Chapter ML:III

III. Decision Trees

- □ Decision Trees Basics
- Impurity Functions
- □ Decision Tree Algorithms
- Decision Tree Pruning

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Overfitting

Definition 10 (Overfitting)

Let D be a set of examples and let H be a hypothesis space. The hypothesis $h \in H$ is considered to overfit D if an $h' \in H$ with the following property exists:

$$Err(h, D) < Err(h', D)$$
 and $Err^*(h) > Err^*(h')$,

where $\mathit{Err}^*(h)$ denotes the <u>true misclassification rate</u> of h, while $\mathit{Err}(h,D)$ denotes the error of h on the example set D.

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Reasons for overfitting are often rooted in the example set D:

- \Box D is noisy
- □ *D* is biased and hence non-representative
- D is too small and hence pretends unrealistic data properties

Overfitting (continued)

Let $D_{tr} \subset D$ be the training set. Then $\mathit{Err}^*(h)$ can be estimated with a test set $D_{ts} \subset D$ where $D_{ts} \cap D_{tr} = \emptyset$ (holdout estimation). The hypothesis $h \in H$ is considered to overfit D if an $h' \in H$ with the following property exists:

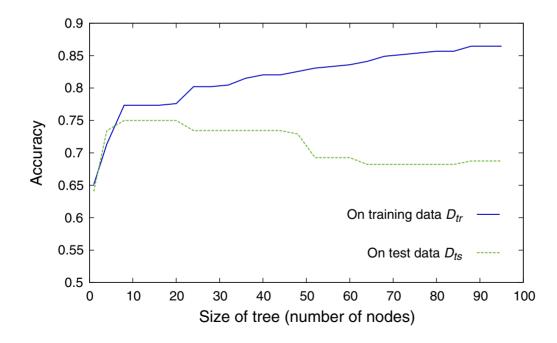
$$Err(h, D_{tr}) < Err(h', D_{tr})$$
 and $Err(h, D_{ts}) > Err(h', D_{ts})$

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Overfitting (continued)

Let $D_{tr} \subset D$ be the training set. Then $\mathit{Err}^*(h)$ can be estimated with a test set $D_{ts} \subset D$ where $D_{ts} \cap D_{tr} = \emptyset$ (holdout estimation). The hypothesis $h \in H$ is considered to overfit D if an $h' \in H$ with the following property exists:

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 and $Err(h, D_{ts}) > Err(h', D_{ts})$



[Mitchell 1997]

Remarks:

- □ Accuracy is the percentage of correctly classified examples.
- \Box When does $Err(T, D_{tr})$ of a decision tree T become zero?
- □ The training error $Err(T, D_{tr})$ of a decision tree T is a monotonically decreasing function in the size of T. See the following Lemma.

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Overfitting (continued)

Lemma

Let t be a node in a decision tree T. Then, for each induced splitting $D(t_1), \ldots, D(t_s)$ of a set of examples D(t) holds:

$$\underline{\textit{Err}_{\textit{cost}}(t,D(t))} \ \geq \sum_{i \in \{1,\dots,s\}} \textit{Err}_{\textit{cost}}(t_i,D(t_i))$$

The equality is given in the case that all nodes t, t_1, \ldots, t_s represent the same class.

ML:III-95 Decision Trees

Overfitting (continued)

Proof Sketch

$$\begin{split} \textit{Err}_{\textit{cost}}(t,D(t)) &= \min_{c' \in C} \sum_{c \in C} p(c \mid t) \cdot p(t) \cdot \textit{cost}(c' \mid c) \\ &= \sum_{c \in C} p(c,t) \cdot \textit{cost}(\textit{label}(t) \mid c) \\ &= \sum_{c \in C} (p(c,t_1) + \ldots + p(c,t_{k_s})) \cdot \textit{cost}(\textit{label}(t) \mid c) \\ &= \sum_{i \in \{1,\ldots,k_s\}} \sum_{c \in C} (p(c,t_i) \cdot \textit{cost}(\textit{label}(t) \mid c) \end{split}$$

$$\begin{aligned} \textit{Err}_{\textit{cost}}(t,D(t)) - \sum_{i \in \{1,\dots,k_s\}} \textit{Err}_{\textit{cost}}(t_i,D(t_i)) = \\ \sum_{i \in \{1,\dots,k_s\}} \left(\sum_{c \in C} p(c,t_i) \cdot \textit{cost}(\textit{label}(t) \mid c) - \min_{c' \in C} \sum_{c \in C} p(c,t_i) \cdot \textit{cost}(c' \mid c) \right) \end{aligned}$$

The summands on the right equation side are greater than or equal to zero.

Remarks:

	The lemma	does also	hold if the	misclassification	rate is used	as performance measure.
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The algorithm template for the construction of decision trees, $\underline{DT\text{-}construct}$, prefers larger trees, entailing a more fine-grained partitioning of D. A consequence of this behavior is a tendency to overfitting.

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Overfitting (continued)

Approaches to counter overfitting:

- 1. Stopping of the decision tree construction process during training.
- 2. Pruning of a decision tree after training:
 - □ Partitioning of *D* into three sets for training, validation, and test:
 - (a) reduced error pruning
 - (b) minimal cost complexity pruning
 - (c) rule post pruning
 - \Box statistical tests such as χ^2 to assess generalization capability
 - heuristic pruning

Stopping

Possible criteria for stopping [splitting criteria]:

- 1. Size of D(t).
 - D(t) will not be partitioned further if the number of examples, |D(t)|, is below a certain threshold.
- 2. Purity of D(t).

D(t) will not be partitioned further if all induced splittings yield no significant impurity reduction $\Delta \iota$.

Problems:

- ad 1) A threshold that is too small results in oversized decision trees.
- ad 1) A threshold that is too large omits useful splittings.
- ad 2) $\Delta \iota$ cannot be extrapolated with regard to the tree height.

Pruning

The pruning principle:

- 1. Construct a sufficiently large decision tree T_{max} .
- 2. Prune T_{max} , starting from the leaf nodes towards the tree root.

Each leaf node t of T_{max} fulfills one or more of the following conditions:

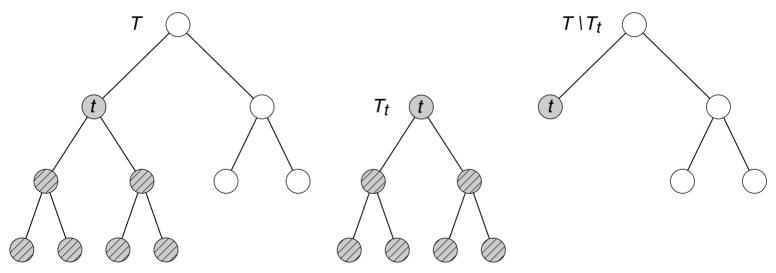
- D(t) is sufficiently small. Typically, $|D(t)| \leq 5$.
- \Box D(t) is comprised of examples of only one class.
- \Box D(t) is comprised of examples with identical feature vectors.

Pruning (continued)

Definition 10 (Decision Tree Pruning)

Given a decision tree T and an inner (non-root, non-leaf) node t. Then pruning of T wrt. t is the deletion of all successor nodes of t in T. The pruned tree is denoted as $T \setminus T_t$. The node t becomes a leaf node in $T \setminus T_t$.

Illustration:



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Pruning (continued)

Definition 11 (Pruning-Induced Ordering)

Let T' and T be two decision trees. Then $T' \leq T$ denotes the fact that T' is the result of a (possibly repeated) pruning applied to T. The relation \leq forms a partial ordering on the set of all trees.

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Pruning (continued)

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Let T' and T be two decision trees. Then $T' \leq T$ denotes the fact that T' is the result of a (possibly repeated) pruning applied to T. The relation \leq forms a partial ordering on the set of all trees.

Problems when assessing pruning candidates:

- o Pruned decision trees may not stand in the \leq -relation.
- \Box Starting with T_{max} , promising candidates may not result from locally optimum pruning decisions (greedy strategy).
- \Box Its monotony disqualifies $Err(T, D_{tr})$ as an estimator for $Err^*(T)$. [Lemma]

Pruning (continued)

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Control pruning with validation set D_{vd} , where $D_{vd} \cap D_{tr} = \emptyset$, $D_{vd} \cap D_{ts} = \emptyset$:

- 1. $D_{tr} \subset D$ for decision tree construction.
- 2. $D_{vd} \subset D$ for overfitting analysis *during* pruning.
- 3. $D_{ts} \subset D$ for decision tree evaluation *after* pruning.

Pruning: Reduced Error Pruning

Reduced error pruning for decision tree T_{max} and validation set D_{vd} :

- 1. $T = T_{\text{max}}$
- 2. Choose an inner node t in T.
- 3. Tentative pruning of T wrt. t: $T' = T \setminus T_t$. Based on D(t) assign class to t. [DT-construct]
- 4. If $Err(T', D_{vd}) \leq Err(T, D_{vd})$ then accept pruning: T = T'.
- 5. Continue with Step 2 until all inner nodes of T are tested.

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Reduced error pruning for decision tree T_{max} and validation set D_{vd} :

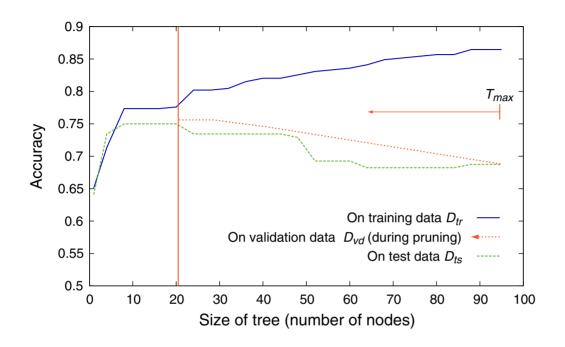
- 1. $T = T_{\text{max}}$
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- 4. If $Err(T', D_{vd}) \leq Err(T, D_{vd})$ then accept pruning: T = T'.
- 5. Continue with Step 2 until all inner nodes of T are tested.

Problem:

If D is small, its partitioning into three sets for training, validation, and test will discard valuable information for decision tree construction.

Improvement: rule post pruning

Pruning: Reduced Error Pruning (continued)



[Mitchell 1997]

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Extensions

- consideration of the misclassification cost introduced by a splitting
- "surrogate splittings" for insufficiently covered feature domains
- splittings based on (linear) combinations of features
- regression trees

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