \\ 3_{\Delta} & 4 \end{bmatrix}$$

$$f \oplus g = \max\{f_{0,1} + 0, f_{0,0} + 3, f_{1,1} + 3, f_{1,0} + 4\}$$

$$D_g(f,g) = \begin{bmatrix} * & 0 & 3 & 5 & 5 & 5 & 4 \\ * & 3 & 5 & 6 & 9 & 6 & 5 \\ * & 4 & 6 & 9 & 10 & 6 & 5 \\ * & 3 & 9 & 10 & 11 & 6 & 5 \\ * & 4 & 5 & 9 & 10 & 5 & 4 \\ * & 4 & 5 & 5 & 6 & 6 & 5 \\ * & * & * & * & * & * \end{bmatrix}$$

$$f$$
\$  $g = \min\{f_{-1,0} - 4, f_{-1,-1} - 3, f_{0,0} - 3, f_{0,-1} - 0\}$ 

$$E_g(f,g) = \begin{bmatrix} * & -2 & -1 & -2 & -3 \\ * & -3 & 2 & -2 & -3 \\ * & -3 & -2 & -3 & * \\ * & -4 & -3 & -2 & * \\ * & * & * & * & * \end{bmatrix}$$

$$f \circ g = (f \ \ g) \oplus g$$

$$f \circ g = \begin{bmatrix} * & -2 & 1 & 2 & 1 & 0 \\ * & 1 & 2 & 5 & 2 & 1 \\ * & 0 & 5 & 6 & 2 & 1 \\ * & 0 & 1 & 2 & 1 & * \\ * & -1 & 0 & 1 & 2 & * \\ * & * & * & * & * & * \end{bmatrix}$$

# **Projects**

### Project1

- Write your own code to realize dilation, erosion, opening and closing operations in grayscale.
- Requirement:
  - Design your own UI and display I/O images
  - Try to apply fast operations in case

### Project2

- Write code to realize the next functions:
  - Morphological edge detection
  - Morphological Reconstruction
    - —Conditional dilation in binary image
    - -Gray scale Reconstruction
  - Morphological gradient
- Requirement:
  - Design your own UI and display I/O images
  - Try to apply fast operations in case

# Discussion

