

## 5911. Walking Robot Simulation II

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A  $width \times height$  grid is on an XY-plane with the **bottom-left** cell at  $(0, 0)$  and the **top-right** cell at  $(width - 1, height - 1)$ . The grid is aligned with the four cardinal directions ("North", "East", "South", and "West"). A robot is **initially** at cell  $(0, 0)$  facing direction "East".

The robot can be instructed to move for a specific number of **steps**. For each step, it does the following.

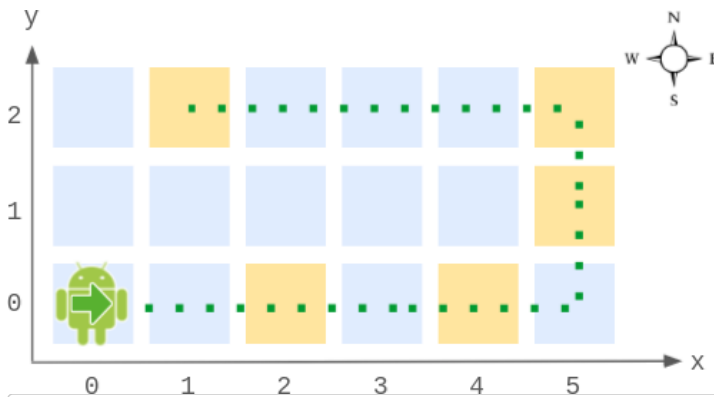
- Attempts to move **forward one** cell in the direction it is facing.
- If the cell the robot is **moving to** is **out of bounds**, the robot instead **turns** 90 degrees **counterclockwise** and retries the step.

After the robot finishes moving the number of steps required, it stops and awaits the next instruction.

Implement the `Robot` class:

- `Robot(int width, int height)` Initializes the  $width \times height$  grid with the robot at  $(0, 0)$  facing "East".
- `void move(int num)` Instructs the robot to move forward `num` steps.
- `int[] getPos()` Returns the current cell the robot is at, as an array of length 2,  $[x, y]$ .
- `String getDir()` Returns the current direction of the robot, "North", "East", "South", or "West".

**Example 1:**



### Input

```
["Robot", "move", "move", "getPos", "getDir", "move", "move", "move", "getPos", "getDir"]
[[6, 3], [2], [2], [], [], [2], [1], [4], [], []]
```

### Output

```
[null, null, null, [4, 0], "East", null, null, null, [1, 2], "West"]
```

### Explanation

```
Robot robot = new Robot(6, 3); // Initialize the grid and the robot at (0, 0) facing East.
robot.move(2); // It moves two steps East to (2, 0), and faces East.
robot.move(2); // It moves two steps East to (4, 0), and faces East.
robot.getPos(); // return [4, 0]
robot.getDir(); // return "East"
robot.move(2); // It moves one step East to (5, 0), and faces East.
                // Moving the next step East would be out of bounds, so it turns and faces North.
                // Then, it moves one step North to (5, 1), and faces North.
robot.move(1); // It moves one step North to (5, 2), and faces North (not West).
robot.move(4); // Moving the next step North would be out of bounds, so it turns and faces West.
                // Then, it moves four steps West to (1, 2), and faces West.
robot.getPos(); // return [1, 2]
robot.getDir(); // return "West"
```

**Constraints:**

- $2 \leq \text{width}, \text{height} \leq 100$
- $1 \leq \text{num} \leq 10^5$
- At most  $10^4$  calls in total will be made to `move`, `getPos`, and `getDir`.

JavaScript



```
1 /**
2  * @param {number} width
3  * @param {number} height
4  */
5 var Robot = function(width, height) {
6
7 };
8
9 /**
10 * @param {number} num
11 * @return {void}
12 */
13 Robot.prototype.move = function(num) {
14
15 };
16
17 /**
18 * @return {number[]}
19 */
20 Robot.prototype.getPos = function() {
21
22 };
23
24 /**
25 * @return {string}
26 */
27 Robot.prototype.getDir = function() {
28
29 };
30
31 /**
32 * Your Robot object will be instantiated and called as such:
33 * var obj = new Robot(width, height)
34 * obj.move(num)
35 * var param_2 = obj.getPos()
36 * var param_3 = obj.getDir()
37 */
```

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