## NEW

May 26, 2016

# 1 PCA as a tool for preprocessing and Kernel PCA

This problem sheet explores applications and extensions of PCA. The first two exercises deal with PCA as a method for preprocessing and the third one illustrates how to find nonlinear structure via kernel PCA.

```
In [2]: import numpy as np
    import matplotlib.pyplot as plt
    import scipy.linalg
    import scipy.spatial.distance
    import pandas as pd
    from PIL import Image
    %matplotlib inline

!python --version

Python 3.4.3 :: Anaconda 2.3.0 (x86_64)
```

## 1.1 4.1 Preprocessing

- 1. Load the dataset pca2.csv. Compte the Principal Components PC1 and PC2 and plot the data in the coordinate system PC1 vs. PC2 What do you observe?
- 2. Remove Observations 17 and 157 and redo the first two steps. What is the difference?

```
In [10]: # (a)
         pca2 = np.loadtxt(open("pca2.csv"),delimiter=",",skiprows=1)
         pca2_centered = pca2 - pca2.mean(0)
         cov = np.cov(pca2_centered.T)
         # eigen-values and -vectors
         values, vectors = np.linalg.eigh(cov)
         fig = plt.figure(figsize=(15,7))
         plt.subplot(1,2,1)
         plt.axhline(0, color="black", alpha=0.5)
         plt.axvline(0, color="black", alpha=0.5)
         plt.title("Original data a")
         plt.plot(pca2[:,0], pca2[:,1], 'ro', alpha=0.2)
         plt.quiver(0,0,vectors[0][0],vectors[0][1],angles='xy',scale_units='xy',scale=0.3)
         plt.quiver(0,0,vectors[1][0],vectors[1][1],angles='xy',scale_units='xy',scale=0.3)
         plt.xlabel("X1")
         plt.ylabel("X2")
         plt.axis([-15, 15, -15, 15])
```

```
# transform the data into the pcas coordinate system
  pca2_data_transormed = np.dot(pca2, vectors)
  plt.subplot(1,2,2)
  plt.axhline(0, color="black", alpha=0.5)
  plt.axvline(0, color="black", alpha=0.5)
  plt.title("Data in PCA1 and PCA2 coordinate system a")
  plt.plot(pca2_data_transormed[:,0],pca2_data_transormed[:,1] ,'ro', alpha=0.2)
  plt.xlabel("PCA1")
  plt.ylabel("PCA2")
  plt.axis([-15, 15, -15, 15])
  plt.show()
                Original data a
                                                      Data in PCA1 and PCA2 coordinate system a
10
                                               10
-10
                                              -10
                                              -15 ∟
-15
-15 L
-15
                                 10
                                                      -10
                                                                  PCA1
```

#### Observation:

When transformed into the PCA1 - PCA2 coordinate system, one would think the data would fit along the a

```
In [30]: # (a)
    pca2 = np.delete(pca2, [16,156],0)

center = pca2.mean(0)
    pca2_centered = pca2 - center

cov = np.cov(pca2_centered.T)

# eigen-values and -vectors
    values2, vectors2 = np.linalg.eigh(cov)

fig = plt.figure(figsize=(15,7))

plt.subplot(1,2,1)
    plt.axhline(0, color="black", alpha=0.5)
    plt.axvline(0, color="black", alpha=0.5)
```

```
plt.title("Original data b")
  plt.plot(pca2[:,0], pca2[:,1], 'ro', alpha=0.2)
  plt.quiver(0,0,vectors2[0][0],vectors2[0][1],angles='xy',scale_units='xy',scale=0.3)
  plt.quiver(0,0,vectors2[1][0],vectors2[1][1],angles='xy',scale_units='xy',scale=0.3)
  plt.xlabel("X1")
  plt.ylabel("X2")
  plt.axis([-15, 15, -15, 15])
  # tranform data into pcas coordinate system
  pca2_data_transormed = np.dot(pca2, vectors2)
  x = np.empty([len(pca2), 2])
  for i in range (len(pca2)):
      x[i,:]=np.dot(pca2[i,:],vectors2)
  vectors_transformed = np.dot(vectors2, vectors)
  plt.subplot(1,2,2)
  plt.axhline(0, color="black", alpha=0.5)
  plt.axvline(0, color="black", alpha=0.5)
  plt.title("Data in PCA1 and PCA2 coordinate system b, \n(Quivers represent the eigen vectors of
  plt.plot(pca2_data_transormed[:,0],pca2_data_transormed[:,1],'ro', alpha=0.1)
  plt.quiver(0,0,vectors_transformed[0][0],vectors_transformed[0][1],angles='xy',scale_units='xy
  plt.quiver(0,0,vectors_transformed[1][0],vectors_transformed[1][1],angles='xy',scale_units='xy
  plt.xlabel("PCA1")
  plt.ylabel("PCA2")
  plt.axis([-15, 15, -15, 15])
  plt.show()
                                                   Data in PCA1 and PCA2 coordinate system b,
                                                (Quivers represent the eigen vectors of the original data)
                Original data b
10
                                             10
-10
                                            -10
                                            -15 ∟
-15
                                                               PCA1
```

We observe that the data in coordinate system b is rotated a little bit from the data in a. The quivers represent the eigen vectors of the data from a. Them being off from the x and y axis show this rotation.

### 1.2 4.2 Whitening

- 1. Load the dataset pca4.csv and check for outliers in the individual variables.
- 2. Do PCA on a reasonable subset of this data. Use a scree plot to determine how many PCs represent the data well.
- 3. "Whiten" the data, i.e. create a set of 4 uncorrelated variables with mean  $\theta$  and standard deviation equal to 1. This can be done e.g. using the transformation

$$Z = X E D^{-\frac{1}{2}}$$

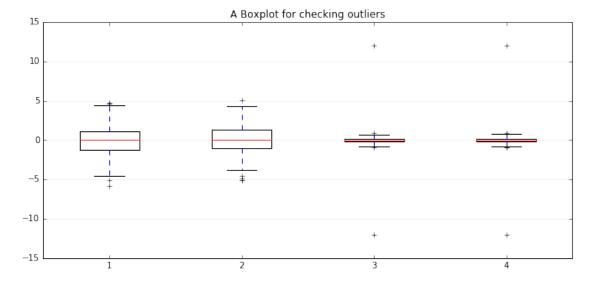
The new variables zi form the columns of Z, E is a matrix containing the normalized eigenvectors of the covariance matrix Sigma of the centered data X and D is a diagonal matrix containing the corresponding eigenvalues.

4. Make 3 heat plots of the (i) 4x4 covariance matrix Sigma, (ii) the covariance matrix of the data projected onto PC1-PC4, and (iii) of the whitened variables.

```
In [5]: # (a)
    pca4 = np.loadtxt(open("pca4.csv"),delimiter=",",skiprows=1)

fig, ax1 = plt.subplots(figsize=(10,6))
    plt.title('A Boxplot for checking outliers')
    plt.subplots_adjust(left=0.075, right=0.95, top=0.9, bottom=0.25)

bp = plt.boxplot(pca4, notch=0, sym='+', vert=1, whis=1.5)
    plt.setp(bp['boxes'], color='black')
    plt.setp(bp['whiskers'], color='blue')
    plt.setp(bp['fliers'], color='green', marker='+')
    ax1.yaxis.grid(True, linestyle='-', which='major', color='lightgrey',alpha=0.5)
    plt.show()
```



Interpretation: In X1 and X2 the data is spread out widely. Outliers are still visible according to the boxplots, but there are located very near to the whiskers. We won't treat these values as outliers. In X3 and X4 however, the data is much more dense. Four observations lie far off the rest of the data. These are clearly outliers.

```
# first we chose a subset: complete data except outliers
outliers = []
for i in range(pca4.shape[0]) :
    if (abs(pca4[i][2]) > 10 or abs(pca4[i][3]) > 10) :
        outliers.append(i)

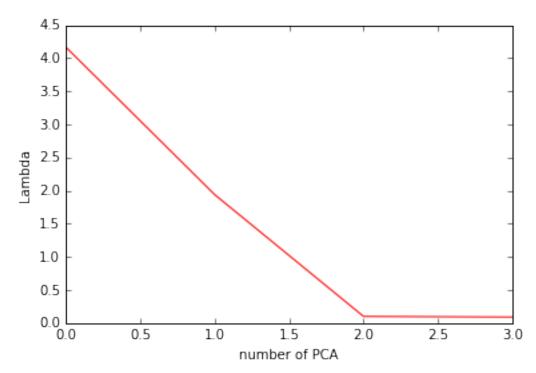
pca4_subset = np.delete(pca4, outliers, axis=0)

pca4_sub_centerd = pca4_subset - pca4_subset.mean(0)

pca4_sub_cov = np.cov(pca4_sub_centerd.T)

val_sub, vec_sub = np.linalg.eig(pca4_sub_cov)

line = plt.plot(val_sub, color='r')
plt.xlabel('number of PCA')
plt.ylabel('Lambda')
plt.show()
print "as we can see in the graph, we only need the first and second PCs to represeent the data
```



as we can see in the graph, we only need the first and second PCs to represeent the data well

```
In [7]: # (c)
    # E matrix of eigenvectors
    pca4_centerd = pca4 - pca4.mean(0)

pca4_cov = np.cov(pca4_centerd.T)
```

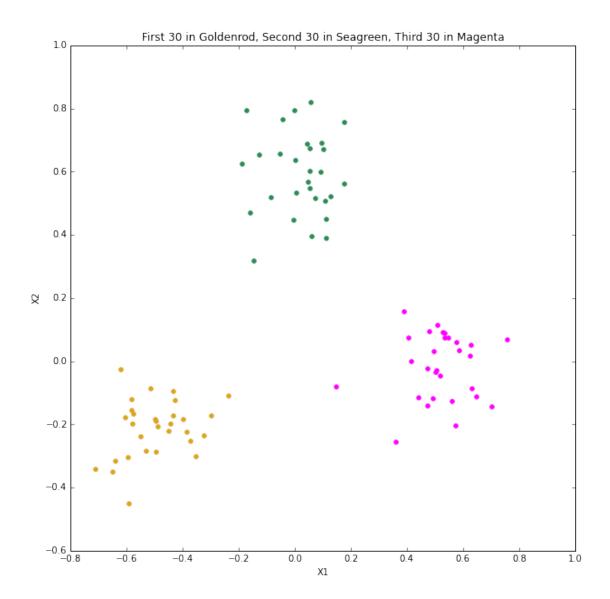
In [6]: # (b)

```
val_pca4, vec_pca4 = np.linalg.eig(pca4_cov)
         # eigenvalues and vector are sorted
        E = vec_pca4.copy()
         # eigenvalues
        D = np.diag(val_pca4)
        Z = (pca4_centerd.dot(E)).dot(np.diag(1/np.sqrt(val_pca4)))
In [8]: # (d) Make 3 heat-plots of the
              (i) 4x4 covariance matrix E,
              (ii) the covariance matrix of the data projected onto PC1-PC4, and
              (iii) of the whitened variables.
        proj = pca4.dot(vec_pca4)
        proj_cov = np.cov(proj.T)
        fig = plt.figure(figsize=(15,5))
        ax1 = fig.add_subplot(1,3,1)
         ax1.imshow(pca4_cov, interpolation='none')
        ax1.set_title("Covariance Matrix original pca4.csv data")
        ax2 = fig.add_subplot(1,3,2)
        ax2.imshow(proj_cov, interpolation='none')
        ax2.set_title("Covariance Matrix of projected data onto PC1-PC4")
        ax3 = fig.add_subplot(1,3,3)
        ax3.imshow(np.cov(Z.T), interpolation='none')
         ax3.set_title("Covariance Matrix of Whitened data")
        plt.show()
                                    Covariance Matrix of projected data onto PC1-PC4__0.5 Covariance Matrix of Whitened data
        Covariance Matrix original pca4.csv data
      0.0
                                     0.0
                                                                   0.0
      0.5
                                     0.5
                                                                   0.5
      1.5
                                     1.5
                                                                   1.5
      2.0
                                     2.0
                                                                   2.0
                                     2.5
      2.5
      3.0
                                     3.0
      3.5
-0.5 0.0 0.5 1.0 1.5 2.0 2.5 3.0 3.5
                                     3.5
-0.5 0.0 0.5 1.0 1.5 2.0 2.5 3.0 3.5
```

### 1.3 4.3 Kernel PCA: Toy Data

1. Create a toy dataset of 2-dimensional data points . . .

```
data[1,0:30] = np.random.normal(-0.2, 0.1, 30)
dataVis[0,0:2500] = np.random.normal(-0.5, 0.1, 2500)
dataVis[1,0:2500] = np.random.normal(-0.2, 0.1, 2500)
# center: (0.0, 0.1)
data[0,30:60] = np.random.normal(0.0, 0.1, 30)
data[1,30:60] = np.random.normal(0.6, 0.1, 30)
dataVis[0,2500:5000] = np.random.normal(0.0, 0.1, 2500)
dataVis[1,2500:5000] = np.random.normal(0.6, 0.1, 2500)
# center: (-0.5, 0)
data[0,60:90] = np.random.normal(0.5, 0.1, 30)
data[1,60:90] = np.random.normal(0.0, 0.1, 30)
dataVis[0,5000:7500] = np.random.normal(0.5, 0.1, 2500)
dataVis[1,5000:7500] = np.random.normal(0.0, 0.1, 2500)
plt.figure(figsize=(10,10))
plt.scatter(data[0,0:30],data[1,0:30], color='goldenrod')
plt.scatter(data[0,31:60],data[1,31:60], color='seagreen')
plt.scatter(data[0,61:90],data[1,61:90], color='magenta')
ax = plt.gca()
ax.set_xlabel('X1')
ax.set_ylabel('X2')
ax.set_title('First 30 in Goldenrod, Second 30 in Seagreen, Third 30 in Magenta')
plt.show()
```



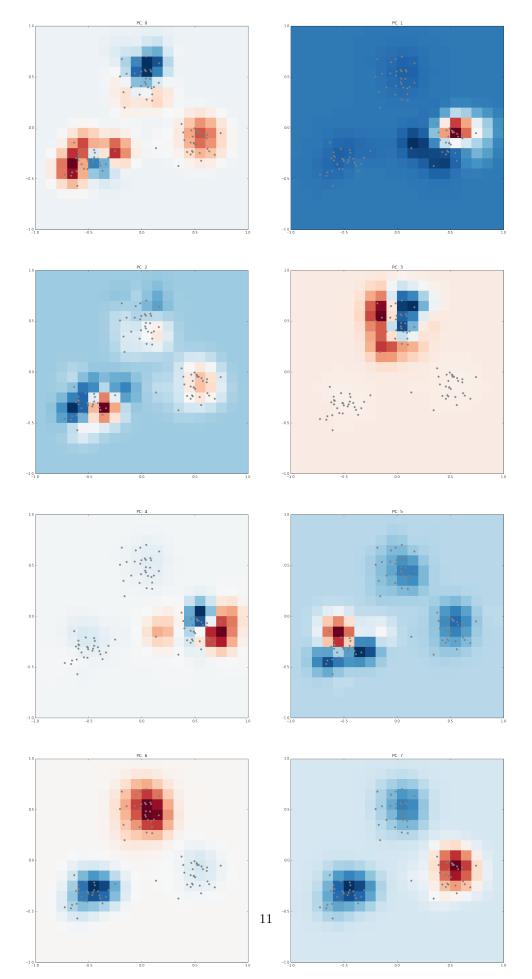
```
In [190]: #(b)

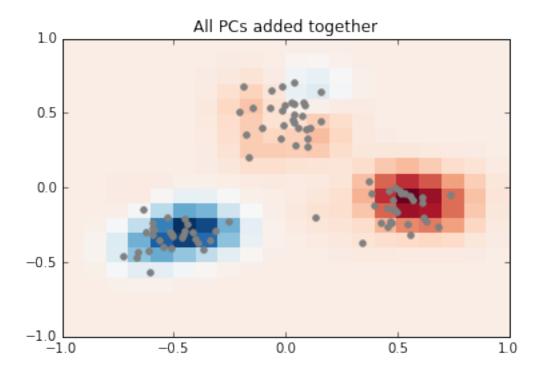
#(0) center data
#print(np.mean(data.T, axis=0).shape)
datac = (data - np.mean(data.T, axis=0).reshape(-1,1)).T

#(1) calculate the unnormalized kernel matrix
sigma = .1
p = datac.shape[0]
#pxp
Khat = np.zeros((p, p))

for a in range(p):
    for b in range(p):
        Khat[a, b] = np.exp(- (np.power(np.linalg.norm(datac[b] - datac[a]), 2))/(2*np.power(
```

```
#(2) normalize to 0 mean
\#K = K - rowavg - colavg + matrixavg
K = Khat - Khat.sum(axis=0)/p - Khat.sum(axis=1)/p + Khat.sum()/np.power(p,2)
#(3) solve the eigenvalue problem
D, U = np.linalg.eigh(K)
Dsub = D[-8:][::-1]
Usub = U[:,-8:][::-1]
#(4) normalize eigen vectors to unit length
Unorm = Usub / (np.sqrt(p * Dsub) * np.linalg.norm(Usub))
#(5) project onto eigen vectors
proj = np.dot(Unorm.T, K)
#(c)
datam = np.zeros((1,2))
xs = np.arange(-1, 1.1, .1)
ys = np.arange(-1, 1.1, .1)
for x in xs:
    for y in ys:
        datam = np.vstack( (datam, [x, y]) )
datam = datam[1:]
Kbd = np.zeros( (p, len(datam)) )
for b in range(p):
    for d in range(len(datam)):
        Kbd[b, d] = np.exp(- (np.power(np.linalg.norm(datac[b] - datam[d]), 2))/(2*np.power(s
rowavg = Kbd.sum(axis=0)/Kbd.shape[1]
colavg = Kbd.sum(axis=1)/Kbd.shape[0]
matrixavg = Kbd.sum()/(Kbd.shape[0]*Kbd.shape[1])
for b in range(Kbd.shape[0]):
    Kbd[b,:] -= rowavg
for d in range(Kbd.shape[1]):
    Kbd[:,d] -= colavg
for b in range(Kbd.shape[0]):
    for d in range(Kbd.shape[1]):
        Kbd[b, d] += matrixavg
datap = np.dot(Unorm.T, Kbd)
fig, axarray = plt.subplots(4,2)
fig.set_figheight(48)
fig.set_figwidth(24)
for i in range(8):
    axarray[np.floor(i/2),i\%2].pcolor(np.repeat(xs.reshape(-1,1), 21, axis=1), np.repeat(ys.reshape(-1,1), 21, axis=1))
    axarray[np.floor(i/2),i%2].scatter(datac.T[0], datac.T[1], color="grey")
    axarray[np.floor(i/2),i%2].set_title('PC: '+str(i))
    axarray[np.floor(i/2),i\%2].axis([-1,1,-1,1])
```





Each different PC seems to show a cluster.