

# view\_frames Result

Recorded at time: 1729615505.6739244

os\_sensor

Broadcaster: default\_authority  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

os\_imu

base\_link

Broadcaster: default\_authority  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

Broadcaster: default\_authority  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

os\_lidar

odom

