

# IMPROVING GENERALIZATION OF EVOLUTIONARY FEATURE CONSTRUCTION WITH MINIMAL COM- PLEXITY KNEE POINTS IN REGRESSION

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1 Background

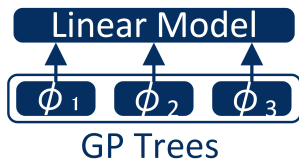
2 Method

3 Settings

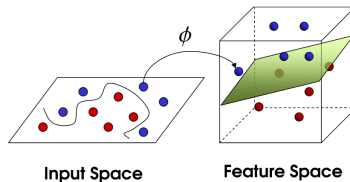
4 Results

# BACKGROUND

- **Objective:** Construct a set of new features,  $\{\phi_1, \dots, \phi_m\}$ , to enhance learning on the dataset  $\{\{x_1, y_1\}, \dots, \{x_n, y_n\}\}$  compared to learning on the original features  $\{x^1, \dots, x^p\}$ .
- **Approaches:**
  - ▶ Kernel Methods: Black-box, non-parametric.
  - ▶ Neural Networks: Black-box, gradient-based.
  - ▶ Genetic Programming: Interpretable, gradient-free.



(a) Feature Construction on Linear Regression



(b) New Feature Space

- **High accuracy** is crucial but may lead to complex models prone to overfitting.
- **Tree size** in genetic programming (GP) serves as a measure of model complexity.
- The key is to find an optimal balance: **Maximize accuracy while minimizing tree size.**

## Occam's Razor in Modeling

Simpler models (smaller trees) are more likely to generalize well to unseen data, reducing the risk of overfitting.

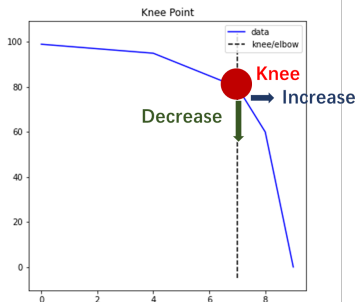
- Utilize **multi-objective optimization** to address the dual objectives of high accuracy and low complexity.
- Solutions on the **Pareto front** represent the best trade-offs between competing objectives.

## How to Select the Final Model?

Choose a model from the Pareto front that offers a balanced compromise, such as **knee point**, to ensure robust generalization.

## Definition

A **knee point** in the context of multi-objective optimization is a point on the Pareto front where a **small improvement** in one objective would lead to a **significant deterioration** in another objective.



## Potential Knee Points

Point	Improvement in Obj. 1	Deterioration in Obj. 2
A	3%	10%
B	4%	20%
C	1%	3%

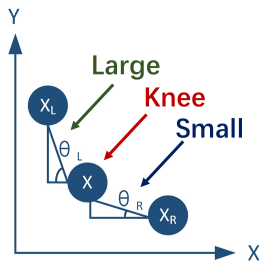
- Each point represents a potential knee point.
- The "significance" of improvements and deteriorations is subjective, leading to ambiguity in knee point selection.

## Key Insight

The identification of knee points is influenced by subjective interpretations of **small improvement** and **significant deterioration**.



- Angle-based Method <sup>1</sup>
- Utility Function <sup>2</sup>
- Distance To Extreme Line <sup>3</sup>



Bend Angle Calculation

<sup>1</sup>Deb and Gupta 2011

<sup>2</sup>Rachmawati and Srinivasan 2009

<sup>3</sup>Schütze, Laumanns, and Coello 2008

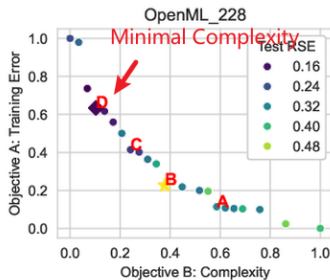
# METHOD

## Core Hypothesis

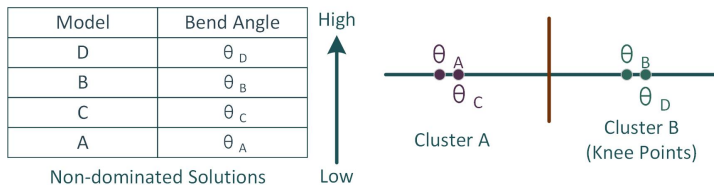
A significant increase in model complexity for small improvements in training accuracy may signal overfitting.

## Minimal Complexity Knee Points

Opt for models at knee points with the least complexity to mitigate overfitting risks.



- Calculate the bend angle of each model on the Pareto front.
- Apply a clustering algorithm to group models.
- Identify clusters with largest bend angles.



## Key Advantage

Clustering automates the identification of thresholds for knee points, eliminating the need for manual threshold setting.

**Task:** Multi-tree GP for feature construction on a linear regression model.

**Objectives:** Minimize cross-validation loss and tree size.

**Process:**

- Initialize population with GP trees.
- Evaluate individuals using cross-validation loss and tree size.
- Select parents and generate offspring with GP operators.
- Use NSGA-II for environmental selection.

**Final Model:** Selected from Pareto front based on knee point strategy.

# SETTINGS

- 58 real-world datasets from the Penn Machine Learning Benchmark (PMLB).
- Excluded synthetic datasets to focus on real-world datasets.

## **Model Selection Methods:**

- Angle Knee Selection (AKS)
- Four Angle Knee Selection (FAKS)
- Bended Angle Knee Selection (BAKS)
- Utility Function Knee Selection (UFKS)
- Distance To Extreme Line Knee Selection (DELKS)
- Best Training Accuracy
- Best Harmonic Mean Rank
- Standard GP (without Model Size as Objective)

## **Machine Learning Methods:**

- SVR, KNN, Ridge, and DT



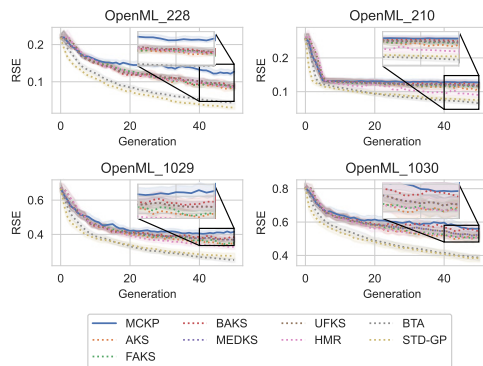
# RESULTS

- MCKP strategy **enhances generalization** on 32 datasets compared to standard GP (STD-GP).
- MCKP outperforms traditional knee point selection strategies, including AKS, indicating **better overfitting control**.

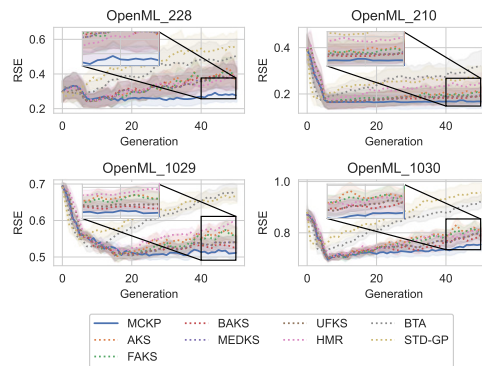
Statistical comparison of test RSE.

	AKS	FAKS	BAKS	MEDKS
MCKP	20(+)/31(~)/7(-)	15(+)/36(~)/7(-)	10(+)/37(~)/11(-)	10(+)/40(~)/8(-)
AKS	—	0(+)/58(~)/0(-)	0(+)/56(~)/2(-)	0(+)/54(~)/4(-)
FAKS	—	—	0(+)/55(~)/3(-)	0(+)/56(~)/2(-)
BAKS	—	—	—	0(+)/58(~)/0(-)
MEDKS	—	—	—	—
UFKS	—	—	—	—
HMR	—	—	—	—
BTA	—	—	—	—
	UFKS	HMR	BTA	STD-GP
MCKP	11(+)/37(~)/10(-)	16(+)/30(~)/12(-)	31(+)/15(~)/12(-)	32(+)/15(~)/11(-)
AKS	0(+)/55(~)/3(-)	2(+)/51(~)/5(-)	23(+)/28(~)/7(-)	21(+)/29(~)/8(-)
FAKS	0(+)/56(~)/2(-)	2(+)/52(~)/4(-)	22(+)/28(~)/8(-)	24(+)/26(~)/8(-)
BAKS	0(+)/58(~)/0(-)	3(+)/52(~)/3(-)	24(+)/29(~)/5(-)	24(+)/27(~)/7(-)
MEDKS	0(+)/58(~)/0(-)	3(+)/52(~)/3(-)	24(+)/28(~)/6(-)	26(+)/26(~)/6(-)
UFKS	—	3(+)/52(~)/3(-)	23(+)/29(~)/6(-)	25(+)/27(~)/6(-)
HMR	—	—	24(+)/31(~)/3(-)	27(+)/26(~)/5(-)
BTA	—	—	—	1(+)/53(~)/4(-)

- MCKP exhibits good generalization performance on unseen data, unlike some other knee point selection strategies that may overfit.

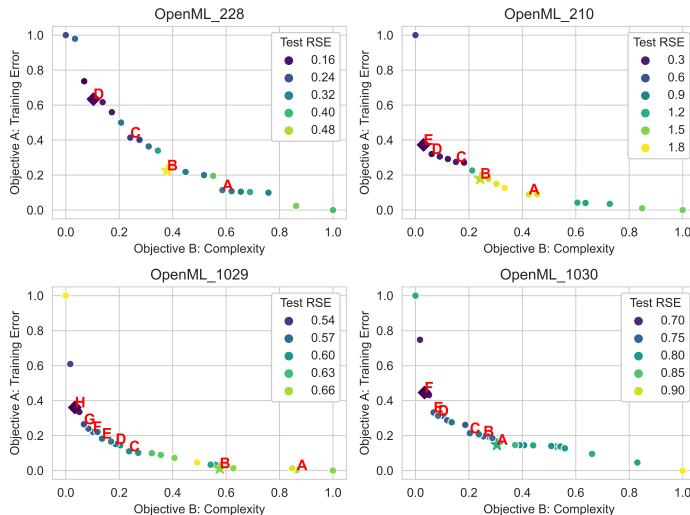


(a) Training RSE

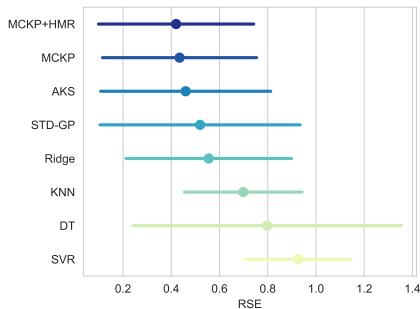


(b) Test RSE

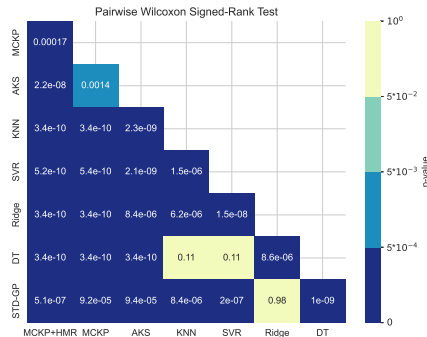
- *Knee points with minimal complexity yield optimal results in many cases.*



- GP with **MCKP** outperforms SVR, KNN, Ridge, and DT in sample-limited scenarios.
- Ensemble Learning: Combining MCKP with HMR yields even better results.



**(a)** Median RSE of different learning methods.



**(b)** Pairwise statistical comparison of different learning methods.

## Key Takeaways

### ■ Ensemble Model:

- ▶ If an ensemble model is acceptable, combine **MCKP** with any existing knee point selection method for enhanced performance.

### ■ Single Model:

- ▶ If an ensemble model is not suitable, use **cross-validation** on the training set to decide between **MCKP** and **existing knee point selection methods**.

# THANKS FOR LISTENING!

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GITHUB PROJECT: [HTTPS://GITHUB.COM/HENGZHE-ZHANG/KNEEPOINT-PYTHON](https://github.com/HENGZHE-ZHANG/KNEEPOINT-PYTHON)