

STAT 151A Lecture 39

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Remark 0.1

So far: Models have the form $Y = \mathbf{X}\beta + \varepsilon$

Requires that $\mathbb{E}[Y|\mathbf{X}]$ is a hyperplane

What if $\mathbb{E}[Y|\mathbf{X}]$ is actually nonlinear or “curved”

Seen this in special cases

Transformations - linear after a specific transformation

Logistic Regression - linear after a specific transformation

This week: Be more general about nonlinearity

Remark 0.2 (Roadmap)

Univariate x (Regression Splines), Generalized Additive Models (Multivariate x):

Polynomial Regression

Piecewise Constant

Regression Trees

Big picture: Move away from thinking about individual coefficients.

Basis expansion: Model in ?

Remark 0.3 (Polynomial Regression)

$$y_i = \hat{\alpha} + \hat{\beta}x_i \rightarrow y_i \approx \hat{\alpha} + \hat{\beta}_1x_i + \hat{\beta}_2x_i^2 + \hat{\beta}_3x_i^3 + \dots$$

Fits very nicely into our traditional regression framework: Define a design matrix

$$\mathbf{X} = \begin{pmatrix} 1 & x_1 & x_1^2 & x_1^3 & \dots \\ 1 & x_2 & x_2^2 & x_2^3 & \dots \\ \vdots & \vdots & \vdots & \vdots & \\ 1 & x_n & x_n^2 & x_n^3 & \dots \end{pmatrix}$$

Proceed as usual: $\hat{\beta} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top y$ and so on, \hat{y}, \vec{e}, R^2 , etc.

Inference: Assume NLM

$$Y = \mathbf{X}\beta + \varepsilon, \varepsilon \sim \mathcal{N}(\vec{0}, \sigma^2 \mathbb{I}_n)$$

All of the usual diagnostics and inference results still hold

Biggest difference: We don't really care about individual $\hat{\beta}_j$'s anymore, the role or impact of change of difference in x_i is now explained by many different $\hat{\beta}_j$'s

Still might want to get uncertainty estimates for \hat{y}_i or $\mathbb{E}[\hat{y}_i|x_i]$

$$\hat{y}_i = \hat{f}(x_i) = \hat{\beta}_0 + \hat{\beta}_1x_i + \hat{\beta}_2x_i^2 + \dots + \hat{\beta}_dx_i^d$$

Assume NLM: and let $\vec{z}_i = (1 \quad x_i \quad x_i^2 \quad \dots \quad x_i^d)$

$$\text{Var}(\hat{y}_i) = \vec{z}_i^\top (\sigma^2 (\mathbf{Z}^\top \mathbf{Z})^{-1}) \vec{z}_i$$

Also $\hat{y}_i \sim N, \hat{\sigma}^2 \sim \chi_{n-p-1}^2$

Create pointwise CI for $\hat{f}(x_i) : \hat{f}(x_i) \pm t_{1-\alpha/2, n-p-1} \cdot \hat{\sigma} \sqrt{\vec{z}_i^\top (\mathbf{Z}^\top \mathbf{Z})^{-1} \vec{z}_i}$

Remark 0.4 (Downsides)

- Can overfit a lot, especially for high powers of x
- Fitted models do very weird things outside the range of observed data (global implications for every point)

Remark 0.5 (Piecewise Constant Regression)

Goal: keep local information local

$\vec{x} \rightarrow$ choose quantiles c_1, \dots, c_k

Define $C_0(x_i) = 1 \{x_i < c_1\}$

$C_1(x_i) = 1 \{c_1 \leq x_i < c_2\}$

\vdots

$C_k(x_i) = 1 \{c_k \leq x_i\}$

Create a design matrix

$$\mathbf{X} = \begin{pmatrix} \uparrow & \uparrow & & \uparrow \\ C_0(\vec{x}) & C_1(\vec{x}) & \cdots & C_k(\vec{x}) \\ \downarrow & \downarrow & & \downarrow \end{pmatrix}$$

Fit a linear model

$$\hat{y}_i = \sum_{j=1}^k \hat{\beta}_j C_j(x_i)$$

Piecewise constant, mean of each quantile

Good: Very simple and does not extrapolate

Bad: Overfits with small bins, choosing bins is a headache, discontinuities are ugly and make it hard to model trends

Remark 0.6 (Big Idea)

Combine piecewise constant and polynomial regression \rightarrow Both do basis expansion, take a single $\vec{x} \rightarrow$ turn into many columns

First attempt: Piecewise polynomials \rightarrow not good \rightarrow Take a piecewise polynomial model:

- Add restrictions

- (1) Require continuity of cut points (knots), functions agree
- (2) Require differentiability at cut points, functions derivatives agree (regression spline)