## TEP4156 Formula sheet

$$\begin{aligned} \frac{\partial u_i}{\partial x_j} &= \dot{\varepsilon}_{ij} + \dot{\Omega}_{ij} \\ \dot{\varepsilon}_{ij} &= \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \\ \dot{\varepsilon}_{ij} &= \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \\ \dot{\Omega}_{ij} &= \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right) \\ \dot{\Omega}_{ij} &= \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right) \\ \dot{\Omega}_{ij} &= \frac{1}{2} \varepsilon_{ijk} \dot{\Omega}_{ij} \\ \dot{\Omega}_{ij} &= \frac{1}{2} \varepsilon_{ijk} \dot{\Omega}_{ij} \\ \dot{\Omega}_{ij} &= \frac{\partial u_j}{\partial x} + v \frac{\partial u_j}{\partial y} = U \frac{dU}{dx} + v \frac{\partial^2 u}{\partial y^2} \\ \dot{\Omega}_{ij} &= \frac{\partial v_j}{\partial x} + v \frac{\partial v_j}{\partial y} = \frac{v_j}{\partial x} + v \frac{\partial v_j}{\partial y} \\ \dot{\Omega}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial x_j} + \rho f_i \\ \dot{\partial}_{ij} &= \frac{\partial v_j}{\partial$$