Cheat sheet



This is a rather incomplete and loose collection of equations and constants

Use with caution and check / think critical if equation is applicable

Electric charge & field

$$k pprox 9.0 imes 10^9 ext{N m}^2/ ext{C}^2$$
 $\epsilon_0 = rac{1}{4\pi k} = 8.854 imes 10^{-12} rac{ ext{C}^2}{ ext{N m}^2}$ $F = k rac{Q_1 Q_2}{r^2} \quad ext{in [N]}$ $\vec{\mathbf{F}}_{12} = rac{1}{4\pi \epsilon_0} rac{Q_1 Q_2}{r_{21}^2} \hat{\mathbf{r}}_{21}$ $\vec{\mathbf{E}} = rac{\vec{\mathbf{F}}}{q}$ $E = rac{F}{q} = rac{ma}{q} \quad ext{in [N/C]}$ $E = rac{1}{4\pi \epsilon_0} rac{Q}{r^2}$ $dE = rac{1}{4\pi \epsilon_0} rac{dQ}{r^2}$ $\vec{\mathbf{E}} = \int d\vec{\mathbf{E}}$

$$E = \frac{\sigma}{\epsilon_0} = \frac{Q}{\epsilon_0 A}$$
 e.g. for parallel, oppositely charged plates

Note on
$$[E] = \frac{\mathrm{N}}{\mathrm{C}} = \frac{\mathrm{N} \; \mathrm{m}}{\mathrm{C} \; \mathrm{m}} = \frac{\mathrm{J}}{\mathrm{C} \; \mathrm{m}} = \frac{\mathrm{V}}{\mathrm{m}} \quad \mathrm{with} \; \mathrm{J} = \mathrm{Nm} \; \backslash \& \; \mathrm{V} = \mathrm{J/C}$$

Electric flux & electric potential

$$\Phi_E = \vec{\mathbf{E}}\vec{\mathbf{A}} = EA\cos\theta = E_\perp A = EA_\perp$$

$$\Phi_E = \oint ec{{f E}} dec{{f A}} = rac{Q_{enc}}{\epsilon_0}$$

 $W=Fd=qEd=-\Delta U \quad {
m for \ a \ homogenous \ E \ field}$

$$egin{align} V_{BA} = V_B - V_A &= rac{U_B - U_A}{q} = rac{\Delta U_{BA}}{q} = -rac{W_{BA}}{q} & ext{in } [ext{J/C}] = [ext{V}] \ & \Delta U_{BA} = -\int_A^B ec{ ext{f E}} dec{ ext{I}} \ & V_{BA} = -\int_A^B ec{ ext{f E}} dec{ ext{I}} \ & \end{array}$$

 $V_{BA} = -Ed$ for uniform E-field

 $V=rac{1}{4\pi\epsilon_0}rac{Q}{r} \quad ext{for a point charge with } V=0 ext{ at } r=\infty$

Capacitance, batteries, & resistance

$$Q = CV$$

$$U = \frac{1}{2} \frac{Q^2}{C} = \frac{1}{2} CV^2 = \frac{1}{2} QV$$

$$\epsilon = K\epsilon_0$$

$$C = \frac{Q}{V} = K\epsilon_0 \frac{A}{d} = \epsilon \frac{A}{d} \quad \text{for a parallel-plate capacitor}$$

$$I = \frac{dQ}{dt}$$

$$V = IR$$

$$R = \rho \frac{l}{A}$$

$$P = VI = I^2 R = \frac{V^2}{R}$$

$$I = \int \vec{\mathbf{j}} d\vec{\mathbf{A}}$$

DC circuits & Kirchhoff' laws

 $R_{eq} = \sum R_i$ for resistances in series

Magnetism & magnetic field

 $F = IlB \sin heta \quad ext{within an uniform magnetic field}$ $d\vec{\mathbf{F}} = Id\vec{\mathbf{l}} imes \vec{\mathbf{B}} \quad ext{in general}$ $\vec{\mathbf{F}} = q\vec{\mathbf{v}} imes \vec{\mathbf{B}} \quad ext{single moving particle}$ $\frac{e}{m_e} = \frac{v}{Br} = \frac{E}{B^2r} \quad ext{within uniform fields}$ $qvB = m\frac{v^2}{r} \quad ext{within uniform magnetic field}$ $\vec{\mathbf{F}} = q(\vec{\mathbf{E}} + \vec{\mathbf{v}} imes \vec{\mathbf{B}}) \quad ext{Lorentz Equation}$ $U_H = E_H d = v_d B d \quad ext{Hall voltage}$ $B = \frac{\mu_0}{2\pi} \frac{I}{r} \quad ext{magnetic field of a straight wire}$ $\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{l}} = \mu_0 I_{enc} \quad ext{Ampère's law}$ $\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{l}} imes \hat{\mathbf{r}}}{r^2} \quad ext{Biot-Savart law}$

Electromagnets, induction & inductance

$$B = rac{\mu_0 NI}{l}$$
 for solenoids $B = rac{\mu_0 NI}{2\pi r}$ for toroids

 $\Phi_B = B_\perp A = BA\cos\theta = ec{f B}ec{f A} \quad {
m for \ uniform \ magnetic \ field}$

$$\Phi_B = \int ec{f B} d ec{f A}$$
 $V_{ind} = -N rac{d\Phi_B}{dt} = -L rac{dI}{dt}$ $V_1 = -M rac{dI_2}{dt}$

 $V_{ind} = Blv \quad ext{for a conductor moving perp. in a uni. mag. field}$

$$\oint ec{f E} dec{f l} = -rac{d\Phi_B}{dt} \quad ext{general form of Faraday's law}$$
 $U = rac{1}{2} L I^2$

Alternating current (AC)

$$egin{aligned} V(t) &= V_0 \sin(2\pi f t) = V_0 \sin(\omega t) \ I(t) &= rac{V(t)}{R} = rac{V_0}{R} \sin(2\pi f t) = I_0 \sin(\omega t) \ I_{rms} &= \sqrt{ar{I}^2} = \sqrt{rac{1}{2} I_0^2} = rac{I_0}{\sqrt{2}} \ V_{rms} &= \sqrt{ar{V}^2} = \sqrt{rac{1}{2} V_0^2} = rac{V_0}{\sqrt{2}} \ ar{P} &= rac{1}{2} I_0^2 R = rac{1}{2} rac{V_0^2}{R} \ ar{P} &= I_{RMS} V_{RMS} = I_{RMS}^2 R = rac{V_{RMS}^2}{R} \end{aligned}$$

AC circuits & Electromagnetic oscillations

LR-circuit

$$au=rac{L}{R}$$
 $I(t)=rac{V_0}{R}(1-e^{-rac{t}{ au}})~~ ext{switching DC on}$ $I(t)=I_0e^{-rac{t}{ au}}~~ ext{switching DC off}$

LC-circuit

$$I(t)=-rac{dQ}{dt}=\omega Q_0\sin(\omega t+\phi)=I_0\sin(\omega t+\phi)$$
 $\omega=\sqrt{rac{1}{LC}}$ $U=U_B+U_E=rac{Q_0^2}{2C}\sin^2(\omega t+\phi)+rac{Q_0^2}{2C}\cos^2(\omega t+\phi)=rac{Q_0^2}{2C}$

R, L & C in AC circuits

Component	Voltage- Current Relationship	Phase Difference	Reactance
Resistor (R)	V = IR	In phase (0°)	R
Inductor (L)	$V=Lrac{dI}{dt}$	Voltage leads current by 90°	$X_L = \omega L$
Capacitor (C)	$I = C rac{dV}{dt}$	Current leads voltage by 90°	$X_C = rac{1}{\omega C}$
			Z=R+jX,
			$ an\phi=rac{X_L-X_C}{R}$

LRC in AC mode

$$V_0 = \sqrt{V_{R0}^2 + (V_{L0} - V_{C0})^2} = I_0 \sqrt{R^2 + (X_L - X_C)^2} = I_0 Z$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$
 $an \phi = rac{V_{L0} - V_{C0}}{V_{R0}} = rac{I_0(X_L - X_C)}{I_0 R} = rac{X_L - X_C}{R}$ $an \phi = frac V_{R0} V_0 = frac I_0 R I_0 Z = frac R Z$ $P = I_{rms}^2 R = I_{rms}^2 Z \cos \phi = V_{rms} I_{rms} \cos \phi$

Maxwell's equations & Electromagnetic waves

Equation Name	Integral Form	Differential Form
Gauss's law for electricity	$\oint ec{\mathbf{E}} \cdot dec{\mathbf{A}} \ = rac{Q}{\epsilon_0}$	$ec{ abla}\cdotec{\mathbf{E}}=rac{ ho}{\epsilon_0}$
Gauss's law for magnetism	$ \oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} \\ = 0 $	$ec{ abla}\cdot ec{\mathbf{B}} = 0$
Faraday's law of induction	$\oint ec{f E} \cdot dec{f l} = onumber \ -rac{d\Phi_B}{dt}$	$ec{ abla} imesec{\mathbf{E}}=-rac{\partial ec{\mathbf{B}}}{\partial t}$
Ampère's law with Maxwell's correction	$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{l}} \ = \mu_0 I \ + \mu_0 \epsilon_0 rac{d\Phi_E}{dt}$	$egin{aligned} ec{ abla} imes ec{\mathbf{B}} &= \mu_0 ec{\mathbf{j}} \ + \mu_0 \epsilon_0 rac{\partial ec{\mathbf{E}}}{\partial t} \end{aligned}$

$$E=E_y=E_0\sin(kx-\omega t)$$
 $B=B_z=B_0\sin(kx-\omega t)$
 $k=rac{2\pi}{\lambda}$
 $\omega=2\pi f$
 $u=f\lambda=rac{\omega}{k}$
 $u=rac{E_0}{B_0}=rac{\omega}{k}$
 $u=rac{E_0}{B_0}=rac{E}{k}$
 $u=rac{E}{\sqrt{\epsilon_0\mu_0}}=c$
 $u=rac{E}{B}$

$$u = u_E + u_B = \frac{1}{2}\epsilon_0 E^2 + \frac{1}{2}\frac{B^2}{\mu_0}$$

$$u = \epsilon_0 E^2 = \epsilon_0 c^2 B^2 = \frac{B^2}{\mu_0} = \epsilon_0 c E B = \sqrt{\frac{\epsilon_0}{\mu_0}} E B$$

$$\overline{S} = \frac{1}{2}\epsilon_0 c E_0^2 = \frac{1}{2}\frac{c}{\mu_0} B_0^2 = \frac{E_0 B_0}{2\mu_0} = \frac{E_{rms} B_{rms}}{\mu_0}$$

$$P = \frac{\overline{S}}{c} \quad \text{radiation fully absorbed}$$

$$P = \frac{\overline{2S}}{c} \quad \text{radiation fully reflected}$$

$$c = \frac{E}{B} = \frac{1}{\sqrt{\epsilon_0 \mu_0}} = 300.000.000 \text{ m/s} = 300 \times 10^6 \text{ m/s}$$

$$c = \lambda f$$

Geometrical optics: Refection & refraction

Mirror equation:

$$\frac{1}{d_0} + \frac{1}{d_i} = \frac{1}{f}$$

The angle of incidence and the angle of reflection are equal $heta_i = heta_r$.

Snell's law of refraction: $n_1\sin\theta_1=n_2\sin\theta_2$

Lateral magnification (mirror): $m=rac{h_i}{h_o}=-rac{d_i}{d_0}$

Geometrical optics: Optical instruments

Lensmaker's equation: $rac{1}{f}=(n-1)(rac{1}{R_1}+rac{1}{R_2})$

Thin lens equation for convex/converging lenses: $rac{1}{d_0}+rac{1}{d_i}=rac{1}{f}$

Thin lens equation for concave/diverging lenses: $rac{1}{d_0}-rac{1}{d_i}=rac{1}{f}$

Lateral magnification (lens): $m=rac{h_i}{h_o}=-rac{d_i}{d_0}$

Wave optics: Interference & polarization

Malus's law: $I=I_0\cos^2\theta$

Brewster's law: $an heta_p = rac{n_2}{n_1}$

Newtons rings:

- Dark rings (destructive interference): Occur when this condition is met: $2t+\frac{\lambda}{2}=\frac{\lambda}{2}(2m+1)=(m+\frac{1}{2})\lambda \text{ with } m=0,1,2,\dots \text{ as the order of the dark rings.}$ Rearranging this, we get $2t=\lambda m$.
- Bright rings (constructive interference): Occur when this condition is met: $2t + \frac{\lambda}{2} = m\lambda$, with $m=1,2,\ldots$ as the order of the bright rings. Rearranging this, we get $2t=(m-\frac{1}{2})\lambda$.

Double slit:

• **Constructive interference**, resulting in a bright fringe on the screen, happens when the path difference is an integer multiple of the wavelength (λ) of the monochromatic light:

$$d\sin\theta = m\lambda, \quad m = 0, 1, 2, \dots$$

• **Destructive interference**, resulting in a dark fringe on the screen, occurs when the path difference is a half-integer multiple of the wavelength:

$$d\sin heta = (m+rac{1}{2})\lambda, \quad m=0,1,2,\ldots$$

Wave optics: Diffraction

Diffraction at single-slit:

- $\Delta = D\sin\theta \leftrightarrow D\sin\theta = m\lambda$
- **Central maximum:** Rays passing straight through the slit are in phase, creating a central bright region at an angle $\theta = 0$.
- **Minima:** Minima occur at angles θ where the path difference between rays from the top and bottom of the slit is an integer multiple of the wavelength λ :

$$D\sin\theta = m\lambda, \quad m = \pm 1, \pm 2, \dots$$

• **Higher-order maxima:** Between the minima, weaker maxima appear approximately where the path difference is a half-integer multiple of the wavelength:

$$D\sin hetapprox(m+rac{1}{2})\lambda,\quad mpprox.\pmrac{3}{2},\pmrac{5}{2},\ldots$$

Intensity of diffraction patterns:

$$ullet$$
 single-slit $I_{ heta}=I_0\Big(rac{\sin(eta/2)}{eta/2}\Big)^2=I_0igg(rac{\sin\Big(rac{\pi D\sin heta}{\lambda}\Big)}{rac{\pi D\sin heta}{\lambda}}igg)^2$

• double-slit $I_{ heta} = I_0 \Big(rac{\sin(eta/2)}{eta/2}\Big)^2 \cos^2\Big(rac{\delta}{2}\Big)$