

HENRY BURON

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in [linkedin.com/in/henryburon](https://www.linkedin.com/in/henryburon)

github.com/henryburon

Education

Northwestern University | McCormick School of Engineering

Sep. 2023 – Dec. 2024 (Expected)

M.S. in Robotics

Evanston, IL

- **Portfolio:** henryburon.github.io

William & Mary

Sep. 2019 – May 2023

B.S. in Engineering Physics, Cum Laude

Williamsburg, VA

Relevant Coursework

- Embedded Systems in Robotics, SLAM for Robotics, Machine Learning, Robotic Manipulation, Theory of Machines–Dynamics, Mechatronics, Classical Mechanics, Ordinary Differential Equations, Linear Algebra

Skills

Software: Python, C/C++, Linux, Bash, CMake, Version Control (Git/GitHub)

Robotics: ROS/ROS2, SLAM, Motion Planning, Machine Learning, CV, Gazebo, Coppeliasim, ArduPilot

Hardware: Electronics, Microcontrollers (PIC32, Arduino), CNC Machining, 3D Printing, CAD (Inventor/OnShape)

Projects

SLAM from Scratch on TurtleBot3 [Current] | C++, ROS2, CMake

Jan. 2024 - Present

- Implementing SLAM algorithm from scratch in a ROS2 C++ package for localization of a TurtleBot3.
- Creating a kinematics control and odometry library for differential drive robot.

Mobile Robot with Auxiliary Drone Deployment [Current] | ROS2, Multi-Robot System

Jan. 2024 - Present

- Exploration robot capable of deploying drone from the field to enhance sensing and operational capabilities.
- Building from scratch with ros2_control; designed to identify targets and transmit live video to base station.

Polyglotbot: A 7 DoF Robot Arm that Writes Translated Text and Speech | ROS2, Python

Dec. 2023

- Co-developed a ROS2 package for a Franka Emika robot arm that plans and executes cartesian paths.
- Created a custom Python API for the ROS2 MoveIt! package to control the robot arm's motion.
- Localized AprilTags, created speech-to-text functionality, converted waypoints to movement with MoveIt! package.

Machine Learning Emotion Classification | Python, Image Processing, Feature Extraction

Nov. 2023

- Developed a machine learning pipeline for emotion classification in facial images, achieving up to 77% accuracy.
- Employed Histogram of Oriented Gradients (HOG) feature extraction to capture subtle changes and edges.

Computer Vision-Controlled Robot Arm | Computer Vision, Python, Image Processing

Sep. 2023

- Designed pipeline using CV and inverse kinematics to detect, localize, and grasp a purple pen with robot arm.
- Utilized RGB image segmentation, depth map alignment, and coordinate transformation to guide the end-effector.

Unmanned Electric Race Boat | ArduPilot, Electronics, Autonomous Systems

Sep. 2022 - May 2023

- Led a team in building electric catamaran from scratch, earning 3rd place in the competition's Unmanned Division.
- Primarily responsible for ArduPilot integration and electric propulsion systems, enabling autonomous navigation.

Experience

Baltimore Aircoil Company

May 2022 – August 2022

Mechanical Design Engineer Intern

Jessup, MD

- Collaborated with engineers to design intricate sheet metal parts for manufacturing in Autodesk Inventor.
- Enhanced sheet metal design consistency and reduced errors through use of automated updates with parametric models.

William & Mary Makerspace

Sep. 2021 – May 2023

Senior Makerspace Student Engineer

Williamsburg, VA

- Operated and managed the Makerspace's 3D printing, electronics, and prototyping services for R&D.
- Led workshops on additive manufacturing, CNC machining, laser cutting, and building FPV drones from scratch.