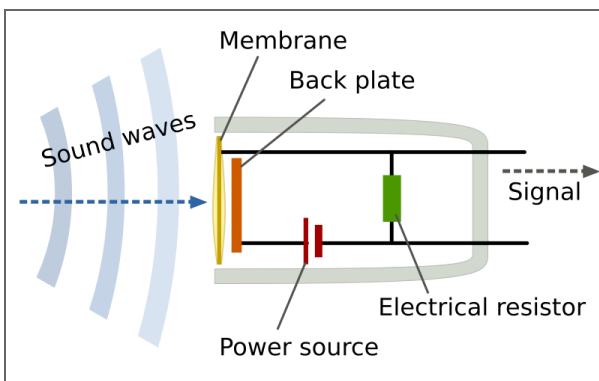
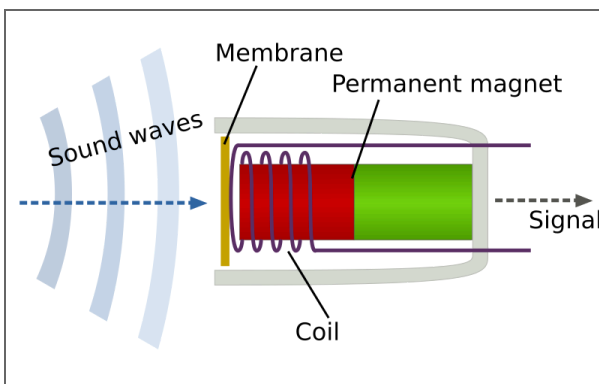


2.6.

## Electromagnets, induction & inductance



### How does a microphone work?



*[left] from wikipedia under CC Attribution-ShareAlike 3.0*

*Unported; [right] from wikipedia under CC Attribution-ShareAlike 3.0 Unported*

## Interaction of coil & magnet

- previous lecture we used **constant** magnetic field to understand:
  1. electric current produces magnetic field
  2. magnetic field exerts a force on electric currents/moving electric particles

### **What happens when we change the magnetic field over time?**

em18 - magnet drop

- Joseph Henry (1797-1878) & Michael Faraday (1791-1867) described independently that **changing magnetic field induces an electric field**
- **concepts to understand:**
  - alternating voltage/current
  - electromagnetic induction

- inductance & electromagnets

What influences the induced voltage ? (1/2)

em12 - flux

**Impact of geometry and orientation**

## The flux strikes back: Magnetic flux

simulation mag. flux

- magnetic flux  $\Phi_B$  defined as:

$$\Phi_B = \int \mathbf{B} \cdot d\mathbf{A}$$

- here  $\mathbf{A}$  is the vector normal to the area  $A$
- in contrast to the electric flux  $\Phi_E$ , "regular" integral instead of closed surface integral
- for a **uniform field** simplifies to:

$$\Phi_B = B_{\perp} A = BA \cos \theta = \mathbf{B} \cdot \mathbf{A}$$

- measured in *weber* [Wb] = [T m<sup>2</sup>]

What influences the induced voltage ? (2/2)

em12 - flux

## **Impact of change over time and number of loops**

- **only changing magnetic fields induce a voltage**
- rate of change scales with induced voltage, i.e.  
 $\frac{d\Phi_B}{dt}$
- for same  $\frac{d\Phi_B}{dt}$ , coil with more loops shows higher induced voltage

## Faraday's law of induction

- $V_{\text{ind}} = -N \frac{d\Phi_B}{dt}$
- with:
  - $N$  - number of loops in coil
  - $\frac{d\Phi_B}{dt}$  - change in magnetic flux

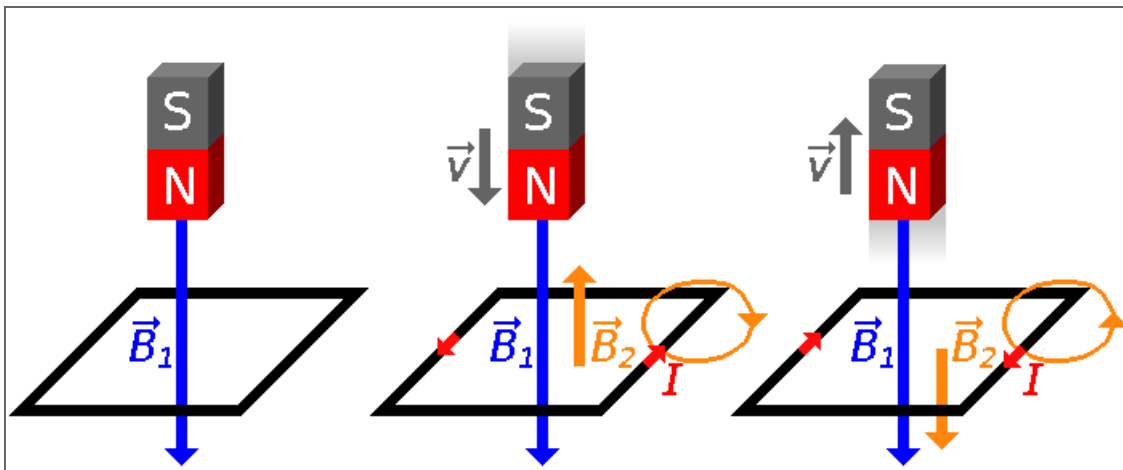
**Why is there a minus?**



# Lenz's law

em14 - Rings

**A change in the magnetic flux through a conducting loop induces a voltage, so that the resulting current generates a magnetic field that opposes the change in magnetic flux.**



from [wikipedia](#) under [CC0 1.0 Universal](#); image was edited

## E-field from electrostatics vs. electromagnetism

- remember electrostatics: **static charges generate electric field:**
  - $V_{AB} = \int_a^b \vec{E} \cdot d\vec{l}$
  - thus, for closed path,  $V = \oint \vec{E} \cdot d\vec{l} = 0$   
→ work is zero
  - **conservative** → path independence & can define potential energy
- **changing magnetic flux induce voltage that generate an electric field:**
  - voltage induced by changing magnetic flux is:  $V_{\text{ind}} = -\frac{d\Phi_B}{dt}$
  - work per unit charge due to induced voltage:  $V_{\text{ind}} = \oint \vec{E} \cdot d\vec{l}$
  - **general form of Faraday's law**  
 $\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$
  - work for closed path not necessarily zero → **non-conservative**

- changing magnetic field induces  
**electric field with closed field lines**

# Eddy currents

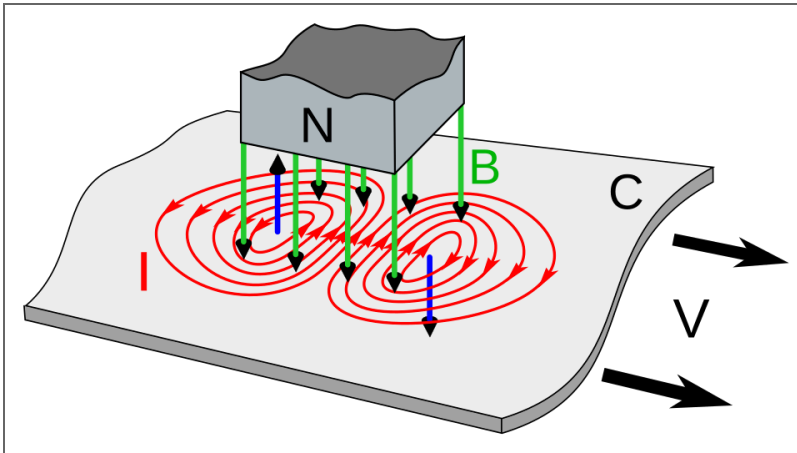
## em25 - Waltenhofen's pendulum

- conductor (pendulum) moves through magnetic field generated by an electromagnet
- → changing magnetic flux in conductor → voltage induced
- part leaving the electromagnetic field:
  - decrease in magnetic flux (number of field lines passing through)
  - generates a field that repels this motion (Lenz's law), i.e. field generated that **attracts** towards the electromagnet
- part entering the electromagnetic field:
  - increase in magnetic flux (number of field lines passing through)

- generates a field that repels this motion (Lenz's law), i.e. field generated that **repels** towards the electromagnet

## Eddy currents (cont')

em25 - Waltenhofen's pendulum



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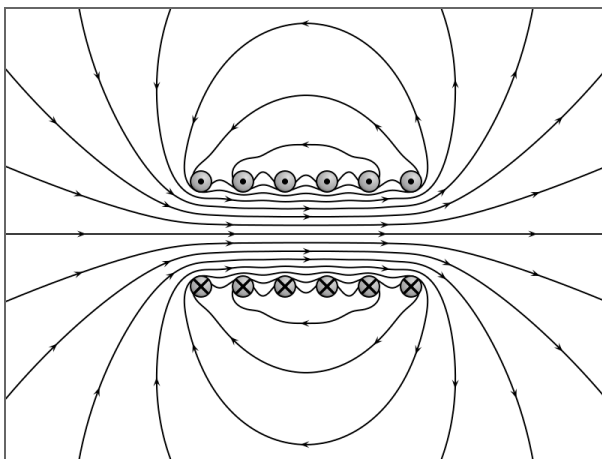
- **direction of induced current via RHR-1'**

# Electromagnets - solenoids

## em10 + simulation B-field solenoid

- tightly wound helical coils of wire
- found in many devices: generators, loudspeakers, MRI scanners, and many more
- produce an almost uniform magnetic field inside the coil and weak field outside
- with loop density  $n$ , the field is:

$$B = \mu_0 \frac{N}{l} I = \mu_0 n I$$



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**Unported**

## AC electric generator

em38

- convert mechanical energy into electrical energy via a **rotating armature** in a **static magnetic field**
- assuming a uniform magnetic field, **induced voltage in rotating coil** is:

$$V_{\text{ind}} = -\frac{d\Phi_B}{dt} = -\frac{d}{dt}(\int \vec{B} \cdot d\vec{A}) = -\frac{d}{dt}(BA \cos \theta)$$

- **only angle  $\theta$  is time dependent**
- assuming initial angle  $\theta_0 = 0$  and constant rotation velocity  $\omega = \frac{d\theta}{dt}$ :

$$V_{\text{ind}} = -BA \frac{d \cos(\omega t)}{dt} = BA\omega \sin(\omega t)$$

- for N loops and maximally induced voltage  $V_{\text{ind},0} = NBA\omega$  :

$$V_{\text{ind}} = NBA\omega \sin(\omega t) = V_{\text{ind},0} \sin(\omega t)$$



- principle can be **reversed** to work as **electric motors**

## Primer on alternating current (AC)

- AC == time varying voltage & current
- for sinusoidal behavior, with  $\omega = 2\pi f$ , voltage alternates between  $+V_0$  and  $-V_0$  described as:

$$V(t) = V_0 \sin(2\pi ft) = V_0 \sin(\omega t)$$

- current is given by:

$$I(t) = \frac{V(t)}{R} = I_0 \sin(\omega t)$$

## Using Root-Mean-Squared (RMS) values

- often RMS values are used in AC:

$$V_{\text{RMS}} = \sqrt{\overline{V(t)^2}} = \sqrt{\overline{V_0^2 \sin^2(\omega t)}}$$

- with  $\sin^2(\omega t) = \frac{1}{2}$

$$V_{\text{RMS}} = \frac{V_0}{\sqrt{2}}$$

$$I_{\text{RMS}} = \frac{I_0}{\sqrt{2}}$$

- for example, a 220V outlet has a peak voltage  $V_0 \approx 311 \text{ V}$

## Power in AC circuits

- power is  $P(t) = I(t)V(t)$
- for sinusoidal current/voltage, average power over a period is **non-zero**:

$$\bar{P} = I_0 \sin(\omega t) V_0 \sin(\omega t) = I_0 V_0 \sin^2(\omega t)$$

- for one period  $\sin^2(\omega t) = \frac{1}{2}$ ,  $I_{\text{RMS}} = \frac{I_0}{\sqrt{2}}$  and

$$V_{\text{RMS}} = \frac{V_0}{\sqrt{2}}$$

$$\bar{P} = \sqrt{2} I_{\text{RMS}} \sqrt{2} V_{\text{RMS}} \frac{1}{2} = I_{\text{RMS}} V_{\text{RMS}}$$

# Transformers

em46

- transformer consists of a *primary* and *secondary* coil
- two coils **do not** form a closed circuit, but only their proximity is essential for the transformer to work

**What influences the voltage in the secondary coil?**

## Transformers - What influences the voltage in the secondary coil?

- iron core (geometry, layered, etc.)
- ratio of loops:
  - without energy loss, the induced voltages in both coils are:

$$V_2 = N_2 \frac{d\Phi_B}{dt} \quad \& \quad V_1 = N_1 \frac{d\Phi_B}{dt}$$

- taking the voltage ratio & using conservation of power,  $P_1 = P_2$ , we get:

$$\frac{V_2}{V_1} = \frac{I_1}{I_2} = \frac{N_2}{N_1}$$

- depending on the ratio of the loop numbers:
  - step-up transformer: For  $N_2 > N_1$  the voltage  $V_2$  will be larger than  $V_1$
  - step-down transformer: For  $N_2 < N_1$  the voltage  $V_2$  will be smaller than  $V_1$

## Mutual inductance

- relates the induced voltage in one coil to the rate of change of current in a neighboring coil
- defined as proportionality constant:

$$M_{21} = \frac{N_2 \Phi_{21}}{I_1}$$

- the induced voltage in one coil can directly be related to change in current in the other coil:

$$V_2 = -N_2 \frac{d\Phi_{21}}{dt} = -M_{21} \frac{dI_1}{dt} \quad \& \quad V_1 = -M_{12} \frac{dI_2}{dt}$$

- mutual inductance only depends on geometric variables, i.e. the spacing between the coils and their individual shape, size, and number of loops:

$$M = M_{21} = M_{12}$$

- **inductance** is expressed in **units of henry** [H]  
= [V s / A] = [ $\Omega$  s]

# Self-inductance & inductors

## YouTube - James Bond

em13

- even for a **single coil**, we find the phenomenon of inductance, a.k.a **self-inductance**
- **changing current** passes through the coil **induces voltage in coil itself** with **opposed direction**
- defined as proportionality constant (depends on coil geometry):

$$L = \frac{N\Phi_B}{I}$$

$$V_{\text{ind}} = -N \frac{d\Phi_B}{dt} = -L \frac{dI}{dt}$$

- often referred simply to as inductance and measured in henry [H].
- **inductors are fundamental circuit elements alongside resistors and capacitors**



## Energy stored in the magnetic field

em17 - Thomson

- power supplied to an inductor is:

$$P = I V_{\text{ind}} = I L \frac{dI}{dt}$$

- the work done to build up the current is:

$$dW = P dt = I L \frac{dI}{dt} dt = I L dI$$

$$W = \int_0^I I L dI = \frac{1}{2} L I^2$$

- energy stored in the magnetic field is:

$$U = \frac{1}{2} L I^2$$

- analogous to the energy stored in a capacitor:

$$U = \frac{1}{2} C V^2$$