Henry Buron

henryburon2024@u.northwestern.edu | linkedin.com/in/henryburon | github.com/henryburon

Education

Northwestern University | McCormick School of Engineering **Sep. 2023 – Dec. 2024 (Expected)**
M.S. in Robotics *Evanston, IL*

- **Portfolio**: henryburon.github.io

William & Mary **Sep. 2019 – May 2023**
B.S. in Engineering Physics, Cum Laude *Williamsburg, VA*

Relevant Coursework

- Embedded Systems in Robotics, SLAM for Robotics, Machine Learning, Robotic Manipulation, Theory of Machines–Dynamics, Mechatronics, Classical Mechanics, Ordinary Differential Equations, Linear Algebra

Skills

Software: Python, C/C++, Linux, Bash, CMake, Version Control (Git/GitHub)
Robotics: ROS/ROS2, SLAM, Motion Planning, Machine Learning, OpenCV, Gazebo, CoppeliaSim, ArduPilot
Hardware: Electronics, Microcontrollers (PIC32, Arduino), CNC Machining, 3D Printing, CAD (Inventor/OnShape)

Projects

EKF SLAM from Scratch on TurtleBot3 [Current] | *C++, ROS2, CMake* **Jan. 2024 - Present**

- Implementing Extended Kalman Filter SLAM from scratch in a ROS2 C++ package for localization of a TurtleBot3.
- Creating a kinematics control and odometry library for differential drive robot.

Mobile Robot with Auxiliary Drone Deployment [Current] | *ROS2, Multi-Robot System* **Jan. 2024 - Present**

- Exploration robot capable of deploying drone from the field to enhance sensing and operational capabilities.
- Building from scratch with ros2_control; designed to identify targets and transmit live data to base station.

Polyglotbot: A 7 DoF Robot Arm that Writes Translated Text and Speech | *ROS2, Python* **Dec. 2023**

- Co-developed a ROS2 package for a Franka Emika robot arm that plans and executes cartesian paths.
- Created a custom Python API for the ROS2 MoveIt! package to control the robot arm's motion.
- Localized AprilTags, created speech-to-text functionality, converted waypoints to movement with MoveIt! package.

Machine Learning Emotion Classification | *Python, Image Processing, Feature Extraction* **Nov. 2023**

- Developed a machine learning pipeline for emotion classification in facial images, achieving up to 77% accuracy.
- Employed Histogram of Oriented Gradients (HOG) feature extraction to capture subtle changes and edges.

Computer Vision-Controlled Robot Arm | *Computer Vision, Python, Image Processing* **Sep. 2023**

- Designed pipeline using CV and inverse kinematics to detect, localize, and grasp a purple pen with robot arm.
- Utilized RGB image segmentation, depth map alignment, and coordinate transformation to guide the end-effector.

Unmanned Electric Race Boat | *ArduPilot, Electronics, Autonomous Systems* **Sep. 2022 - May 2023**

- Led a team in building electric catamaran from scratch, earning 3rd place in the competition's Unmanned Division.
- Primarily responsible for ArduPilot integration and electric propulsion systems, enabling autonomous navigation.

Experience

Baltimore Aircoil Company **May 2022 – August 2022**
Mechanical Design Engineer Intern *Jessup, MD*

- Collaborated with engineers to design intricate sheet metal parts for manufacturing in Autodesk Inventor.
- Enhanced sheet metal design consistency and reduced errors through use of automated updates with parametric models.

William & Mary Makerspace **Sep. 2021 – May 2023**
Senior Makerspace Student Engineer *Williamsburg, VA*

- Operated and managed the Makerspace's 3D printing, electronics, and prototyping services for R&D.
- Led workshops on additive manufacturing, CNC machining, laser cutting, and building FPV drones from scratch.