

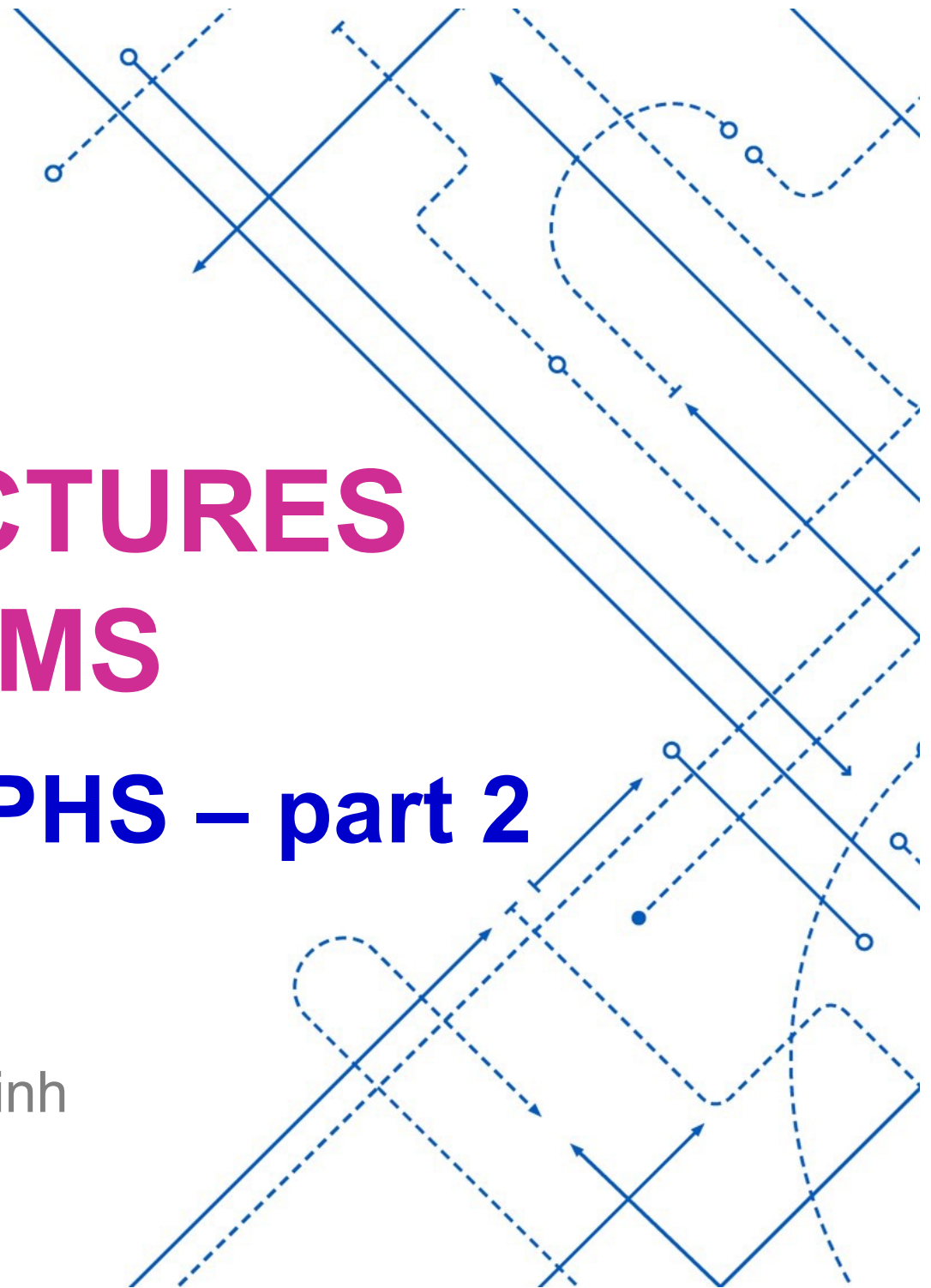


fit@hcmus

DATA STRUCTURES & ALGORITHMS

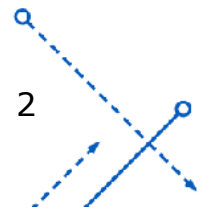
Lecture 7: GRAPHS – part 2

Lecturer: Dr. Nguyen Hai Minh



OUTLINE

- Other applications of Graphs
 - Shortest Path
 - Circuits
 - Difficult Problems





SHORTEST PATH

Dijkstra's Algorithm

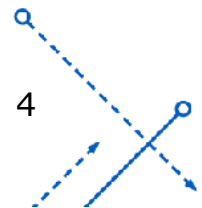
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Shortest Paths

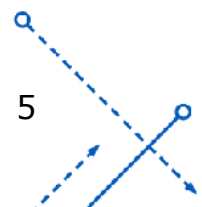
- Many problems can be modeled using graphs with weights assigned to their edges:
 - Airline flight problems
 - Computer networks problems
 - GPS navigation systems



Airline Flight Problems



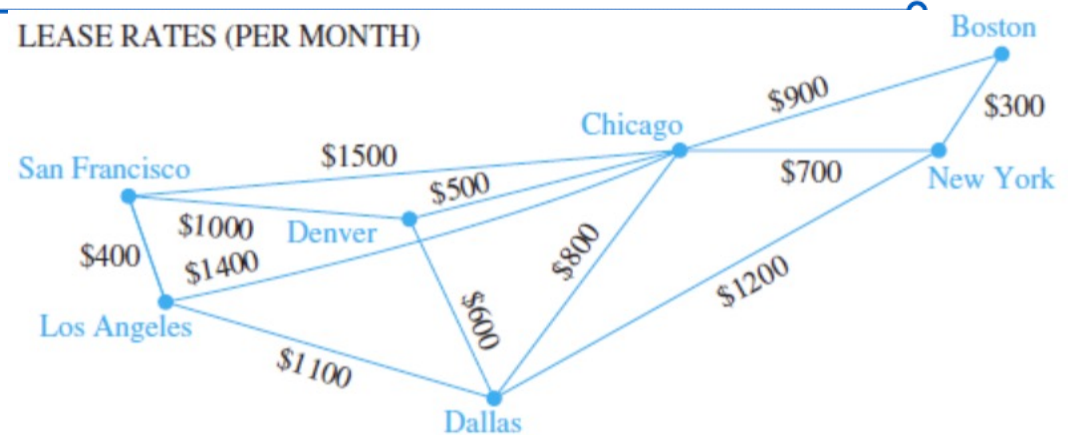
- ☐ Vertices: cities
- ☐ Edges: flights
- ☐ Weights of edges depend on the problem.
 - ☒ Distance between cities
 - ☒ Flight fare
 - ☒ Flight time
 - ☒ ...



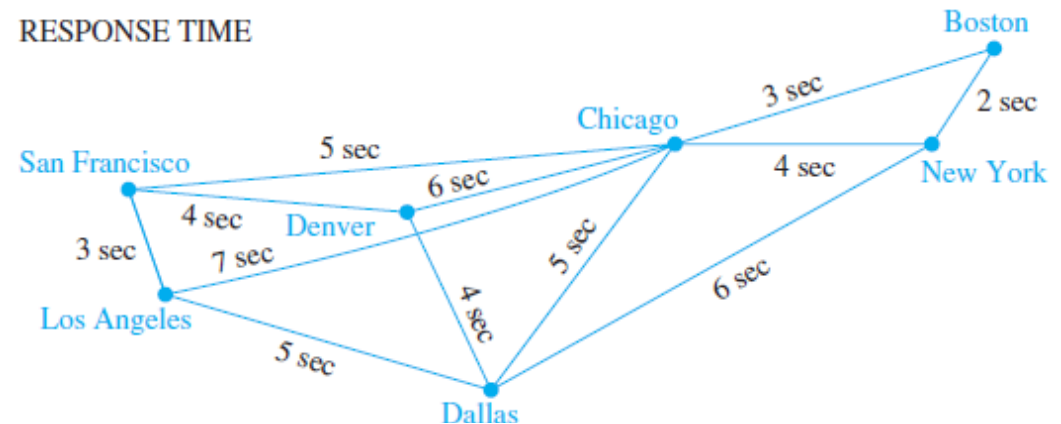
Computer Networks Problems

- Vertices: computers
- Edges: lines between computers
- Weights:
 - Communication costs (e.g., monthly cost of leasing a telephone line)
 - Response times of the computers over these lines
 - Distances between computers

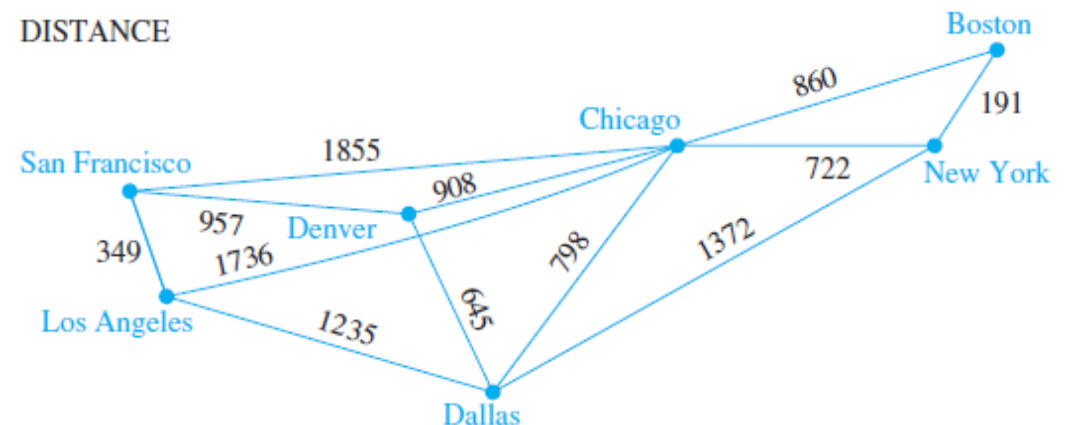
LEASE RATES (PER MONTH)



RESPONSE TIME



DISTANCE



Shortest Paths

- The input to the shortest-paths problem is a weighted, directed graph $G = (V, E)$, with a weight function $w: E \rightarrow \mathbb{R}$ mapping each edges to real-valued weights.
- We define the *shortest-path weight* $\delta(u, v)$ from u to v by

$$\delta(u, v) = \begin{cases} \min \{w(p): u \xrightarrow{p} v\} & \text{if there is a path from } u \text{ to } v \\ \infty & \text{otherwise} \end{cases}$$

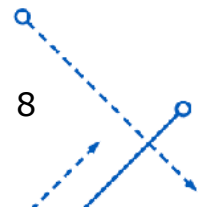
where

$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$ is the weight of path $p = \langle v_0, v_1, \dots, v_k \rangle$



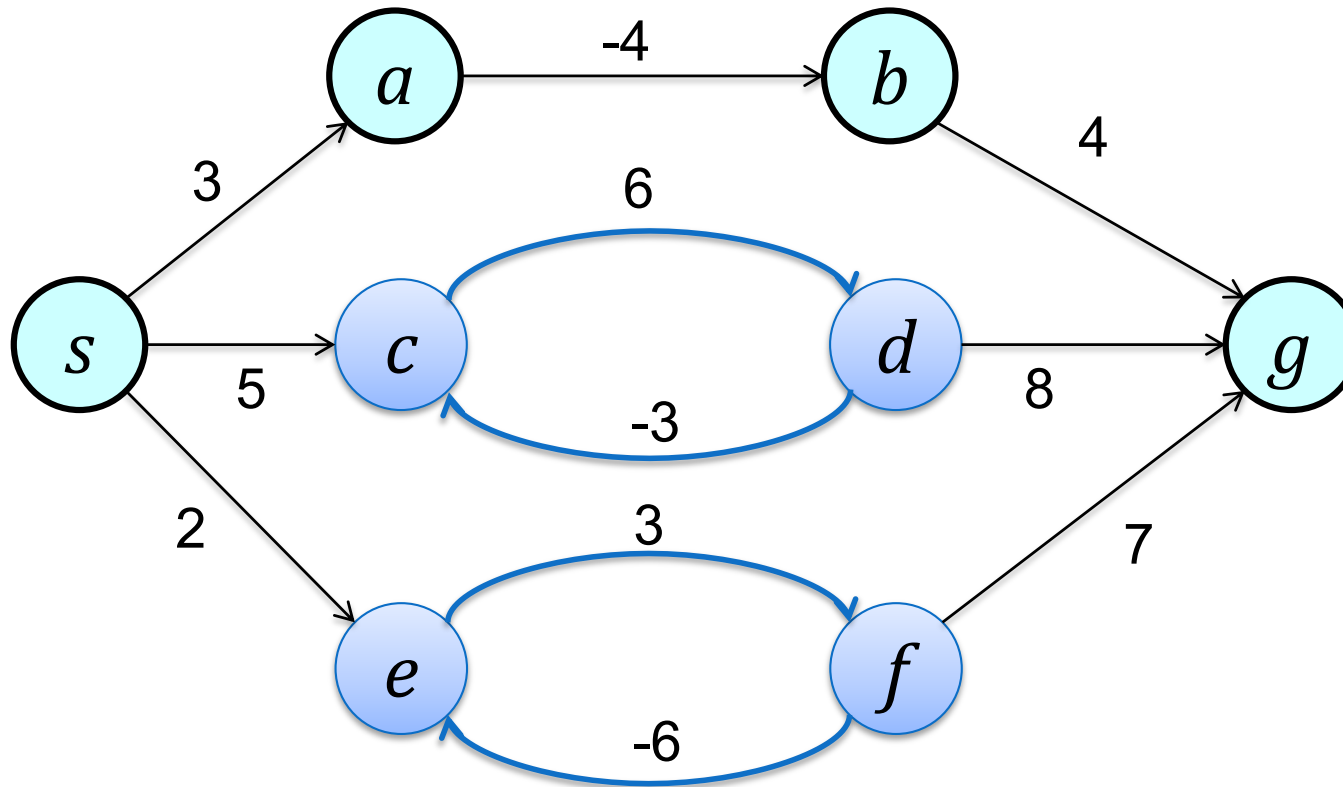
Shortest Paths – Variants

- Single-source shortest paths problem
- Single-destination shortest paths problem
- Single-pair shortest paths problem
- All-pairs shortest paths problem



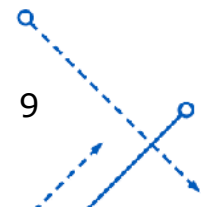
Shortest Paths – Negative-weight

□ Negative-weight edges



Negative cycles

Shortest path	cost
$s \rightarrow a$	3
$s \rightarrow b$	-1
$s \rightarrow c$	5
$s \rightarrow d$	11
$s \rightarrow e$	$-\infty$
$s \rightarrow f$	$-\infty$
$s \rightarrow g$	$-\infty$



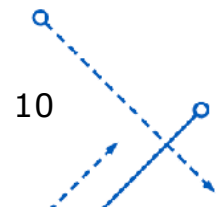
Shortest Paths

□ Cycles:

- A shortest path cannot contain a cycle

□ Representing shortest paths: each vertex v in the graph G has:

- A predecessor $v.\pi$ that is another vertex or NIL
- A shortest-path estimate $v.d$ which is an upper bound on the weight of a shortest path from source s to v

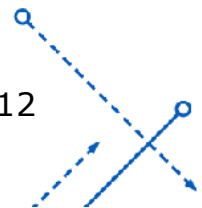


Shortest Paths

- **Dijkstra's** shortest-path algorithm
 - Determine the shortest path between a given vertex and all other vertices (Single-source shortest paths)
 - Assume that weight of edges ≥ 0
 - The directed graph G is stored in the adjacency-list representation.

Dijkstra's Algorithm Idea

- We maintain a set of vertices **S** whose final shortest path lengths have already been determined
 - In each time we consider not yet discovered vertices in the graph, and all edges going from a discovered vertex (u) to an undiscovered vertex (v).
 - We choose an undiscovered vertex with an edge from u to v , that gives the shortest path length.
 - The length from u to v for each vertex v , is given by the length of u , plus the weight between u and v .
- In the initialization step:
 - We include source node S in the set of discovered nodes and set its length to 0.
 - All other lengths are initially infinity.
- Then we keep expanding set S of discovered nodes in a greedy manner.



Dijkstra's Algorithm

INITIALIZE-SINGLE-SOURCE(G, s)

```
1  for each vertex  $v \in G.V$ 
2       $v.d = \infty$ 
3       $v.\pi = \text{NIL}$ 
4   $s.d = 0$ 
```

DIJKSTRA(G, w, s)

```
1 INITIALIZE-SINGLE-SOURCE( $G, s$ )
```

```
2  $S = \emptyset$ 
```

```
3  $Q = \emptyset$ 
```

```
4 for each vertex  $u \in G.V$ 
```

```
5     INSERT( $Q, u$ )
```

```
6 while  $Q \neq \emptyset$ 
```

```
7      $u = \text{EXTRACT-MIN}(Q)$ 
```

```
8      $S = S \cup \{u\}$ 
```

```
9     for each vertex  $v$  in  $G.Adj[u]$ 
```

```
10        RELAX( $u, v, w$ )
```

```
11        if the call of RELAX decreased  $v.d$ 
```

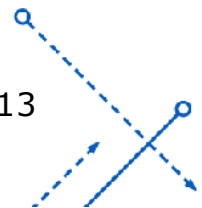
```
12            DECREASE-KEY( $Q, v, v.d$ )
```

RELAX(u, v, w)

```
1  if  $v.d > u.d + w(u, v)$ 
2       $v.d = u.d + w(u, v)$ 
3       $v.\pi = u$ 
```

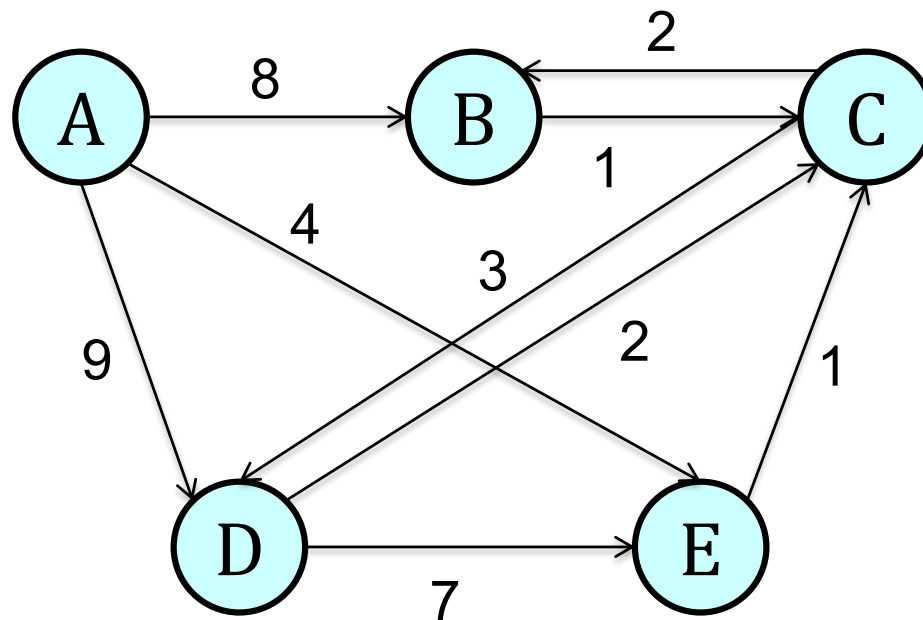
Update the min-priority queue

EXTRACT-MIN(H) deletes the element from heap H whose key is minimum, returning a pointer to the element.



Dijkstra's Algorithm – Example

- A weighted directed graph and its adjacency list

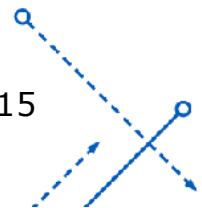


A	B ₈	D ₉	E ₄
B	C ₁		
C	B ₂	D ₃	
D	C ₂	E ₇	
E	C ₁		



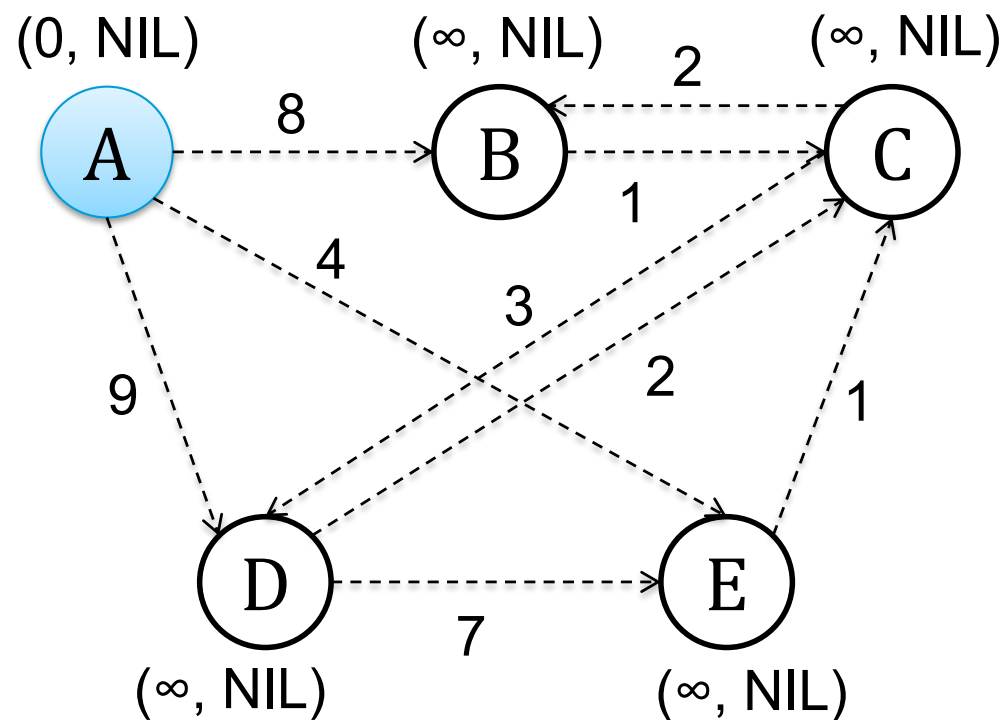
Dijkstra's Algorithm – Example

Step	Q	S	$(v.d, v.\pi)$				
			A	B	C	D	E
Init	A, B, C, D, E	\emptyset	$(0, NIL)$	(∞, NIL)	(∞, NIL)	(∞, NIL)	(∞, NIL)
1	B, C, D, E	A	$(0, NIL)$	$(8, A)$	(∞, NIL)	$(9, A)$	$(4, A)$
2	B, C, D	A, E	$(0, NIL)$	$(8, A)$	$(5, E)$	$(9, A)$	$(4, A)$
3	B, D	A, E, C	$(0, NIL)$	$(7, C)$	$(5, E)$	$(8, C)$	$(4, A)$
4	D	A, E, C, B	$(0, NIL)$	$(7, C)$	$(5, E)$	$(8, C)$	$(4, A)$
5	\emptyset	A, E, C, B, D	$(0, NIL)$	$(7, C)$	$(5, E)$	$(8, C)$	$(4, A)$

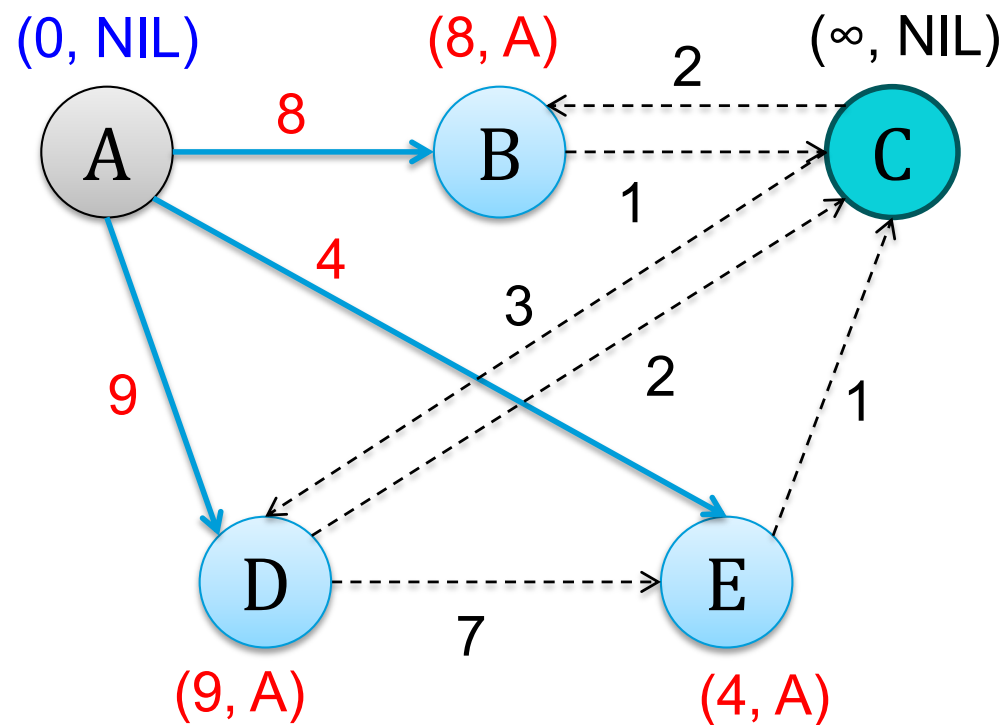


Dijkstra's Algorithm – Example

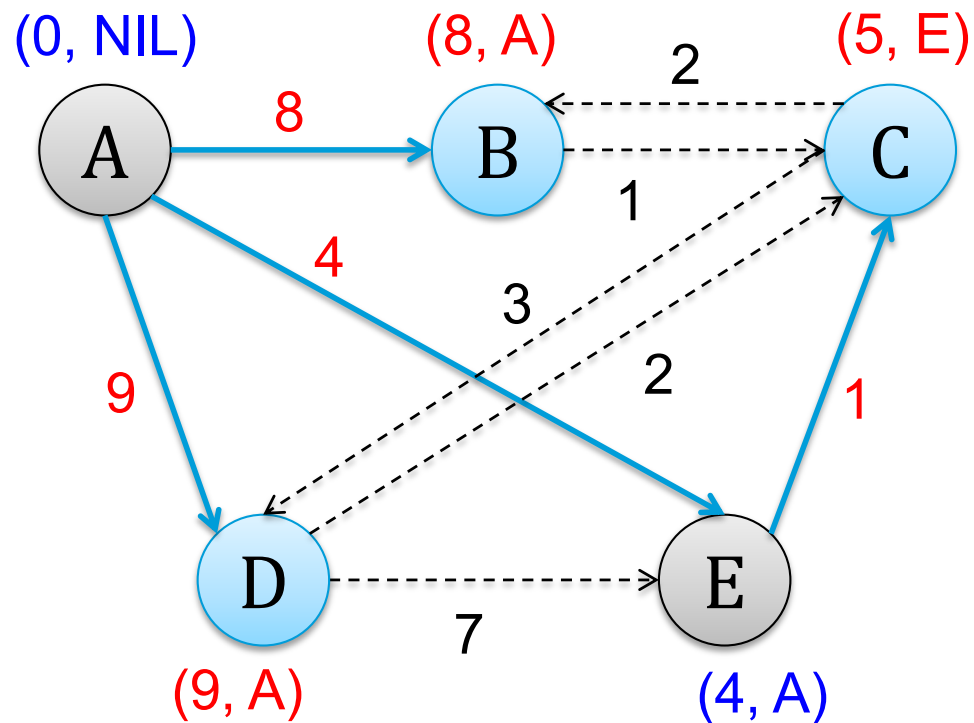
- Init the distances and predecessors from A to all v in G.



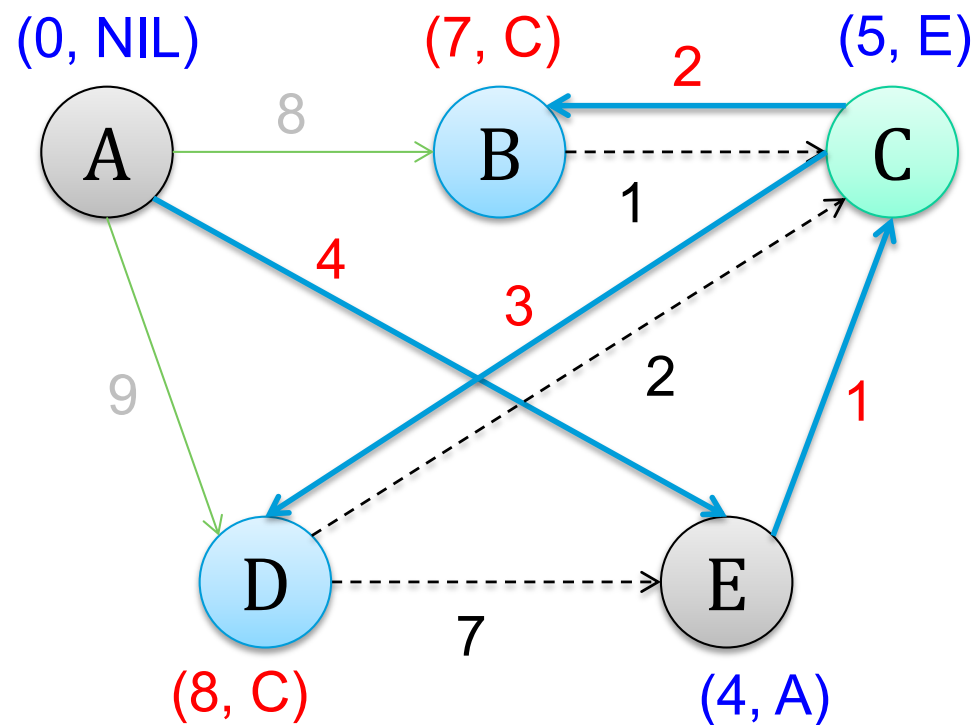
Dijkstra's Algorithm – Example



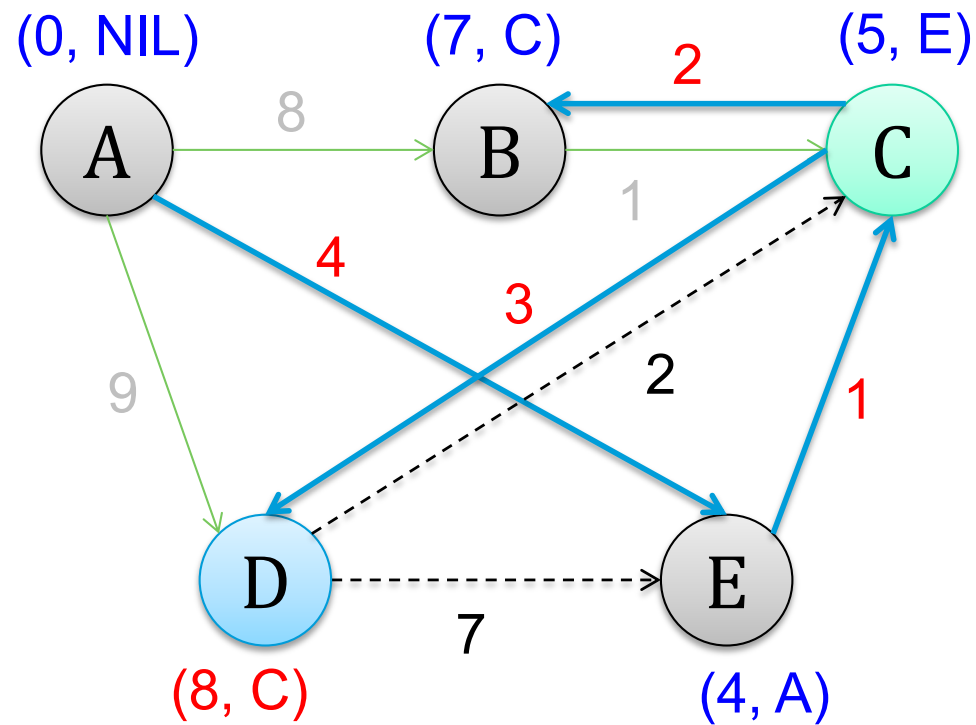
Dijkstra's Algorithm – Example



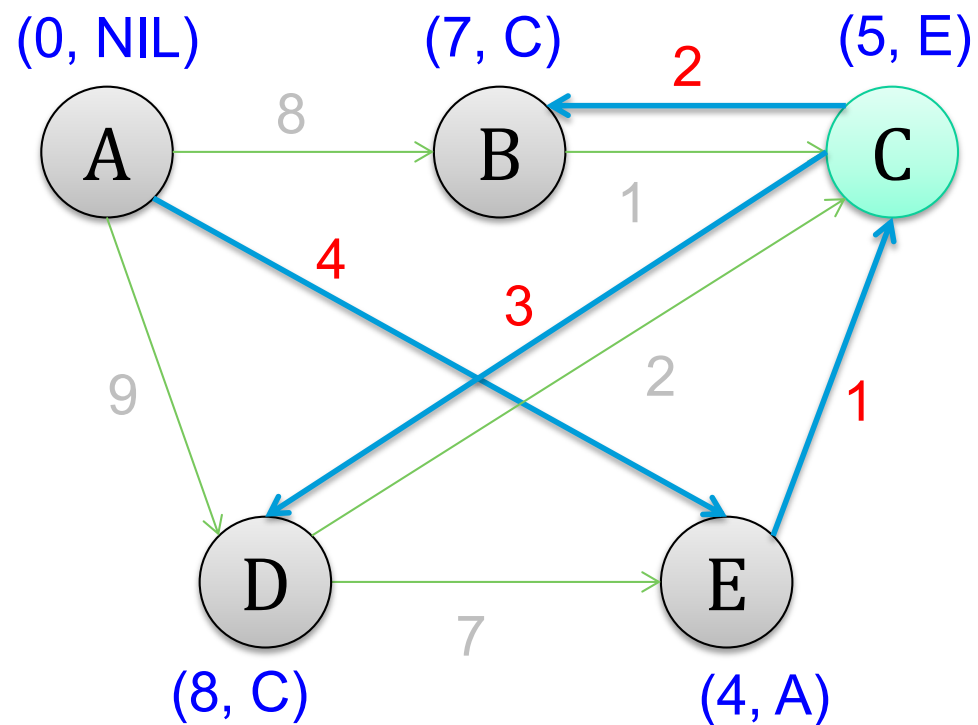
Dijkstra's Algorithm – Example



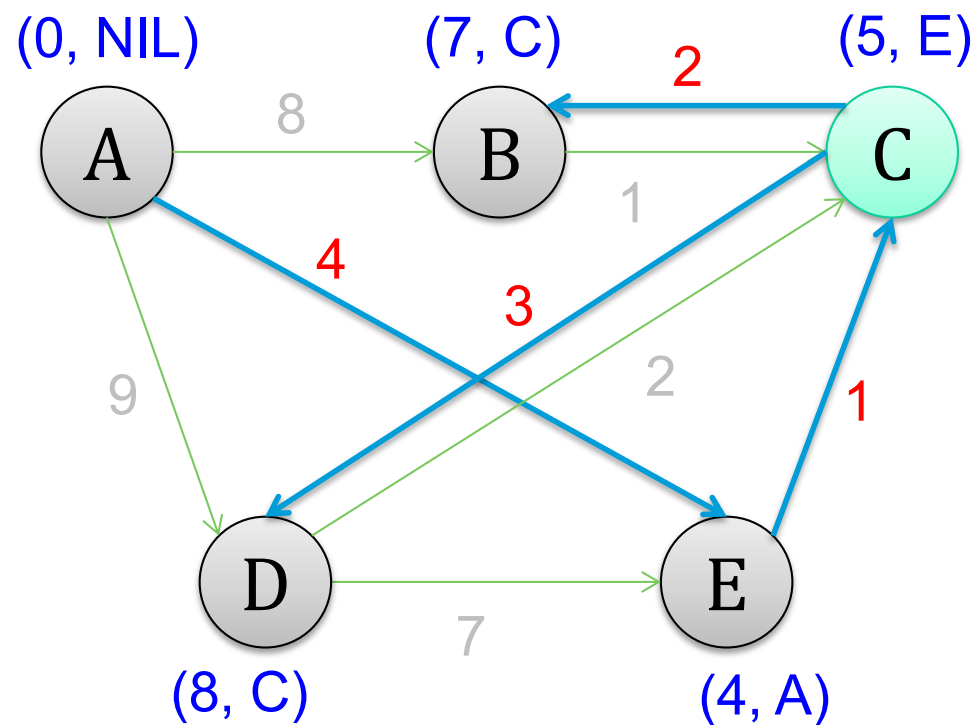
Dijkstra's Algorithm – Example



Dijkstra's Algorithm – Example

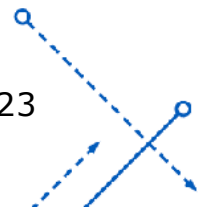


Dijkstra's Algorithm – Example



Dijkstra's Algorithm – Analysis

- We run through each node once.
- For each node we look into its adjacency list.
→ $(|V| + |E|)$ number of operations.
- However, each operation takes time since we need to find the minimum among all possible edges.
→ Use a priority queue with each minimum taking $O(\log_2 |V|)$ time.
- As a consequence, we have $O((|V| + |E|) \log_2 |V|)$ complexity.



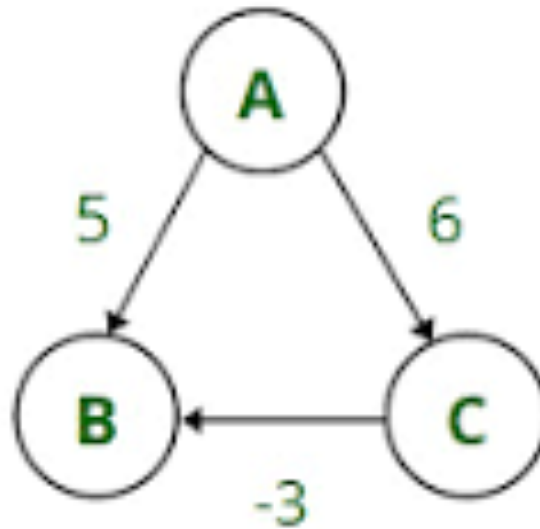
Dijkstra's Algorithm – Analysis

- We can improve this complexity to $O(|E| + |V| \log_2 |V|)$ just like in Prim's algorithm; i.e., implement the min-priority queue using Fibonacci Heap.



Dijkstra's Algorithm – Negative Edges

- Dijkstra's algorithm fails when the graph has negative weight.



CIRCUITS

Euler Circuit

Hamilton Circuit

CIRCUITS

- A **circuit** is simply another name for a type of cycle that is common in some problems.
 - Recall: a cycle in a graph is a path that begins and ends at the same vertex.
- Typical circuits either visit **every vertex once** or visit **every edge once**.



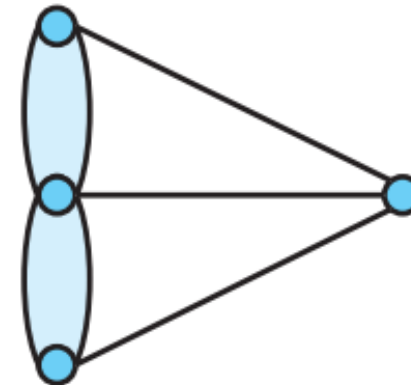
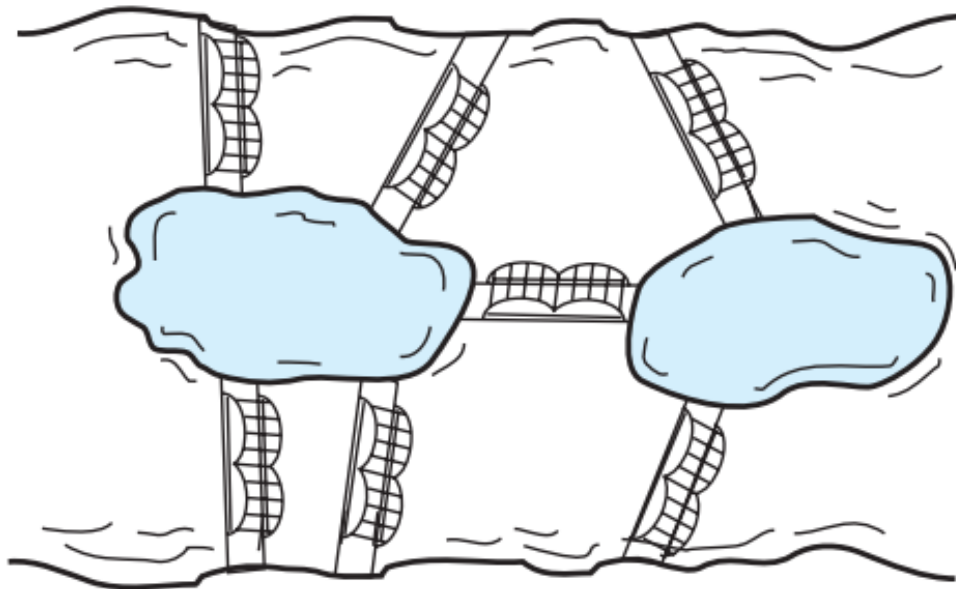
CIRCUITS – The Bridge Problem

- The first application of graphs (early 1700s) by Euler:
 - Two islands in a river are joined to each other and to the river banks by several bridges
 - The bridges → *edges in multigraph*
 - The land masses → *vertices*
 - The problem asked whether you can begin at a vertex v , pass through every edge exactly **once**, and terminate at v .



CIRCUITS – The Bridge Problem

- No solution exists for this particular configuration of edges and vertices.

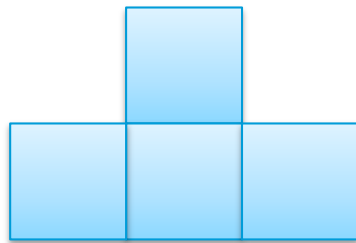


Euler Circuits

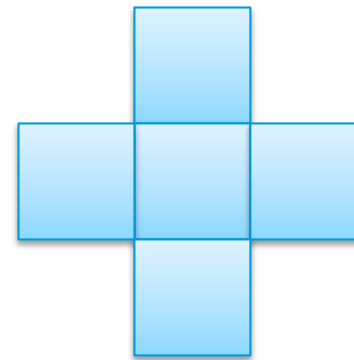
- **Euler circuit:** path that begins at a vertex v , passes through every edge in the graph exactly once, and terminates at v .
- Consider a simple undirected graph rather than a multigraph.
- Euler circuit exists if and only if each vertex touches an even number of edges (or has an even degree).

Euler Circuits – Example

- Pencil and Paper drawings:
 - Drawing without lifting your pencil or redrawing a line, ending at your starting point.



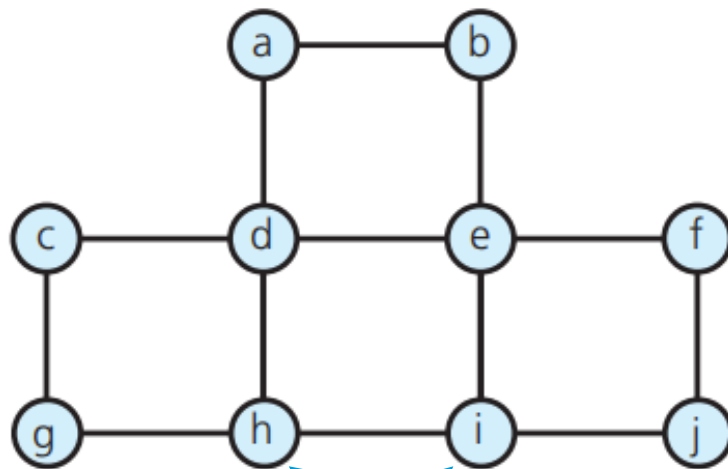
No solution



Has solution

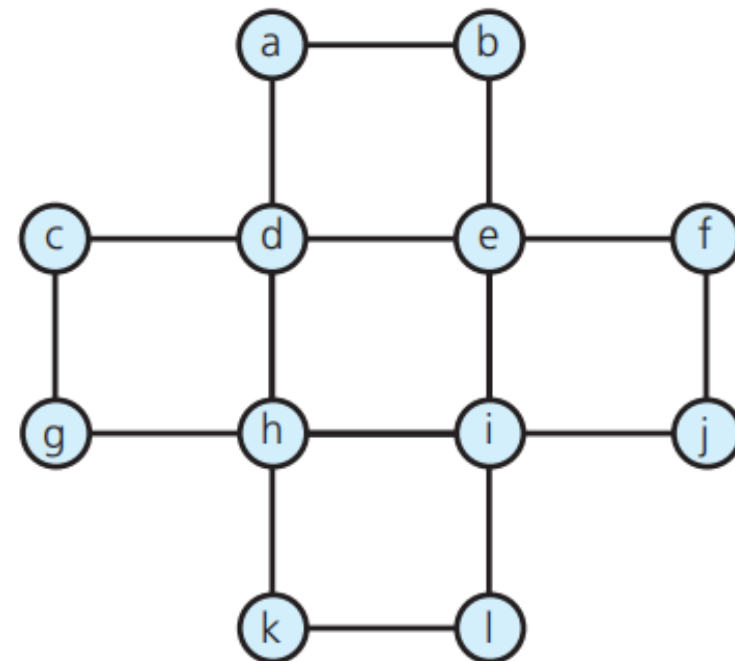
Euler Circuits – Example

- Graphs based on previous example



deg = 3

No solution



Has solution



Euler Circuits – Algorithm

- In case the Euler Circuit exists, we can find it by a strategy using DFS that marks edges instead of vertices as they are traversed.
 - You will find a cycle.
 - Then, find the first vertex along the cycle that touches an unvisited edge.
 - Loop until there is no unvisited edge.



SOME DIFFICULT PROBLEMS

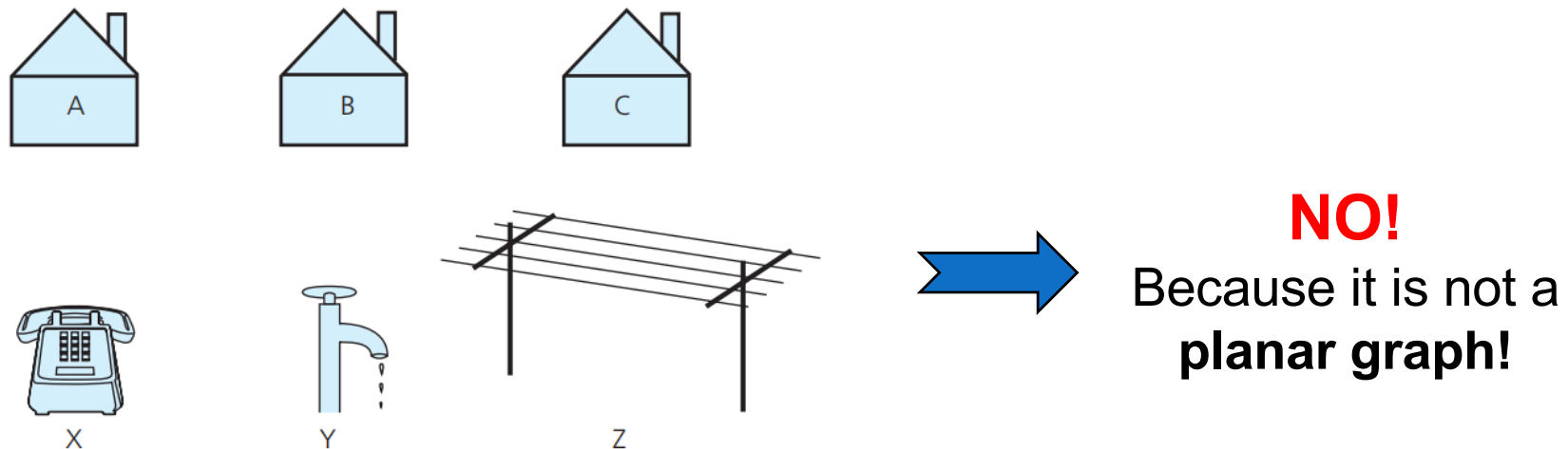
- The travelling salesperson problem
- The three utilities problem
- The four-color problem

The travelling salesperson problem

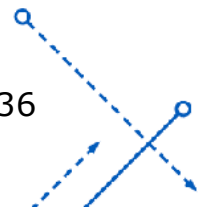
- A **Hamilton circuit** is a path that begins at a vertex v , passes through every vertex in the graph exactly once, and terminates at v .
 - Determine whether a graph contains a Hamilton circuit is difficult!
 - The TSP is a variation of this problem:
 - Involves a weighted graph that represent a roadmap.
 - Each edge has a cost.
 - The salesperson must visit every city exactly once and return to the original city with the least cost.
- *Solving this problem is not easy!*

The three utilities problem

- Is it possible to connect each house to each utility with edges that do not cross one another?



- Generation: Determine whether a given graph is planar?
 - Design an electronic circuit so that the connections do not cross



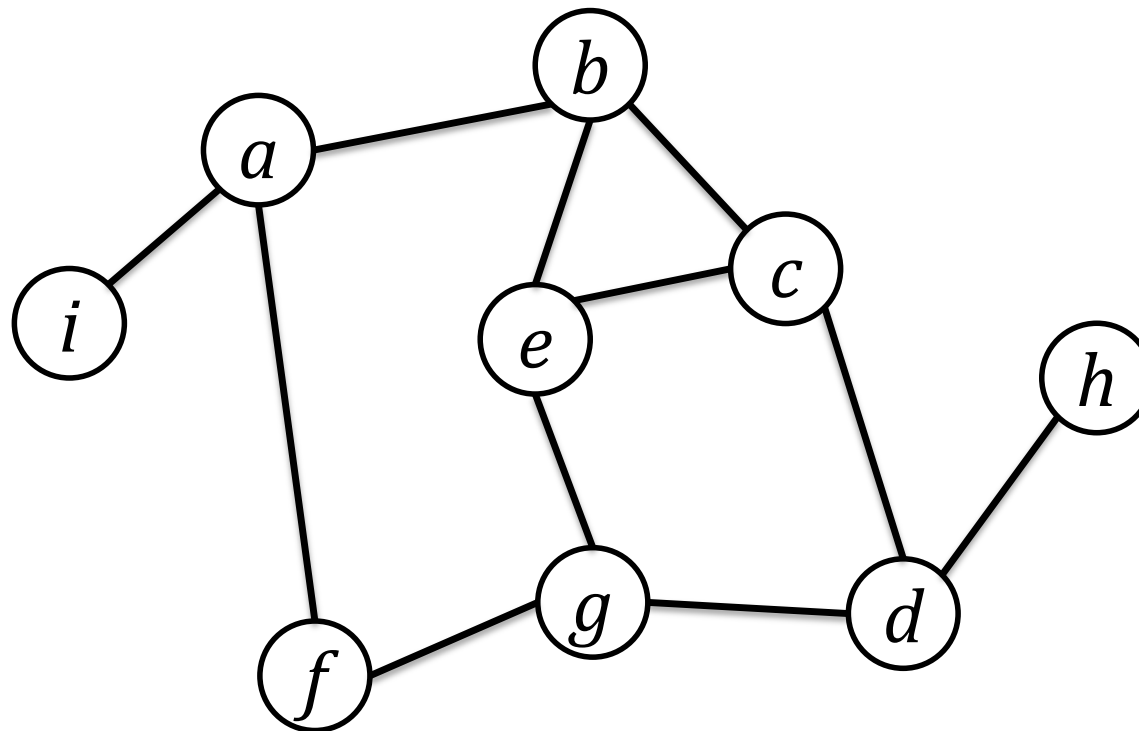
The four-color problem

- Given a planar graph, can you color the vertices so that no adjacent vertices have the same color, if you use at most **four colors**?
- The answer is **YES**, but it is difficult to prove.
- In fact, this problem was posed more than a century before it was solved in the 1970s with the use of a computer.



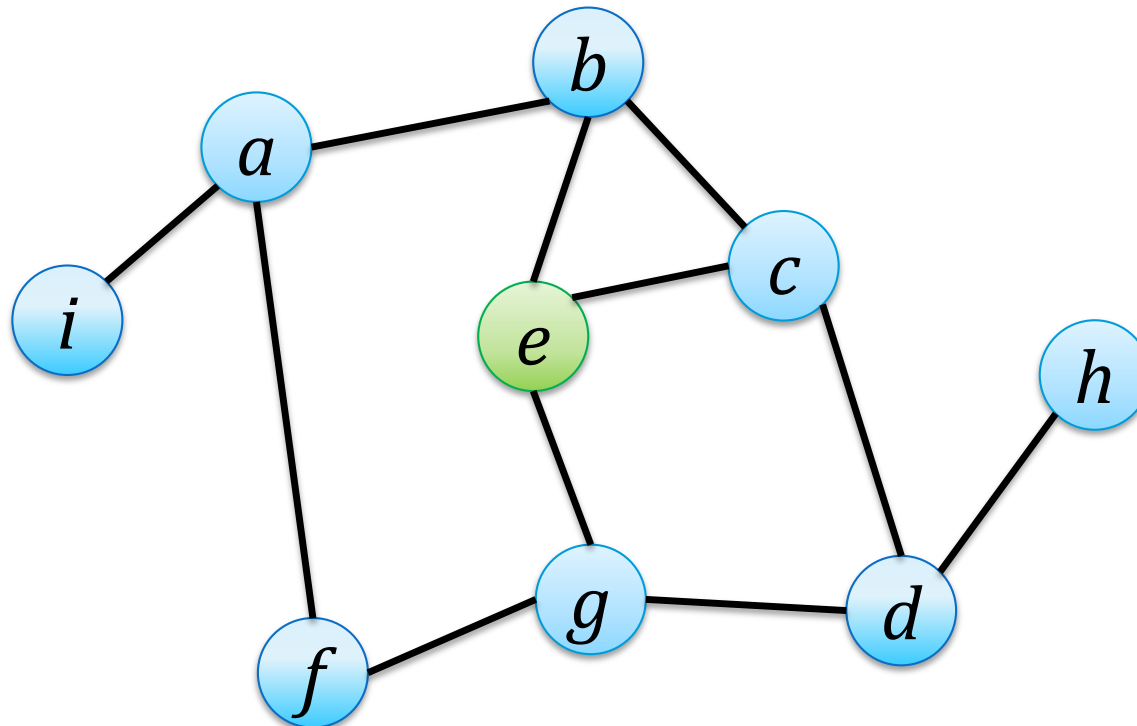
The four-color problem – Example

□ Use 3 colors to color the following map



The four-color problem – Example

□ Use 3 colors to color the following map



What's Next?

□ After today:

- Read Textbook 1: Chapter 20, 21, 22
- Read Textbook 2: Chapter 20

Q & A