$$s_1: \underbrace{\langle 1,0\rangle}_{t_1} \underbrace{\text{SO}} \underbrace{\langle 2,0\rangle}_{t_2} \underbrace{\text{SO}} \underbrace{\langle 3,2\rangle}_{t_3} \underbrace{\text{SO}} \underbrace{\langle 4,2\rangle}_{t_4} \underbrace{\text{SO}} \underbrace{\langle 100,2\rangle}_{t_{100}}$$

$$s_2: \underbrace{\langle 0,1\rangle}_{t_{101}} \underbrace{\text{SO}}_{t_{102}} \underbrace{\langle 0,2\rangle}_{t_{102}}$$