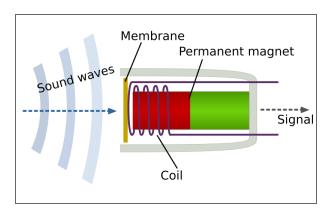
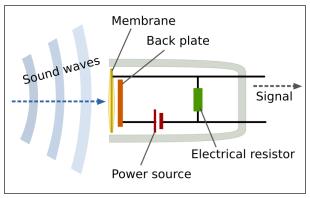
2.6.

Electromagnets, induction & inductance



How does a microphone work?





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Interaction of coil & magnet

- previous lecture we used **constant** magnetic field to understand:
 - electric current produces magnetic field
 - 2. magnetic field exerts a force on electric currents/moving electric particles

What happens when we change the magnetic field over time?

em18 - magnet drop

- Joseph Henry (1797-1878) & Michael Faraday (1791-1867) described independently that changing magnetic field induces an electric field
- concepts to understand:
 - alternating voltage/current
 - electromagnetic induction

inductance & electromagnets

What influences the induced voltage ? (1/2)

em12 - flux

Impact of geometry and orientation

The flux strikes back: Magnetic flux

simulation mag. flux

• magnetic flux Φ_B defined as:

$$\Phi_{\rm B} = \int B dA$$

- here A is the vector normal to the area A
- in contrast to the electric flux Φ_E , "regular" integral instead of closed surface integral
- for a **uniform field** simplifies to:

$$\Phi_{\rm B} = {\rm B}_{\perp}{\rm A} = {\rm BA}\cos\theta = {\rm B}\rightarrow {\rm A}\rightarrow$$

measured in weber [Wb] = [T m²]

What influences the induced voltage ? (2/2)

Impact of change over time and number of loops

- only changing magnetic fields induce a voltage
- rate of change scales with induced voltage, i.e. $\frac{d\Phi_B}{dt}$
- for same $\frac{d\Phi_B}{dt}$, coil with more loops shows higher induced voltage

Faraday's law of induction

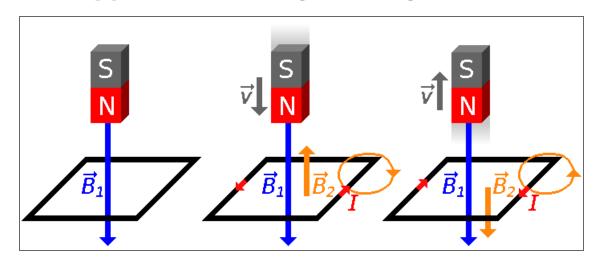
- $V_{\text{ind}} = -N \frac{d\Phi_B}{dt}$
- with:
- N number of loops in coil
- \blacksquare $\frac{d\Phi_B}{dt}$ change in magnetic flux

Why is there a minus?

Lenz's law

em14 - Rings

A change in the magnetic flux through a conducting loop induces a voltage, so that the resulting current generates a magnetic field that opposes the change in magnetic flux.



from **wikipedia** under **CCO 1.0 Universal**; image was edited

E-field from electrostatics vs. electromagnetism

- remember electrostatics: static charges generate electric field:
 - $V_{AB} = \int_a^b E dt$
 - thus, for closed path, $V = \oint E dt = 0$ → work is zero
 - conservative → path independence & can define potential energy
- changing magnetic flux induce voltage that generate an electric field:
 - voltage induced by changing magnetic flux is: $V_{ind} = -\frac{d\Phi_B}{dt}$
 - work per unit charge due to induced voltage: $V_{ind} = \oint E \cdot dt$
 - general form of Faraday's law $\oint E \cdot dt = -\frac{d\Phi_B}{dt}$
 - work for closed path not necessarily zero → non-conservative

changing magnetic field induceselectric field with closed field lines

Eddy currents

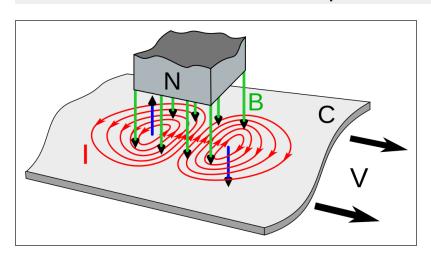
em25 - Waltenhofen's pendulum

- conductor (pendulum) moves through magnetic field generated by an electromagnet
- → changing magnetic flux in conductor → voltage induced
- part leaving the electromagnetic field:
 - decrease in magnetic flux (number of field lines passing through)
 - generates a field that repels this motion (Lenz's law), i.e. field generated that attracts towards the electromagnet
- part entering the electromagnetic field:
 - increase in magnetic flux (number of field lines passing through)

 generates a field that repels this motion (Lenz's law), i.e. field generated that repels towards the electromagnet

Eddy currents (cont')

em25 - Waltenhofen's pendulum



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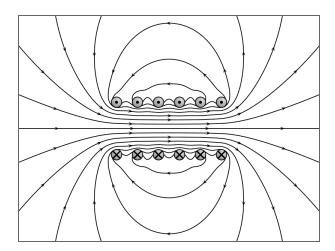
• direction of induced current via RHR-1'

Electromagnets - solenoids

em10 + simulation B-field solenoid

- tightly wound helical coils of wire
- found in many devices: generators,
 loudspeakers, MRI scanners, and many more
- produce an almost uniform magnetic field inside the coil and weak field outside
- with loop density n, the field is:

$$B=\mu_0 \tfrac{N}{1} I=\mu_0 n I$$



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AC electric generator

em38

- convert mechanical energy into electrical energy via a rotating armature in a static magnetic field
- assuming a uniform magnetic field, induced voltage in rotating coil is:

$$V_{ind} = -\frac{d\Phi_B}{dt} = -\frac{d}{dt}(\int B dA) = -\frac{d}{dt}(BA\cos\theta)$$

- only angle θ is time dependent
- assuming initial angle $\theta_0 = 0$ and constant rotation velocity $\omega = \frac{d\theta}{dt}$:

$$V_{ind} = -BA \frac{d \cos(\omega t)}{dt} = BA\omega \sin(\omega t)$$

• for N loops and maximally induced voltage $V_{ind,0} = NBA\omega$:

$$V_{ind} = NBA\omega \sin(\omega t) = V_{ind,0} \sin(\omega t)$$

principle can be reversed to work as electric motors

Primer on alternating current (AC)

- AC == time varying voltage & current
- for sinusoidal behavior, with $\omega = 2\pi f$, voltage alternates between $+V_0$ and $-V_0$ described as:

$$V(t) = V_0 \sin(2\pi f t) = V_0 \sin(\omega t)$$

current is given by:

$$I(t) = \frac{V(t)}{R} = I_0 \sin(\omega t)$$

Using Root-Mean-Squared (RMS) values

often RMS values are used in AC:

$$V_{RMS} = \sqrt{V(t)^2} = \sqrt{V_0^2 \sin^2(\omega t)}$$

• with $\sin^2(\omega t) = \frac{1}{2}$

$$V_{RMS} = \frac{V_0}{\sqrt{2}}$$

$$I_{RMS} = \frac{I_0}{\sqrt{2}}$$

 • for example, a 220V outlet has a peak voltage $V_0 \approx 311 \; \text{V}$

Power in AC circuits

- power is P(t) = I(t)V(t)
- for sinusoidal current/voltage, average power over a period is non-zero:

$$\overline{P} = I_0 \sin(\omega t) V_0 \sin(\omega t) = I_0 V_0 \sin^2(\omega t)$$

• for one period $\sin^2(\omega t)=\frac{1}{2}$, $I_{RMS}=\frac{I_0}{\sqrt{2}}$ and $V_{RMS}=\frac{V_0}{\sqrt{2}}$

$$\overline{P} = \sqrt{2}I_{RMS}\sqrt{2}V_{RMS}\frac{1}{2} = I_{RMS}V_{RMS}$$

Transformers

em46

- transformer consists of a primary and secondary coil
- two coils do not form a closed circuit, but only their proximity is essential for the transformer to work

What influences the voltage in the secondary coil?

Transformers - What influences the voltage in the secondary coil?

- iron core (geometry, layered, etc.)
- ratio of loops:
 - without energy loss, the induced voltages in both coils are:

$$V_2 = N_2 \frac{d\Phi_B}{dt} \quad \& \quad V_1 = N_1 \frac{d\Phi_B}{dt}$$

■ taking the voltage ratio & using conservation of power, $P_1 = P_2$, we get:

$$\frac{V_2}{V_1} = \frac{I_1}{I_2} = \frac{N_2}{N_1}$$

- depending on the ratio of the loop numbers:
 - step-up transformer: For $N_2 > N_1$ the voltage V_2 will be larger than V_1
 - step-down transformer: For $N_2 < N_1$ the voltage V_2 will be smaller than V_1

Mutual inductance

- relates the induced voltage in one coil to the rate of change of current in a neighboring coil
- defined as proportionality constant:

$$M_{21} = \frac{N_2 \Phi_{21}}{I_1}$$

• the induced voltage in one coil can directly be related to change in current in the other coil:

$$V_2 = -N_2 \frac{d\Phi_{21}}{dt} = -M_{21} \frac{dI_1}{dt}$$
 & $V_1 = -M_{12} \frac{dI_2}{dt}$

 mutual inductance only depends on geometric variables, i.e. the spacing between the coils and their individual shape, size, and number of loops:

$$M = M_{21} = M_{12}$$

• inductance is expressed in units of henry [H] = $[V s / A] = [\Omega s]$

Self-inductance & inductors

YouTube - James Bond

em13

- even for a single coil, we find the phenomenon of inductance, a.k.a selfinductance
- changing current passes through the coil induces voltage in coil itself with opposed direction
- defined as proportionality constant (depends on coil geometry):

$$L = \frac{N\Phi_B}{I}$$

$$V_{ind} = -N \frac{d\Phi_B}{dt} = -L \frac{dI}{dt}$$

- often referred simply to as inductance and measured in henry [H].
- inductors are fundamental circuit elements alongside resistors and capacitors

Energy stored in the magnetic field

em17 - Thomson

power supplied to an inductor is:

$$P = I V_{ind} = I L \frac{dI}{dt}$$

• the work done to build up the current is:

$$dW = P dt = IL \frac{dI}{dt} dt = ILdI$$

$$W = \int_{0}^{I} I L dI = \frac{1}{2} LI^{2}$$

energy stored in the magnetic field is:

$$U = \frac{1}{2}LI^2$$

analogous to the energy stored in a capacitor:

$$U = \frac{1}{2}CV^2$$